

# PETROPHYSICS

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By: Mohammad Hossein Saberi

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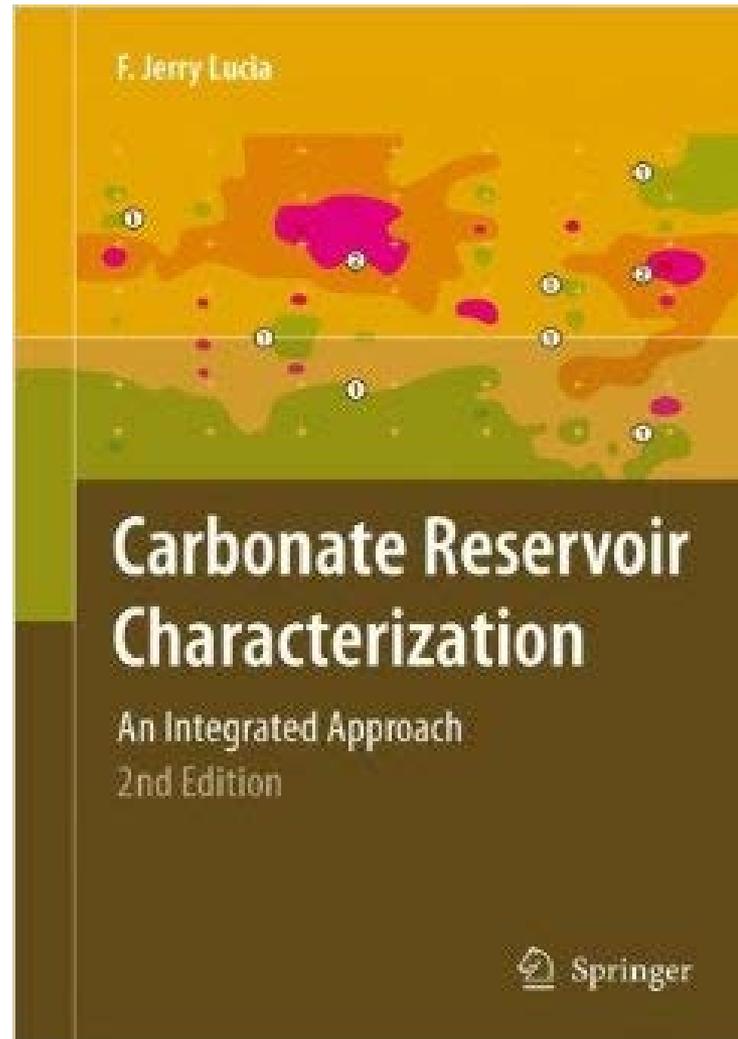
- Petrophysics

1. Reservoir Characterization
2. Well Logging
3. Well Correlation
4. Software- Geolog

- Mid Term Exam

- 1 Presentation

# Reference Books



DANIEL J. TEARPOCK

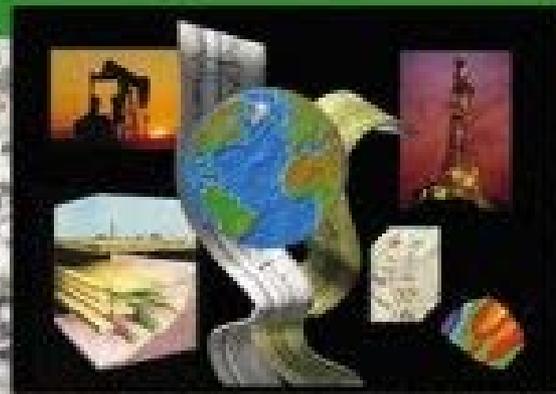
RICHARD E. BISCHKE

*Applied*  
**Subsurface  
Geological  
Mapping**

*With Structural Methods*

2nd Edition

Laurence G. Walker, Editor



Contributions in Petroleum Geology & Engineering Volume 2

# Applied Open-Hole Log Analysis

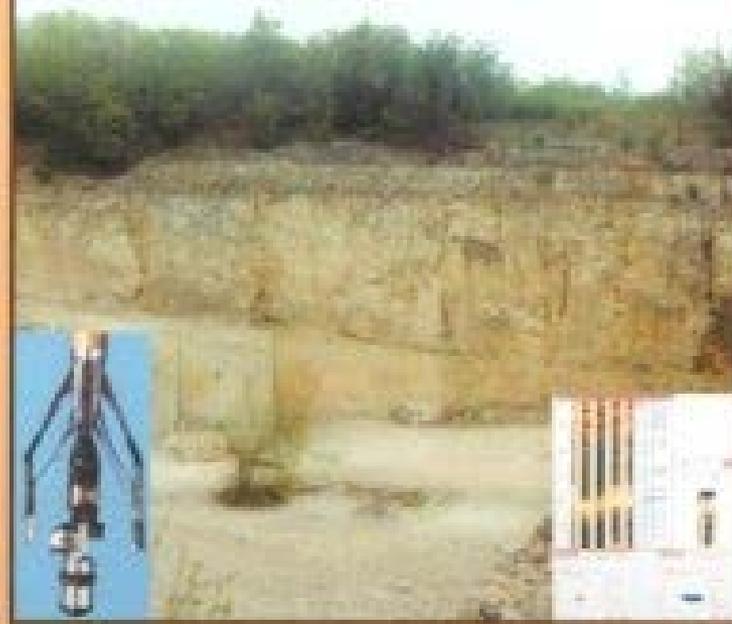
A step-by-step course in well log  
interpretation—from fundamentals  
to advanced concepts

**James Brock**

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# Well Logging and Geology

O. & L. SERRA



 SERRA LOG

# Well Logging

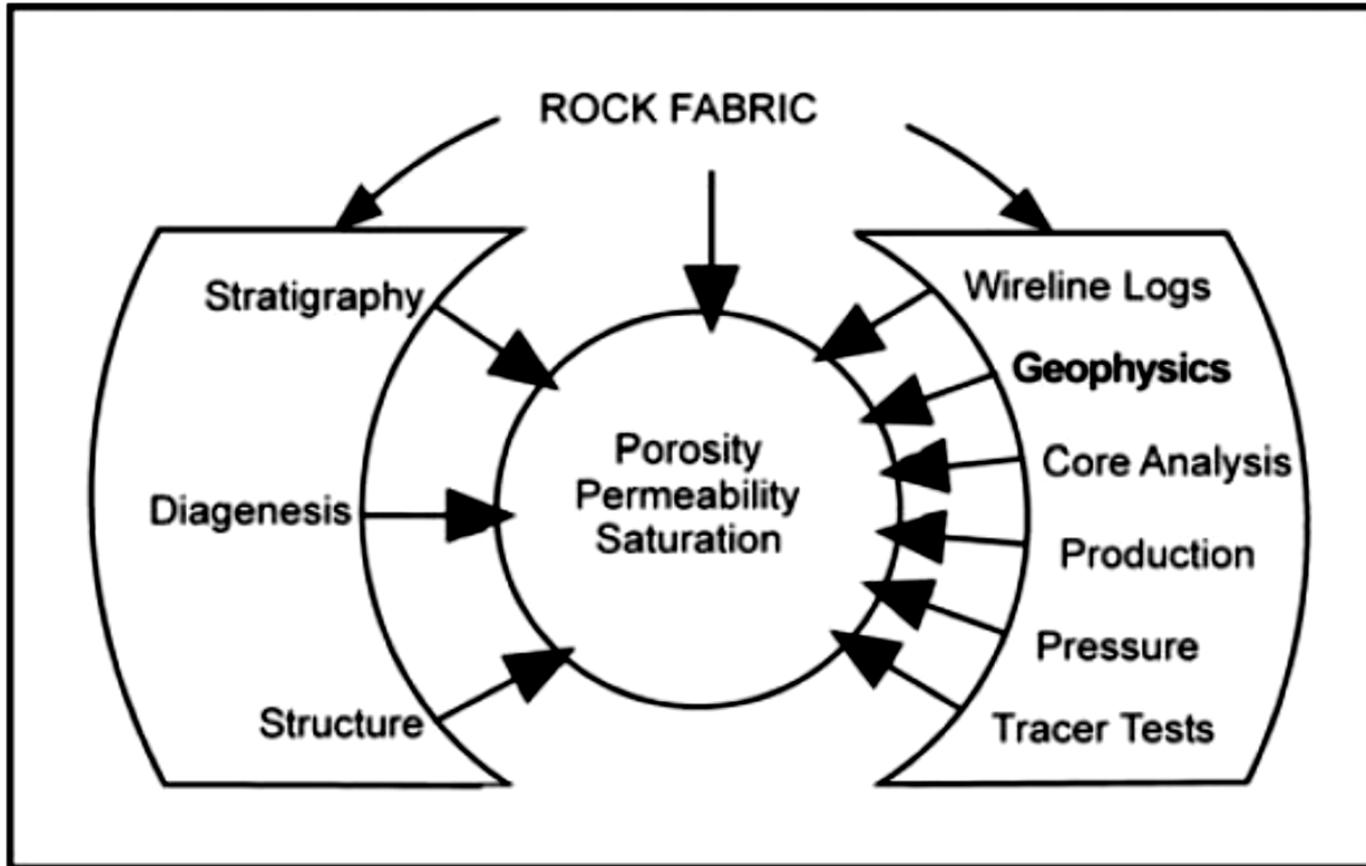
## Data Acquisition and Applications

O. & L. SERRA



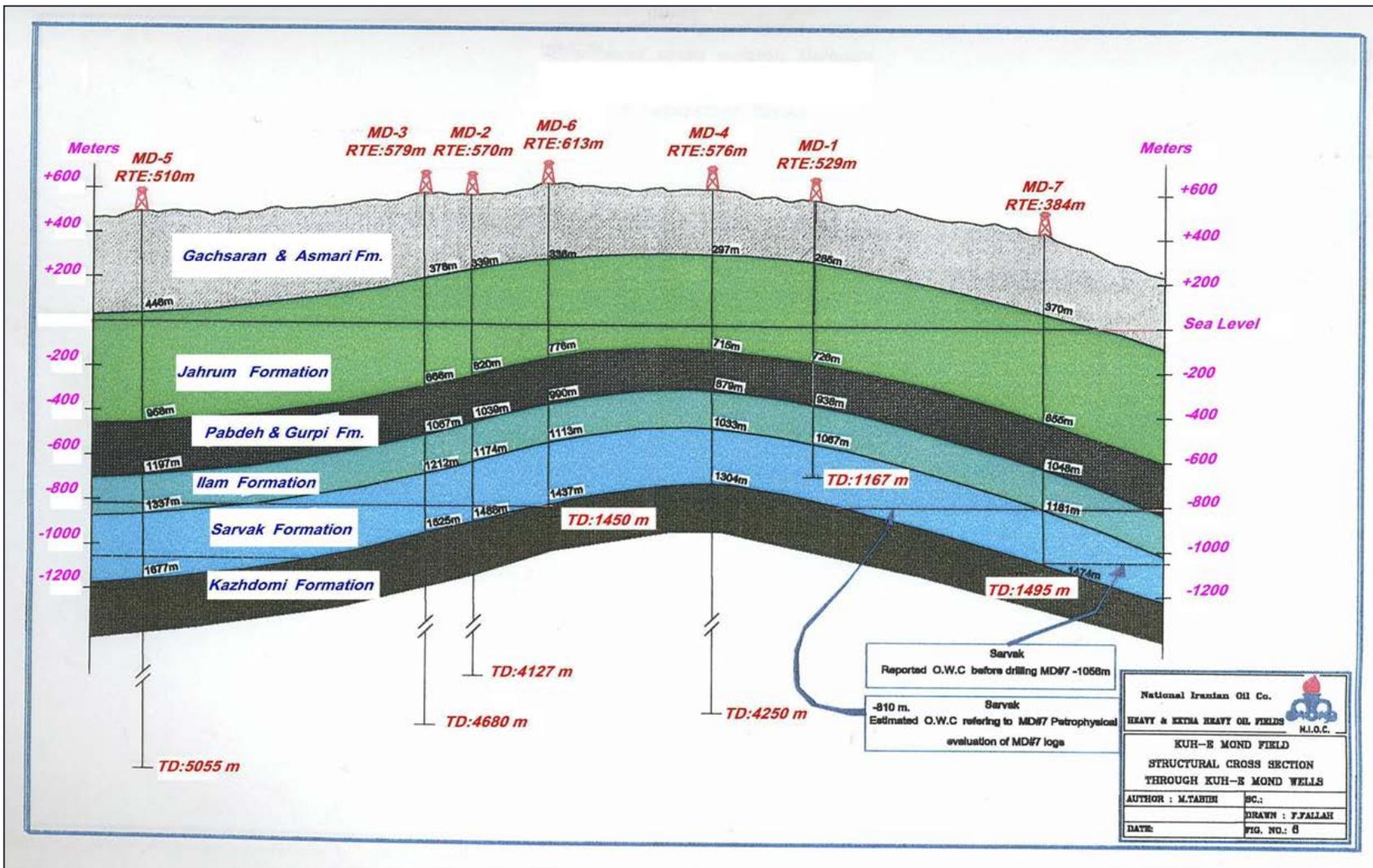
 SERRA LOG

# Reservoir Characterization



# **Petrophysical Evaluation:**

- **Reservoir Geological Analysis**
- **Routine Core Analysis (RCAL)**
- **Special Core Analysis (SCAL)**
- **Wire line log Interpretation**



Sarvak  
Reported O.W.C before drilling MD#7 -1056m

Sarvak  
-810 m.  
Estimated O.W.C referring to MD#7 Petrophysical evaluation of MD#7 logs

|  |                  |
|--|------------------|
| National Iranian Oil Co.   |                  |
| HEAVY & EXTRA HEAVY OIL FIELDS   |                  |
| <br>N.I.O.C. |                  |
| <b>KUH-E MOND FIELD</b><br><b>STRUCTURAL CROSS SECTION</b><br><b>THROUGH KUH-E MOND WELLS</b>    |                  |
| AUTHOR : M.TABEH   | SC.:             |
| DATE:  | DRAWN : F.FALLAH |
|  | FIG. NO.: 8      |





# Differences between carbonate and siliciclastics reservoirs

## Porosity

- ▶ Vuggy porosity common in carbonates, rare in clastics
- ▶ Microporosity common in carbonates
- ▶ High proportion of non-effective porosity in carbonates

## Permeability

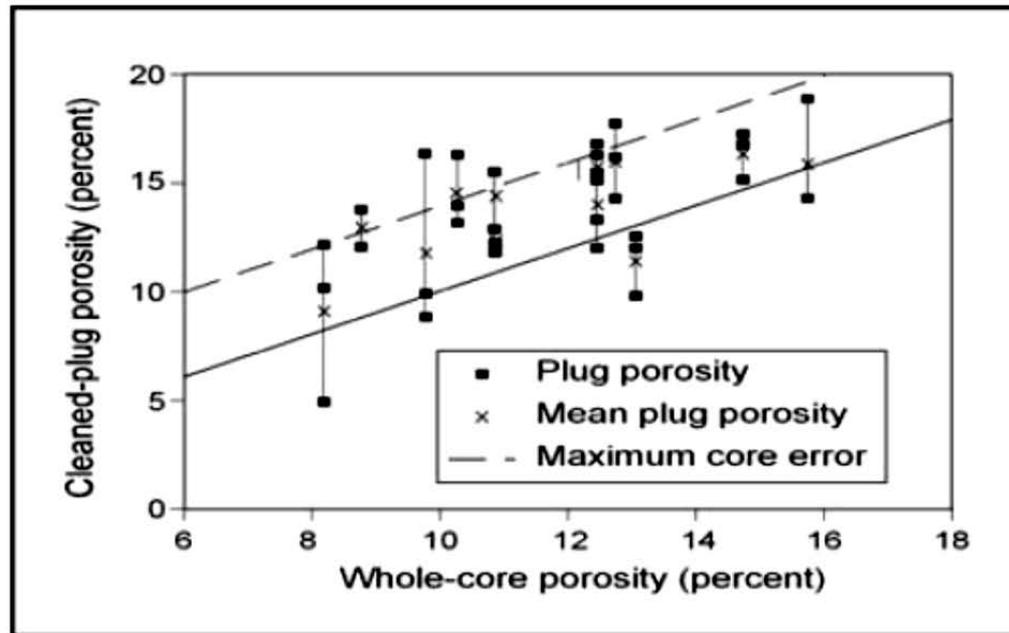
- ▶ High contrasts in permeability common in carbonates
- ▶ Link between porosity and permeability is not straightforward in carbonates and is difficult to predict

# Petrophysical Rock Properties

- **Porosity:**

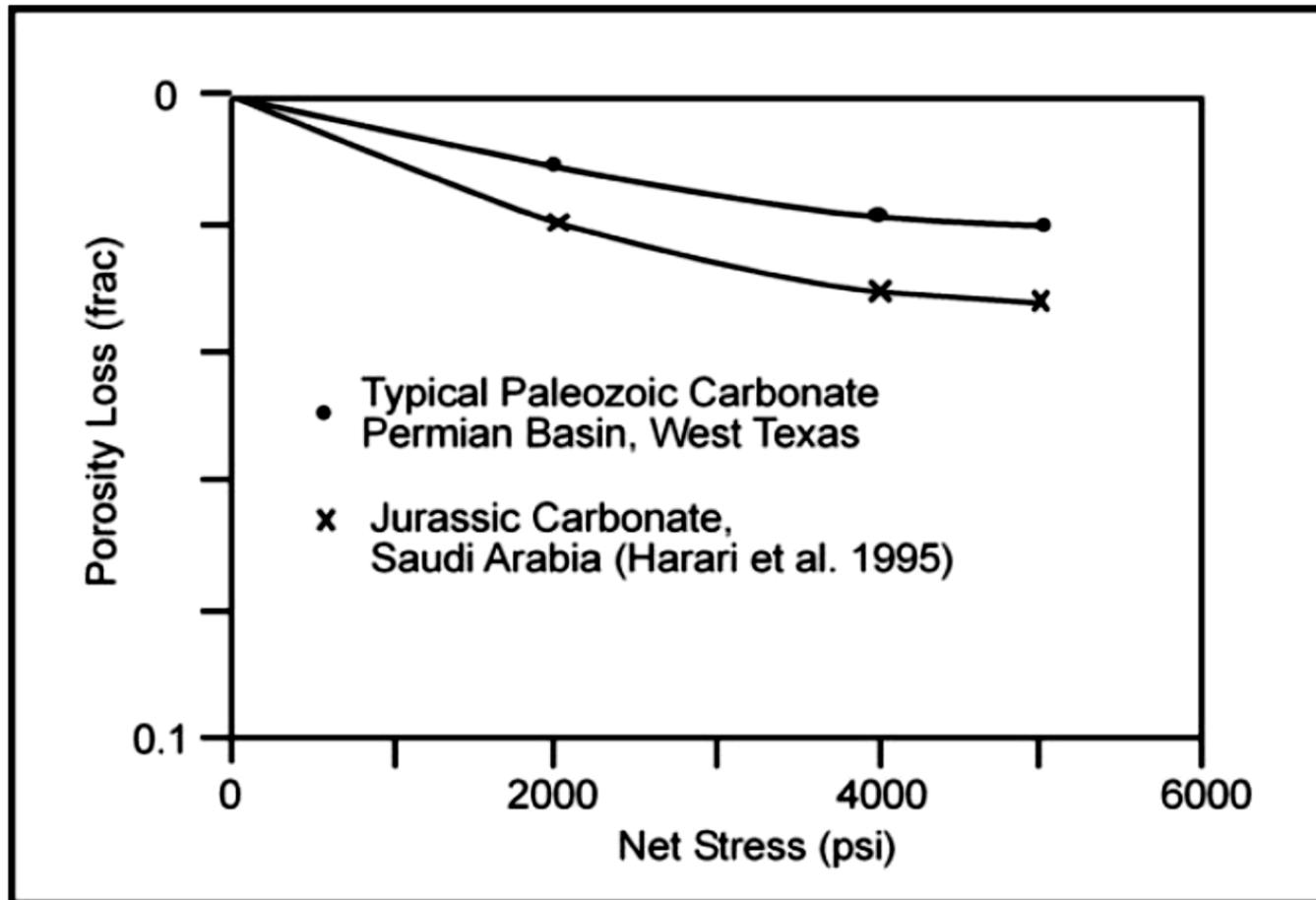
$$Porosity = \frac{\text{Pore volume}}{\text{Bulk volume}} = \frac{\text{Bulk volume} - \text{Mineral volume}}{\text{Bulk volume}}$$

- Effective and Non-Effective
- Visual method and laboratory (Boyle's Law) measurements



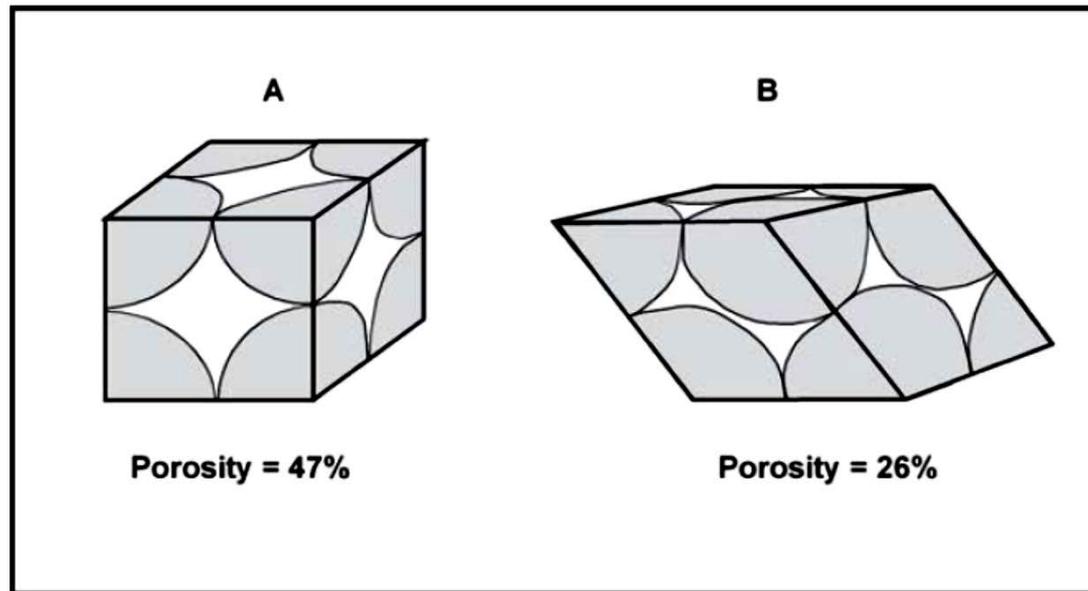
**Fig. 1.1.** Plot of whole-core porosity values versus porosity values of plug samples taken from the whole-core samples and recleaned. Whole-core porosity is too small by 0 – 4 porosity percent

- Porosity measurements should be made at in situ stress conditions because carbonate rocks are compressible, and porosity decreases with increasing effective stress. The common laboratory method is to increase confining pressure while maintaining a constant pore pressure. The resulting decrease in porosity is normally very small (2%) in Paleozoic and many Mesozoic reservoirs, and porosity measurements at ambient conditions are usually adequate (Harari et al. 1995). Porosity values of all high-porosity carbonates, however, should be checked for porosity loss with increasing confining pressure.



**Fig. 1.2.** Effect of confining pressure on porosity in Paleozoic and Jurassic carbonate reservoirs. Porosity loss is defined as confined porosity/unconfined porosity

- In carbonate sediment the shape of the grains and the presence of intragrain porosity as well as sorting have a large effect on porosity.



**Fig. 1.3.** Comparison of porosity in (A) cubic packed spheres and (B) rhombohedral-packed spheres. The porosity is a function of packing, and pore size is controlled by the size and packing of spheres

# • Permeability:

$$\text{Darcy's Law: } Q = A \left( \frac{k}{\mu} \right) \left( \frac{\Delta P}{L} \right), \quad (3)$$

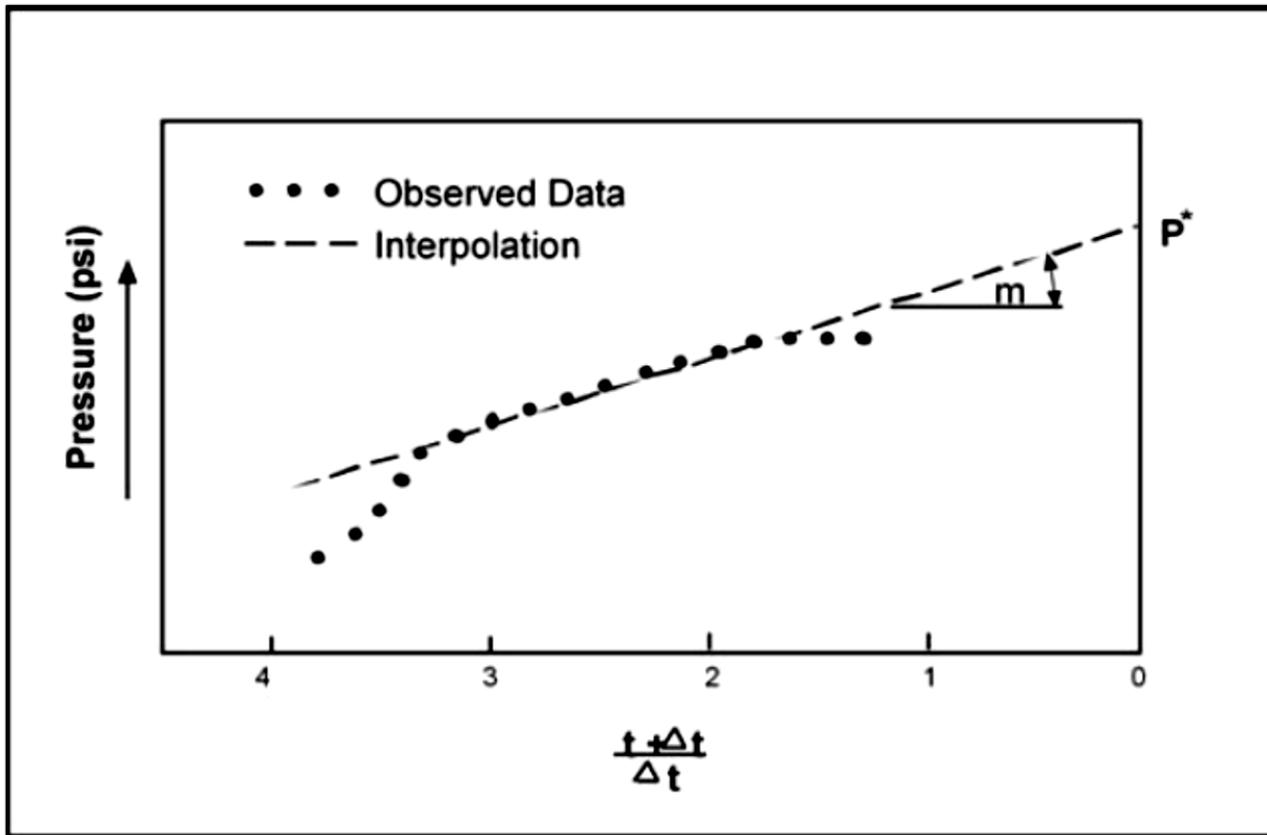
where  $Q$  is rate of flow,  $k$  is permeability,  $\mu$  is fluid viscosity,  $(\Delta P)/L$  is the potential drop across a horizontal sample, and  $A$  is the cross-sectional area of the sample. Permeability is a rock property, viscosity is a fluid property, and  $\Delta P/L$  is a measure of flow potential.

- Normally, either air or brine is used as a fluid and, when high rates of flow can be maintained, the results are comparable. At low rates, air permeability will be higher than brine permeability. This is because gas does not adhere to the pore walls as liquid does, and the slippage of gases along the pore walls gives rise to an apparent dependence of permeability on pressure. This is called the Klinkenberg effect, and it is especially important in low-permeability rocks.

- Permeability is a vector and scalar quantity. Horizontal permeability varies in different directions, and vertical permeability is commonly less than horizontal permeability.
- A measure of permeability can be obtained from production tests using pressure buildup analyses. The pressure in the well is drawn down by production, the well is shut in, and the rate of pressure increase is measured. The rate of pressure increase is a function of the effective permeability of the reservoir. The effective, average permeability of the interval tested is calculated using the following equation:

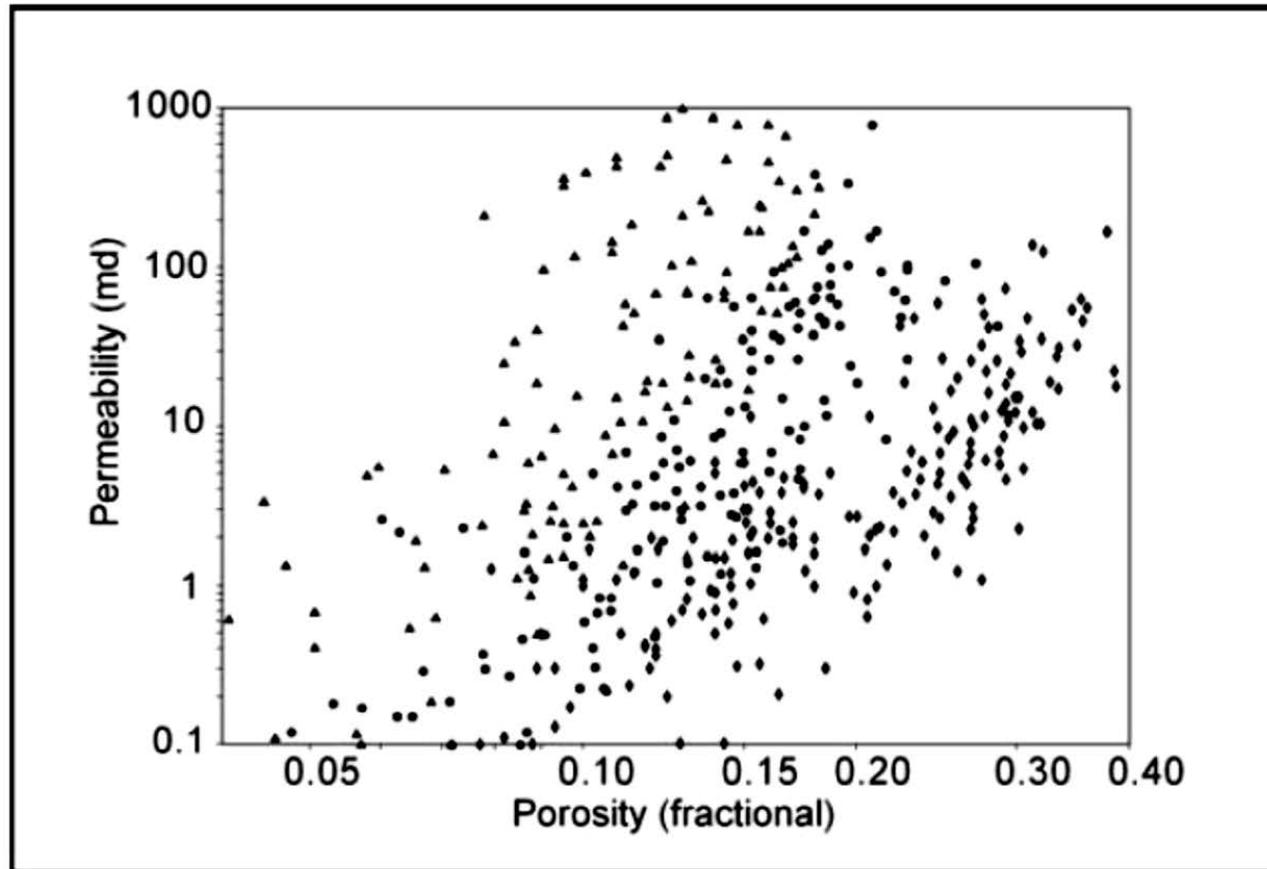
$$\text{Slope (psi/log cycle)} = 162.6(q\mu B_o/kh),$$

- where  $q$  is the flow rate in stock-tank-barrels/day,  $\mu$  = viscosity in centipoises,  $B_o$  is reservoir-barrels/stock-tank-barrels,  $k$  is permeability in millidarcys, and  $h$  is the net reservoir interval in feet.



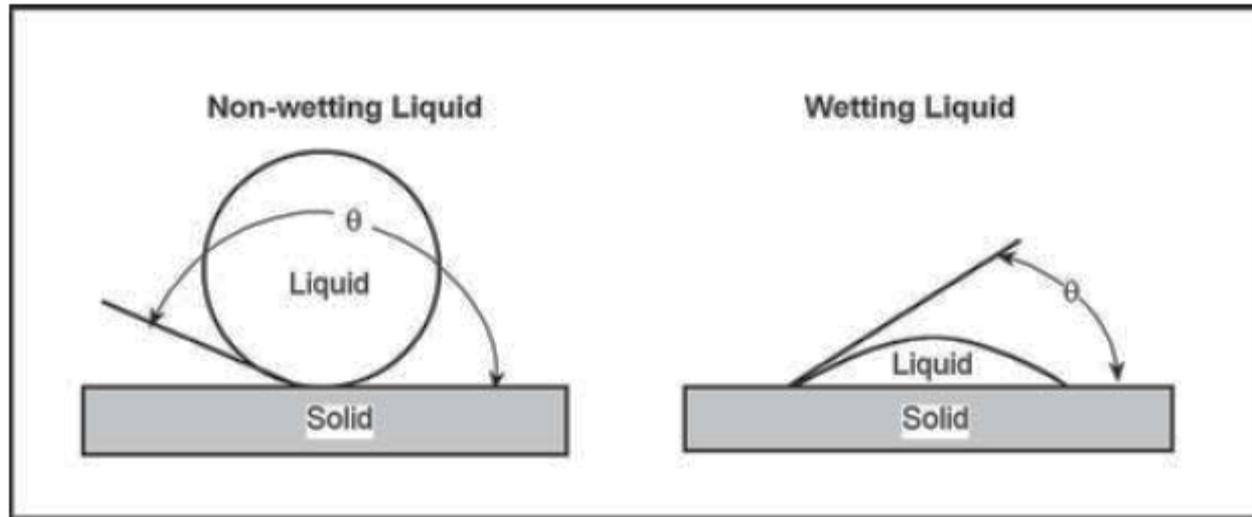
**Fig. 1.6.** Typical Horner pressure buildup plot (after Dake 1978). The slope of the line is a function of permeability-feet ( $kh$ )

- It is common practice to estimate permeability using simple porosity permeability transforms developed from core data. However, porosity permeability cross plots for carbonate reservoirs commonly show large variability, demonstrating that factors other than porosity are important in modeling permeability. These equations illustrate that the size and distribution of pore space, or pore-size distribution, is important along with porosity in estimating permeability. In general it can be concluded that there is no relationship between porosity and permeability in carbonate rocks unless pore-size distribution is included.



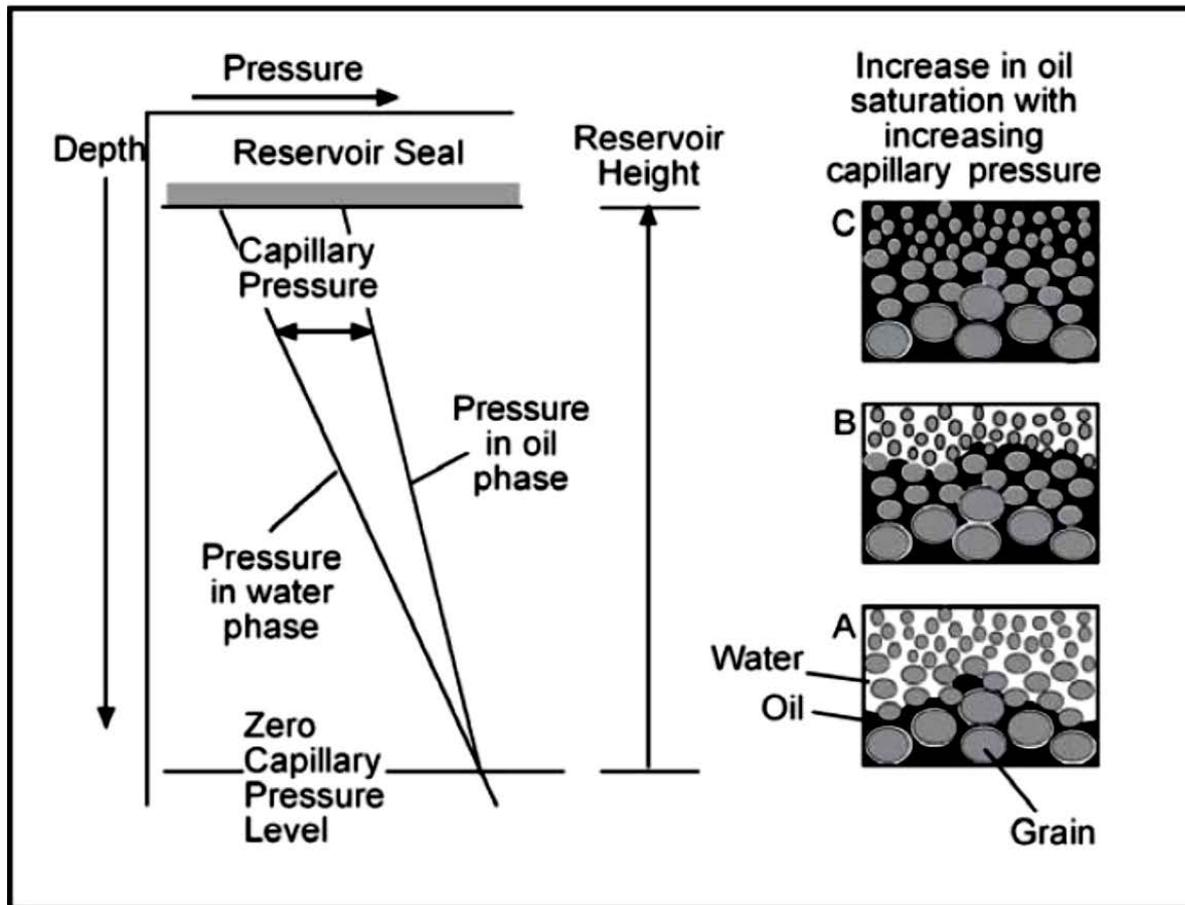
**Fig. 1.7.** Plot of porosity and permeability for carbonate rocks, illustrating that there is no relationship between porosity and permeability in carbonate rocks without including pore-size distribution

- **wettability:**



**Fig. 1.10.** Adhesive forces and the definition of wettability. If the adhesive forces are less than cohesive forces, ( $\theta > 90^\circ$ ), the liquid is said to be nonwetting. If adhesive forces are greater than cohesive forces, ( $\theta < 90^\circ$ ), the liquid is said to be the wetting phase

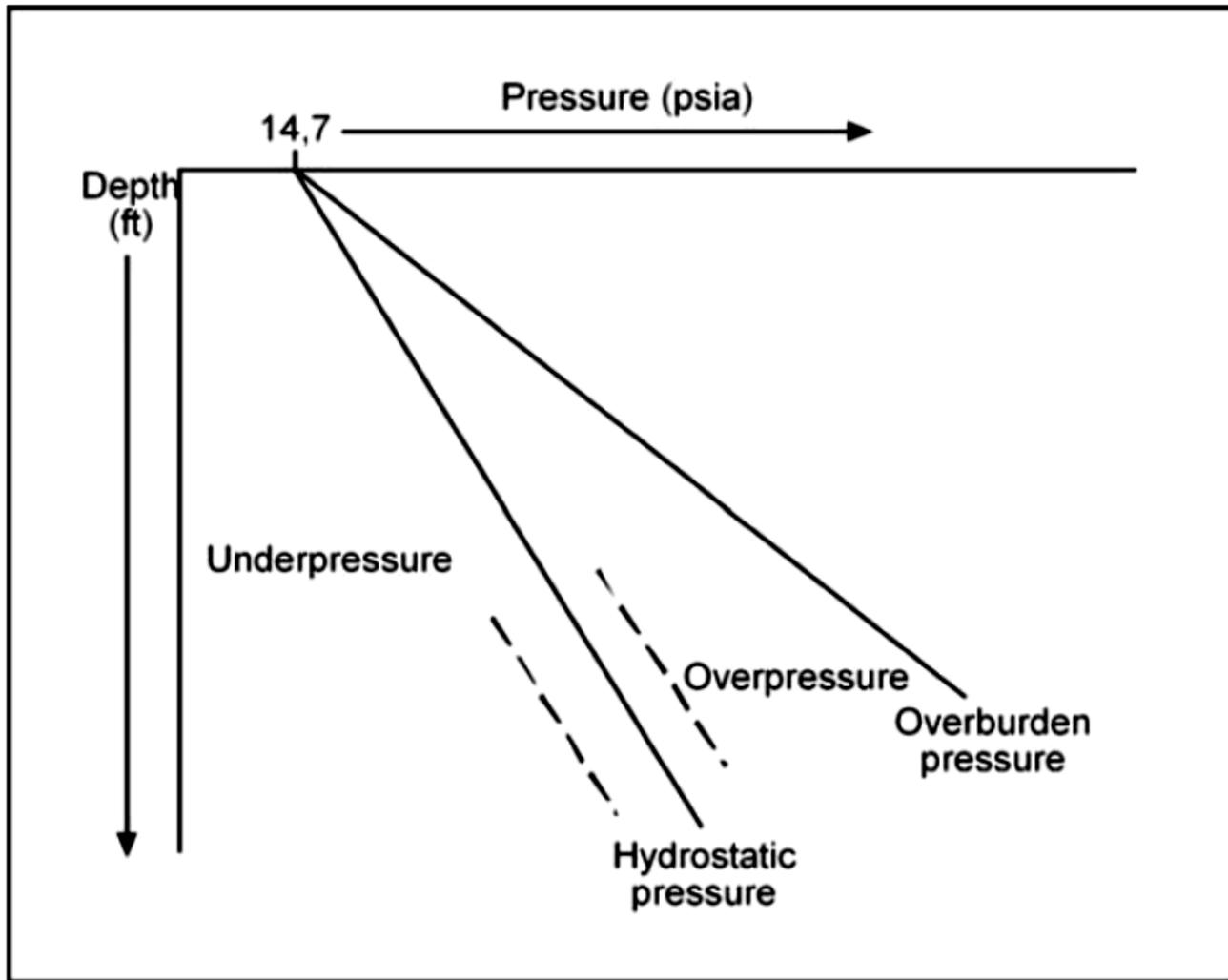
- Hydrocarbon saturation in a reservoir is related to pore size as well as capillary pressure and capillary forces. For oil to accumulate in a hydrocarbon trap and form a reservoir, the surface tension between water and oil must be exceeded. This means that the pressure in the oil phase must be higher than the pressure in the water phase. If the pressure in the oil is only slightly greater than that in the water phase, the radius of curvature will be large and the oil will be able to enter only large pores. As the pressure in the oil phase increases, the radius of curvature decreases and oil can enter smaller pores



**Fig. 1.14.** Diagram showing smaller pores being filled with a non-wetting fluid (oil) displacing a wetting fluid (water) as capillary pressure increases linearly with reservoir height. Pore size is determined by grain size and sorting. (A) Only the largest pores contain oil at the base of the reservoir. (B) Smaller pores are filled with oil as capillary pressure and reservoir height increase. (C) Smallest pores are filled with oil toward the top of the reservoir

- The pressure in the water phase depends upon the degree to which the fluid column is connected to the Earth's surface. In an open system, the fluid pressure is equal to depth times the density of the fluid and is called hydrostatic. The hydrostatic pressure gradient is about 0.434 psi/ft; overburden pressure equals the weight of the overburden sediment and has a gradient of about 1 psi/ft. Deviations from hydrostatic pressure, abnormal pressures, occur when the formation fluid is confined and cannot equilibrate with surface pressure.

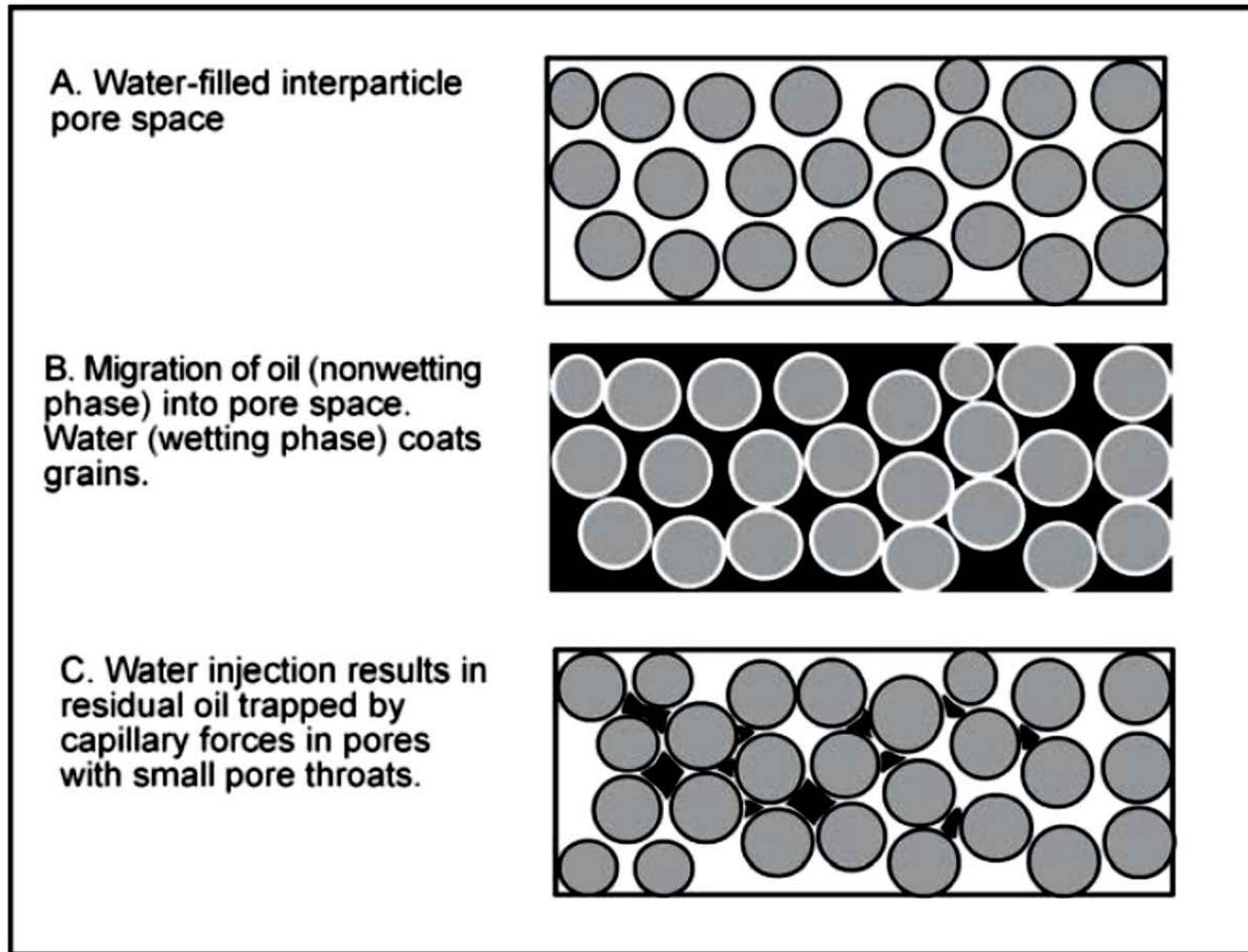
- Over pressuring is the most common abnormal pressure and is produced by (1) compaction during rapid burial, (2) tectonic compression, and (3) hydrocarbon generation and migration (Osborne and Swarbrick 1997). In extreme cases, fluid pressures can equal and even exceed overburden pressures. Uncommonly, pressures can be lower than hydrostatic. Under pressure is often related to erosional unloading that results in an increase in pore volume due to the elastic rebound of the sediment as the overburden is reduced (Bachu and Underschultz 1995).



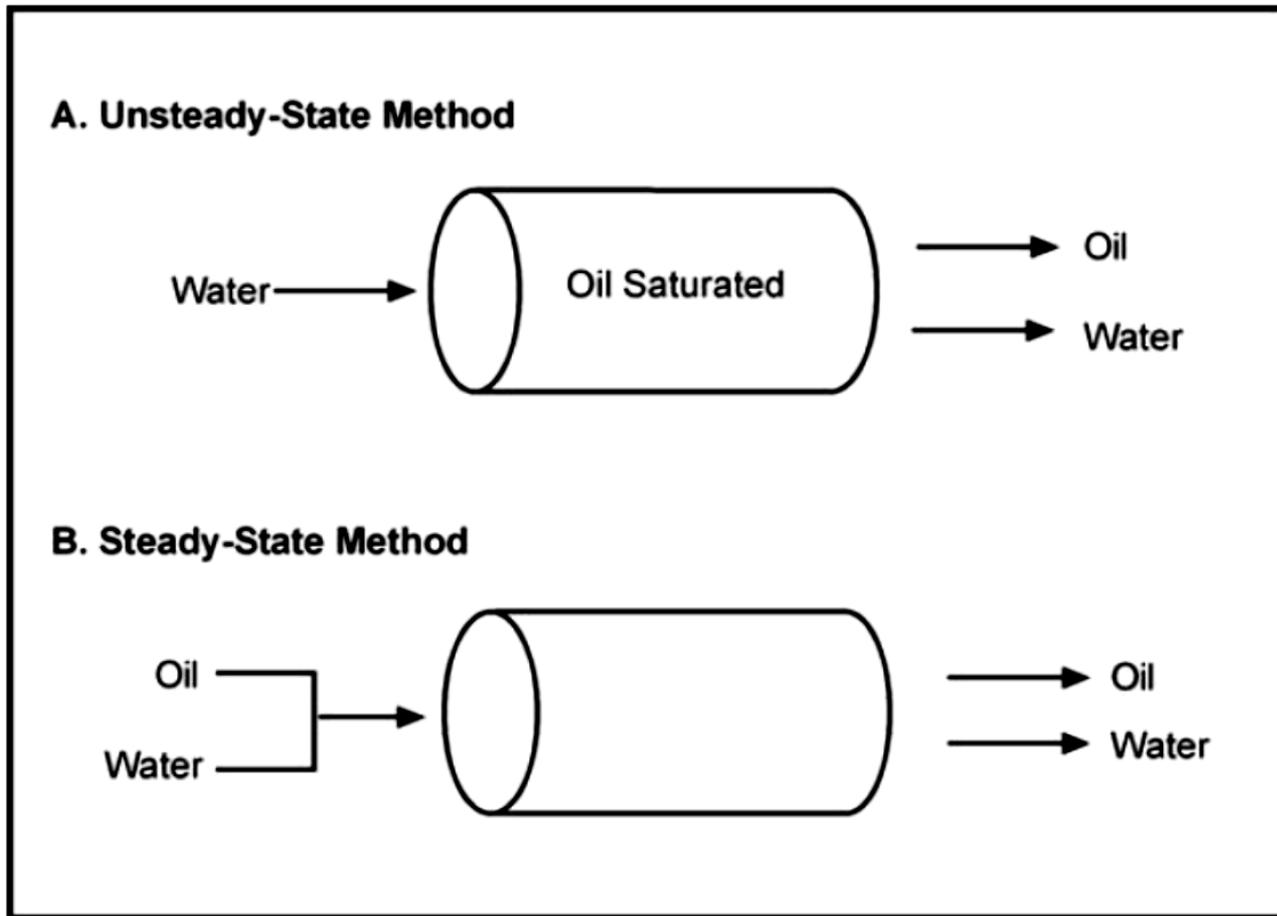
**Fig. 1.16.** Diagram illustrating overburden, normal hydrostatic, and abnormal over- and underpressure regimes. (After Dake 1978)

- **Relative Permeability:**

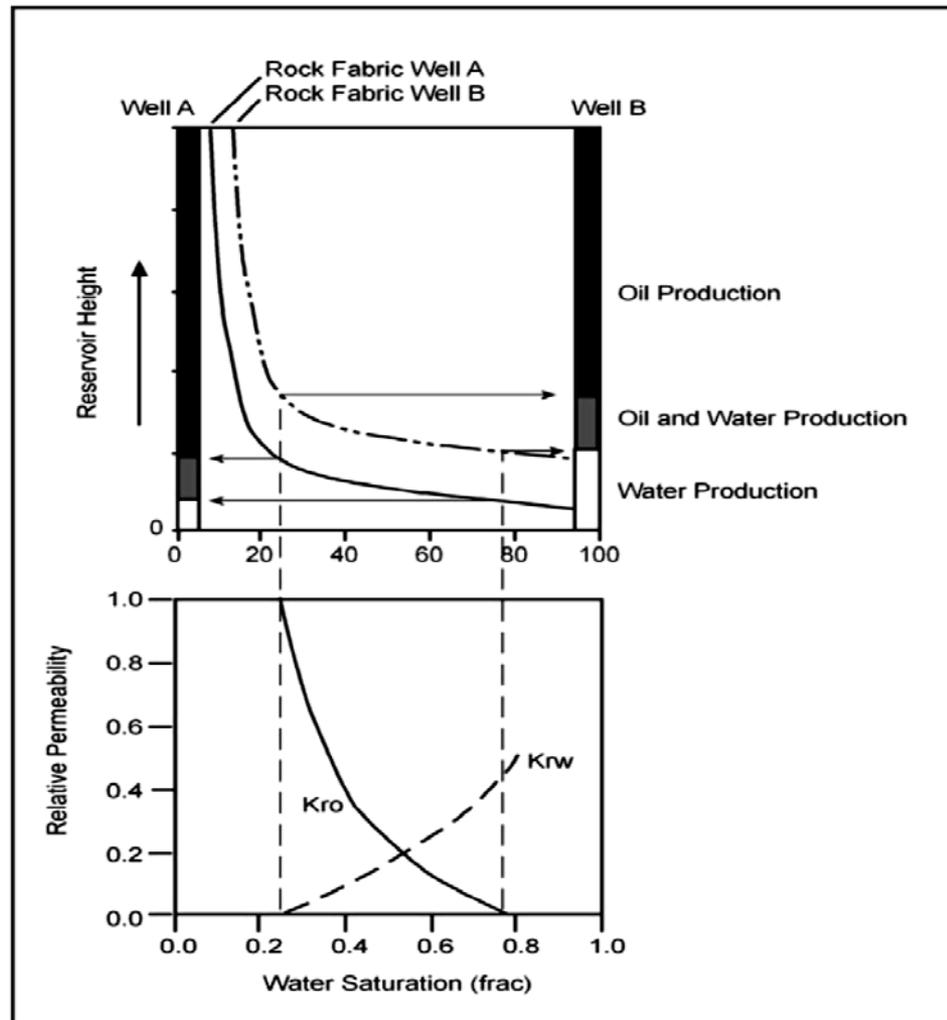
- *Relative permeability* is simply the permeability measured at a specific fluid saturation expressed as a fraction of the total or absolute permeability. *Absolute permeability* is the permeability of a rock that is 100% saturated with a single fluid.



**Fig. 1.17.** Diagram of oil and water distribution in a water-wet rock under three conditions: (A) 100% water saturation, (B) injection of a nonwetting fluid (oil), and (C) injection of a wetting fluid (water)



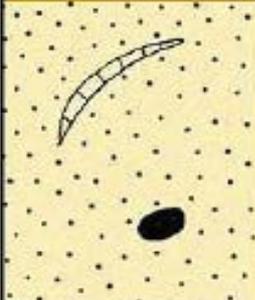
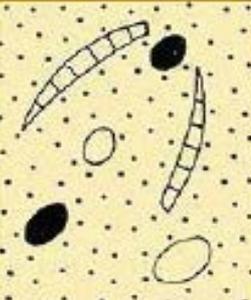
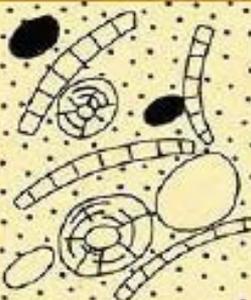
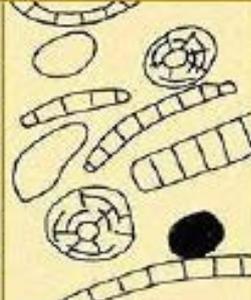
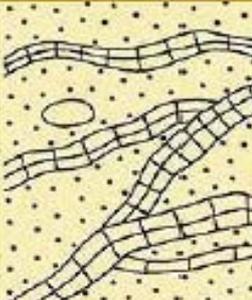
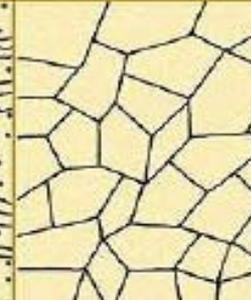
**Fig. 1.19.** Illustration of unsteady-state and steady-state methods of measuring two-phase oil and water relative permeability



**Fig. 1.20.** Simplified illustration showing the relationship between relative permeability to oil and water, capillary pressure converted to reservoir height, water saturation, and pore size. The effect of pore size is illustrated by considering two capillary pressure curves (**rock-fabric A, rock-fabric B**) from carbonate rocks with different pore-size distributions. The change in pore size results in the possibility of intervals where (1) clean oil is produced from rock-fabric A and oil and water from rock-fabric B, and (2) oil and water is produced from rock-fabric A and water from B

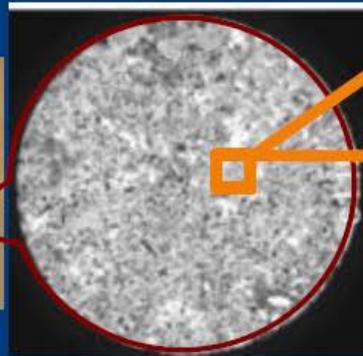
# Rock-Fabric Classification

# Carbonate rock textures: Dunham classification

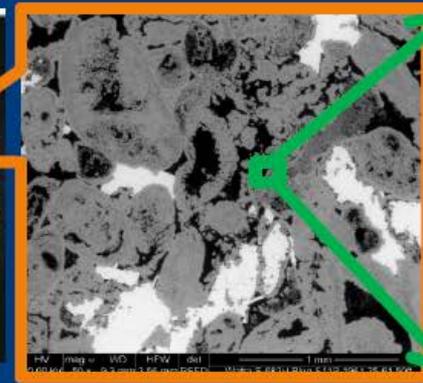
| Depositional texture recognizable   |   |   |  | Depositional texture not recognizable   |   |
|---|---|---|--|---|---|
| Original components not bound together during deposition                            |   |   | Original components were bound together  |   |   |
| Contains mud (clay and fine-silt carbonate)   |   | Lacks mud and is grain supported  |  |   |   |
| Mud - supported   |   | Grain - supported   |  |   |   |
| Less than 10% grains  | More than 10% grains  |   |  |   |   |
| Mudstone  | Wackestone  | Packestone  | Grainstone   | Boundstone  | Crystalline   |
|  |  |  |  |  |  |



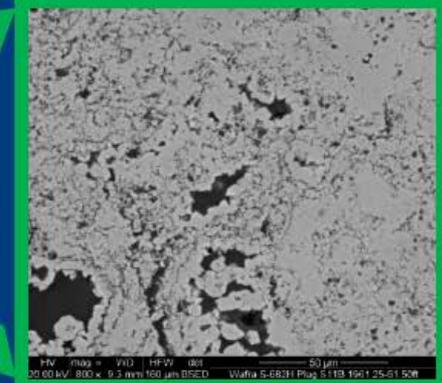
Carbonate Core,  
2100x100x100 mm<sup>3</sup>



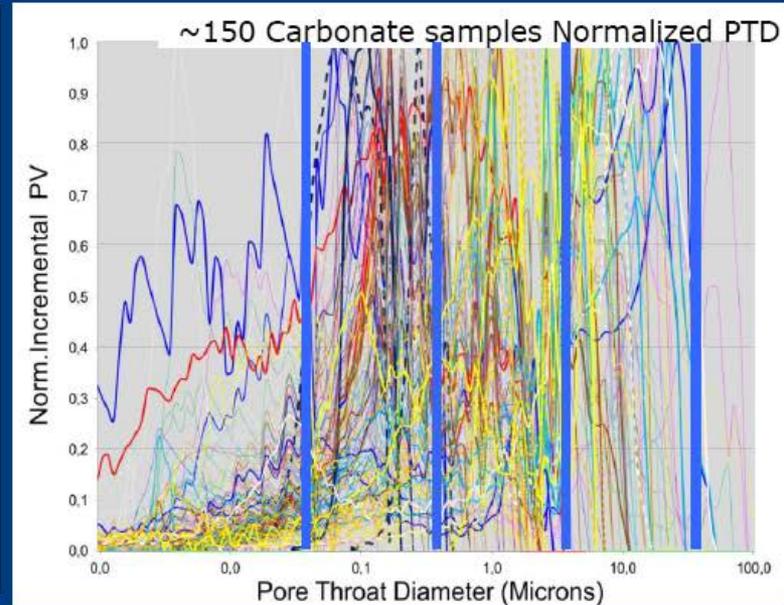
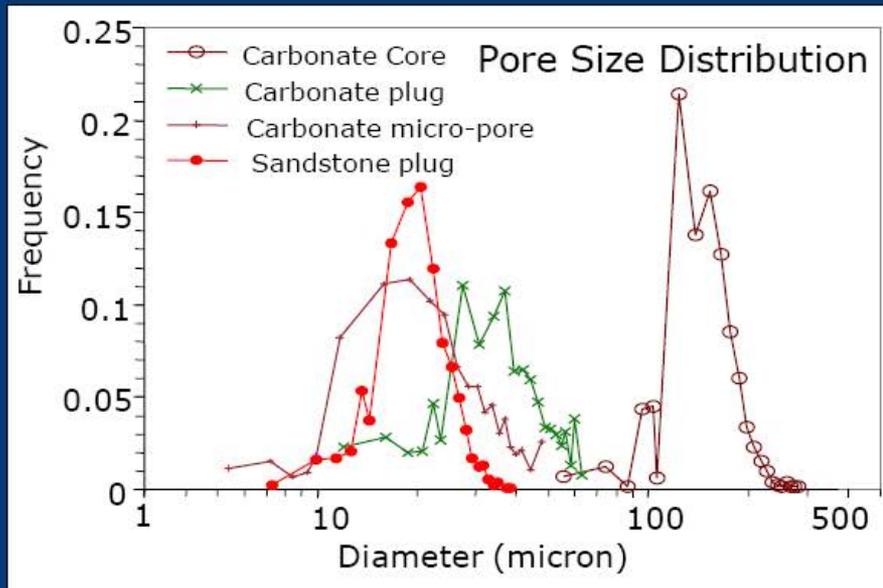
Carbonate plug



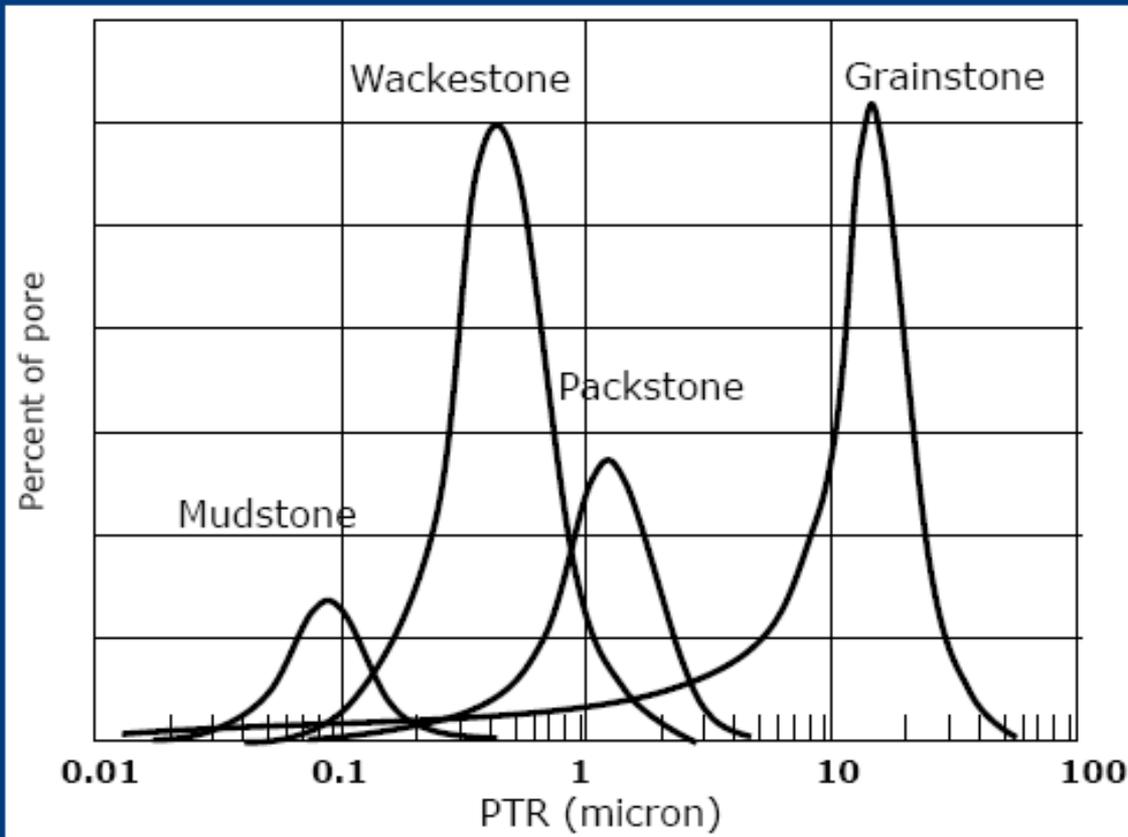
resolution = 1.25 micron



resolution = 0.077 micron



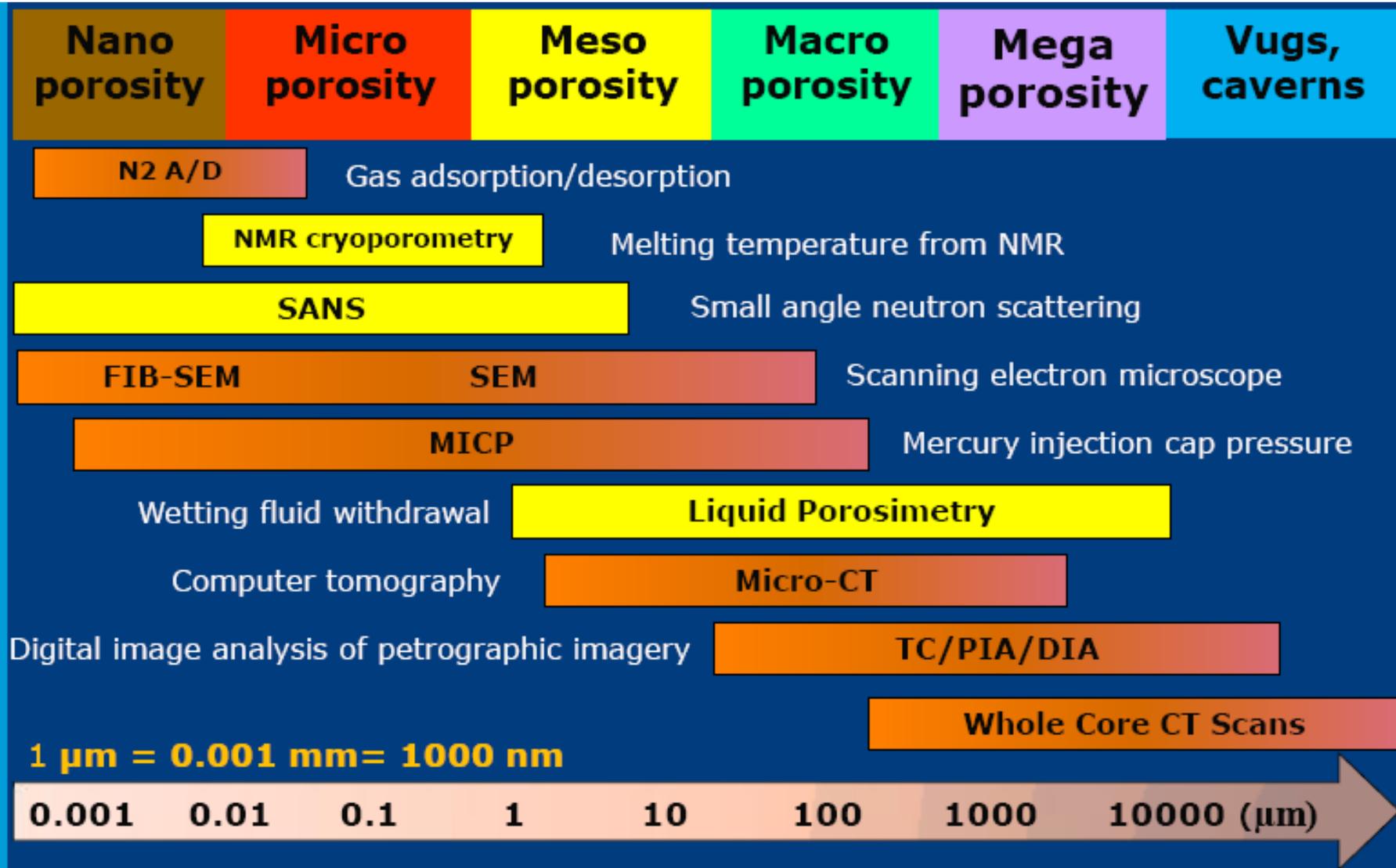
# Pore Throat Size Classes



- Macropores 1: Pore Throat size > 10 microns
- Macropores 2: Pore Throat size between 4 and 10 microns
- Mesopore 1: Pore Throat size between 1 and 4 microns
- Mesopore 2: Pore Throat size between 0.3 and 1 micron
- Micropore: Pore Throat size < 0.3 micron

After Marzouk et al. (1995)

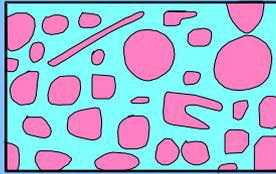
# Core Based Pore Observation Tools



# Porosity classification System

- Classic pore type classification systems mostly observational
- Archie (1952) – textural/petrophysical with 12 pore types
- Choquette and Pray (1970) – definitions of pore types genetic/depositional with 15 pore types
- Lucia (1983, 1995, 1999) – rock fabric/petrophysical with 18 pore types
- Lønøy (2006) – modified Choquette Pray pore size with 20 pore types
- Marzouk, Tazenaki, Suzuki (1998), Clerke et al. (2008) – MICP based

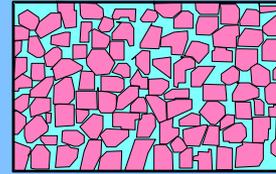
# Idealized Carbonate Porosity Types



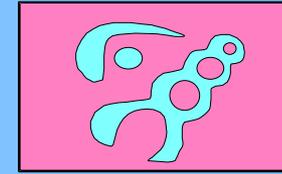
Interparticle



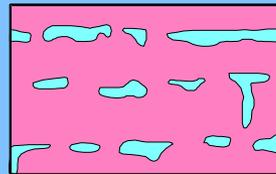
Intraparticle



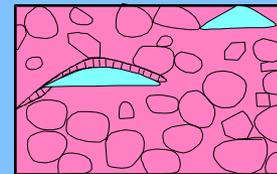
Intercrystal



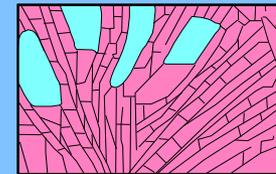
Moldic



Fenestral

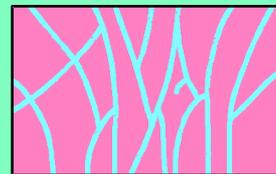


Shelter

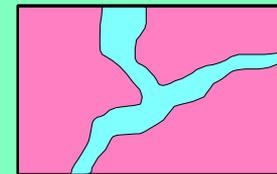


Growth-Framework

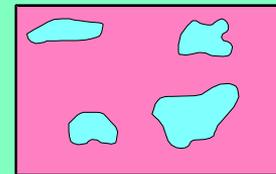
**Fabric  
Selective**



Fracture

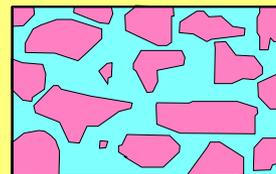


Channel

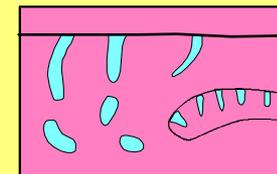


Vug

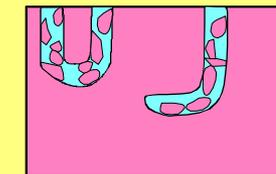
**Non-Fabric  
Selective**



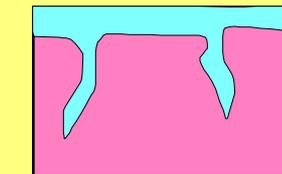
Breccia



Boring



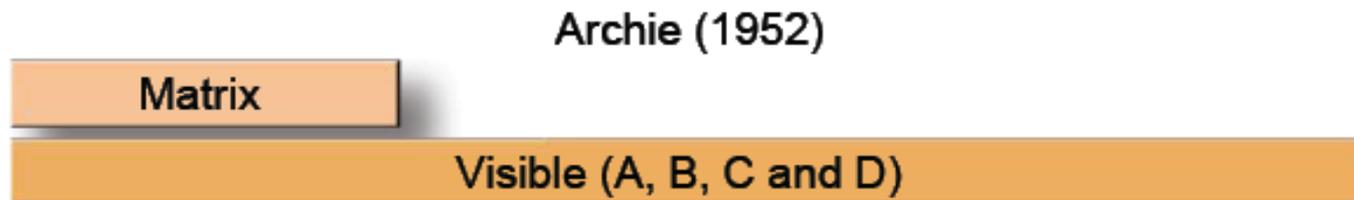
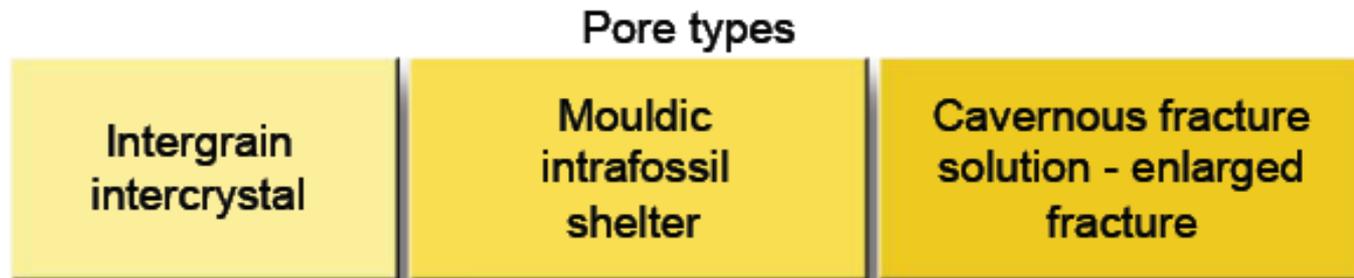
Burrow



Shrinkage

**Fabric Selective or Not Fabric Selective**

# Pore type Classifications



# Carbonate Diagenesis

“The diagenesis of carbonate sediments encompasses all the processes which affect the sediments after deposition until the realms of incipient metamorphism at elevated temperatures and pressures.”

Diagenetic processes include:

- ▶ Cementation
- ▶ Micritisation
- ▶ Neomorphism
- ▶ Dissolution
- ▶ Compaction / fracturing
- ▶ Dolomitisation

| Term                       | Abbreviations |                           |
|----------------------------|---------------|---------------------------|
|                            | Lucia         | Choquette and Pray (1970) |
| Interparticle              | IP            | BP                        |
| Intergrain                 | IG            | -                         |
| Intercrystal               | IX            | BC                        |
| Vug                        | VUG           | VUG                       |
| Separate Vug               | SV            | -                         |
| Moldic                     | MO            | MO                        |
| Intraparticle              | WP            | WP                        |
| Intragrain                 | WG            | -                         |
| Intracrystal               | WX            | -                         |
| Intrafossil                | WF            | -                         |
| Intragrain microporosity   | ig $\mu\phi$  | -                         |
| Shelter                    | SH            | SH                        |
| Touching Vug               | TV            | -                         |
| Fracture                   | FR            | FR                        |
| Solution-enlarged fracture | SF            | CH*                       |
| Cavernous                  | CV            | CV                        |
| Breccia                    | BR            | BR                        |
| Fenestral                  | FE            | FE                        |

\*Channel.

# Classification of Interparticle Pore Space

- In the absence of vuggy porosity, pore-size distribution in carbonate rocks can be described in terms of particle size, sorting, and interparticle porosity.
- Lucia (1983) showed that particle size can be related to mercury capillary displacement pressure in nonvuggy carbonates with more than 0.1 md permeability, suggesting that particle size describes the size of the largest Pores. Whereas the displacement pressure characterizes the largest pores sizes, the shape of the capillary pressure curve characterizes the smaller pore sizes and is dependent on interparticle porosity (Lucia 1983).

- The **petrophysical properties** of interparticle porosity are related to **particle size, sorting** and **interparticle porosity**. Grain size and sorting of grains and micrite is based on Dunham's classification, modified to make it compatible with petrophysical considerations. Instead of dividing fabrics into grain support and mud support, fabrics are divided into grain-dominated and mud-dominated. The important attributes of grain-dominated fabrics are the presence of open or occluded intergrain porosity and a grain-supported texture. The important attribute of mud-dominated fabrics is that the volume between the grains is filled with mud even if the grains appear to form a supporting framework.

# INTERPARTICLE PORE SPACE

Particle size and sorting  
(Matrix interconnection)

PERCENT INTERPARTICLE POROSITY

## GRAIN-DOMINATED FABRIC

### GRAINSTONE

Grain size controls pore size

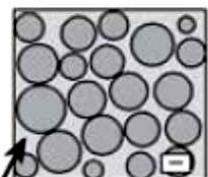


Limestone

Intergrain pore space or cement

Dolomite

Crystal size < 100µm



Intergrain pore space or cement

Crystal size controls pore size

Crystal size > 100µm

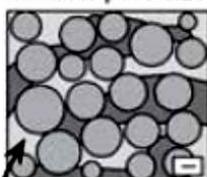


Intercrystal pore space

Note: bar is 100 microns

### PACKSTONE

Grain/mud size controls pore size



Intergrain pore space or cement



Intergrain pore space or cement

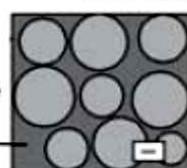


Intercrystal pore space

## MUD-DOMINATED FABRIC

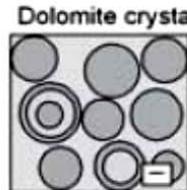
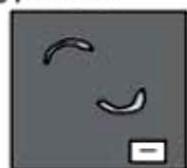
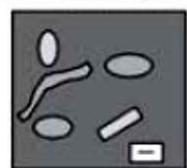
### PACKSTONE WACKESTONE MUDSTONE

Mud size controls connecting pore size



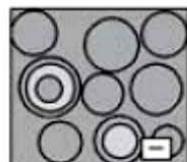
Limestone

micrite

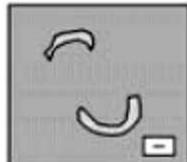
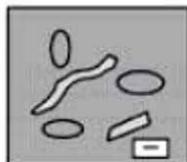


Dolomite

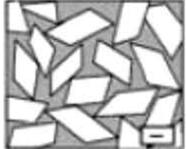
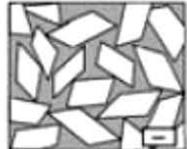
Crystal size < 20µm



Crystal size 20-100µm

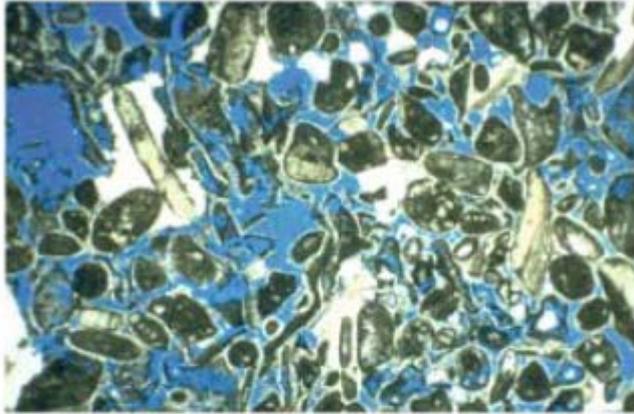


Crystal size > 100µm



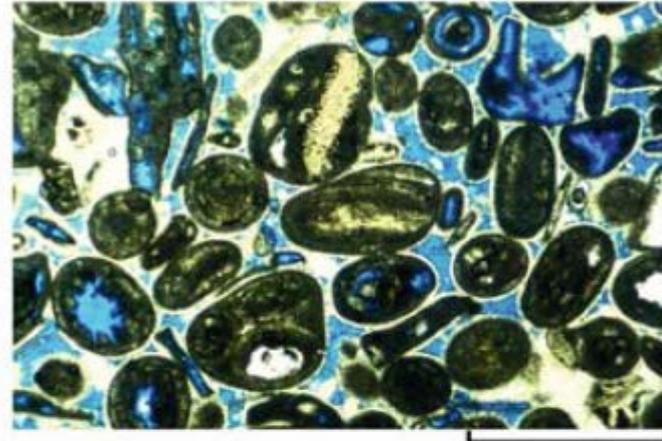
Note: bar is 100 microns

(a)



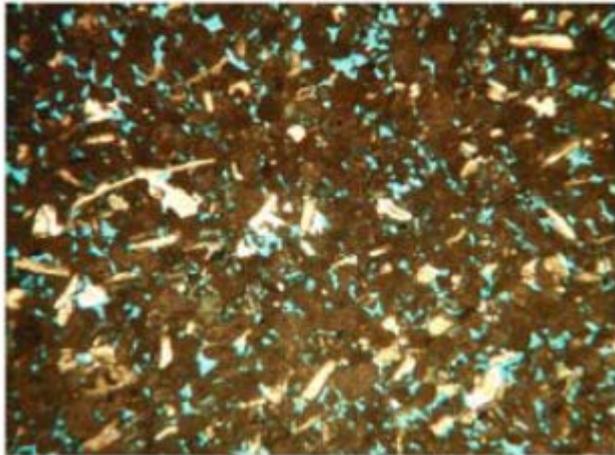
1 mm

(b)

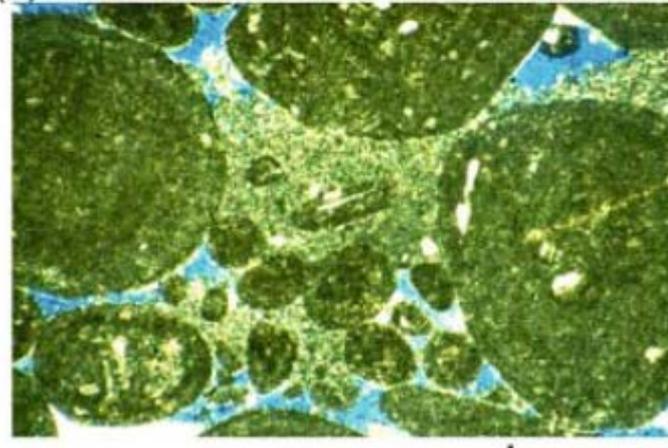


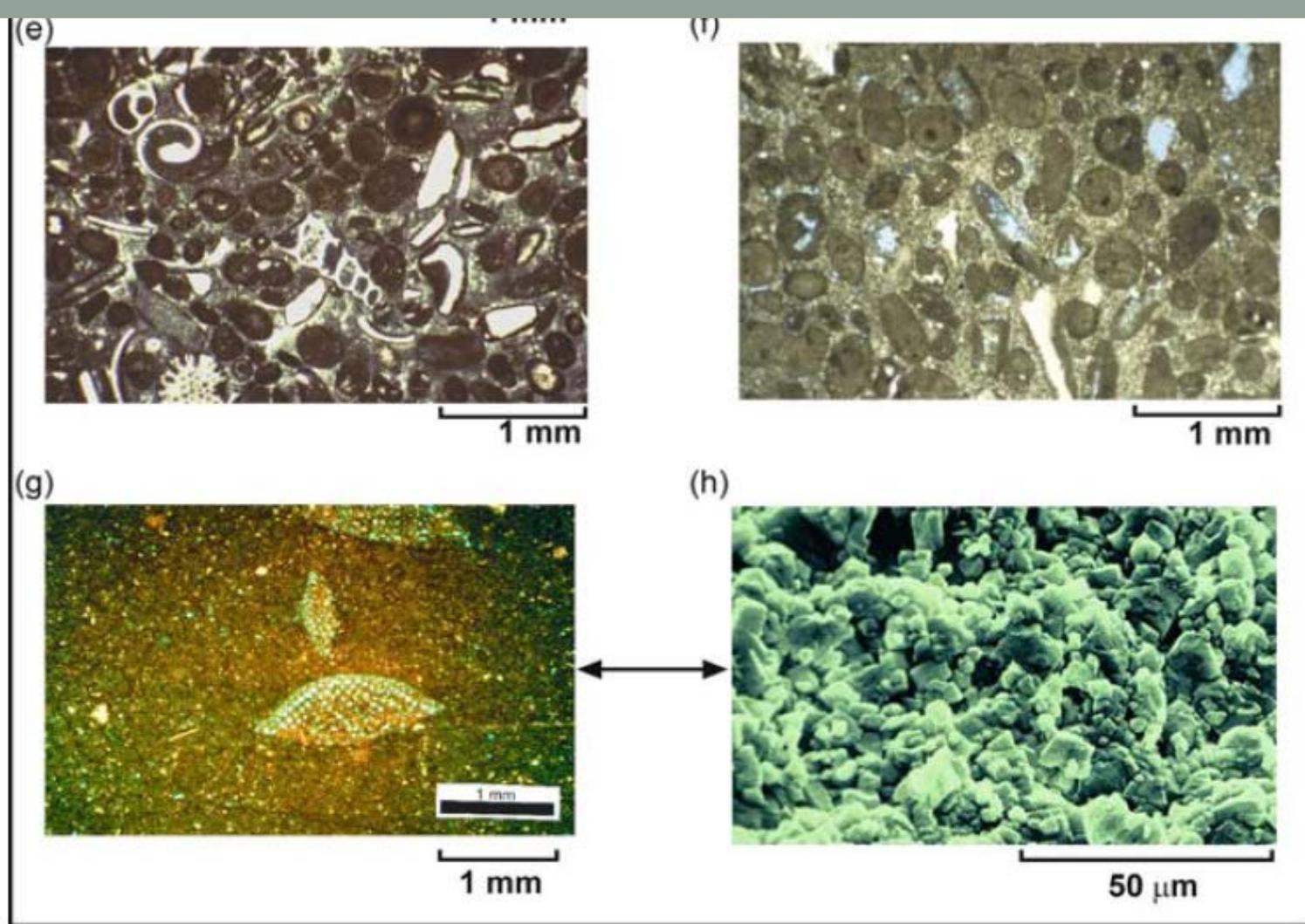
1 mm

(c)

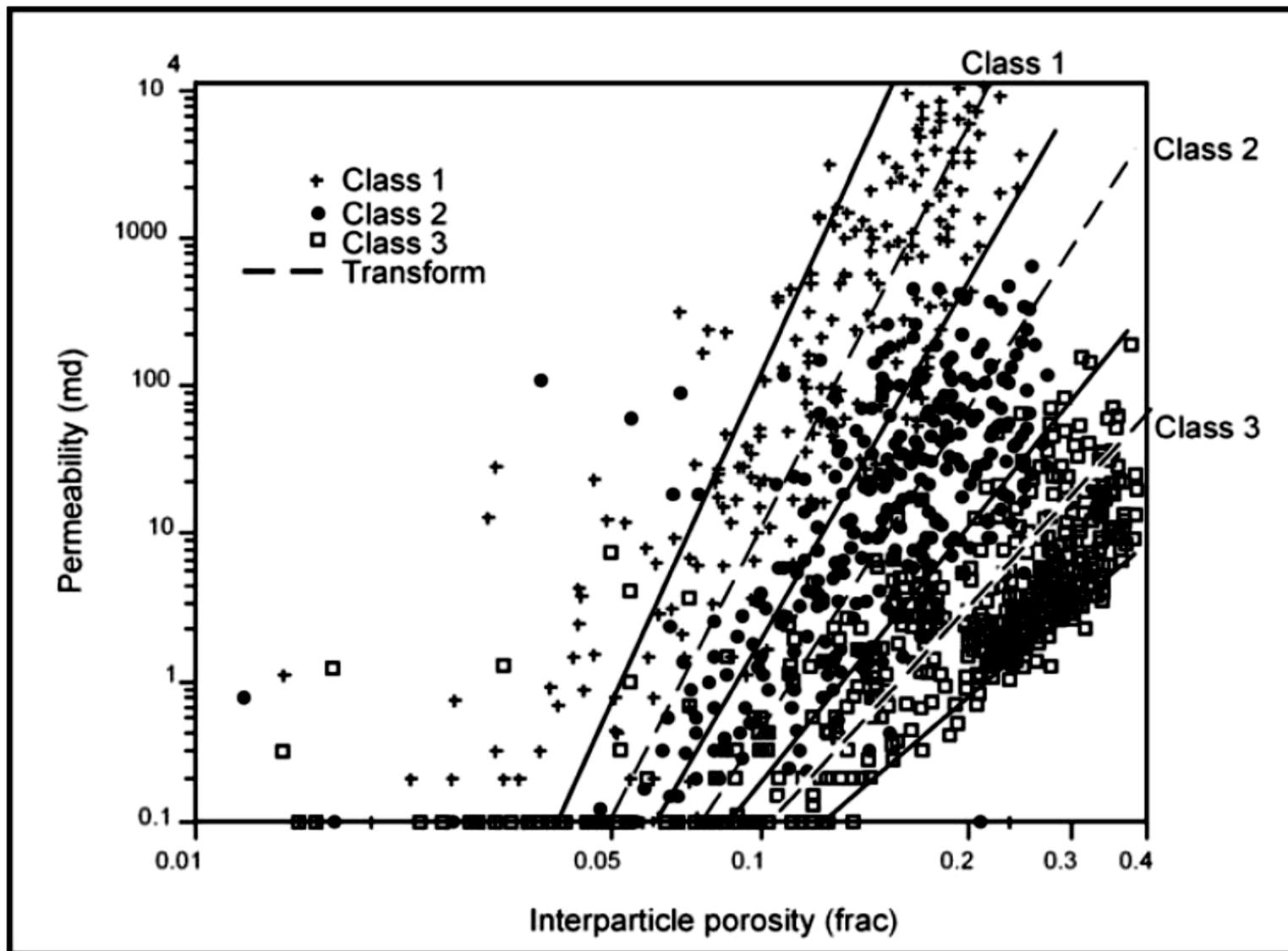


(d)





**Fig. 2.8.** Examples of nonvuggy limestone rock fabrics. (a) Grainstone. (b) Grainstone with some separate-vug pore space. (c) Grain-dominated packstone. (d) Large grain grain-dominated packstone. (e) Mud-dominated packstone. (f) Mud-dominated packstone with some separate-vug pore space. (g) Wackestone with microporosity. (h) Scanning electron microscope photo of microporosity in a wackestone



- Permeability and saturation characteristics of interparticle porosity can be grouped into three rock-fabric/petrophysical classes. Class 1 is composed of grainstones, dolograins, and large crystalline dolostones. Class 2 is composed of grain-dominated packstones, fine to medium crystalline grain-dominated dolopackstones, and medium crystalline mud-dominated dolostones. Class 3 is composed of mud-dominated limestone and fine crystalline mud-dominated dolostones.

# PETROPHYSICAL CLASSES

## GRAIN-DOMINATED FABRIC

GRAINSTONE

PACKSTONE

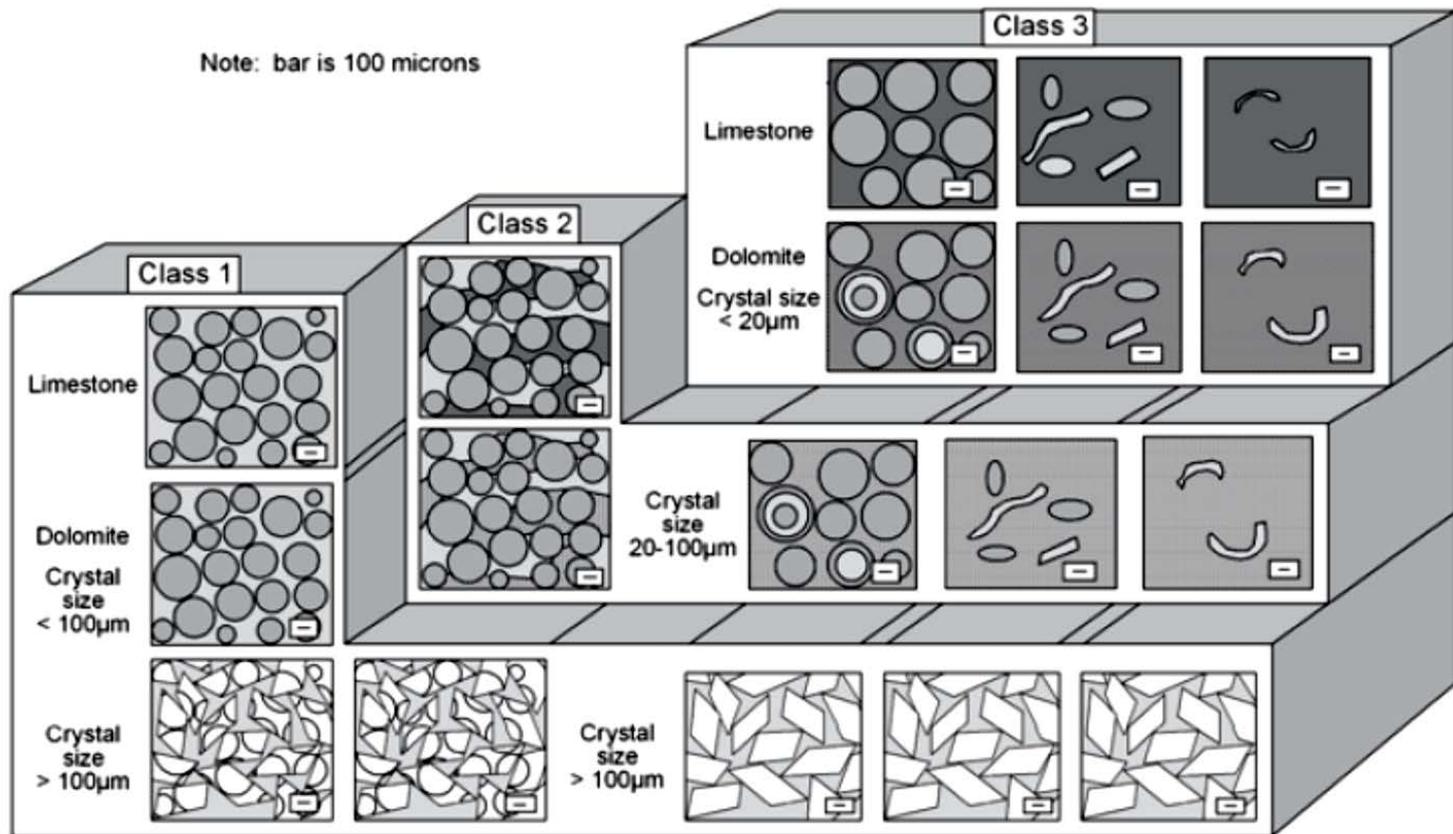
## MUD-DOMINATED FABRIC

PACKSTONE

WACKESTONE

MUDSTONE

Note: bar is 100 microns



Class 1 - Grainstones, dolograins, and large crystalline dolostones.

$$k = (45.35 \times 10^8) \phi_{ip}^{8.537}$$
$$Sw_i = 0.02219 \times H^{-0.316} \times \phi^{-1.745}$$

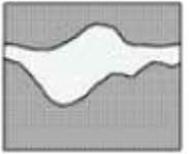
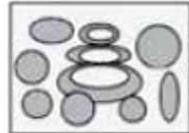
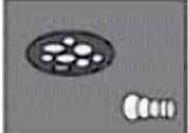
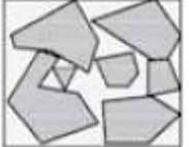
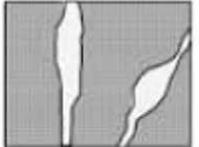
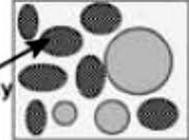
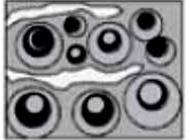
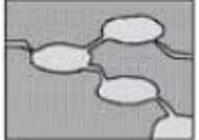
Class 2 - Grain-dominated packstones, fine and medium crystalline grain-dominated dolopackstones, and medium crystal mud-dominated dolostones.

$$k = (2.040 \times 10^6) \phi_{ip}^{6.38}$$
$$Sw_i = 0.1404 \times H^{-0.407} \times \phi^{-1.440}$$

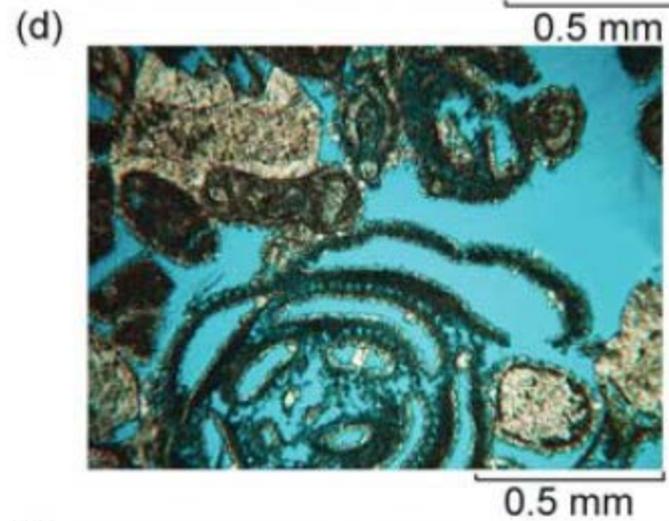
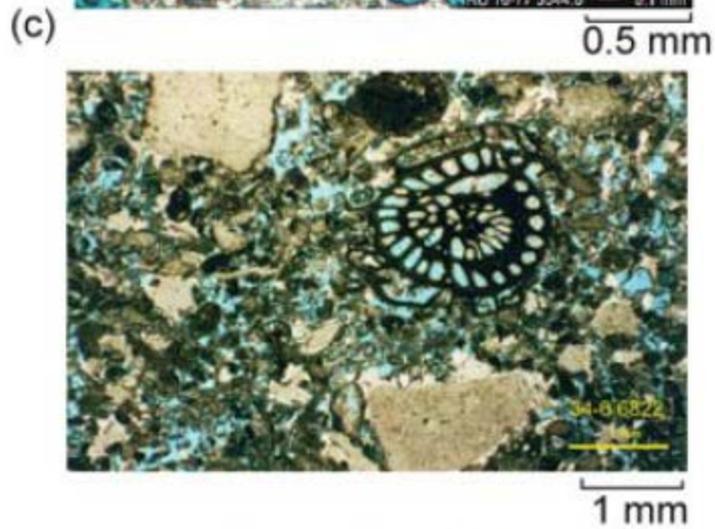
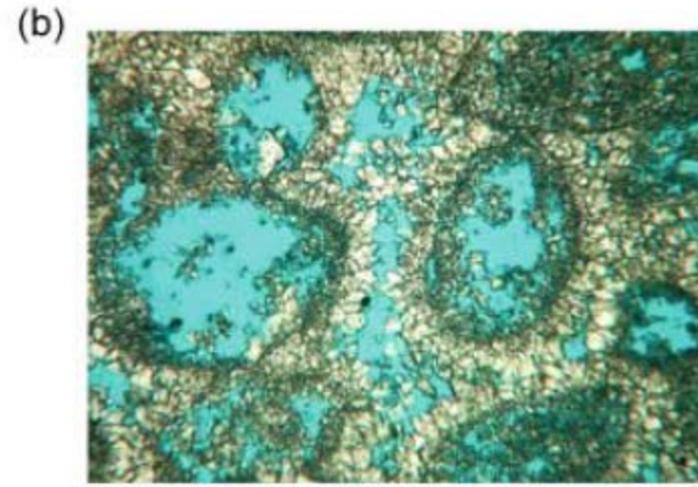
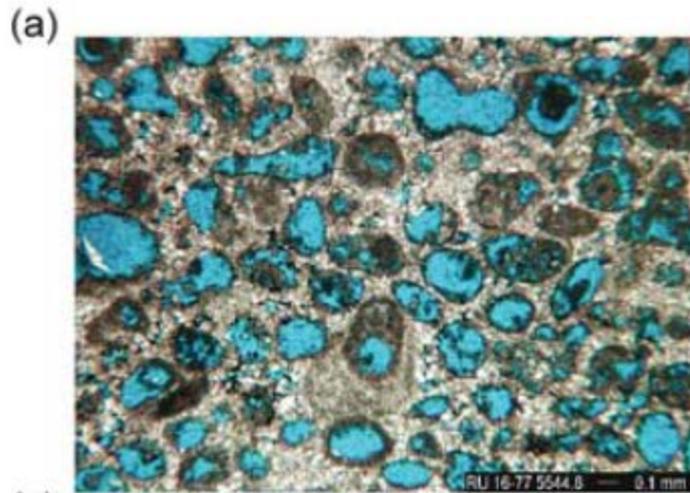
Class 3 - Mud-dominated limestones and fine crystalline mud-dominated dolostones.

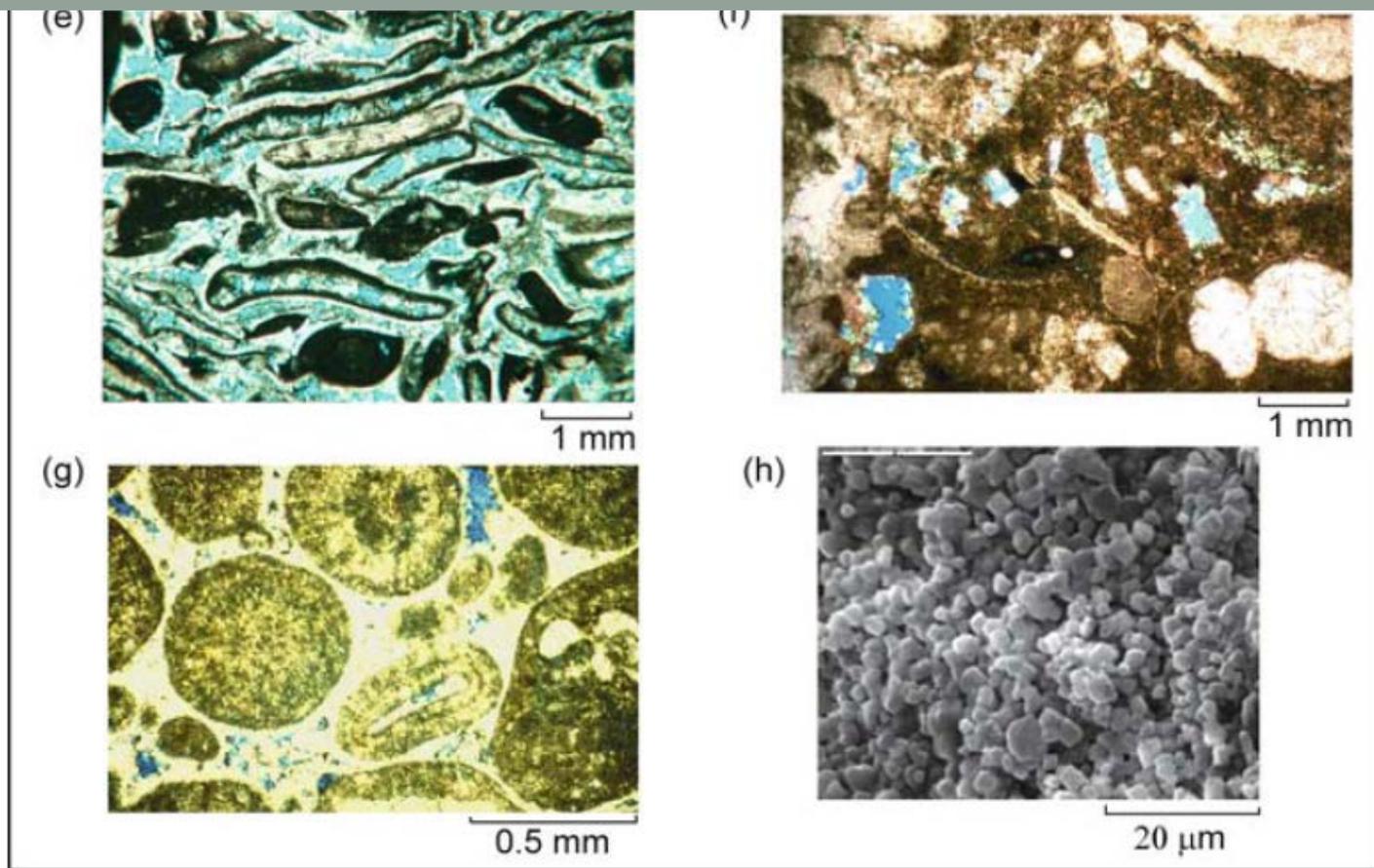
$$k = (2.884 \times 10^3) \phi_{ip}^{4.275}$$
$$Sw_i = 0.6110 \times H^{-0.505} \times \phi^{-1.210}$$

# Vuggy Porosity

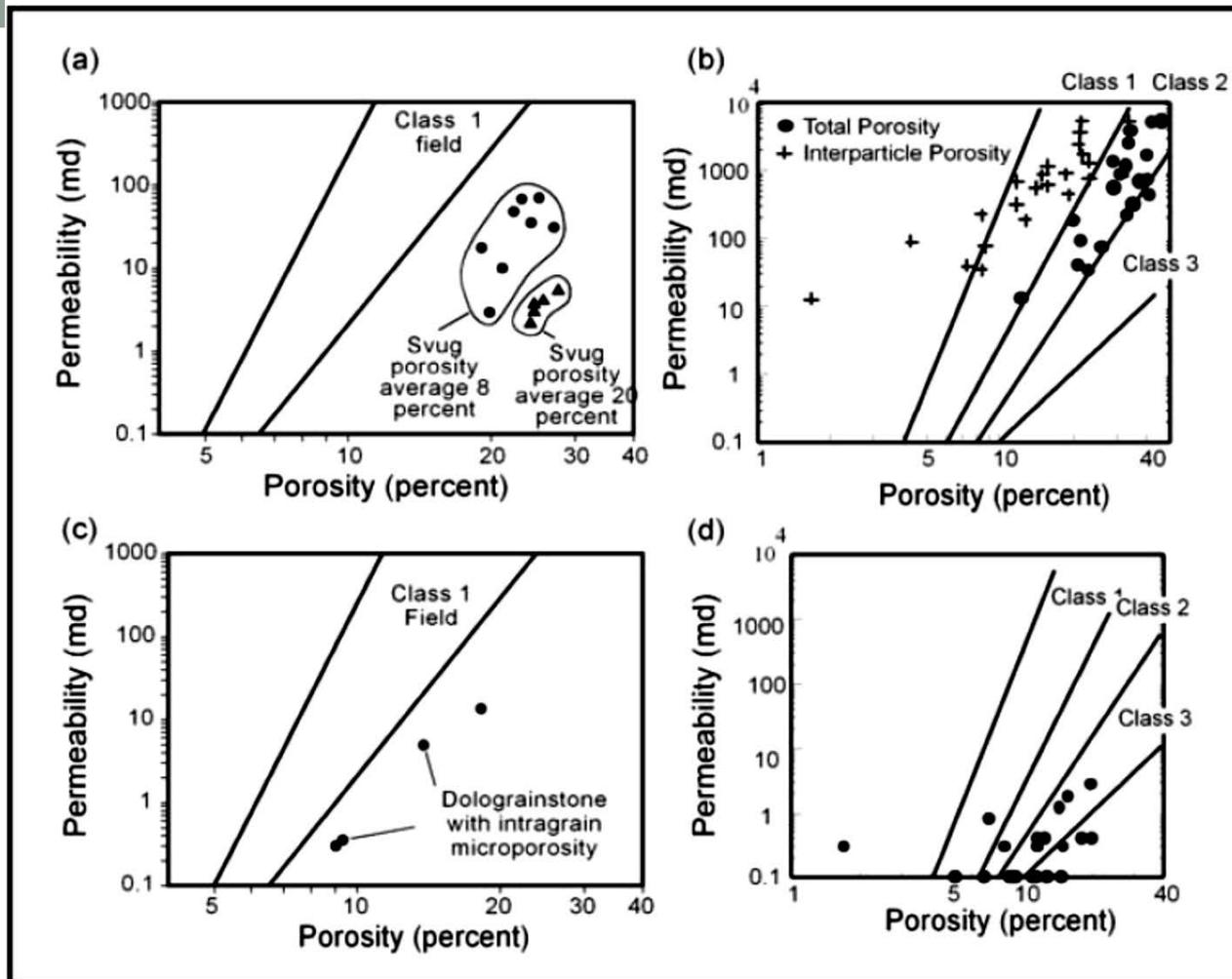
| VUGGY PORE SPACE  |  |  |   |  |
|---|--|--|---|--|
| SEPARATE-VUG PORES<br>(VUG-TO-MATRIX-TO-VUG CONNECTION) |  |  | TOUCHING-VUG PORES<br>(VUG-TO-VUG CONNECTION)   |  |
|   | GRAIN-DOMINATED FABRIC   | MUD-DOMINATED FABRIC   | GRAIN- AND MUD-DOMINATED FABRICS  |  |
|   | EXAMPLE TYPES  | EXAMPLE TYPES  | EXAMPLE TYPES   |  |
| PERCENT SEPARATE-VUG POROSITY                           | Moldic pores<br>              | Moldic pores<br>      | Cavernous<br>  | Fractures<br>                               |
|   | Intrafossil pores<br>         | Intrafossil pores<br> | Breccia<br>    | Solution enlarged fractures<br>             |
|   | Intragrain microporosity<br> | Shelter pores<br>    | Fenestral<br> | Microfractures connecting moldic pores<br> |

# Separate-Vug





**Fig. 2.20.** Examples of separate-vug pore types. (a) Oomolds in oomoldic grainstone. (b) Oomolds and intergrain pore space in a grainstone. (c) Intrafossil pore space in a fusulinid grain-dominated packstone. (d) Intrafossil pore space in a foram with a large opening to interparticle pore space. (e) Skeletal grain molds in moldic skeletal grainstone. (f) Grain molds in a wackestone. (g) Ooid grainstone with intragrain microporosity. (h) Scanning electron photomicrograph of intragrain microporosity showing micropores in a 5-micron rhombic calcite matrix



**Fig. 2.21.** Cross plot illustrating the effect of separate-vug porosity on air permeability. **(a)** Grainstones with separate-vug porosity in the form of grain molds plot to the right of the grainstone field in proportion to the volume of separate-vug porosity. **(b)** Grainstones with intrafossil and intragrain microporosity plot in the class 2 field when plotted against total porosity. **(c)** Dolograinsones with intragrain microporosity plot in the class 2 field. **(d)** Grainstones with intragrain microporosity plot in the class 3 field

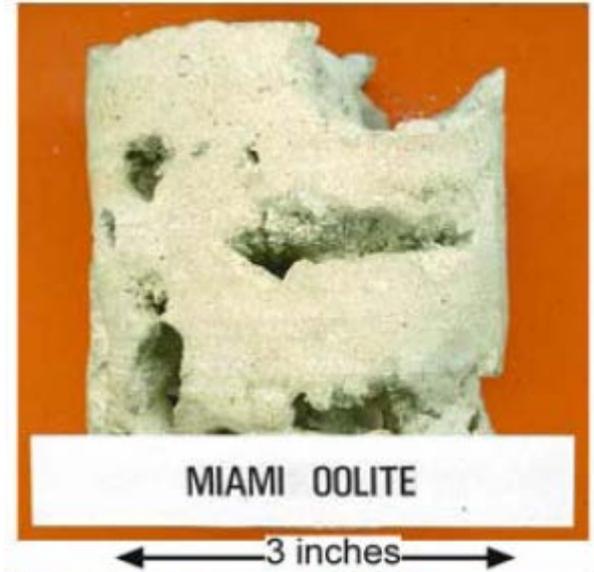
- The addition of separate-vug porosity to interparticle porosity increases total porosity but does not significantly increase permeability. Therefore, it is important to determine interparticle porosity by subtracting separate-vug porosity from total porosity and using interparticle porosity to estimate permeability. The effect of separate vugs on permeability and initial water saturation depends upon the size of the pores connecting the intra- and intergrain pore space. Large separate vugs are normally filled with hydrocarbons above the transition zone. Intragrain microporosity will contain significant amounts of capillary-bound water within the transition zone, resulting in water-free production of hydrocarbons from intervals with high initial water saturations. The transition zone for grainstones with large volumes of separate vugs will be greater than that expected for a nonvuggy grainstone.

# Touching Vug

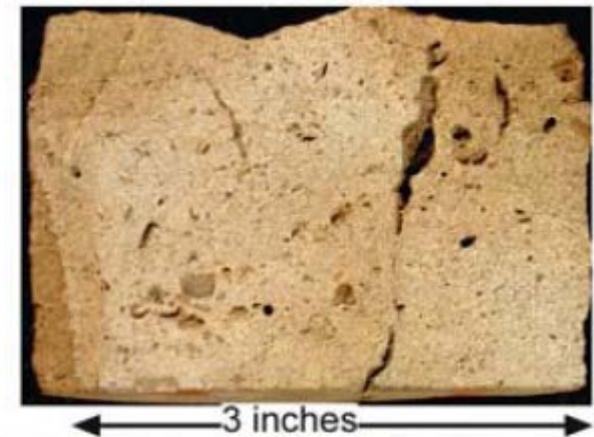
(a)



(b)



(d)

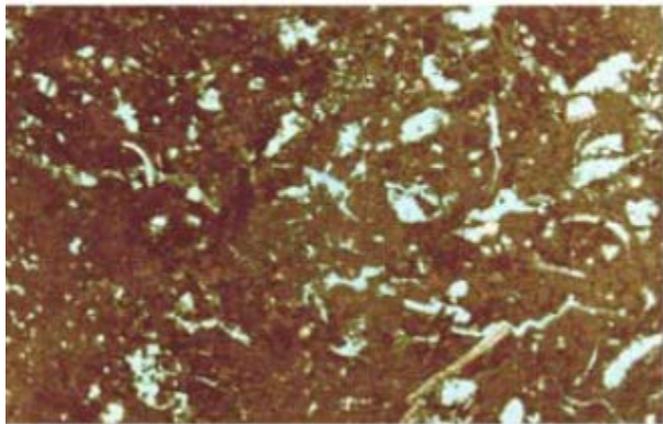


(c)



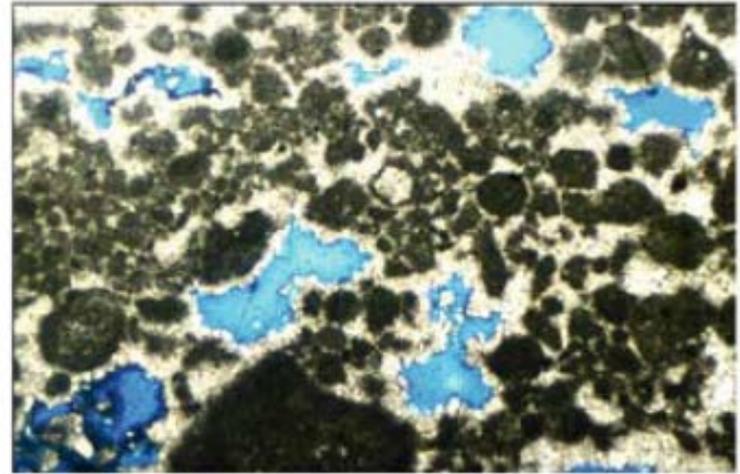
← 3 inches →

(f)



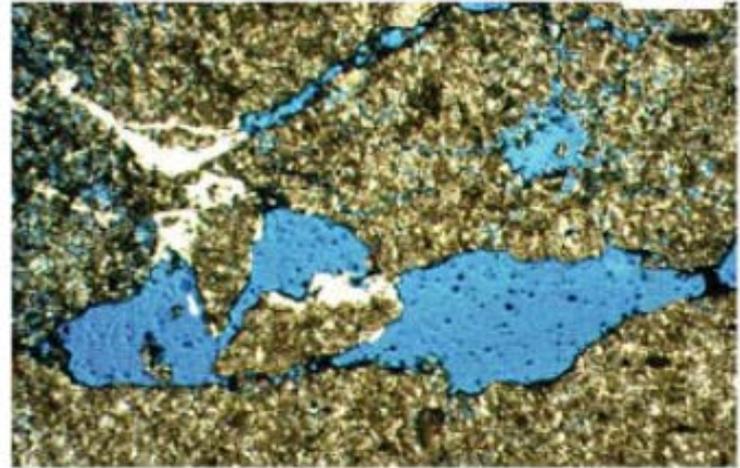
500 μm

(e)

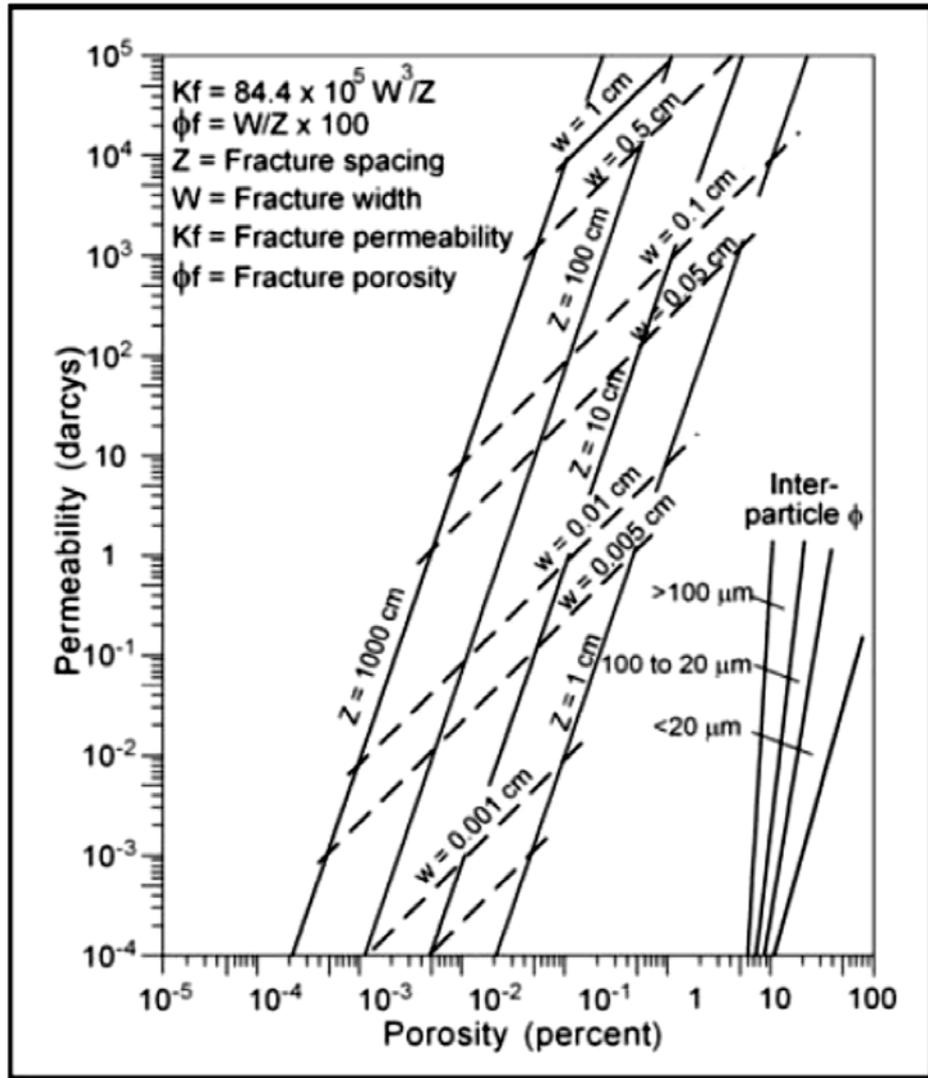


1 mm

(g)



1 mm



- Touching-vug pore systems cannot be related to porosity but are related to the geometry of fracture pore space, large vugs, and collapse breccia. These pore systems are normally larger than the well bore and cannot be adequately studied using cores. Small touching-vug systems formed by microfractures and grain dissolution connecting grain molds can be characterized by core measurements. These systems enhance permeability 5x to 10x over that expected from matrix permeability.

# Making Sense of Carbonate Pore Systems

*Making sense of  
carbonate pore systems*

**Arve Lønøy**

## **AUTHOR**

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Arve Lønøy received a Cand. Real. degree in carbonate sedimentology from the University of Bergen in 1981. He has since then worked as a research geologist on carbonate sedimentology and, to a lesser extent, siliclastic petrography in the Norsk Hydro Research Center. His main work on carbonates has been on Paleozoic carbonates of the Arctic (Norway, Canada, and Russia) and the Mesozoic of western Africa and the Middle East.

Based on empirical data, mostly from Europe and the Middle East, a new pore-type classification system has been developed. The new system not only uses elements from existing pore-type classification systems, but also introduces many new elements. The new pore-type system includes 20 pore-type classes that show a predictable relation between porosity and permeability. It combines sedimentologic and diagenetic features with flow-related properties, and reservoir-critical parameters can thus be predicted using sedimentologic and diagenetic models.

**Table 1.** Porosity-Permeability Coefficients of Determination ( $R^2$ ) for the Lucia (1983, 1995, 1999) and Choquette and Pray (1970) Classification Systems\*

| Pore Type  | $R^2$ |
|--|-------|
| <b>Lucia (1983, 1995, 1999) Classification System</b>  |       |
| Interparticle, class 3                                 | 0.68  |
| Interparticle, class 2                                 | 0.62  |
| Interparticle, class 1                                 | 0.79  |
| Vuggy, separate  | 0.86  |
| Vuggy, touching  | 0.45  |
| <b>Choquette and Pray (1970) Classification System</b> |       |
| Interparticle  | 0.70  |
| Intercrystalline                                       | 0.50  |
| Moldic   | 0.88  |
| Intraparticle  | 0.86  |
| Vuggy  | 0.50  |

\*Using samples from the present study.

**Table 2.** New Porosity Classification System\*

| Pore Type              | Pore Size                          | Pore Distribution | Pore Fabric                          | $R^2$ |
|------------------------|------------------------------------|-------------------|--------------------------------------|-------|
| Interparticle          | Micropores (10–50 $\mu\text{m}$ )  | Uniform           | Interpartide, uniform micropores     | 0.88  |
|                        |                                    | Patchy            | Interpartide, patchy micropores      | 0.79  |
|                        | Mesopores (50–100 $\mu\text{m}$ )  | Uniform           | Interpartide, uniform mesopores      | 0.86  |
|                        |                                    | Patchy            | Interpartide, patchy mesopores       | 0.85  |
|                        | Macropores (>100 $\mu\text{m}$ )   | Uniform           | Interpartide, uniform macropores     | 0.88  |
|                        |                                    | Patchy            | Interpartide, patchy macropores      | 0.87  |
| Intercrystalline       | Micropores (10–20 $\mu\text{m}$ )  | Uniform           | Intercrystalline, uniform micropores | 0.92  |
|                        |                                    | Patchy            | Intercrystalline, patchy micropores  | 0.79  |
|                        | Mesopores (20–60 $\mu\text{m}$ )   | Uniform           | Intercrystalline, uniform mesopores  | 0.94  |
|                        |                                    | Patchy            | Intercrystalline, patchy mesopores   | 0.92  |
|                        | Macropores (>60 $\mu\text{m}$ )    | Uniform           | Intercrystalline, uniform macropores | 0.80  |
|                        |                                    | Patchy            | Intercrystalline, patchy macropores  |       |
| Intraparticle          |                                    |                   | Intrapartide                         | 0.86  |
| Moldic                 | Micropores (<10–20 $\mu\text{m}$ ) |                   | Moldic micropores                    | 0.86  |
|                        | Macropores (>20–30 $\mu\text{m}$ ) |                   | Moldic macropores                    | 0.90  |
| Vuggy                  |                                    |                   | Vuggy                                | 0.50  |
| Mudstone microporosity | Micropores (<10 $\mu\text{m}$ )    |                   | Tertiary chalk                       | 0.80  |
|                        |                                    |                   | Cretaceous chalk                     | 0.81  |
|                        |                                    | Uniform           | Chalky micropores, uniform           | 0.96  |
|                        |                                    | Patchy            | Chalky micropores, patchy            |       |

\*Partly based on Choquette and Pray (1970) and Lucia (1983, 1995, 1999). Porosity-permeability coefficients of determination ( $R^2$ ) are based on samples from the present study.

- the new classification scheme was to incorporate the observation of Lucia (1983) that pore size is a primary factor in understanding porosity-permeability relationships. Whereas Lucia recognized the control of pore size on porosity permeability relationships, his classification scheme uses grain size (of particles or crystals) instead of pore size as the primary means of pore class division (i.e., his interparticle classes 1, 2, and 3). In this study, direct description of pore size was used (instead of particle or crystal size). This is in part because of the range of sorting observed in many samples that made classification of particle size problematic and partly because later cements commonly act to occlude pore space, making the relation of pore size to grain size indirect. The result of incorporating pore size into the system was a further increase in the R<sup>2</sup>.

- Important modifications include the addition of uniform and patchy porosity distribution and the incorporation of mudstone microporosity made to achieve high R2 values.
- In this Article, Thin-section porosity was impregnated with bluedyed epoxy for visualization of pore types. Helium porosity and air permeability (Klinkenberg corrected) were measured on horizontal and a few vertical plugs.

The main differences between the new carbonate pore system and those of Choquette and Pray (1970) and Lucia (1983, 1995, 1999) are as follows:

- Porosity distribution is a major new element in the classification.
- Lucia's subdivision of interparticle porosity has been partly incorporated into the new classification system, but is now based on pore size instead of grain size and sorting.
- Lucia's three interparticle pore-type classes and Choquette and Pray's interparticle and intercrystalline porosity types have been subdivided into 12 new classes (6 interparticle and 6 intercrystalline).
- Micromoldic and macromoldic pores are differentiated.
- A new pore-type category, consisting of four pore types, is introduced: mudstone microporosity.

The new classification system combines sedimentologic and diagenetic features with flow-related properties, and reservoir-critical parameters can thus be predicted using sedimentologic and diagenetic models.

The new classification system is based on three main elements: pore type, pore size, and pore distribution. Age is an important factor for some of the mudstone micropore classes.

## **Pore Type**

Six main pore types are identified: interparticle, intercrystalline, vuggy, intraparticle, moldic, and mudstone microporosity (Table 2). The first five pore types are almost identical to those defined by Choquette and Pray (1970), whereas the last one is new.

## **Pore Size**

Lucia (1983, 1995, 1999) realized that pore-size distribution controls permeability and is related to rock fabric. Therefore, he used average particle size and sorting to differentiate between different interparticle pore-type classes. The term “particle” was used as a general term for grains (multicrystalline particles) and crystals (single-crystal particles) (Lucia, 1983).

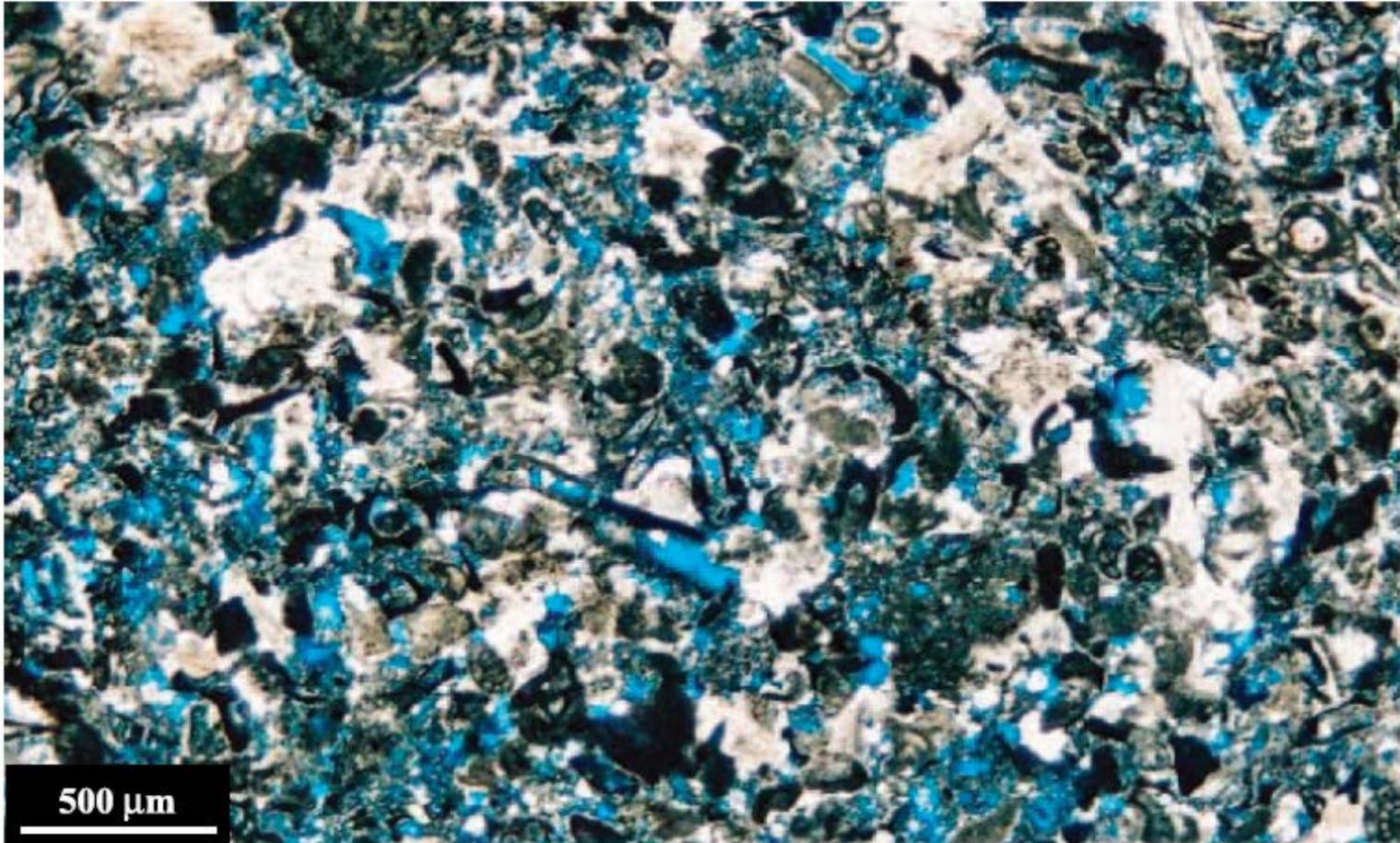
Interparticle pore diameters and size distributions were measured on the reference samples shown in Figure 1a–c. Micropores have a dominant pore diameter in the 10–60- $\mu\text{m}$  range (70% of the pores). Mesopores have a dominant pore diameter of 40–100  $\mu\text{m}$ , although approximately 30% of the pores are in the 100–300- $\mu\text{m}$  range. Macropores are generally larger than 100  $\mu\text{m}$  in diameter (approximately 75% of the pores). Interparticle pore-size groups may thus be defined by 10–50 (micropores), 50–100 (mesopores), and greater than 100  $\mu\text{m}$  (macropores). Porosity with dominant pore diameters less than 10  $\mu\text{m}$  is classified as mudstone microporosity.

Intercrystalline micropores are commonly 10–20  $\mu\text{m}$  in diameter, whereas mesopore diameters mostly are in the 20–60- $\mu\text{m}$  range. Intercrystalline macropores have diameters larger than 60  $\mu\text{m}$ .

Moldic micropore diameters are typically less than 10–20  $\mu\text{m}$ , although they occasionally can be larger. Moldic macropores are larger than 20–30  $\mu\text{m}$ .

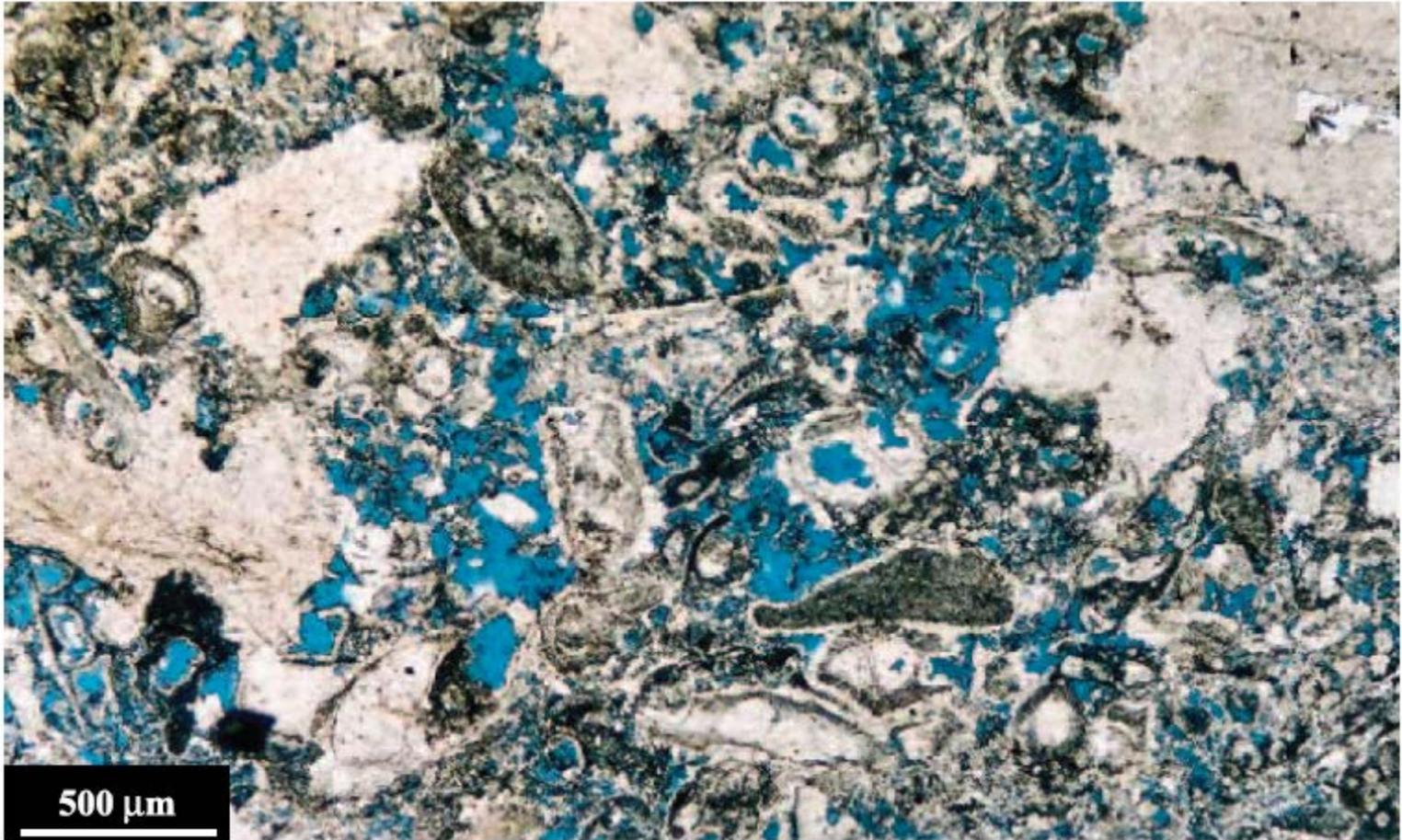
Figure 1. Thin-section micrographs showing samples with a predominance of interparticle porosity, some of which are solution enlarged. Minor intraparticle and moldic pores are present, but interparticle pores predominate

a



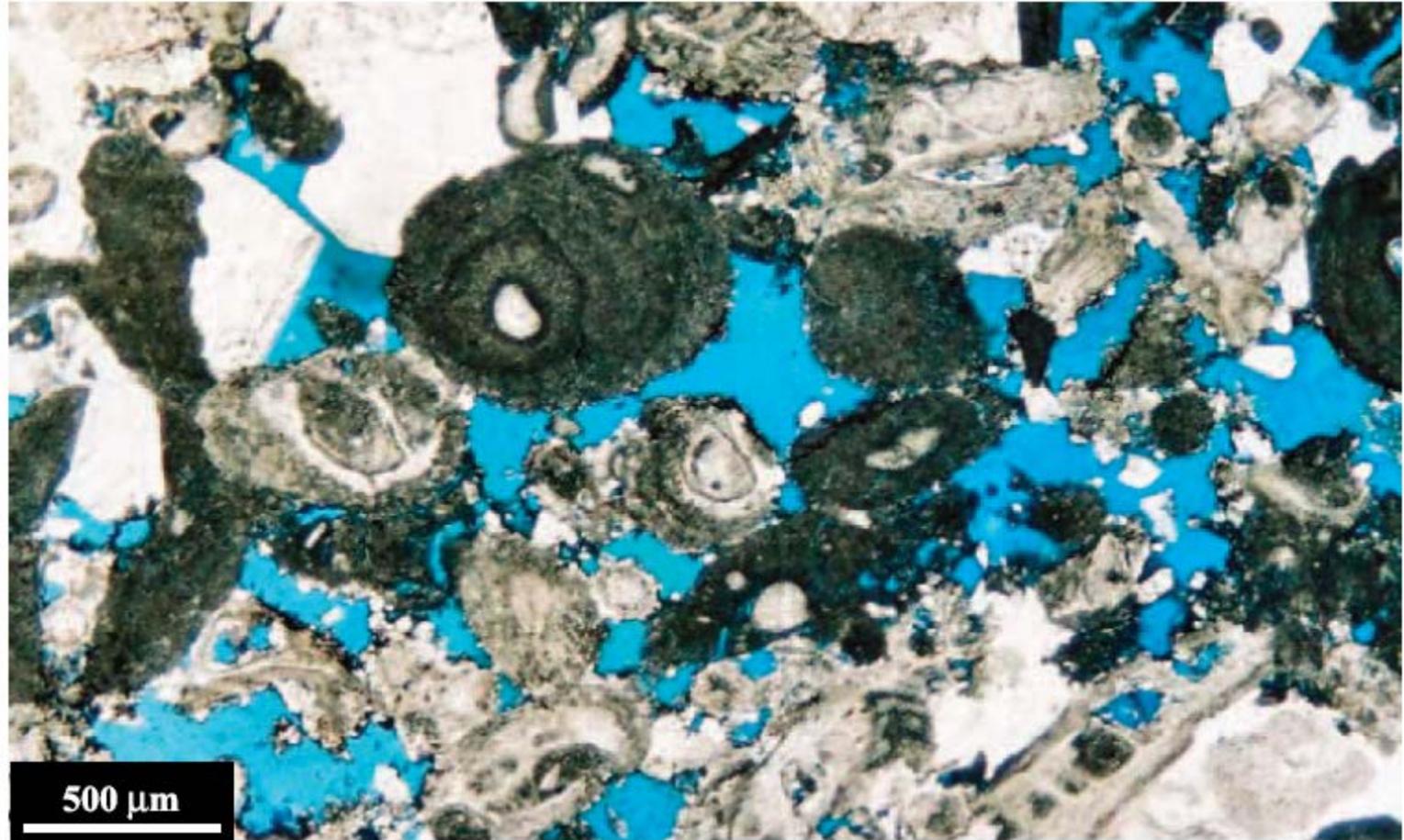
Microporosity (10–50 μm pore diameter) with uniform porosity distribution,  $f = 17.6\%$ ,  $k = 0.84$  md;

b



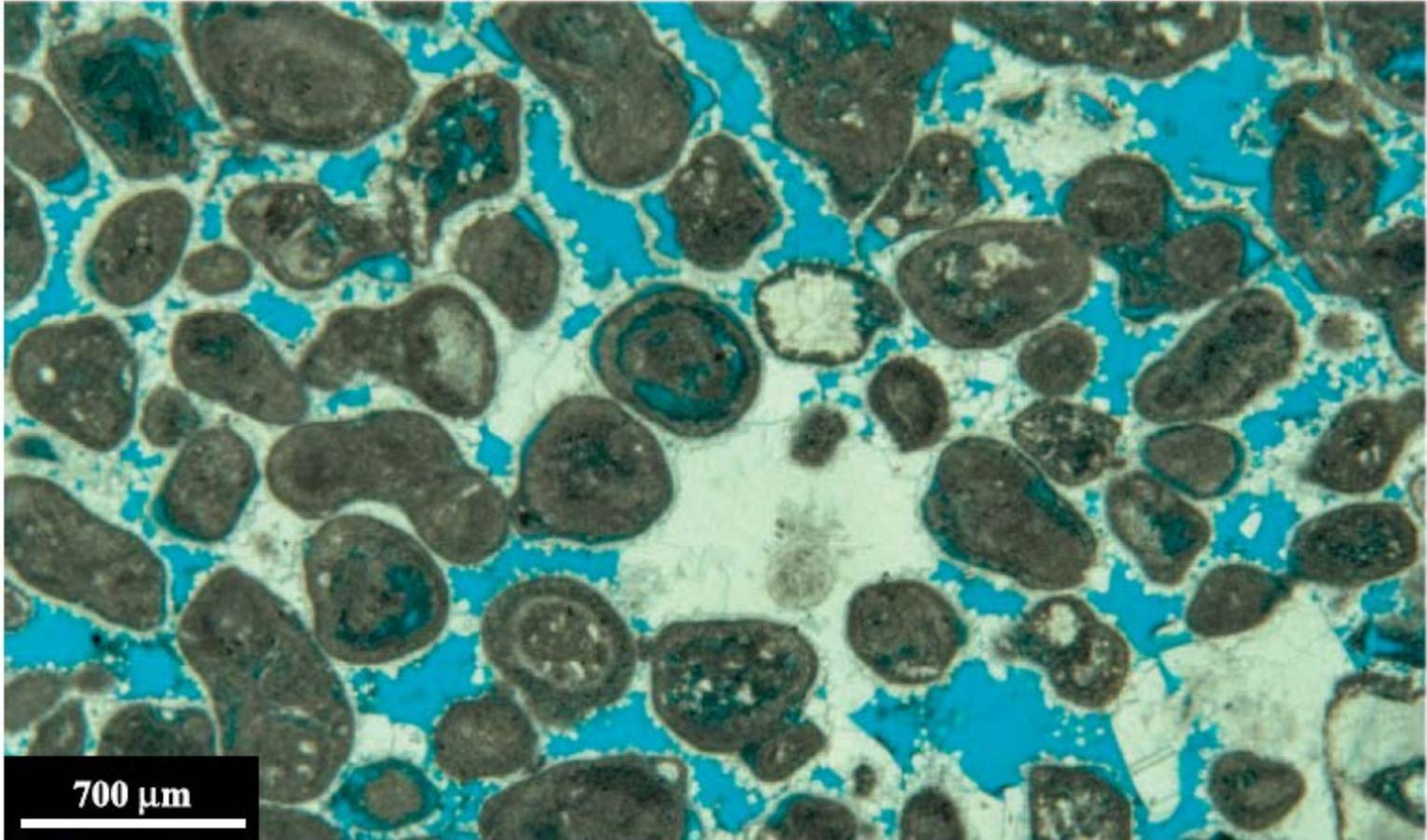
mesoporosity (50–100 nm pore diameter) with uniform porosity distribution,  $f = 19.3\%$ ,  $k = 9.47 \text{ md}$ ;

c



Macroporosity (>100 μm pore diameter) with uniform porosity distribution,  $f = 15.3\%$ ,  $k = 132$  md;

d



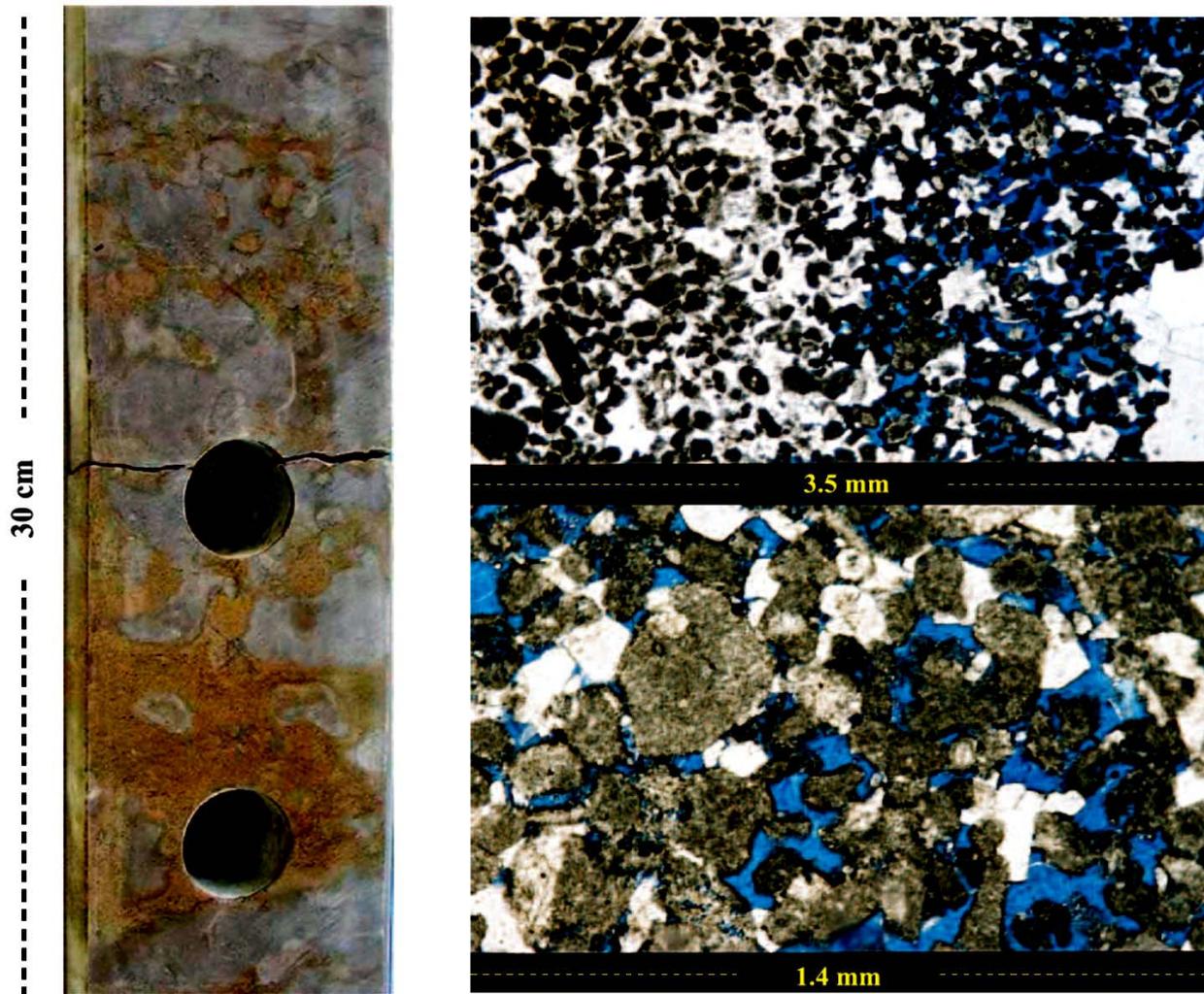
macroporosity ( $>100$  μmpore diameter) with uniform porosity distribution and porelining calcite cement,  $f = 9.7\%$ ,  $k = 0.465$  md.

## **Pore Distribution**

Porosity distribution is a new element in pore-type classification and has a significant effect on porosity-permeability relationships (also noted by Lucia et al., 2004a, b). The distribution of interparticle pores, inter-crystalline pores, and mudstone micropores has been visually classified as either uniform or patchy.

At similar porosities, a patchy porosity distribution is observed to yield significantly higher permeability than uniform porosity distribution. The reason for this is that the porosity is concentrated over a smaller vol-

ume and the pore system is better connected than for an equivalent, uniformly distributed pore volume. Furthermore, a patchy porosity distribution is often related to secondary dissolution with slight corrosion of pore throats, and this process also tends to favor connected pores.



**Figure 2.** Example of patchy interparticle mesoporosity (50–100  $\mu\text{m}$  pore diameter) in Devonian rocks from Russia. Left: core slab showing patchy pore distribution related to differential dissolution. Tight, calcite-cemented areas are gray; porous, oil-stained areas are brown. Right: thin-section photomicrographs showing patchy interparticle mesopores related to differential dissolution of cements. Lower photomicrograph is a close-up showing patchy porosity at a larger scale. Note the abundance of rhombohedral pore outlines, which are indicative of dissolution. Calcite cements are white. Both photomicrographs were taken under plane-polarized light.

# PORE-TYPE DEFINITIONS

## **Interparticle Porosity:**

- Choquette and Pray (1970) defined interparticle porosity as porosity occurring between grains (intergrain). Lucia (1983) extended the term “interparticle” to also include pore spaces between crystals (intercrystal). This redefinition thus included both the interparticle and intercrystalline porosity types of Choquette and Pray (1970). However, the results of this study show that the petrophysical properties of intergrain and intercrystal pores are different.

- Interparticle pores are normally associated with medium- to high-energy depositional settings in the studied data set, such as rimmed, platform-margin shoals, distally steepened ramp-margin shoals, inner-rampfringing shoals, middle-ramp barrier shoals, local platforminterior shoals, gravity-driven flow deposits, beaches, wash-over fans, and others. Micropores and mesopores occur within grain-supported textures composed of extremely small bioclastic fragments, where larger interparticle pores have been partially occluded by cement, or within poorly sorted grainstones. Micropores also occur within recrystallized mud of mud-lean packstones. Macropores are most common in moderately to well sorted, high-energy grainstones.

## **Intercrystalline Porosity:**

- Intercrystalline porosity is the porosity between crystals that may be of either primary or secondary origin (Choquette and Pray, 1970). All intercrystalline pores included in the studied data set are secondary in origin and occur between crystals that have grown more or less in place by calcite recrystallization or dolomitization.

a



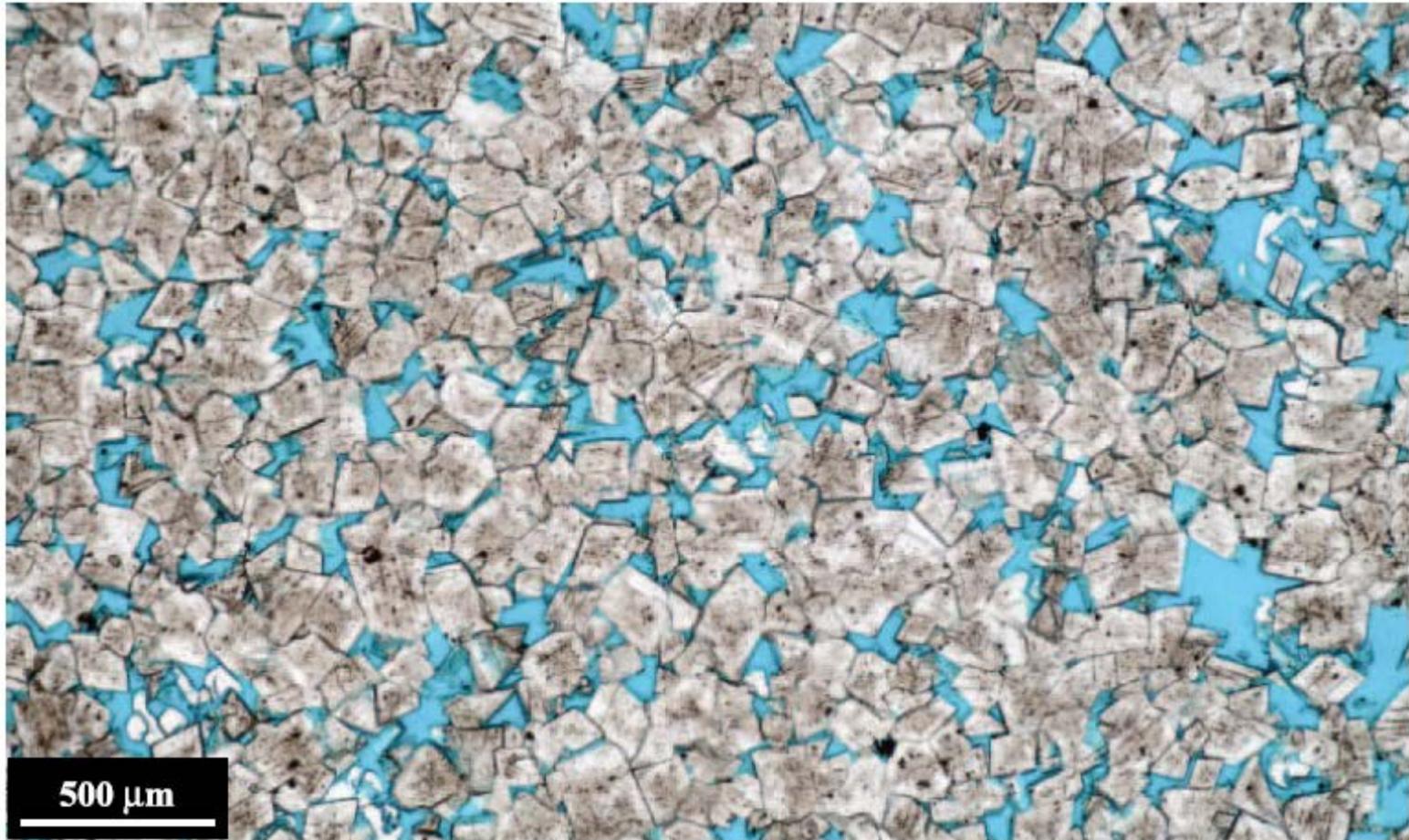
microporosity (10–20 mm pore diameter) with uniform porosity distribution,  $f = 18.1\%$ ,  $k = 0.476$  md;

b



Mesoporosity (20–60  $\mu\text{m}$  pore diameter) with uniform porosity distribution,  $f = 19.3\%$ ,  $k = 4.93 \text{ md}$ ;

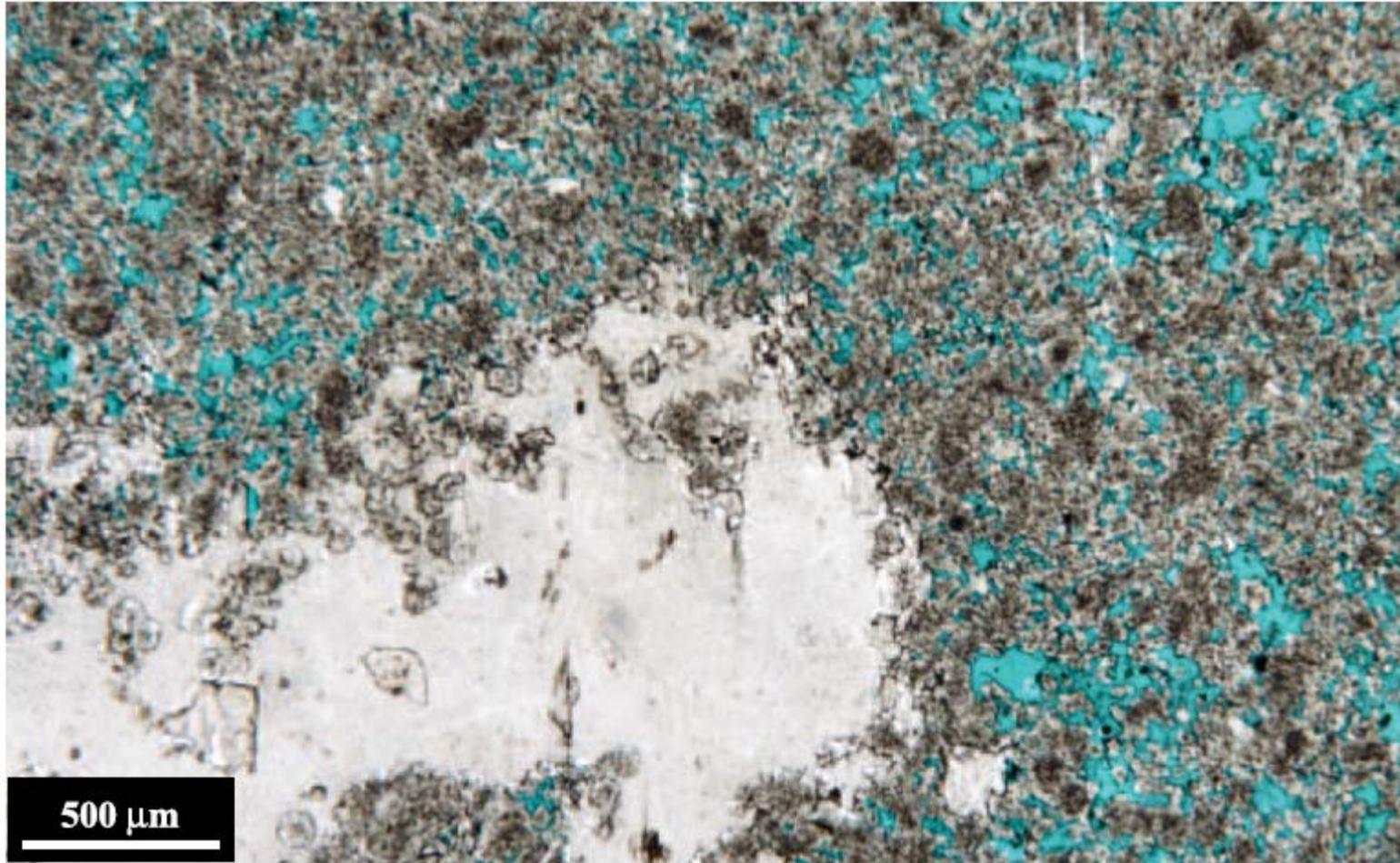
c



500  $\mu\text{m}$

macroporosity ( $>60$  mm pore diameter) with uniform porosity distribution,  $f = 11.0\%$ ,  $k = 16.7$  md;

d



Mesoporosity (20–60 mm pore diameter) with patchy porosity distribution related to gypsum cementation (white);  $f = 12.1\%$ ,  $k = 16.0$  md.

## **Mudstone Microporosity:**

- Mudstone micropores have extremely small pore sizes, commonly a few micrometers in diameter. Individual pores cannot be seen with a standard petrographic microscope.
- Chalk micropores are primary in origin and occur between grains of planktonic calcareous algae (coccospheres) or their component crystal plates (coccoliths). Chalky micropores are not related to chalk, but the pore structure is similar. These pores occur between recrystallized mud particles and may be formed either during early meteoric leaching or deeper burial diagenesis (Pittman, 1971; Budd, 1989; Moshier, 1989). The pores typically form in low-energy, muddy, platform-interior facies.

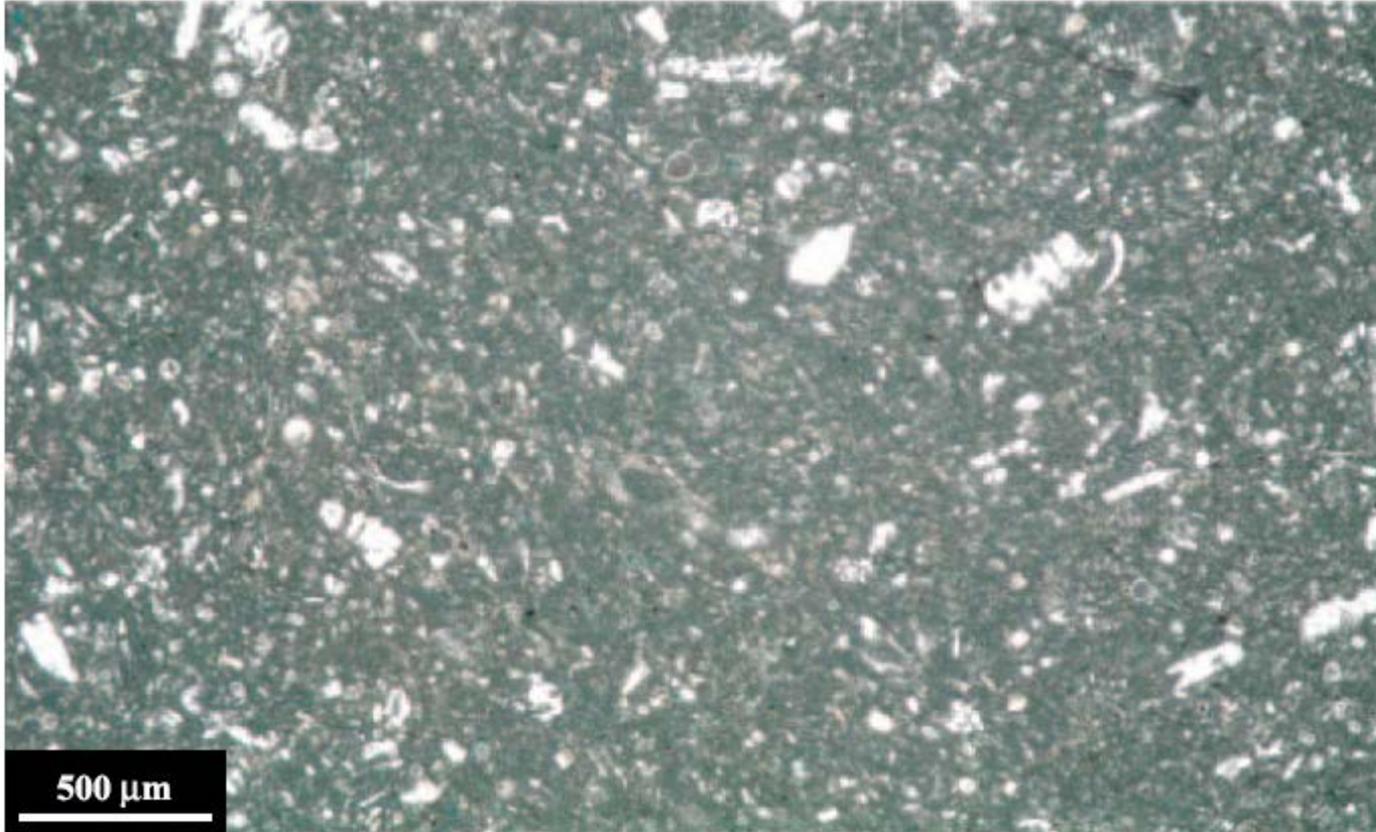
- Four natural classes of mudstone microporosity exist in the database: (1) Tertiary chalk, (2) Cretaceous chalk, (3) chalky micropores with uniform distribution, and (4) chalky micropores with patchy distribution. The distinction between Tertiary and Cretaceous chinks is important because a general decrease in the size of calcareous nannoplankton across the Cretaceous–Tertiary boundary (Macleod et al., 1997) corresponds to a decrease in reservoir quality in Tertiary chinks (Hardman, 1983).

a



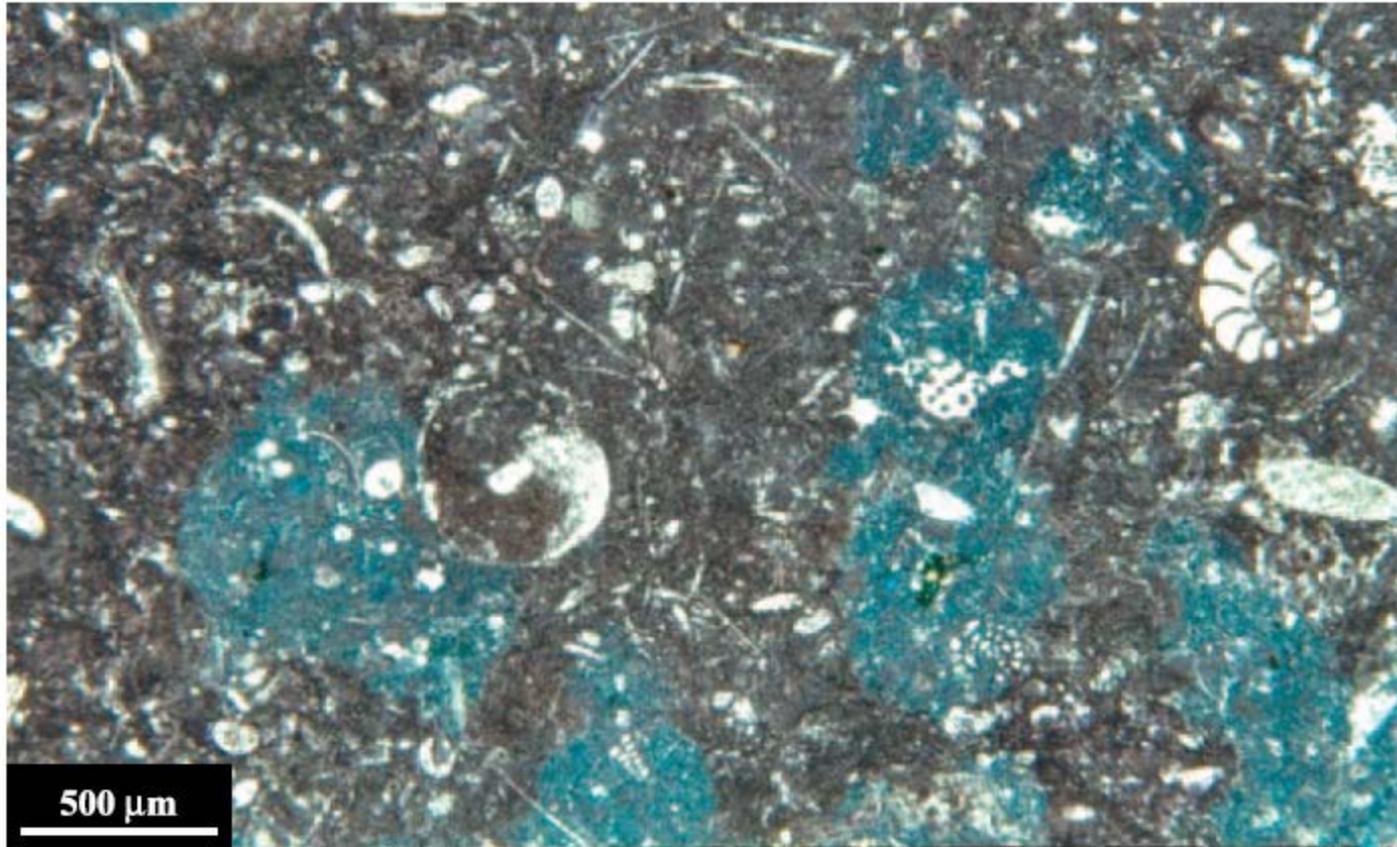
chalk,  $f = 25.4\%$ ,  $k = 0.734$  md;

b



chalky microporosity,  $f = 4.9\%$ ,  $k = 0.01$  md;

C

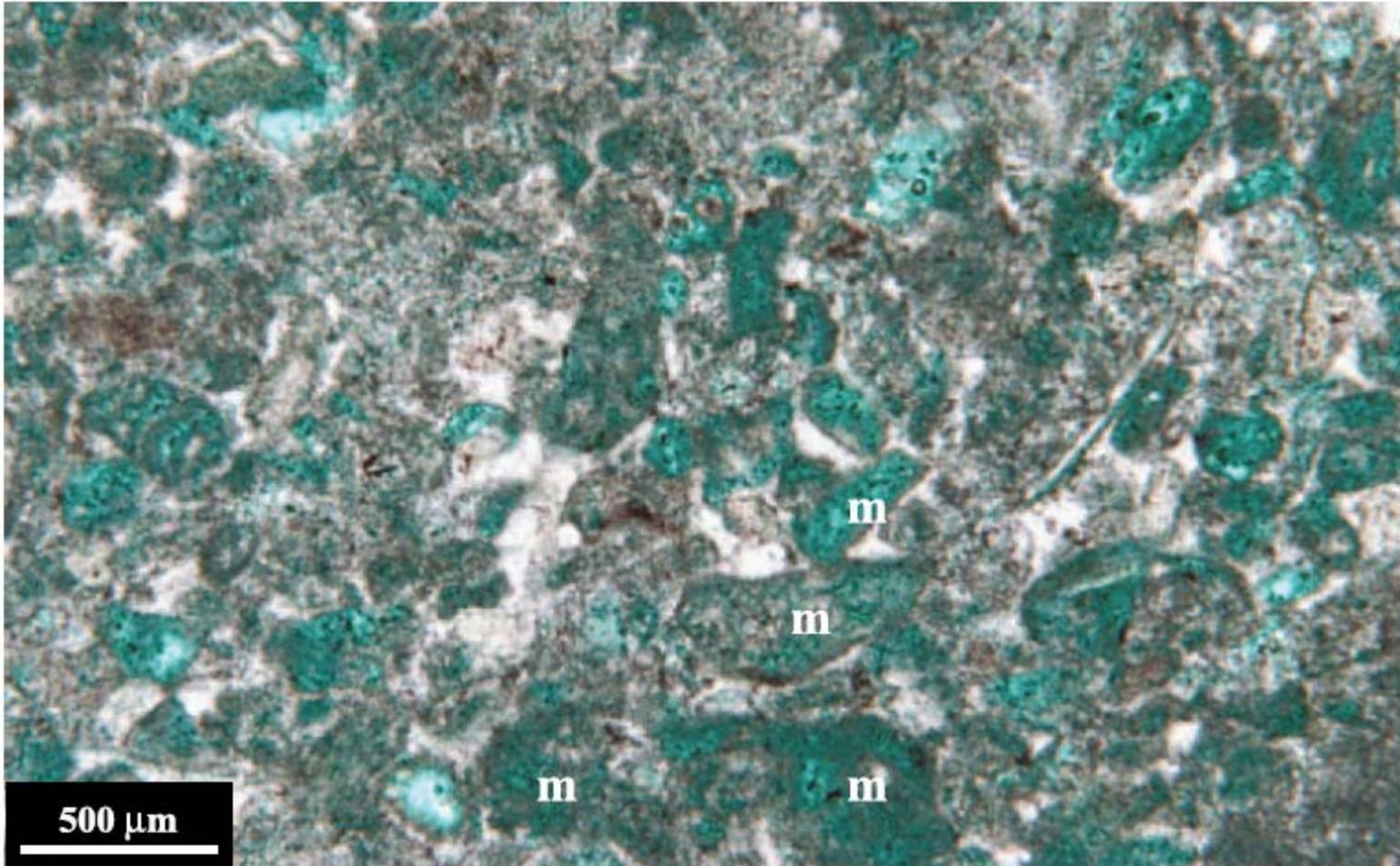


patchily distributed chalky microporosity, no porosity, or permeability measurements are available. Individual pores are too small to be seen, but porosity can be discerned because of impregnation with blue-dyed epoxy.

## **Moldic Porosity:**

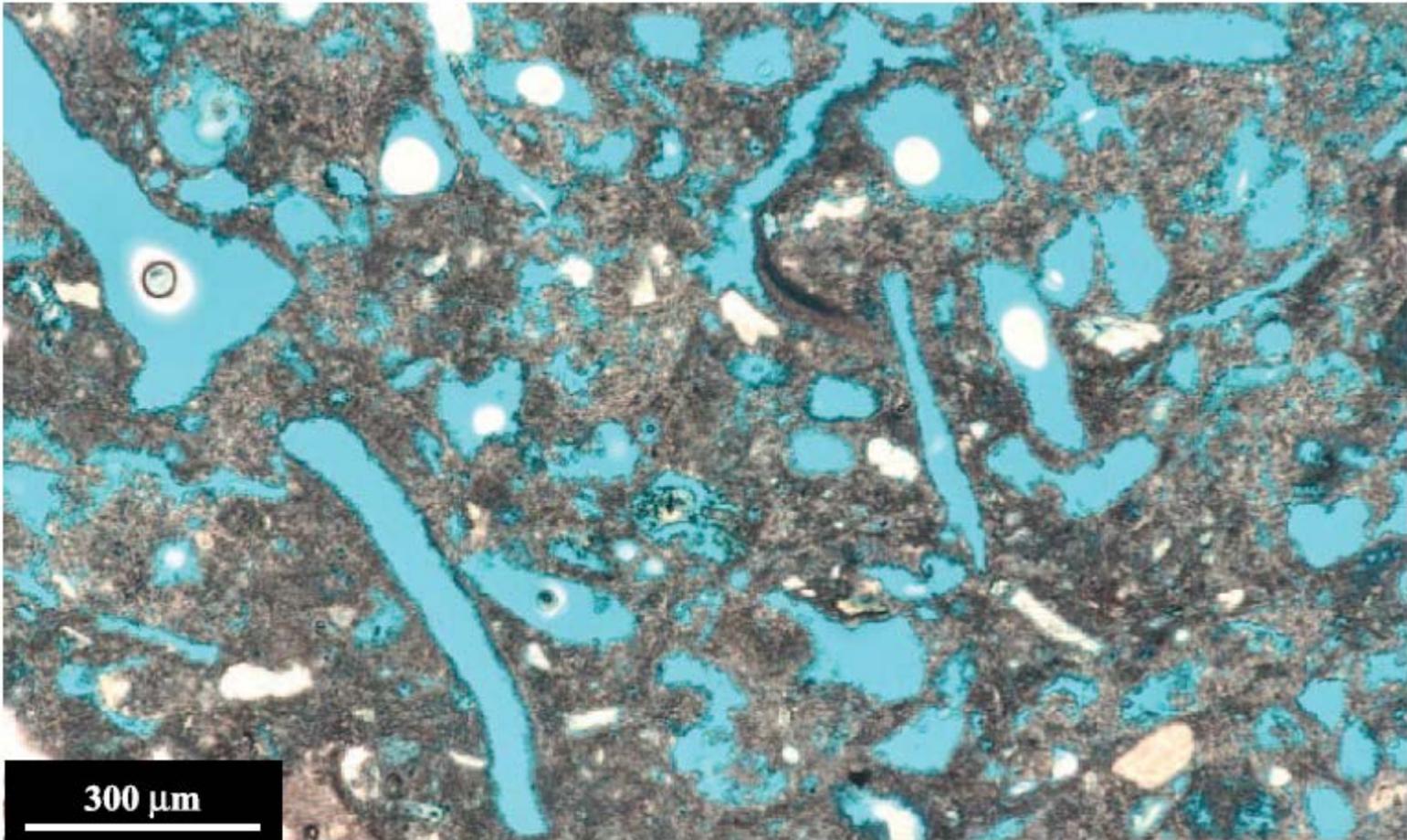
- Moldic pores are secondary pores formed by the selective, complete, or partial dissolution and recrystallization of grains or crystals. This definition is slightly modified from Choquette and Pray (1970) by including pores formed by partial dissolution and recrystallization. A distinctive difference in solubility between grains and/or crystals and the surrounding matrix is commonly needed and is commonly related to mineralogical differences (Moore, 2001).

a



microporosity,  $f = 21.7\%$ ,  $k = 3.45\text{md}$ ;  
Some of the moldic micropores are marked by m

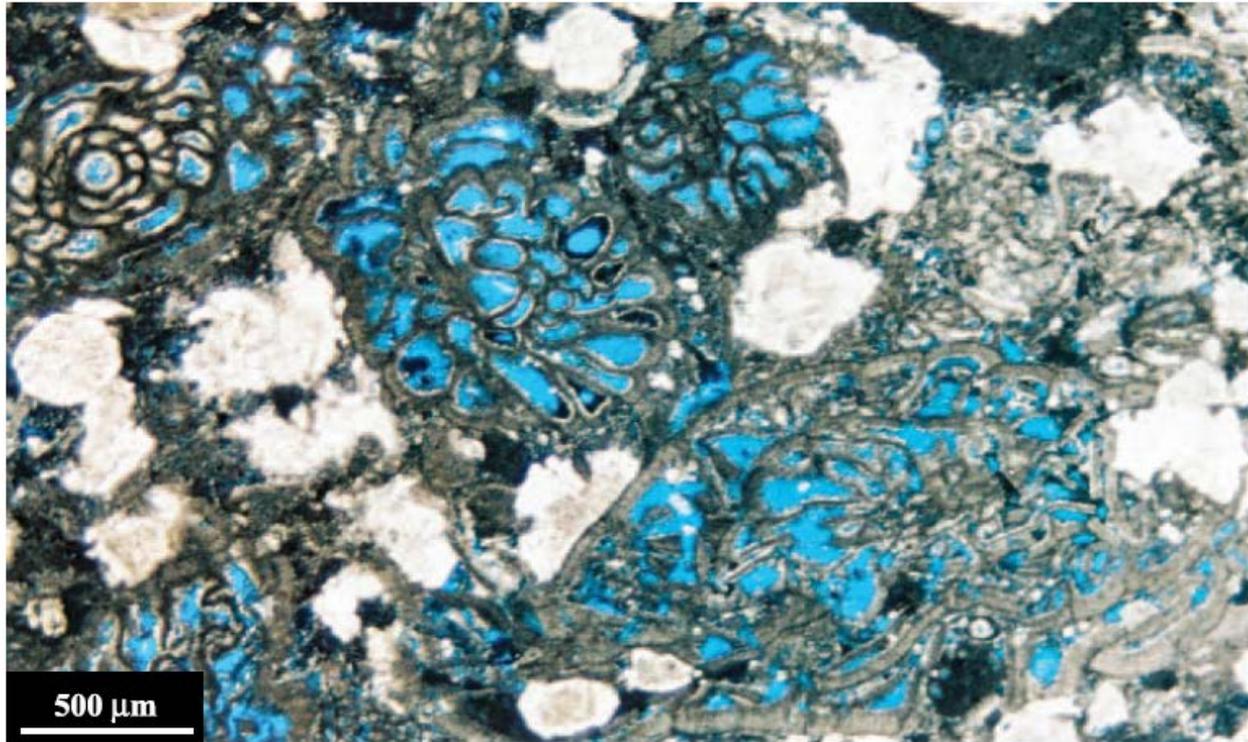
b



macroporosity,  $f = 24.74\%$ ,  $k = 35.2$  md.

## Intraparticle Porosity:

- Intraparticle pores are pore spaces occurring within grains, either of primary origin or formed through the decay of organic material in carbonate skeletons. A skeletal wall will therefore enclose, at least partly, most intraparticle porosity.



intraparticle porosity in fusulinid foraminifera.  $f = 16.0\%$ ,  $k = 1.25$  md.

## **Vuggy Porosity:**

- The definition of vuggy porosity in this article follows the definition of Choquette and Pray (1970). Vuggy pores are secondary solution pores that are not fabric selective (i.e., the pores cut across grains and/or cement boundaries). The pores are of irregular size and shape and may or may not be interconnected. Many vugs are solution-enlarged molds where the outlines of the precursor grains are poorly defined.

- Vuggy porosity (as defined by Choquette and Pray, 1970) is formed by the dissolution of cement, matrix, and grains. This typically occurs under the influence of near-surface meteoric waters (Loucks and Handford, 1992; Saller et al., 1994), but may also be related to deep-burial fluids (Moore and Druckman, 1981; Choquette and James, 1987; Moore and Heydari, 1993). Meteoric diagenesis is commonly associated with sea level low stands and subaerial exposure surfaces in humid climates (Loucks and Handford, 1992; Saller et al., 1994). Deep-burial dissolution may be related to hydrocarbon maturation and shale dewatering (Moore, 1989). Fluid-migration pathways, such as fractures and faults, are the main controls on vuggy porosity distribution during deep burial.

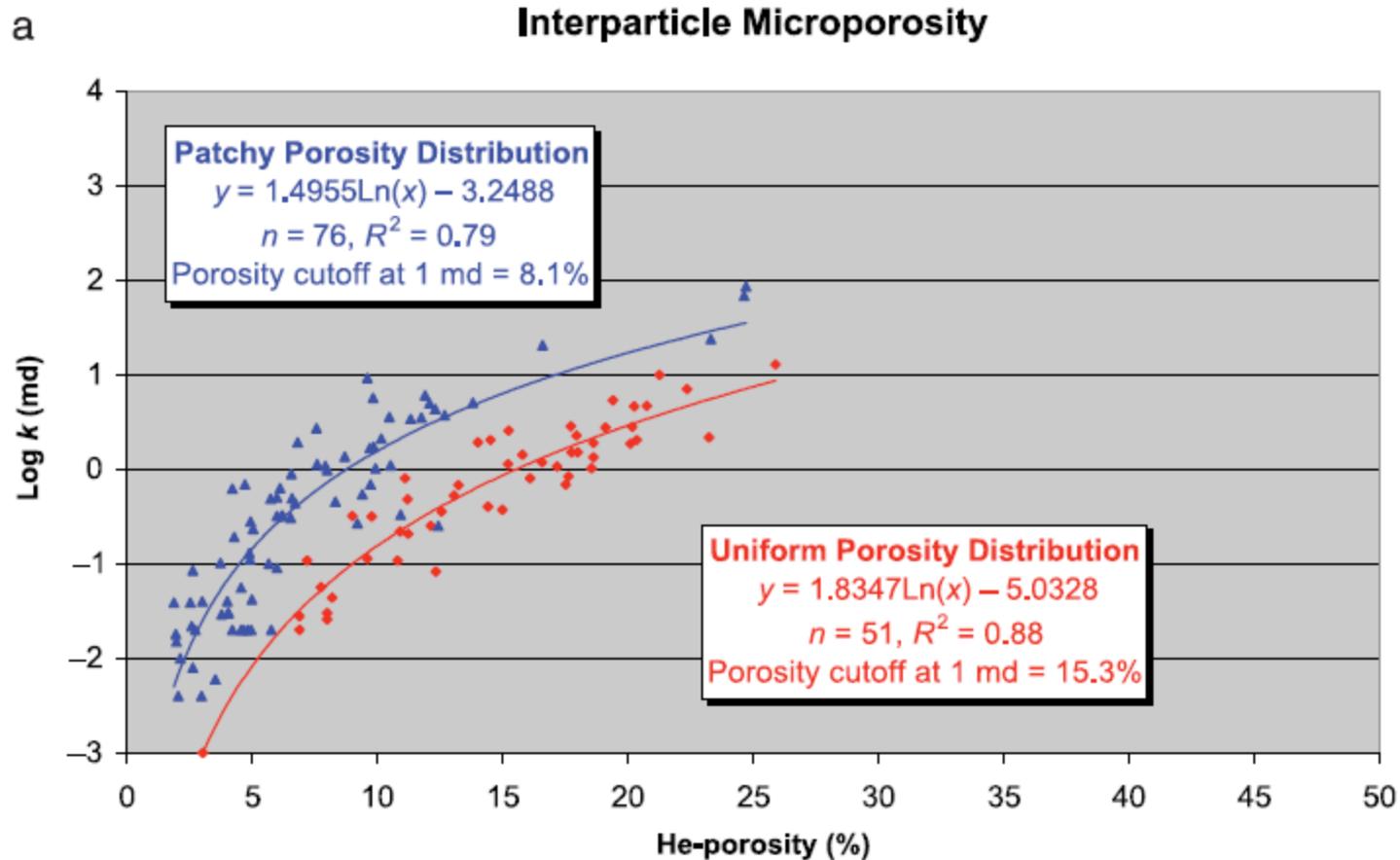


Core slabs showing vuggy porosity. Plug-derived porosities and permeabilities are strongly dependent on the location of core plugs because of the large vug sizes.

# POROSITY-PERMEABILITY RELATIONSHIPS

- Porosity-permeability crossplots are used for predicting permeability from porosity or vice versa. Borehole porosity can be estimated from wire-line logs, but apart from the nuclear magnetic resonance log, there is no log that measures permeability. Therefore, it is common practice to establish porosity-permeability relationships through core analysis and then estimate permeability where cores do not exist using porosity logs and core derived porosity-permeability relationships. This method works well when there is a simple relationship between porosity and permeability, as in many sandstone reservoirs. In carbonate reservoirs, however, the porosity-permeability relationship is very complex because of the great variability of pore types.

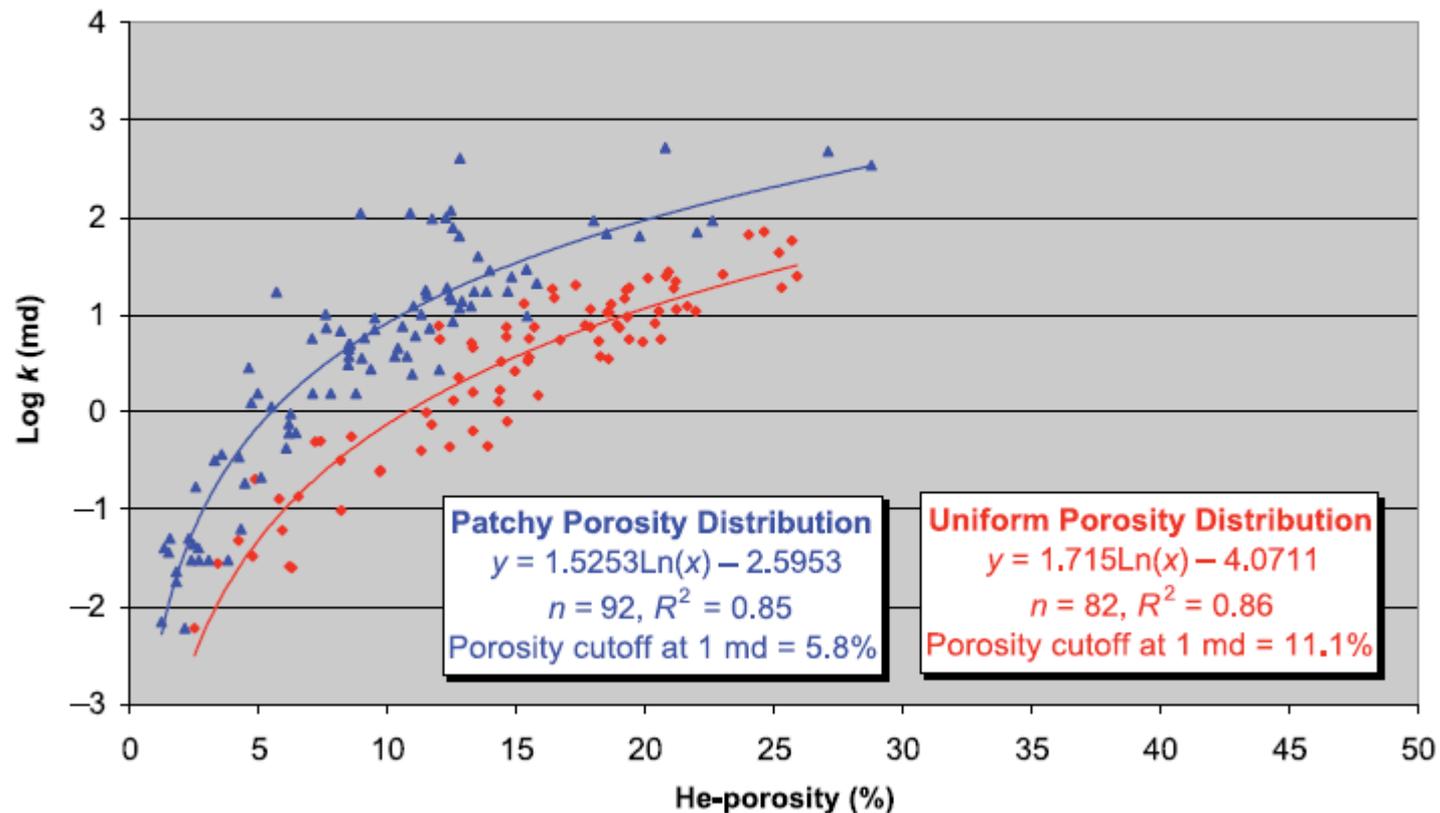
# Interparticle Pore-Type Classes:



Interparticle micropores (10–50  $\mu$ m pore diameter);

b

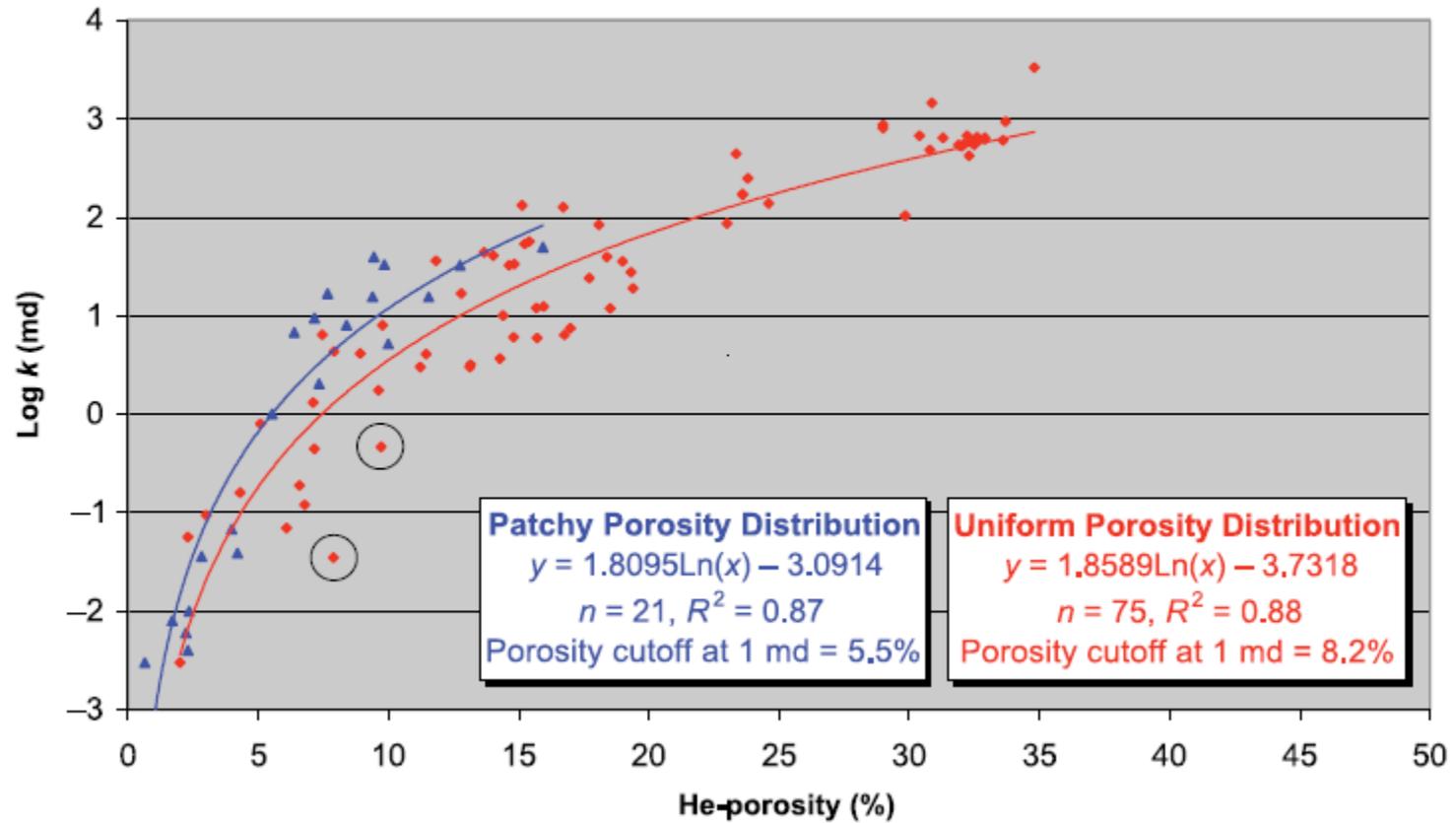
### Interparticle Mesoporosity



interparticle mesopores (50–100 mm pore diameter);

C

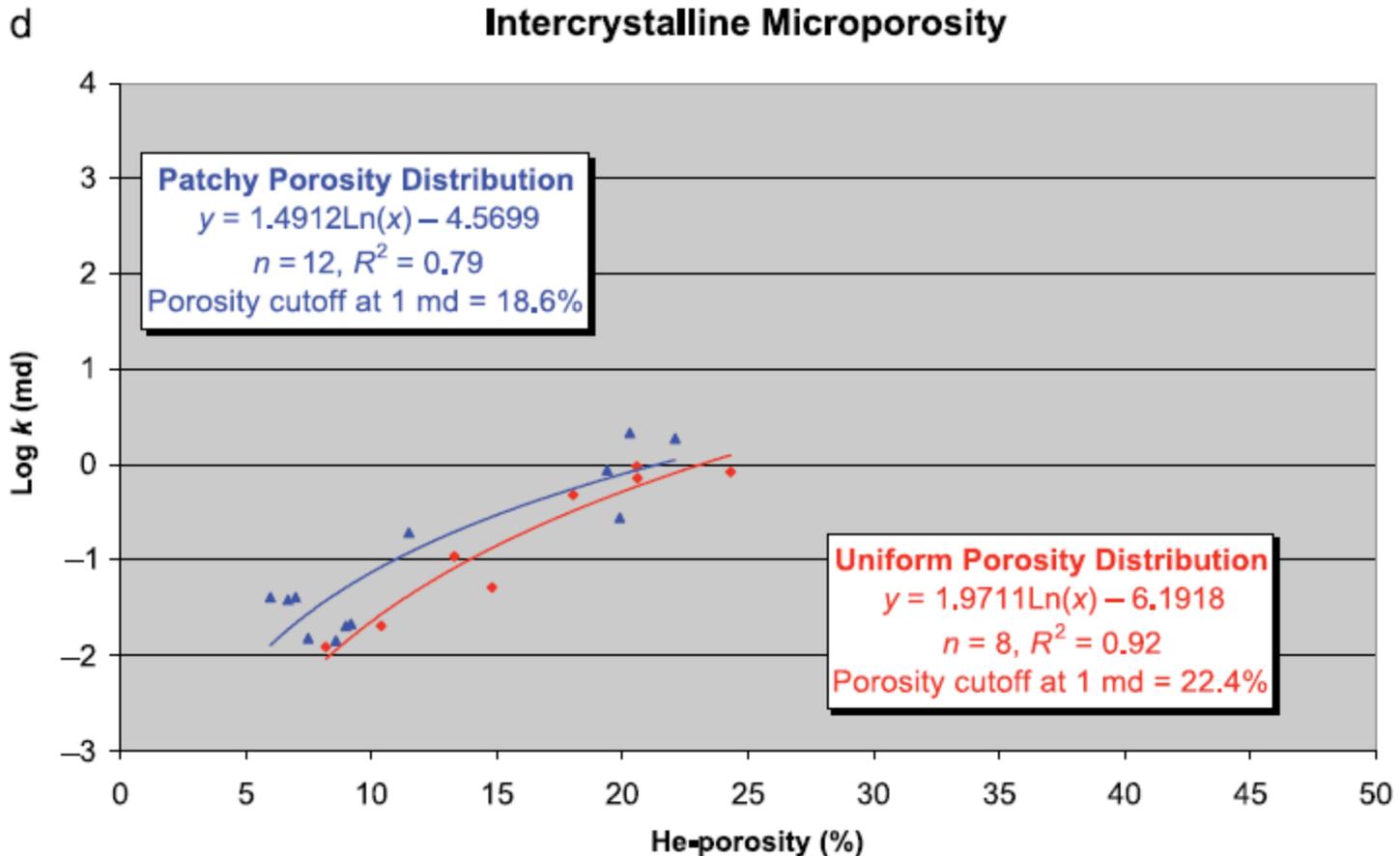
### Interparticle Macroporosity



interparticle macropores (>100 mm pore diameter);

- If 1md is used as the critical flow parameter, the porosity cutoff for interparticle microporosity (10–50-mm pore diameter) is reduced from 15.3% at uniform porosity distribution to 8.1%, when the porosity is patchily distributed. Similarly, for meso- (50–100-mm pore diameter) and macroporosity (>100-mm pore diameter), the porosity cutoff is reduced from 11.1 to 5.8 and 8.2 to 5.5%, respectively, for the corresponding 1-md permeability.

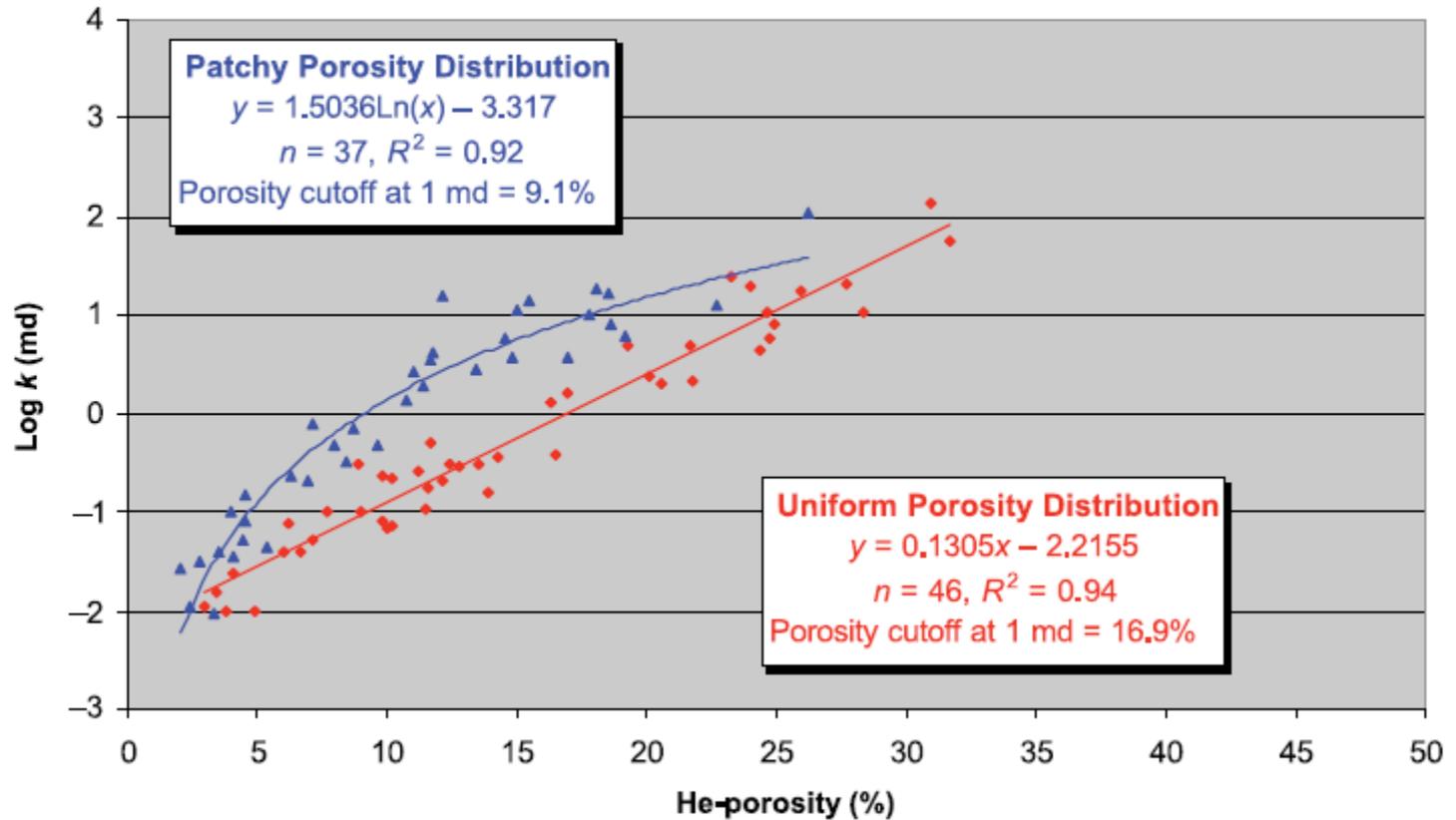
- Intercrystalline Pore-Type Classes:



Intercrystalline micropores (10–20 mm pore diameter);

e

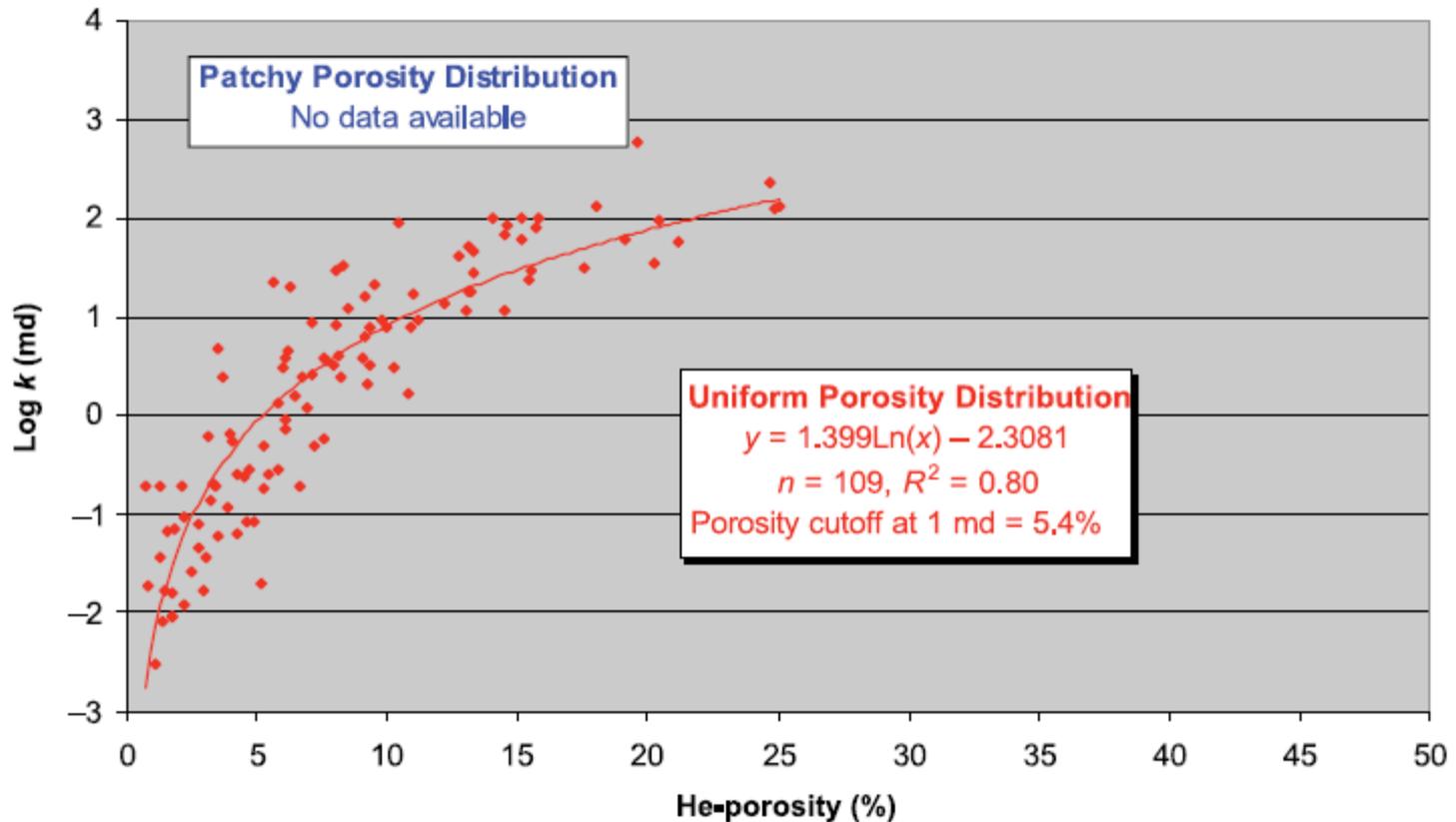
### Intercrystalline Mesoporosity



intercrystalline mesopores (20–60 nm pore diameter);

f

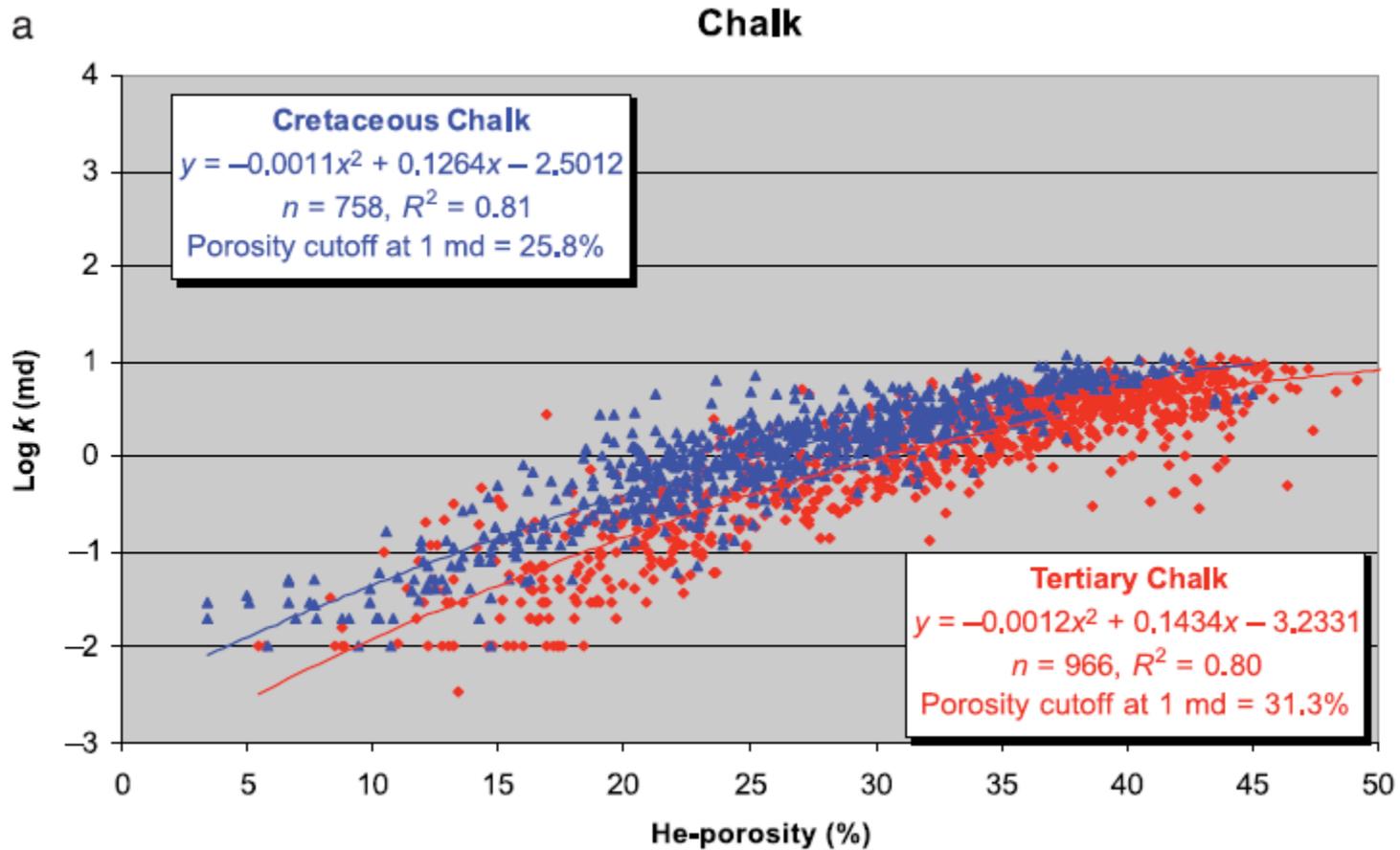
### Intercrystalline Macroporosity



intercrystalline macropores (>60 mm pore diameter).

- As for interparticle pores, pore size and porosity distribution have a clear control on  $k/f$ . A significant increase in  $k/f$  exists when pore size increases and/or porosity distribution becomes patchier. If 1 md is used as the critical flow parameter, the porosity cutoff for intercrystalline microporosity (10–20- $\mu\text{m}$  pore diameter) is reduced from 22.4% at uniform porosity distribution to 18.6%, when the porosity is patchily distributed. Similarly, for mesoporosity (20–60- $\mu\text{m}$  pore diameter), the porosity cutoff is reduced from 16.9 to 9.1%. Uniformly distributed macroporosity (>60- $\mu\text{m}$  pore diameter) has a porosity cutoff of 5.4%.

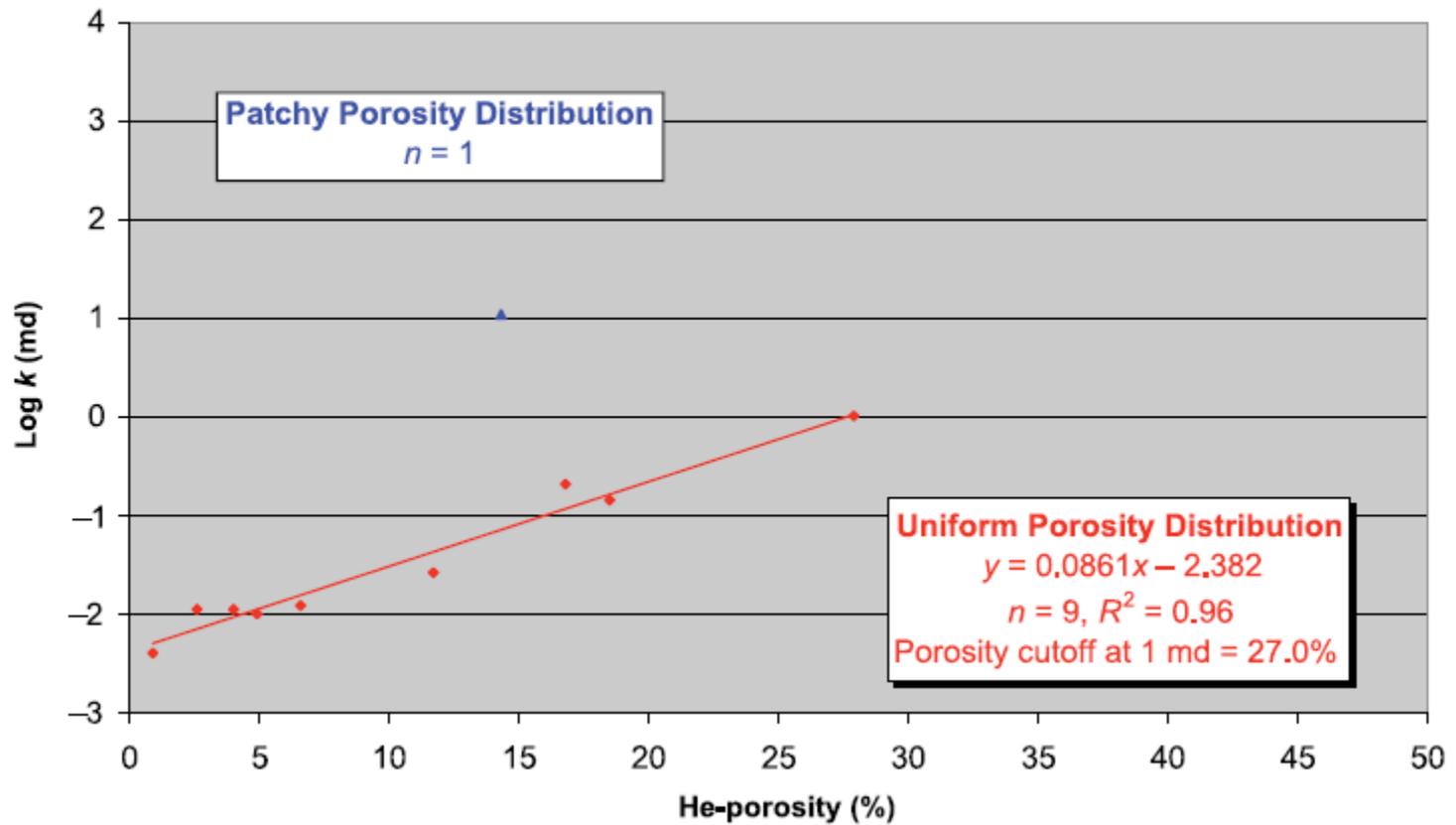
- Mudstone Micropore Classes:



chalk

b

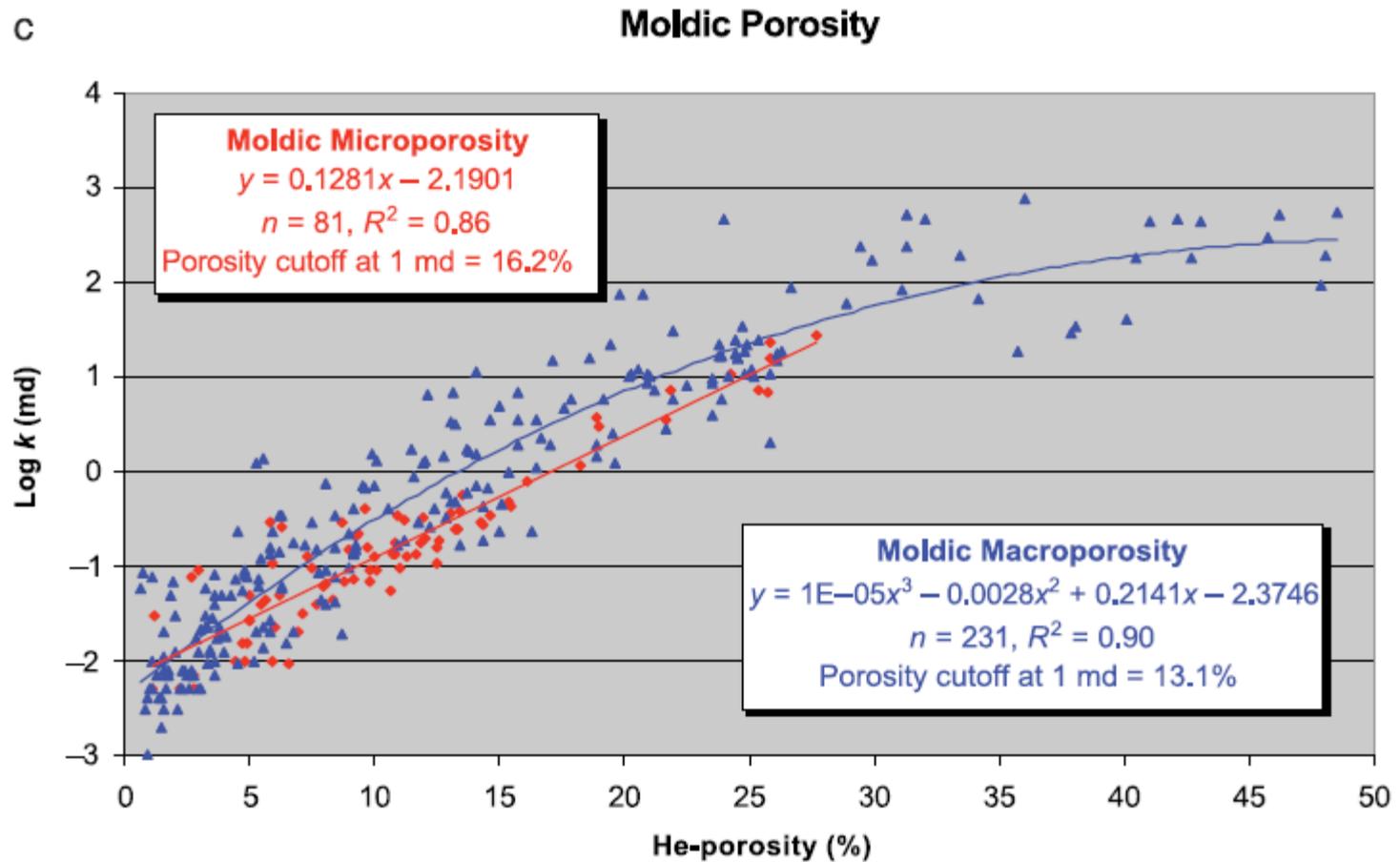
### Chalky Microporosity



chalky micropores

- If 1 md is used as the critical flow parameter, the porosity cutoff is 25.8% for Cretaceous chalk, 31.3% for Tertiary chalk, and 27.0% for chalky microporosity with uniform distribution. The only sample with patchy distribution of chalky micropores shows a significantly higher  $k/f$  than for samples with a uniform porosity distribution

- Moldic Pore-Type Classes:

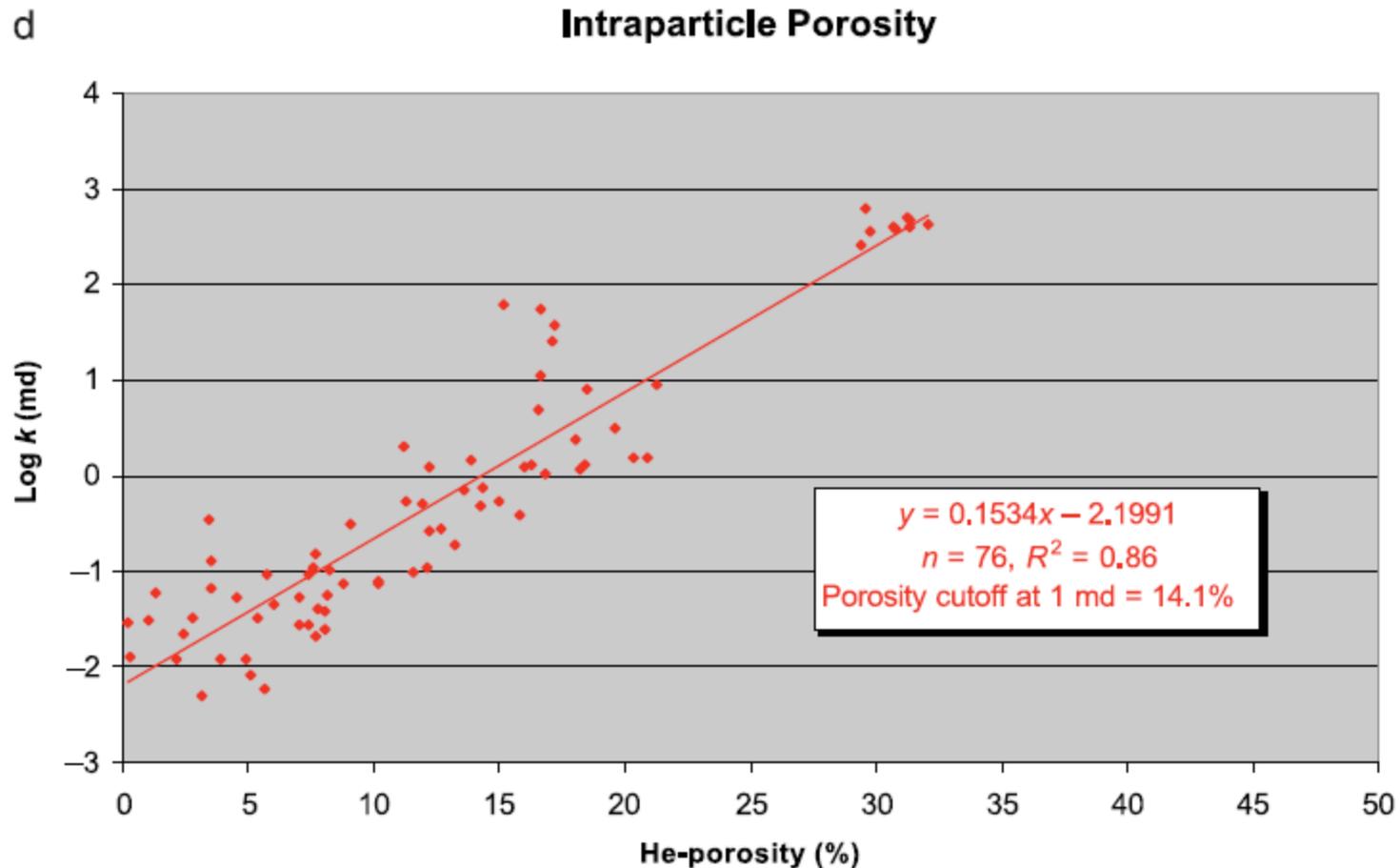


moldic pores,

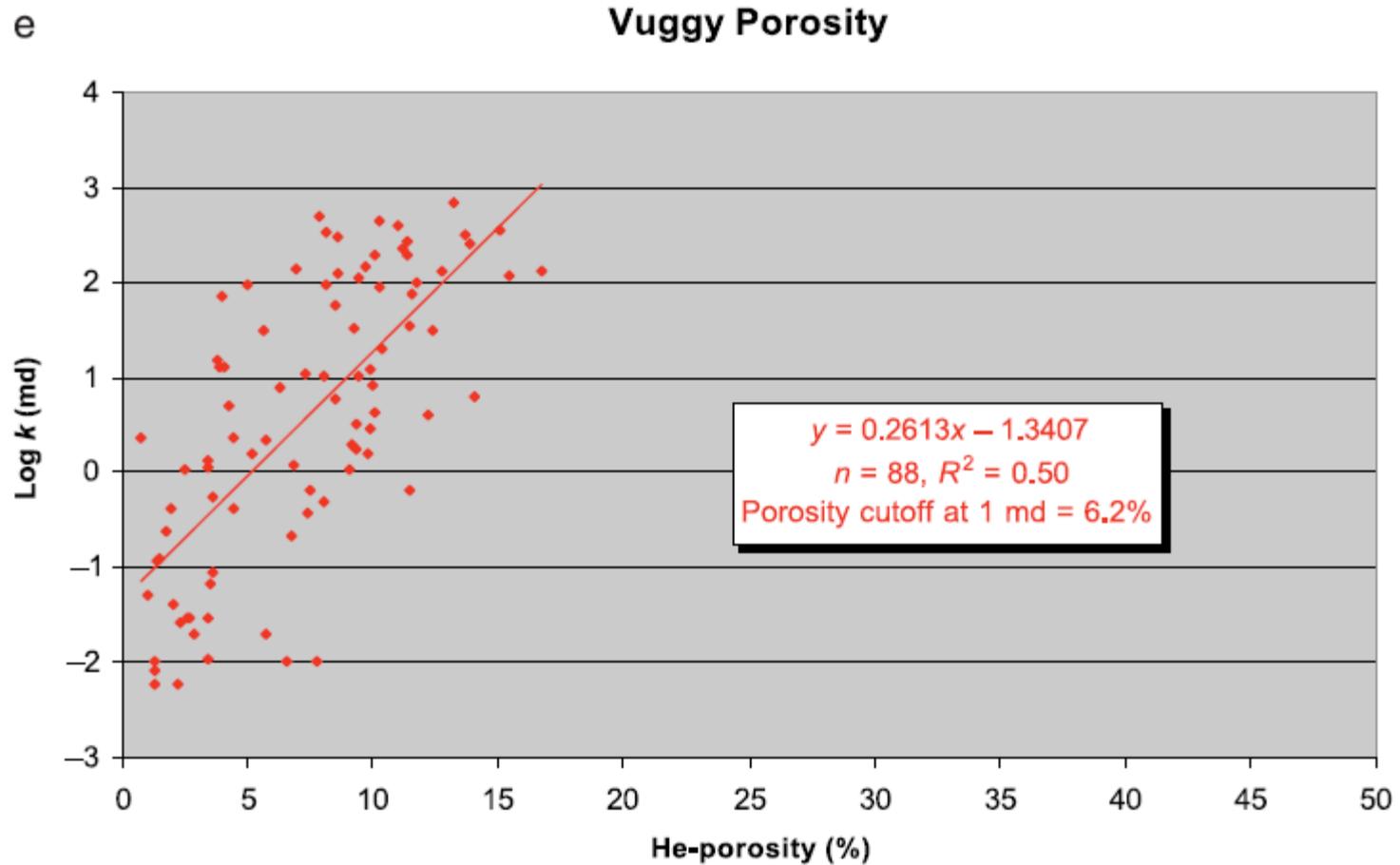
- If 1 md is used as the critical flow parameter, the porosity cutoff is 13.1% for macropores and 16.2% for micropores. Differences in  $k/f$  for the two pore-type classes result from a slight overall reduction in pore-throat diameters, as confirmed by mercury capillary-pressure measurements, and is probably related to the presence of intramold matrix in moldic micropores.

## Intraparticle Porosity:

- If 1md is used as the critical flow parameter, the porosity cutoff is 14.1%.



# Vuggy Porosity:



vuggy pores.

- If 1 md is used as the critical flow parameter, the porosity cutoff is 6.2%. The poor relationship between porosity and permeability is most likely related to a low sample-to vug size ratio (many vugs are more than 1 cm [0.4 in.] in diameter). It may also be argued that the scatter in data points results from a variable degree of connectivity between the vugs, but such an explanation could not be confirmed by the present data set.

# Comparison to Other Classification Systems

1. The effect of patchy porosity distribution on the porosity-permeability relationship
2. The split between interparticle and intercrystal porosity (as in Choquette and Pray, 1970) and the introduction of mudstone microporosity
3. The use of pore-size differentiation instead of particle size and sorting differentiation (samples in the studied data set show widely different pore sizes within each of Lucia's, 1995, 1999, interparticle classes because of the variable extent of interparticle and intercrystalline cementation and allochem sorting)

**Table 2.** New Porosity Classification System\*

| Pore Type              | Pore Size                          | Pore Distribution | Pore Fabric                          | $R^2$ |
|------------------------|------------------------------------|-------------------|--------------------------------------|-------|
| Interparticle          | Micropores (10–50 $\mu\text{m}$ )  | Uniform           | Interpartide, uniform micropores     | 0.88  |
|                        |                                    | Patchy            | Interpartide, patchy micropores      | 0.79  |
|                        | Mesopores (50–100 $\mu\text{m}$ )  | Uniform           | Interpartide, uniform mesopores      | 0.86  |
|                        |                                    | Patchy            | Interpartide, patchy mesopores       | 0.85  |
|                        | Macropores (>100 $\mu\text{m}$ )   | Uniform           | Interpartide, uniform macropores     | 0.88  |
|                        |                                    | Patchy            | Interpartide, patchy macropores      | 0.87  |
| Intercrystalline       | Micropores (10–20 $\mu\text{m}$ )  | Uniform           | Intercrystalline, uniform micropores | 0.92  |
|                        |                                    | Patchy            | Intercrystalline, patchy micropores  | 0.79  |
|                        | Mesopores (20–60 $\mu\text{m}$ )   | Uniform           | Intercrystalline, uniform mesopores  | 0.94  |
|                        |                                    | Patchy            | Intercrystalline, patchy mesopores   | 0.92  |
|                        | Macropores (>60 $\mu\text{m}$ )    | Uniform           | Intercrystalline, uniform macropores | 0.80  |
|                        |                                    | Patchy            | Intercrystalline, patchy macropores  |       |
| Intraparticle          |                                    |                   | Intrapartide                         | 0.86  |
| Moldic                 | Micropores (<10–20 $\mu\text{m}$ ) |                   | Moldic micropores                    | 0.86  |
|                        | Macropores (>20–30 $\mu\text{m}$ ) |                   | Moldic macropores                    | 0.90  |
| Vuggy                  |                                    |                   | Vuggy                                | 0.50  |
| Mudstone microporosity | Micropores (<10 $\mu\text{m}$ )    |                   | Tertiary chalk                       | 0.80  |
|                        |                                    |                   | Cretaceous chalk                     | 0.81  |
|                        |                                    | Uniform           | Chalky micropores, uniform           | 0.96  |
|                        |                                    | Patchy            | Chalky micropores, patchy            |       |

\*Partly based on Choquette and Pray (1970) and Lucia (1983, 1995, 1999). Porosity-permeability coefficients of determination ( $R^2$ ) are based on samples from the present study.

**CF5**



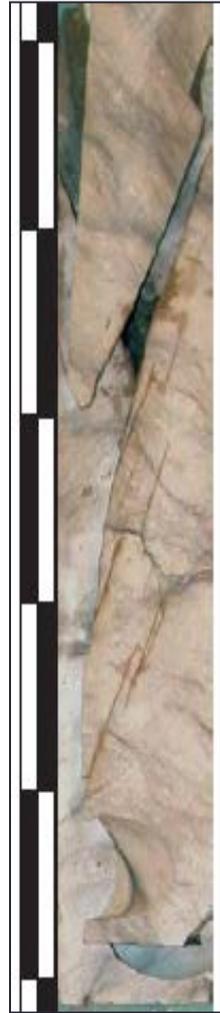
**CF4**



**CF2**



**CF1**



**CF6**



**CF3**

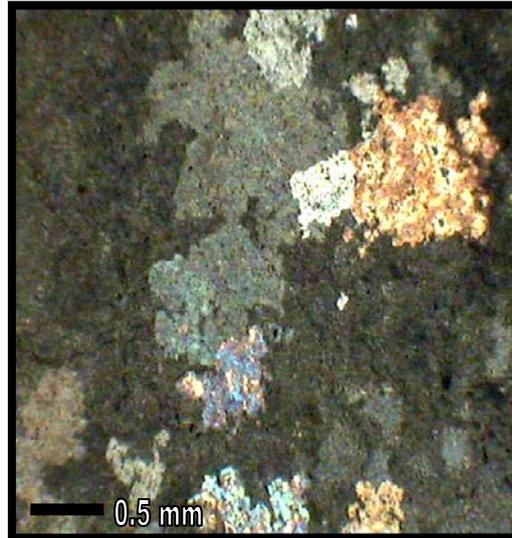
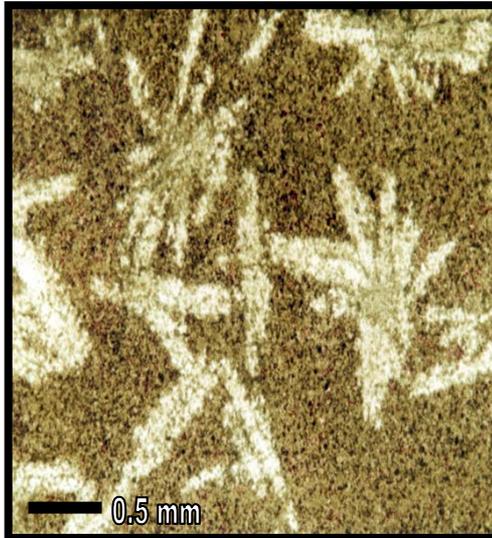


## Primary porosity in the carbonate reservoir

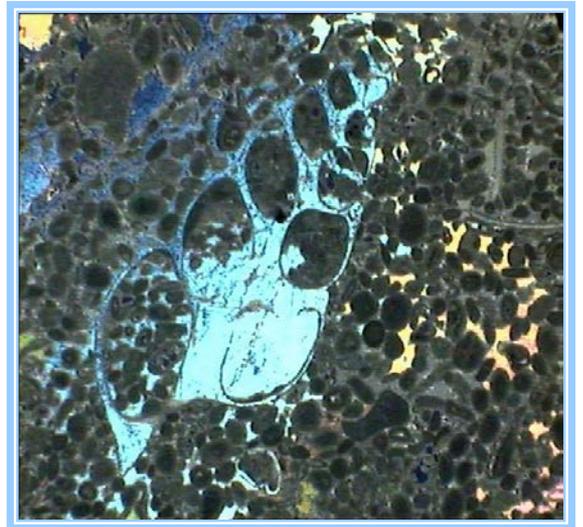
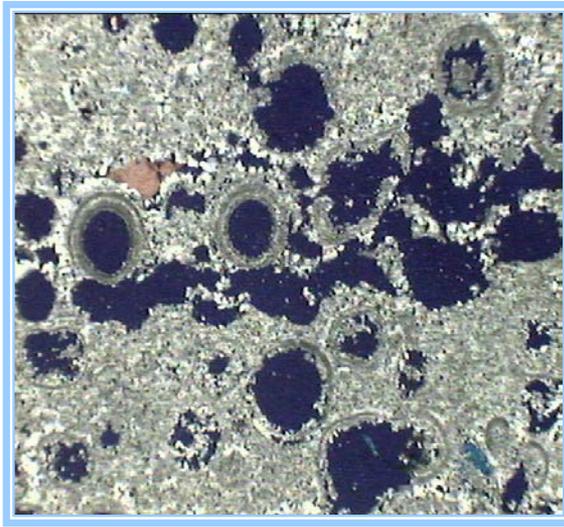
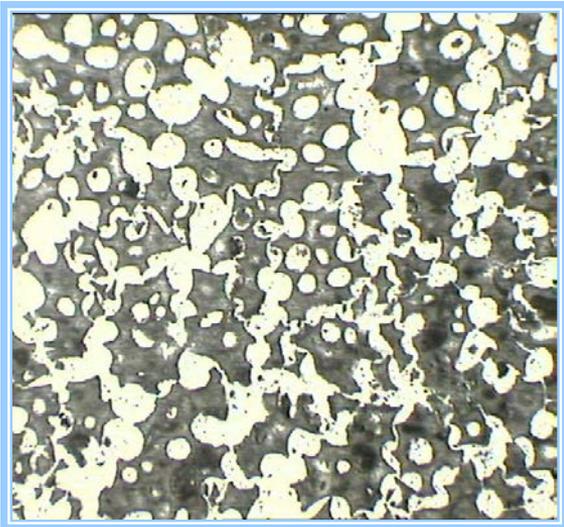
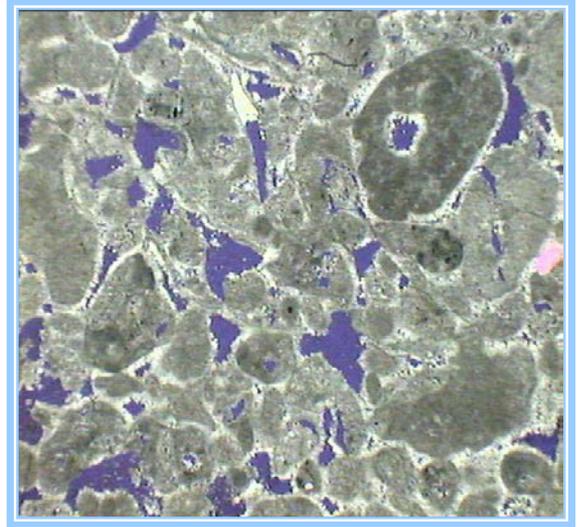
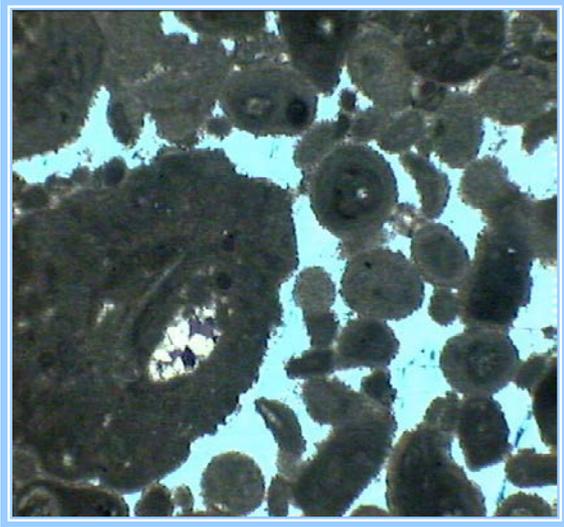


## Non-porous carbonate facies

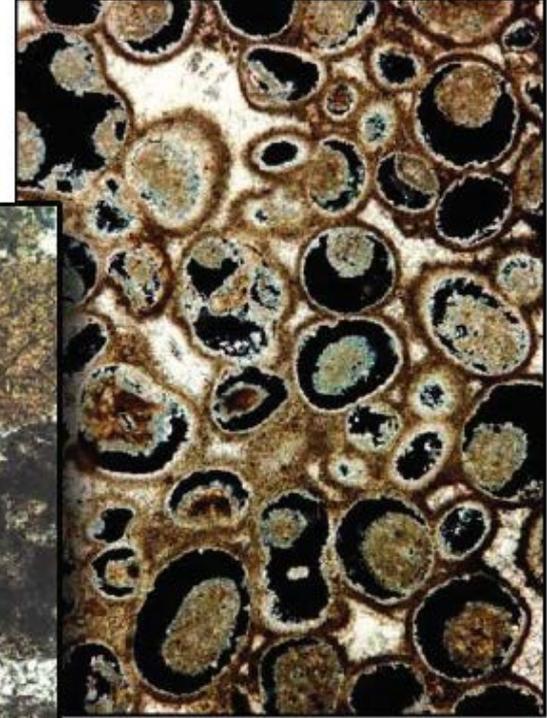
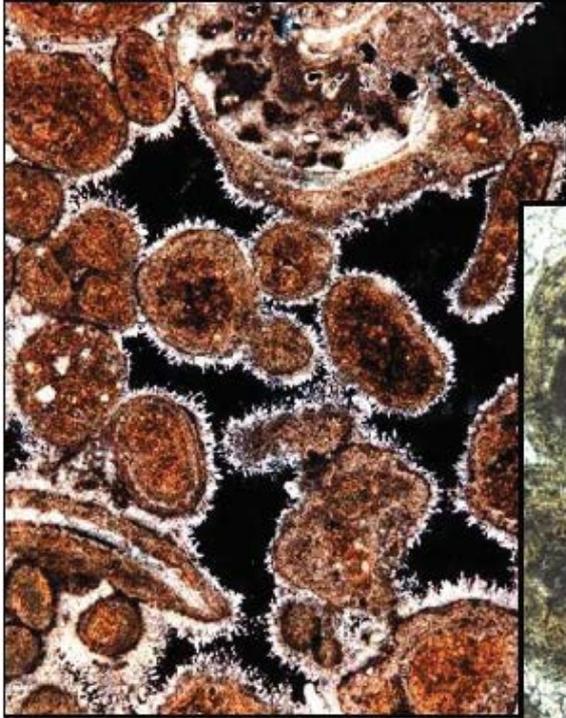




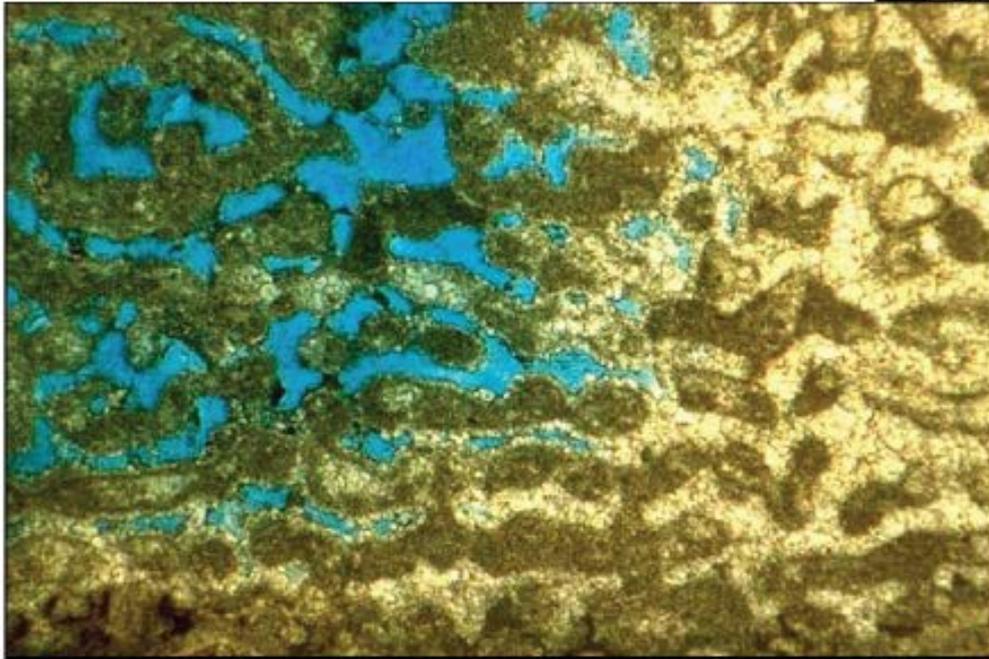
# Porosity Types in the carbonates



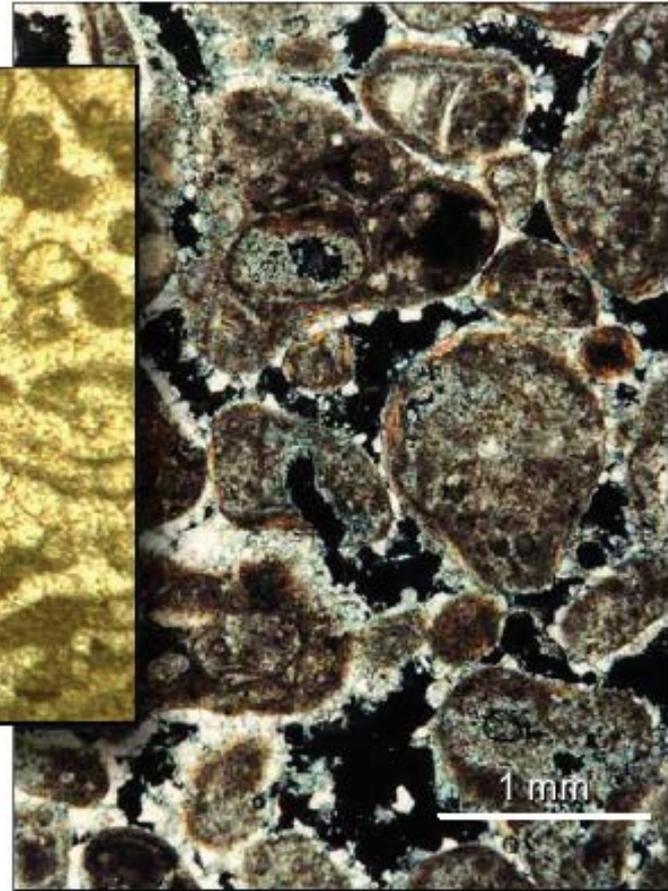
# Diagenetic impact on the porosity



# Carbonate pore types: Intraparticle porosity

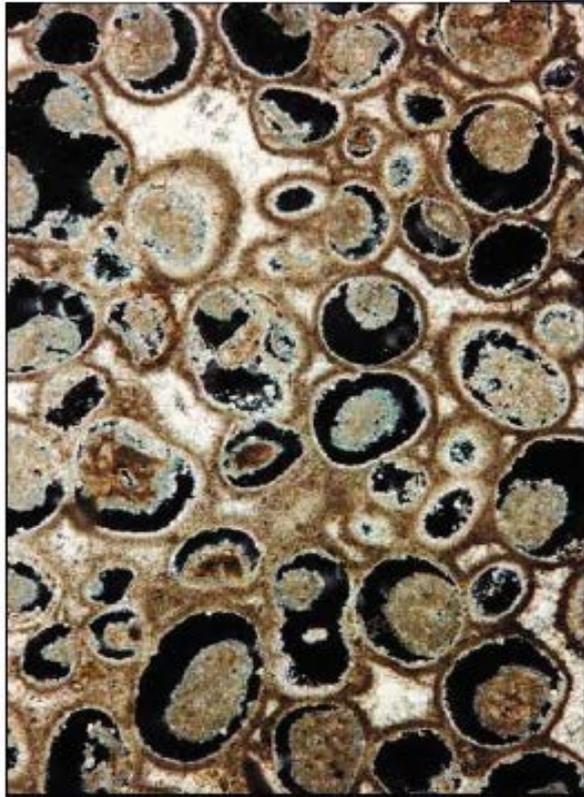


Solution-enhanced intragranular

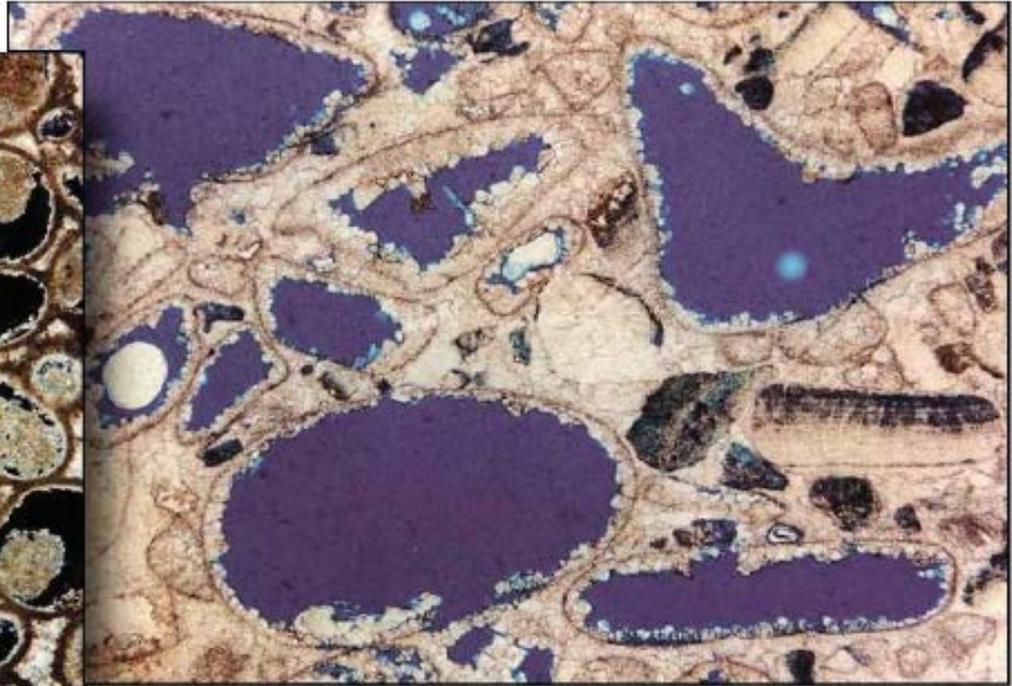


Solution-enhanced intergranular

# Carbonate pore types: Moldic porosity

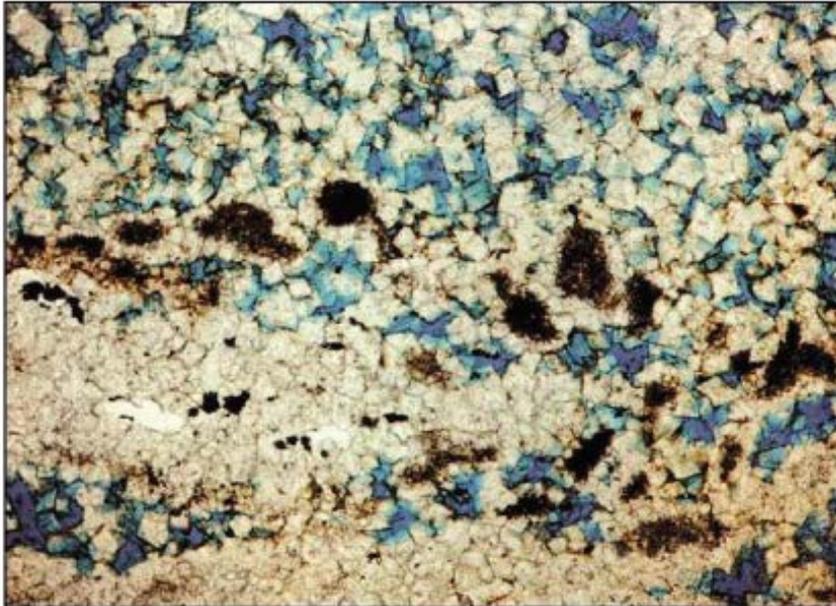


Ooid mouldic



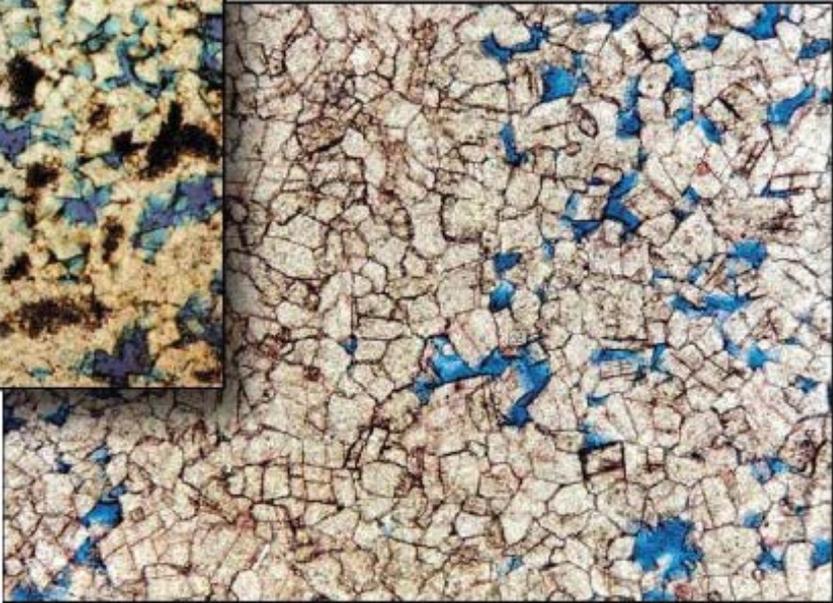
Skeletal mouldic

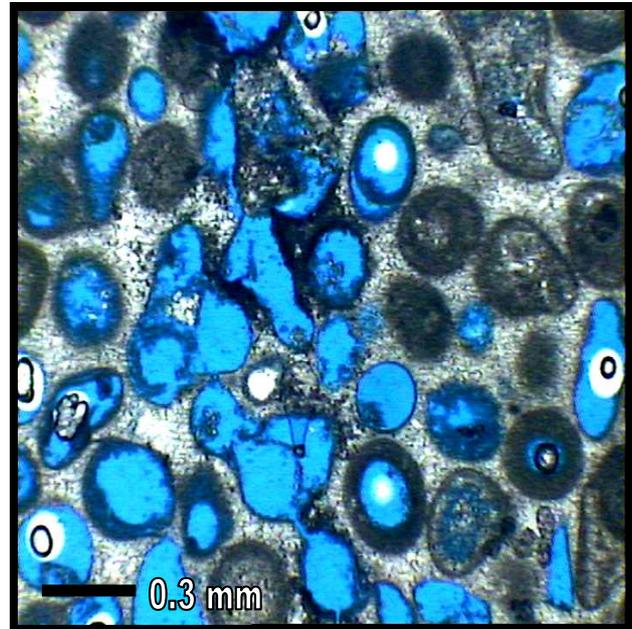
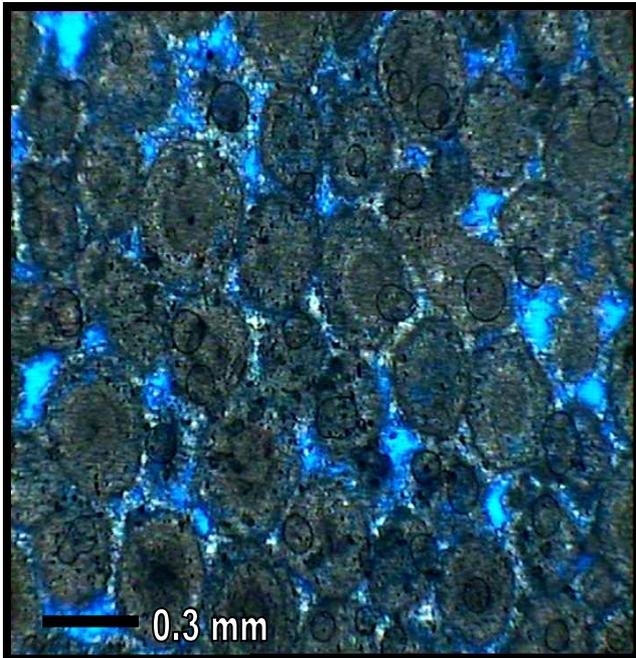
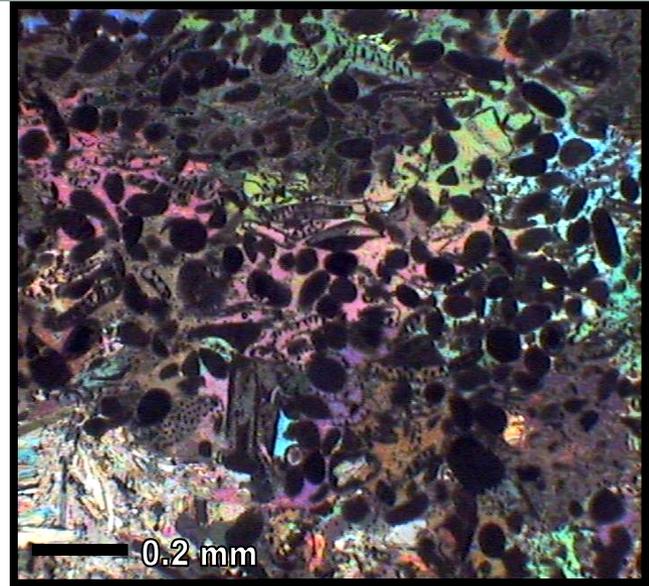
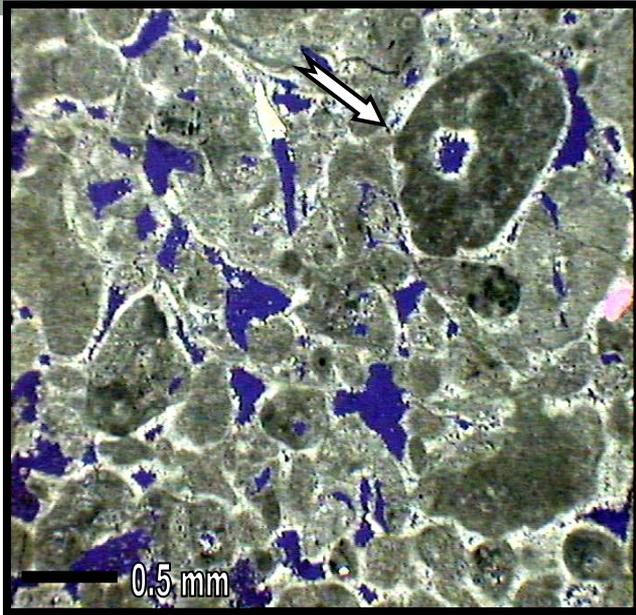
# Carbonate pore types: Intercrystalline



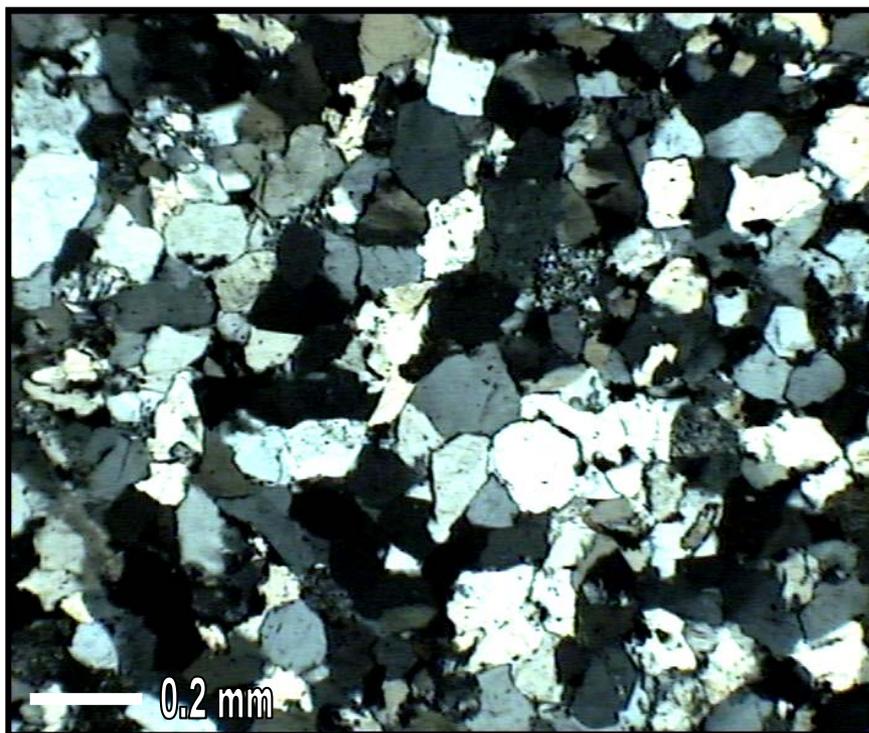
Dolomitic Intercrystalline

Dolomitic Intercrystalline





## Sandstone reservoir with intergranular porosity



# Reservoir Facies Classification

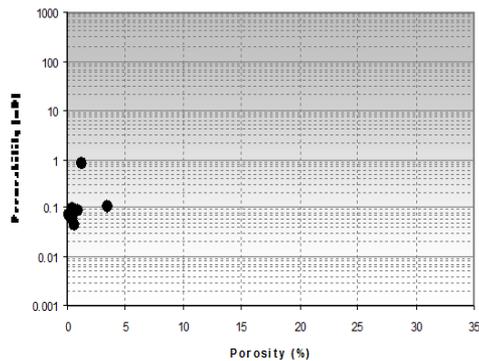
- F1: Massive anhydrite and pervasive anhydrite plugging**
- F2: Dolomitic mudstone often with fenestral fabric.**
- F3: Stromatolite boundstone often with microbial communities.**
- F4: Lime skeletal / peloid wackestone to packstone**
- F5: Medium-grained ooid grainstone with oomoldic porosity.**
- F6: Coarse - grained skeletal grainstone with interparticles porosity.**
- F7: Fine-grained peloid / ooid grainstone.**
- F8: Intra formational conglomerate.**
- F9: Heavily bioturbated mudstone.**
- F10: Fossiliferous mudstone / wackestone.**
- F11: Dark argillaceous mudstone with lamination.**
- F12: Thrombolite boundstone.**

# Reservoir Characterization

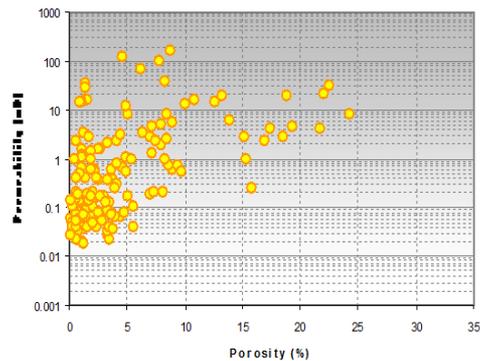
| Core facies | No. | Helium Porosity (%) |       |      |           | Air Permeability (mD) |        |       |           |
|-------------|-----|---------------------|-------|------|-----------|-----------------------|--------|-------|-----------|
|             |     | MAX                 | MEAN  | MIN  | Std. Dev. | MAX                   | MEAN   | MIN   | Std. Dev. |
| CF1         | 9   | 3.56                | 0.90  | 0.13 | 1.07      | 0.782                 | 0.154  | 0.045 | 0.236     |
| CF2         | 160 | 24.22               | 4.52  | 0.10 | 5.11      | 158.692               | 5.467  | 0.019 | 18.748    |
| CF3         | 15  | 15.12               | 3.19  | 0.67 | 4.06      | 15.172                | 2.722  | 0.028 | 4.479     |
| CF4         | 180 | 24.30               | 5.98  | 0.01 | 6.24      | 108.512               | 5.622  | 0.001 | 14.879    |
| CF5         | 179 | 36.32               | 15.79 | 0.21 | 9.02      | 242.815               | 11.297 | 0.010 | 28.535    |
| CF6         | 135 | 32.86               | 9.44  | 0.11 | 7.60      | 213.197               | 8.274  | 0.019 | 23.955    |
| CF7         | 195 | 36.64               | 10.15 | 0.06 | 9.86      | 346.693               | 17.412 | 0.023 | 51.922    |
| CF8         | 6   | 9.99                | 5.06  | 0.90 | 3.74      | 42.134                | 7.132  | 0.043 | 17.147    |
| CF9         | 53  | 26.66               | 7.57  | 1.23 | 7.55      | 80.529                | 6.039  | 0.002 | 15.461    |
| CF10        | 13  | 15.75               | 5.27  | 0.16 | 4.75      | 24.195                | 5.256  | 0.043 | 9.072     |
| CF11        | 0   | -                   | -     | -    | -         | -                     | -      | -     | -         |
| CF12        | 5   | 1.26                | 1.07  | 0.73 | 0.21      | 0.116                 | 0.063  | 0.037 | 0.031     |

# Reservoir Characterization on the carbonate reservoir

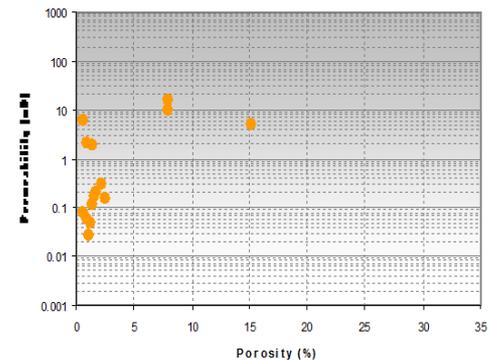
Core Facies 1



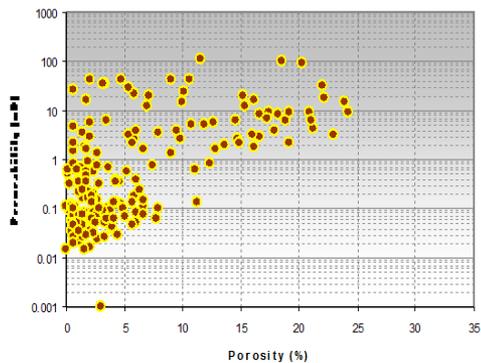
Core Facies 2



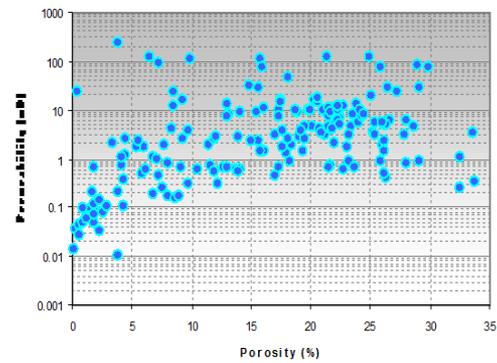
Core Facies 3



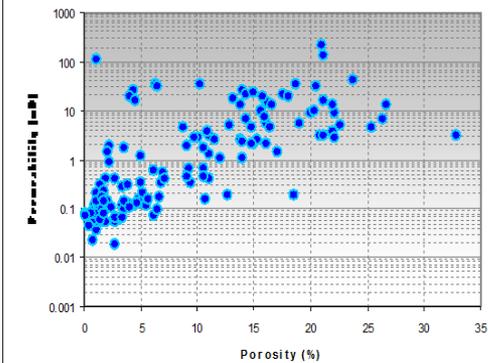
Core Facies 4



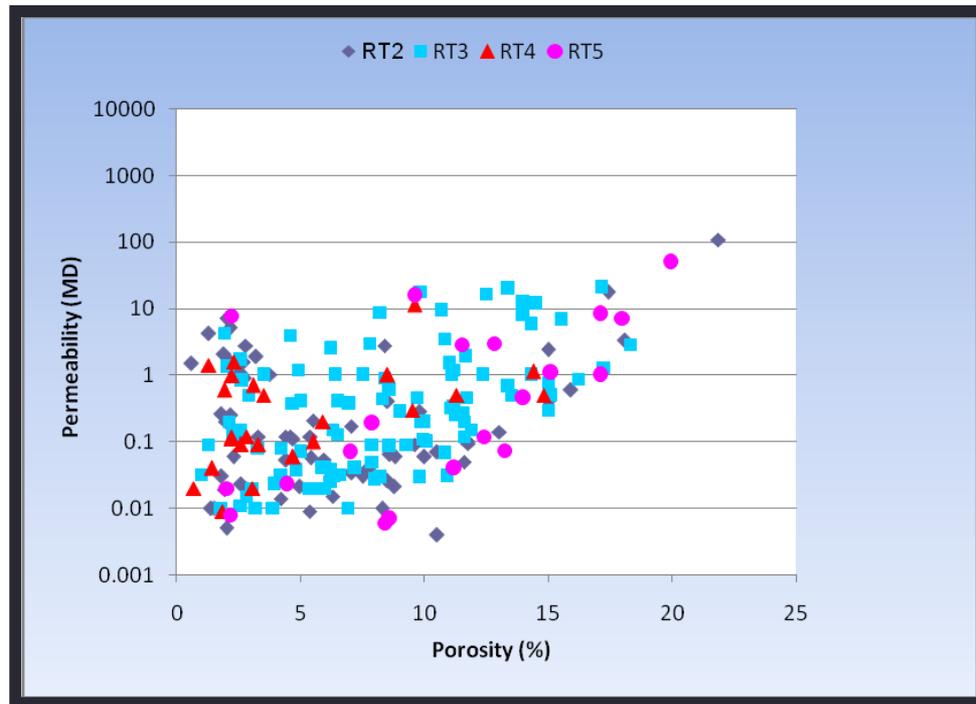
Core Facies 5



Core Facies 6



# Reservoir Rock Typing



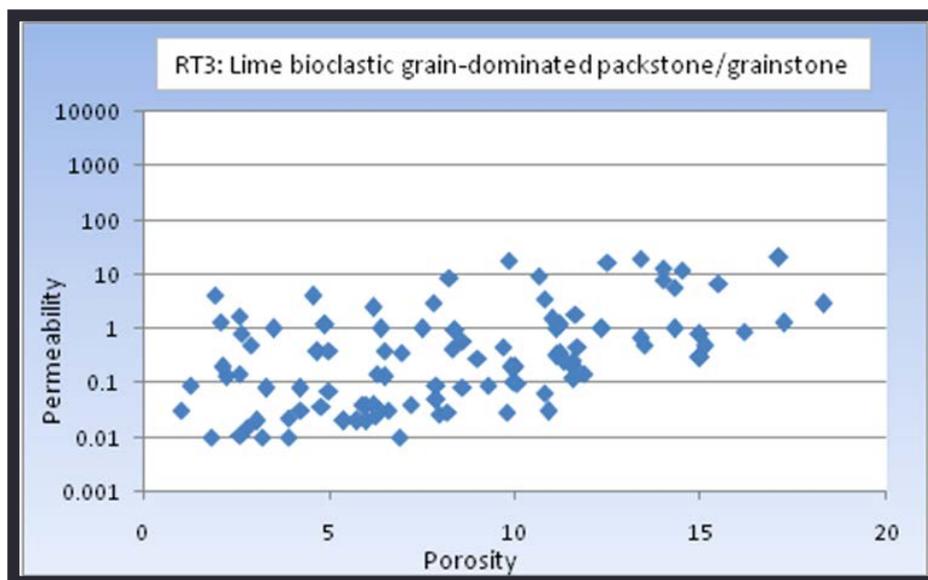
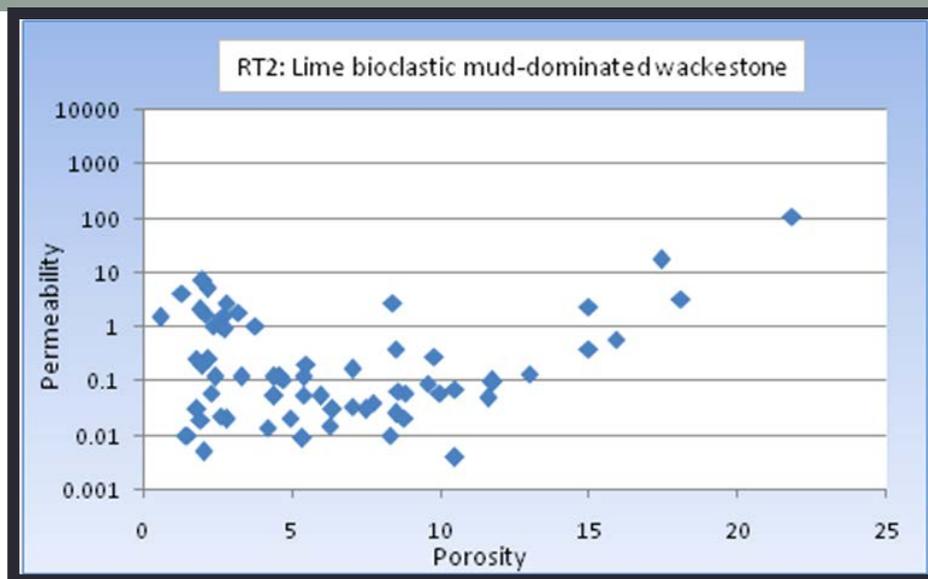
**RT1: Argillaceous mudstone/claystone**

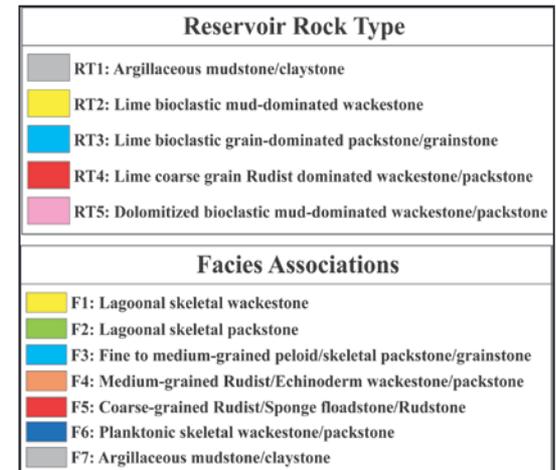
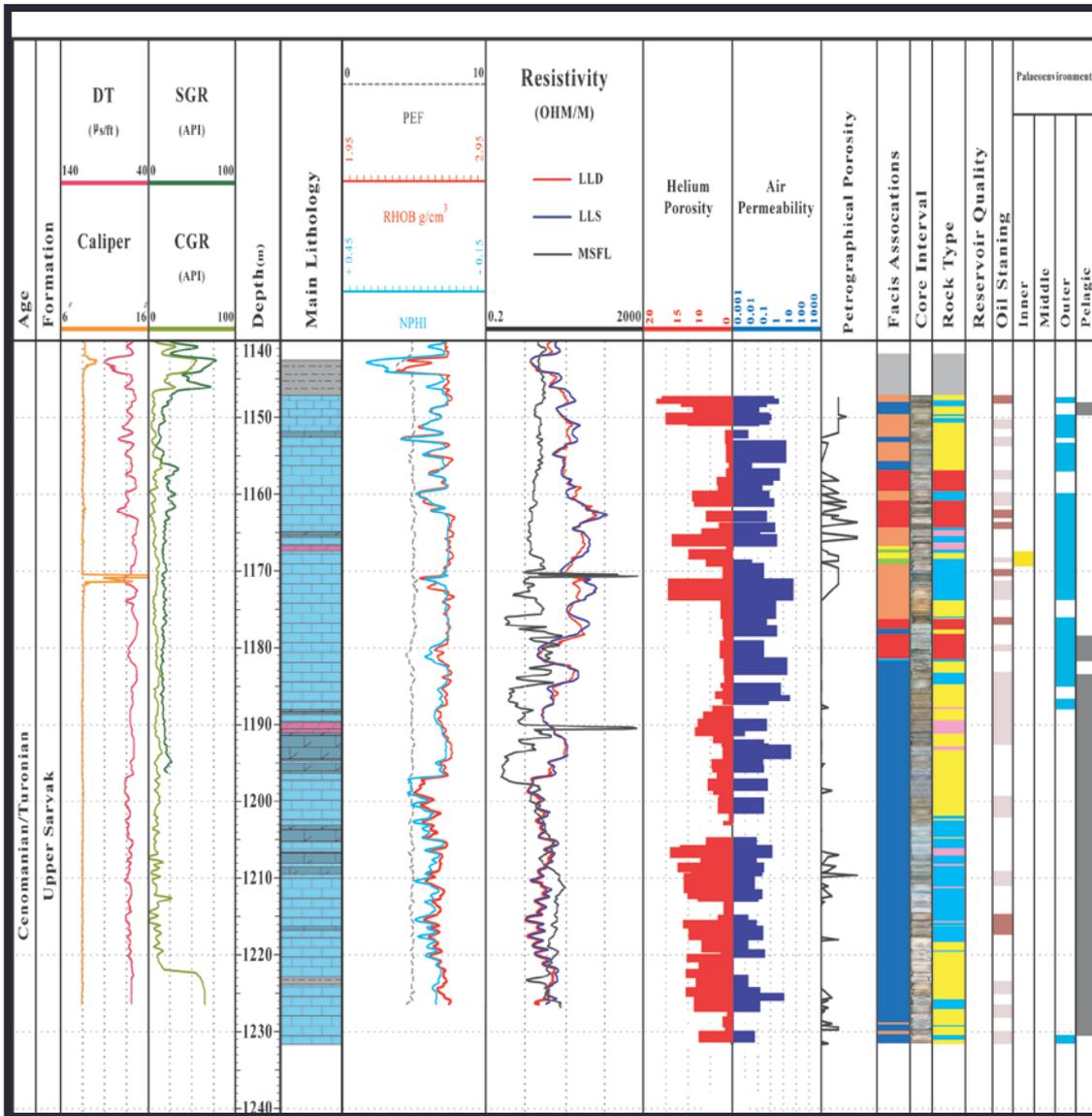
**RT2: Lime bioclastic mud-dominated wackestone**

**RT3: Lime bioclastic grain-dominated packstone/grainstone**

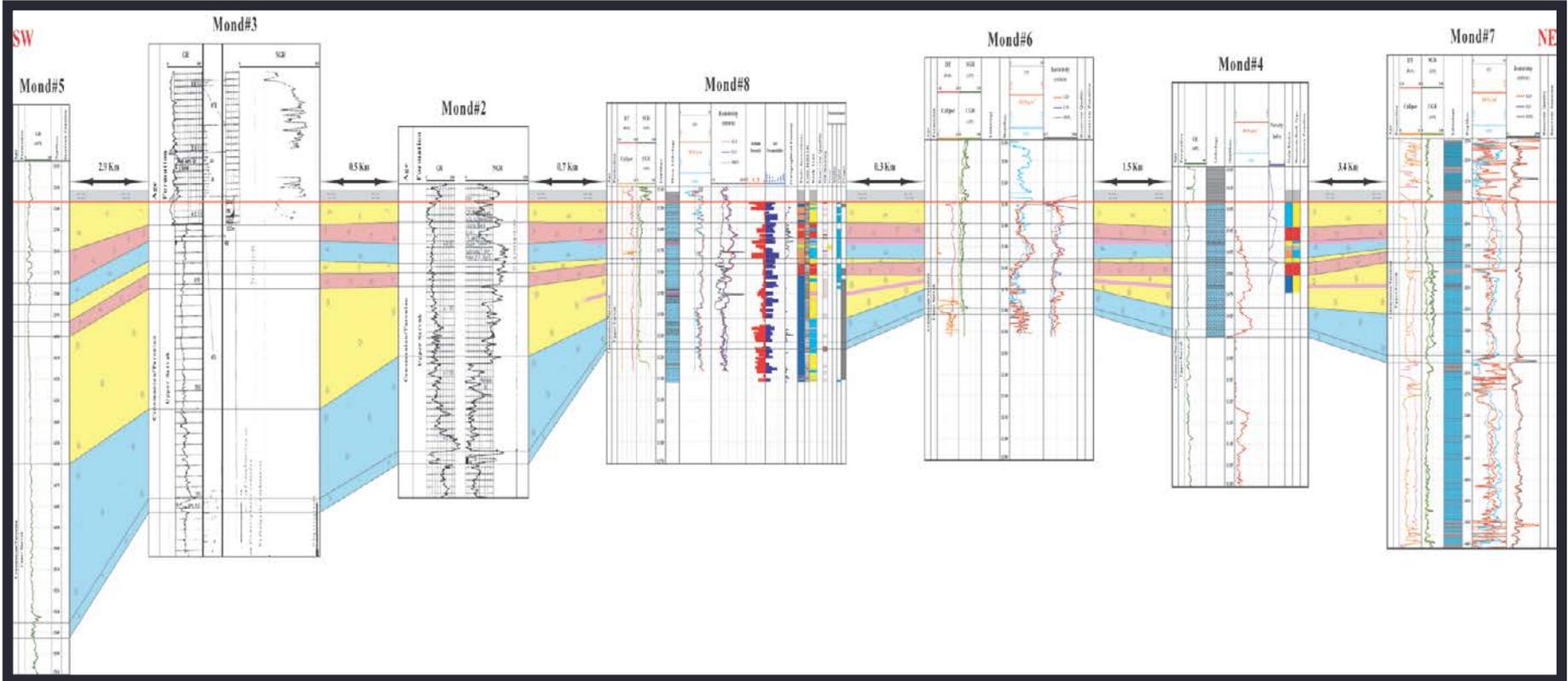
**RT4: Lime coarse grain Rudist dominated wackestone/packstone**

**RT5: Dolomitized bioclastic mud-dominated wackestone/packstone**





# Petrophysical correlation across the Field



# Well Logging

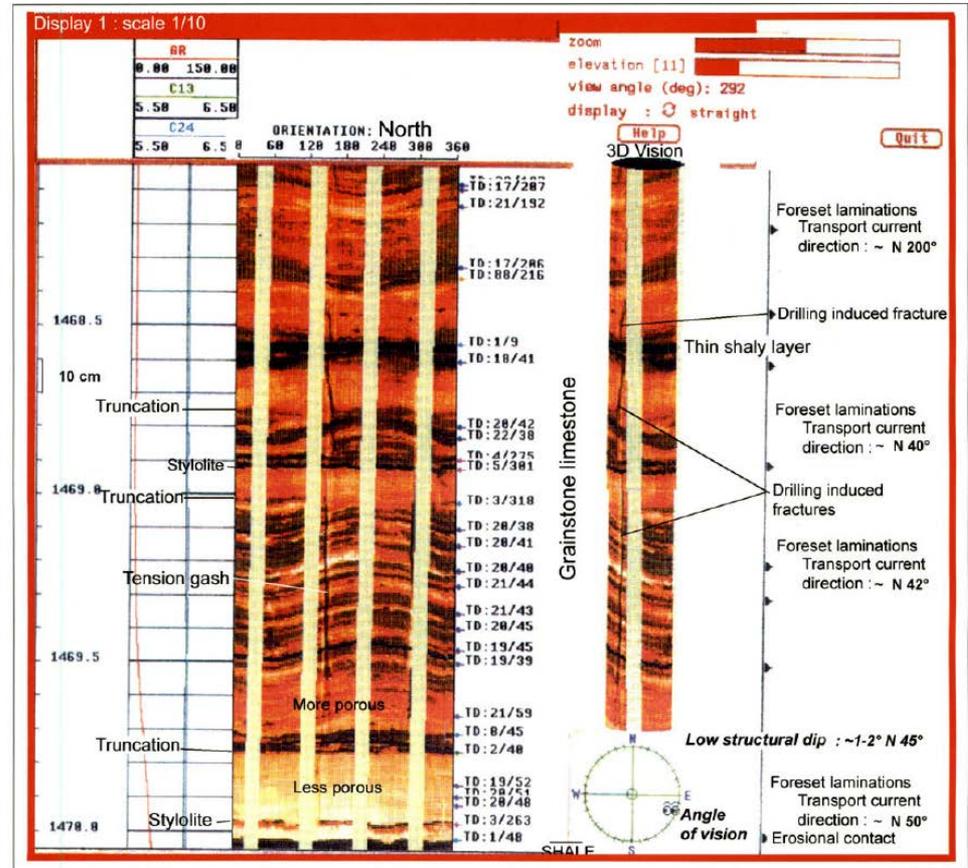
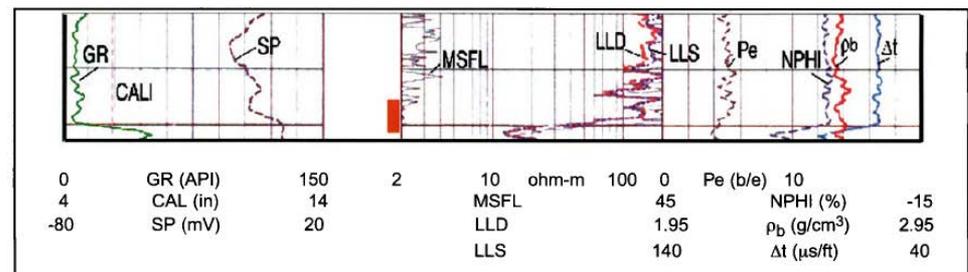
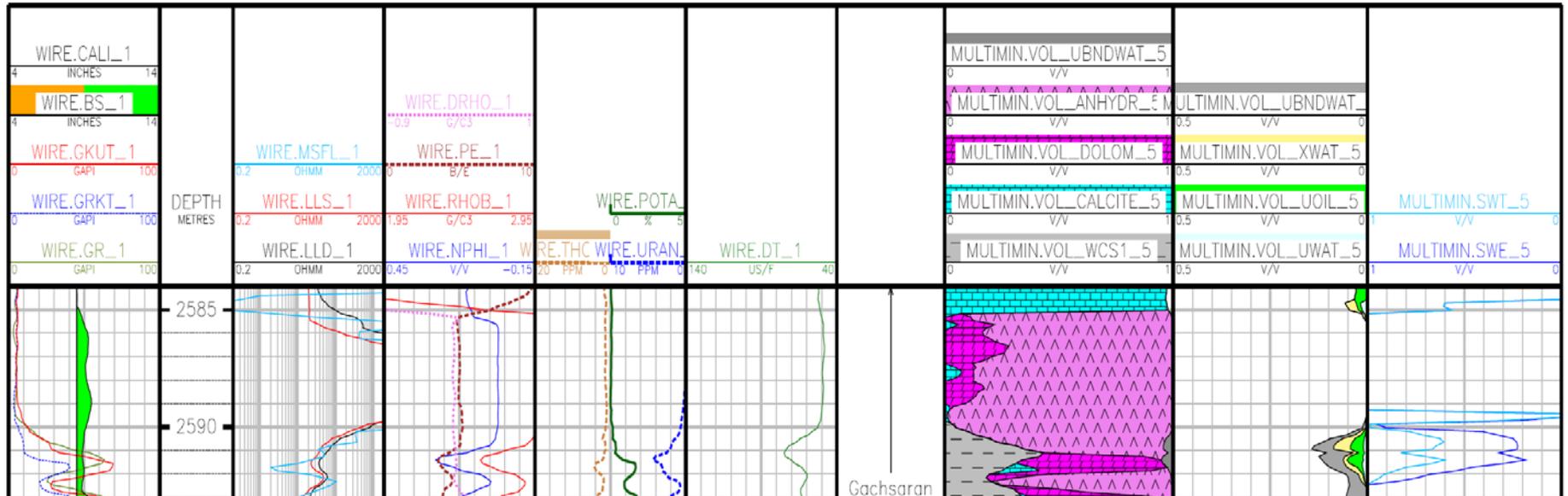


Figure 1-8a - Example of borehole wall images and its interpretation in terms of depositional units, texture, sedimentary structures and dip data.





# General Processes Used For Recording Physical Parameters

## **Natural or spontaneous phenomena**

*Basic equipment : a single detector (passive system)*

Natural gamma radioactivity

Total

Spectrometry

Spontaneous potential

Temperature - Bottom hole temperature

Formation pressure

Borehole diameter

Borehole deviation

**Physical properties measured by inducing from the formation a response to an excitation**

*Basic equipment : source or emitter + detector (s)*

Resistivity

Long-spacing devices

non-focused

focused

Short-spacing devices

non-focused

focused

Ultra-long spacing devices

Conductivity

Dielectric constant (electromagnetic propagation)

Magnetic susceptibility

Total magnetic field

Electronic density

Photoelectric index

Neutron interactions

Epithermal neutron absorption

Thermal neutron absorption

Induced  $\gamma$  ray spectrometry by inelastic collisions

Induced  $\gamma$  ray spectrometry by thermal neutron absorption

Induced  $\gamma$  ray spectrometry by thermal neutron activation

Thermal neutron decay time

Relaxation time of proton spin (nuclear magnetic resonance)

Acoustic velocity

Acoustic-signal amplitude

Well seismics

Formation dip - Dipmeter

Borehole imagery

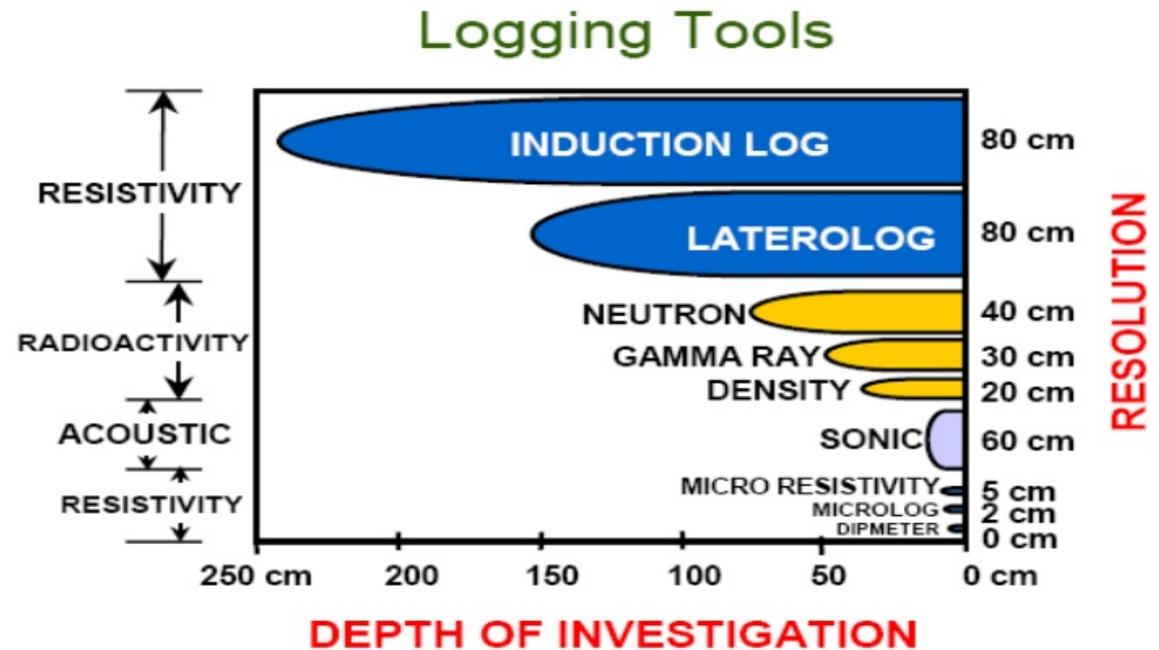
electric

ultrasonic

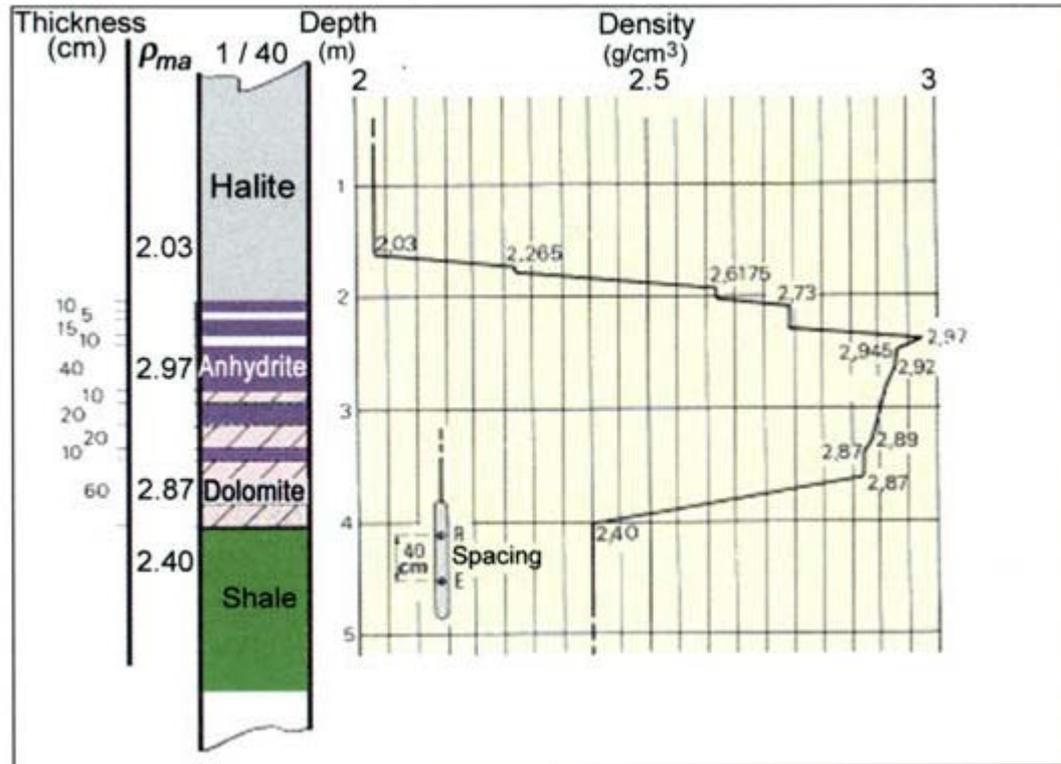
# Basic of Logging

- Depth of investigation
- Vertical Resolution

Depth Of Investigation Of Logging Tools



| Sonde                      | Type         | Spacing or gap   | Searched for parameters        |                     |
|----------------------------|--------------|--|--------------------------------|---------------------|
| E.S.                       | Great normal | M2   | $R_t$                          |                     |
|                            | Lateral      | M1   | $R_i$                          |                     |
|                            | Short normal | O  |                                |                     |
| Resistivity - Conductivity | IL           | 5FF27 5FF40<br>6FF28 6FF32 6FF40<br>DIL<br>Phasor<br>AIT | $R_t$                          |                     |
|                            | LL           | LL3, LL7, LL8<br>DLL<br>ARI                              | $R_t$                          |                     |
|                            | SFL          | HALS, HRLA   | $R_i$                          |                     |
|                            | ML           |  | $R_{xo}$                       |                     |
|                            | MLL          |  | $R_{xo}$                       |                     |
|                            | MSFL         |  | $R_{xo}$                       |                     |
|                            | Neutron      | SNP  | 16"                            | $I_{Hn} \phi_{SNP}$ |
|                            |              | GNT  | 15"1/2<br>or 19"1/2            | $I_{Hn} \phi_N$     |
|                            |              | CNL  | 25" 10"<br>15"                 | $I_{Hn} \phi_{CNL}$ |
|                            | Sonic        | BHC  | E receivers                    | $\Delta t \phi_S$   |
| DSI                        |              | 6"   | $\Delta t_c \Delta t_s \phi_S$ |                     |
| Density                    | FDL          | 16"  | $\rho_b \phi_D$                |                     |
|                            | FDC-LDT      | 18"  | $\rho_b, P_e, \phi_D$          |                     |
|                            | TDT          |  | $\Sigma S_w$                   |                     |



Intrinsic vertical resolution of Schlumberger tools  
(completed from Allen *et al.*, 1988, and Theys, 1991).

| Measurement         | Vertical resolution | Sampling rate | Remarks   |
|---------------------|---------------------|---------------|---|
| SP                  | 6-10 ft             | 6 in.         | Only if salinity contrast                             |
| Phasor Induction    |                     |               |   |
| deep                | 84 - 96 in.         | 6 in.         |   |
| medium              | 60 - 72 in.         |               |   |
| enhanced            | 36 in.              |               |   |
| SFL                 | 30 in.              | 6 in.         |   |
| AIT                 | 18 in.              | 6 in.         | 1, 2 or 4 ft  |
|                     |                     |               | Gives an image of the invasion                        |
| Laterolog           |                     |               |   |
| DLL                 | 28 in.              | 6 in.         |   |
| ARI                 | 8 in.               | 0.5 in.       | Gives an electrical image                             |
| HALS                | 8 - 16 in.          | 0.5 in.       | Gives an electrical image                             |
| Microlog            |                     |               |   |
| Microinverse        | 2 - 4 in.           | 2 in.         | The measure is not focalized                          |
| Micronormal         | 4 in.               |               |   |
| MicroSFL            | 2 - 3 in.           | 2 in.         | Focalized   |
| Dipmeter - Imagery  |                     |               |   |
| HDT                 | 0.5 in.             | 0.2 in.       |   |
| SHDT                | 0.4 in.             | 0.1 in.       |   |
| FMS                 | 0.2 in.             | 0.1 in.       | Gives an electrical image                             |
| FMI                 | 0.2 in.             | 0.1 in.       | Gives an electrical image                             |
| EPT                 |                     |               |   |
| Transit time        | 2 in.               | 2 or 0.4 in.  |   |
| Attenuation         | 2 in.               | 2 or 0.4 in.  | Shale indicator                                       |
| Litho-density       |                     |               |   |
| Density             | 15 in.              | 6 or 2 in.    |   |
| enhanced            | 4 in.               |               |   |
| Pe                  | 2 in.               |               |   |
| Neutron             |                     |               |   |
| Porosity            | 15 in.              | 6 or 2 in.    |   |
| resolution matched  | 24 in.              |               |   |
| enhanced            | 12 in.              |               |   |
| CMR                 | 6 in.               | 6 in.         | Estimation of porosity, permeability, pore size       |
| TDT                 | 6 - 66 in.*         |               |   |
| Gamma ray           |                     |               |   |
| Standard            | 8 - 12 in.          | 6 in.         |   |
| Spectroscopy        | 8 - 12 in.          |               | Measures Th, U and K                                  |
| Sonic               |                     |               |   |
| Standard            | 48 in.              | 6 in.         |   |
| BHC                 | 24 in.              |               |   |
| Six-inch $\Delta t$ | 6 in.               | 1.2 in.       |   |
| DSI                 | 6 in.               |               | Measures compressional shear & Stoneley wave velocity |

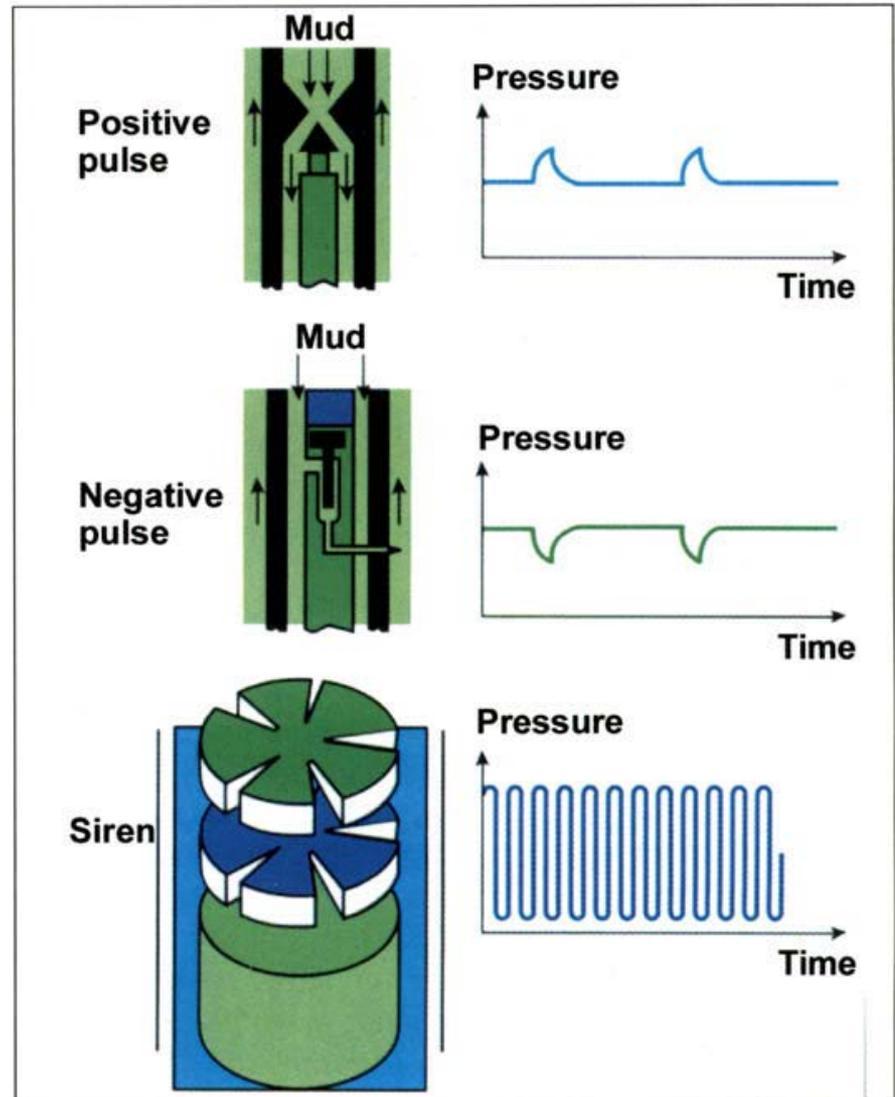
\* depends on the time constant and the depth interval on which the mean value is computed.

Table 2-4  
Recommended maximum logging speeds.

| Measurement        | Maximum logging speed |         |     |
|--------------------|-----------------------|---------|-----|
|                    | (ft/min)              | (m/min) |     |
| SP                 | 100                   | 30      |     |
| Induction          | 83                    | 25      |     |
| Laterolog          | 50                    | 15      |     |
| Rxo measurement    | 33                    | 10      |     |
| Neutron            | TC = 2 sec            | 30      | 9   |
| GR                 | TC = 3 sec            | 20      | 6   |
| Density            | TC = 4 sec            | 15      | 4.5 |
| TDT                |                       |         |     |
| Spectrometry       | 15                    | 4.5     |     |
| Sonic Transit time | 60                    | 18      |     |
| Attenuation        | 35                    | 10      |     |
| Dipmeter           | 50                    | 15      |     |
| Imagery            | 15                    | 4.5     |     |

- **Data Transmission:**

1. Cable transmission
2. Mud pulse telemetry





Fixed-mount Pulser

Retrievable Pulser with Stinger

# Caliper Logs

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## What Do They Measure?

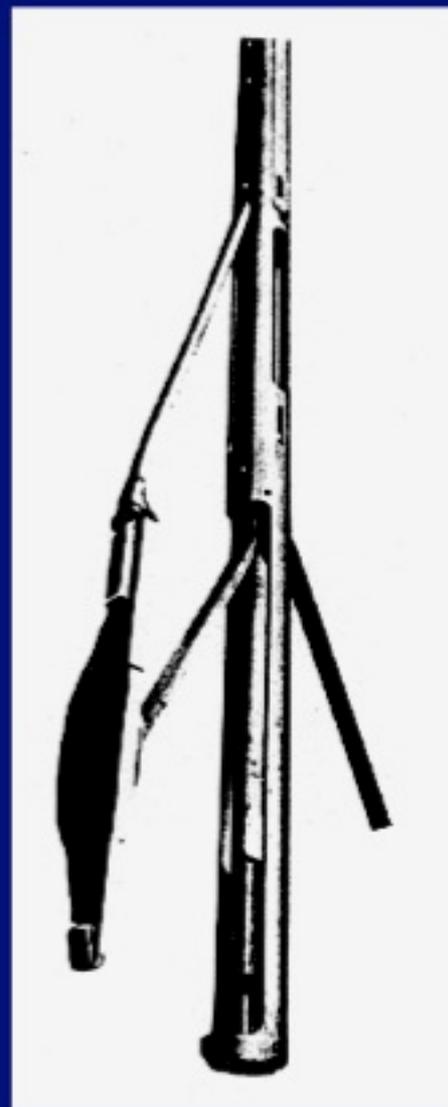
Size and shape of a recently drilled hole.

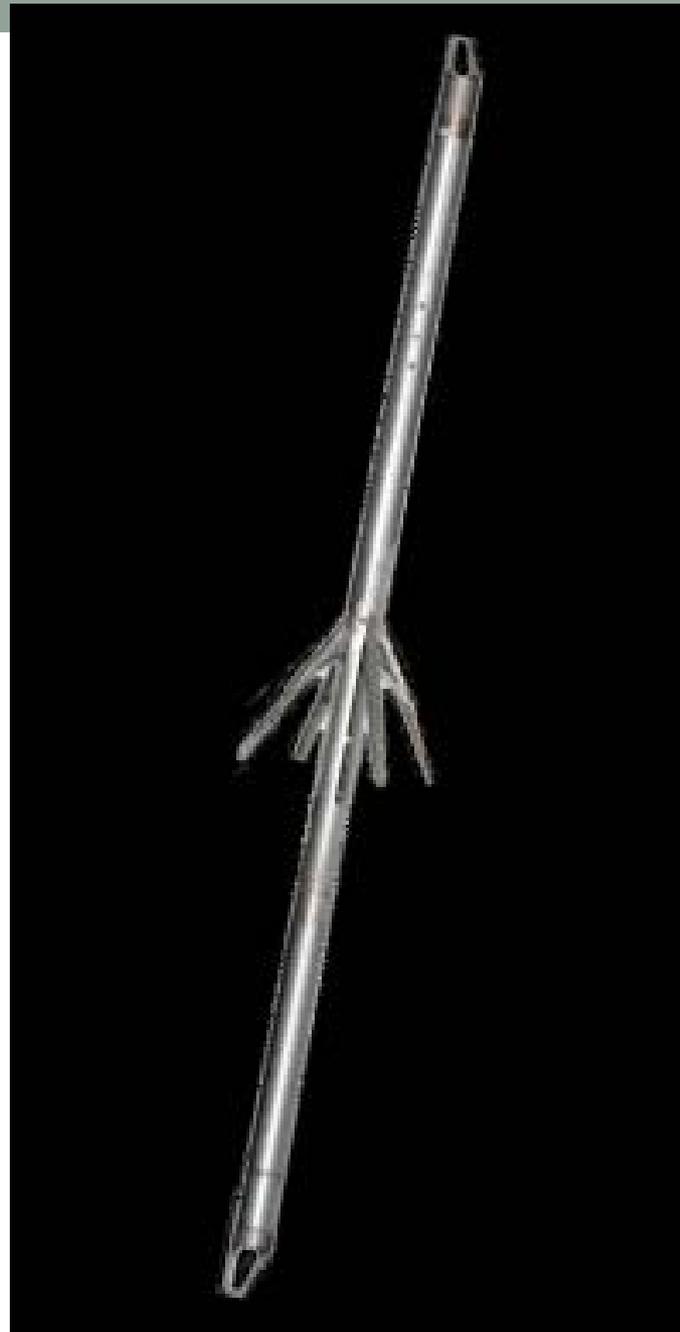
## How Do They Work?

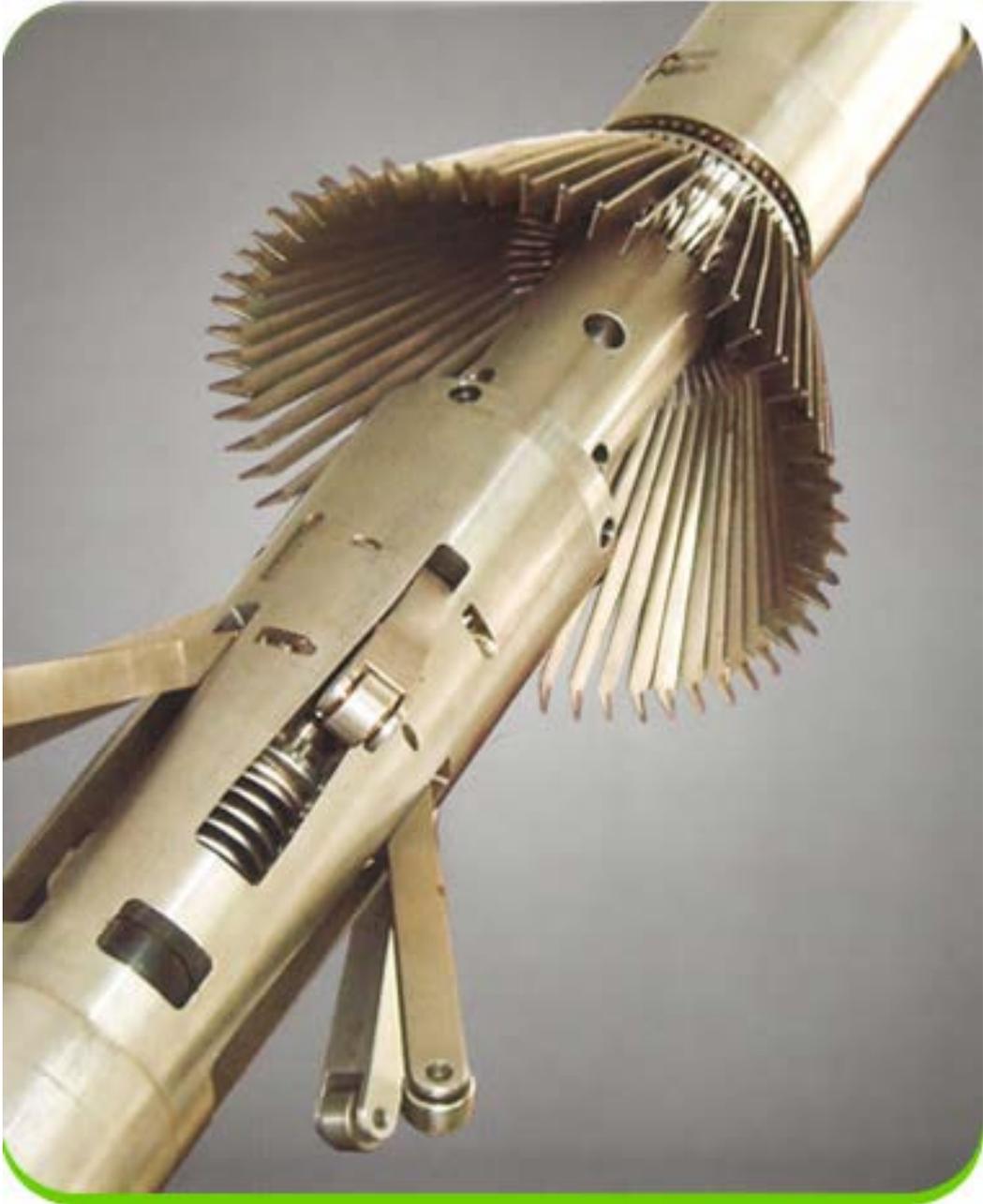
- Mechanical arms record hole size
- Hydraulic systems with calibrated potentiometers.

## How Are They Used?

- Hole size used to correct other logs
- Hole volume for cementing
- Lithologic information
  - washouts indicative of formation properties
- Stress field from hole break-out







# Generalities On Nuclear Measurements

## Principle of the different nuclear logging techniques

|  |
|--|
| <b>Measurement principle</b>   |
| <b>Natural radioactivity</b><br>Natural gamma ( $\gamma$ ) radioactivity (total)<br>Natural gamma ( $\gamma$ ) ray spectroscopy  |
| <b>Radiation induced by neutron bombardment</b><br>Spectroscopy of $\gamma$ rays emitted by the activation of oxygen:<br>$^{16}\text{O}(n,p)^{16}\text{N}(\beta^-)$<br>$^{16}\text{O}^*(\gamma = 6.13 \text{ MeV})^{16}\text{O}$<br>or the activation of a wide range of elements          |
| Spectroscopy of $\gamma$ rays emitted from fast neutron interactions<br>(mainly inelastic):<br>e.g.: $^{16}\text{O}(n,n'\gamma = 6.13 \text{ MeV})^{16}\text{O}$ , $t_{1/2} = 1.7 \times 10^{-11} \text{ sec}$   |
| Spectroscopy of $\gamma$ rays emitted by thermal neutron capture   |
| Epithermal neutron density at a fixed distance from a high-energy neutron source<br>Thermal neutron density at a fixed distance from a high-energy neutron source, by:<br>(a) detection of neutrons themselves<br>(b) detection of gamma rays arising from capture of the thermal neutrons |
| Decay rate of the thermal neutron population. The thermal neutron density is sampled at two different times between neutron bursts, by detecting the capture gamma rays.   |

**Compton scattering of gamma rays**

Gamma rays emitted from a source are scattered by the formation. The count-rate of those reaching the detector is function of the formation density.

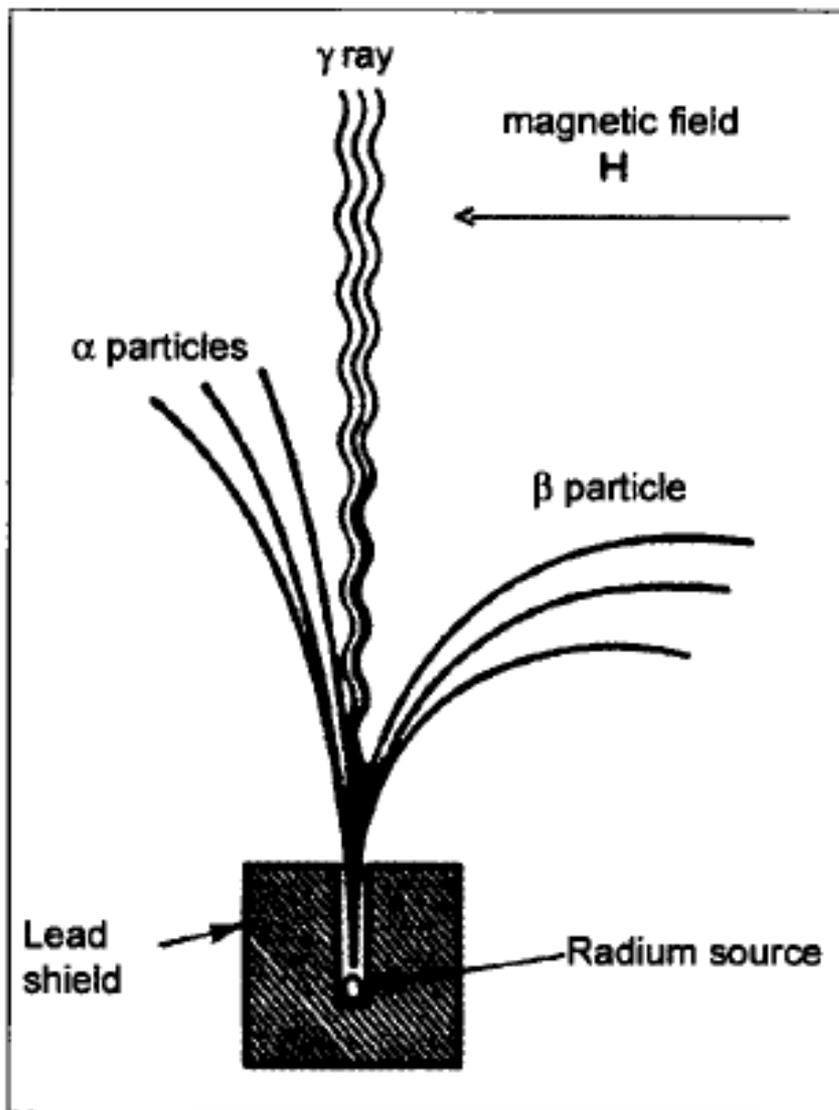
**Photoelectric absorption of low energy gamma rays**

Low-energy gamma absorption and measurement of the photoelectric absorption index of the formation, related to the lithology.

**Decay of proton spin precession induced by a strong magnetic field**

Protons are caused to precess about the local Earth magnetic field by a strong DC magnetic pulse.

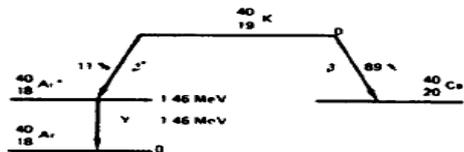
This precession decays with a time characteristic of the formation fluids, porosity and pore size.



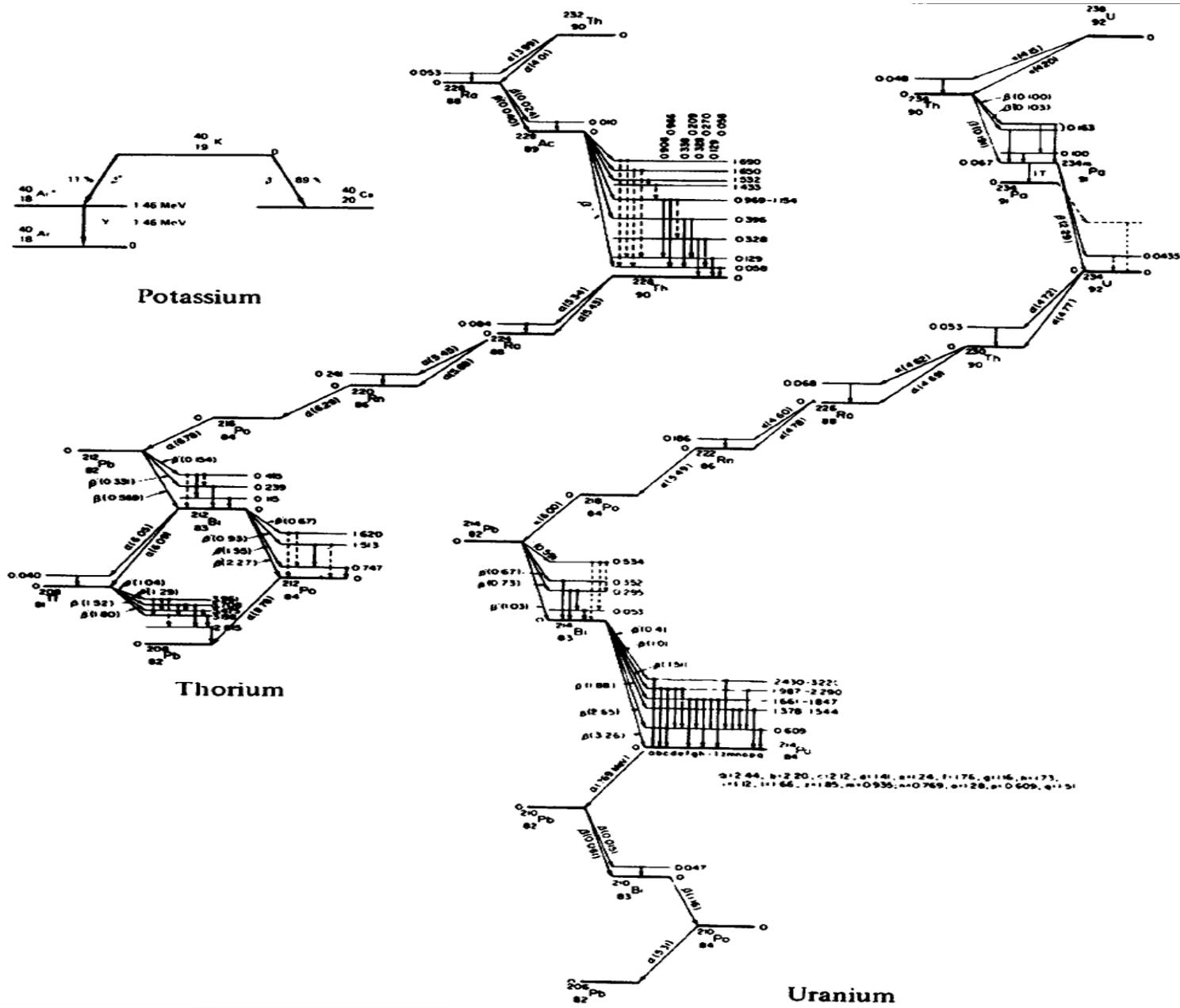
*Figure 10-1 -  
The three types of  
radiation. Only the gamma  
ray is not deviated by a  
magnetic field as it is not  
charged.*

- **$\alpha$  –radiation:** An  $\alpha$  -particle may be emitted from an atomic nucleus during radioactive decay. It is positively charged and has two protons and two neutrons. It is physically identical to the nucleus of the helium atom. By  $\alpha$  -emission the element of atomic number  $Z$  is transformed into an element of atomic number  $Z - 2$  and the number of nucleons decreases from **A** to **A - 4**.
- **$\beta$  particles:**  $\beta$  particles are high-energy, high-speed electrons or positrons emitted by certain types of radioactive nuclei such as potassium-40. The beta particles emitted are a form of ionizing radiation also known as beta rays

- **$\gamma$ -radiation:**  $\gamma$ -radiation may be considered as an electromagnetic wave similar to visible light or X-rays, or as a particle or photon. Gamma rays are electromagnetic radiations emitted from an atomic nucleus during radioactive decay. These radiations are characterized by wave lengths in the range of  $10^{-9}$  to  $10^{-11}$  cm, equivalent to frequencies ranging from  $10^{19}$  to  $10^{21}$  sec<sup>-1</sup>



Potassium



Thorium

Uranium

# Pair production

- When the photon energy is above the threshold value of 1.022 MeV, the interaction of photon and matter leads to pair production, it means the production of a negatron (or negative electron) and a positron (or positive electron) each with an energy of 0.511 MeV

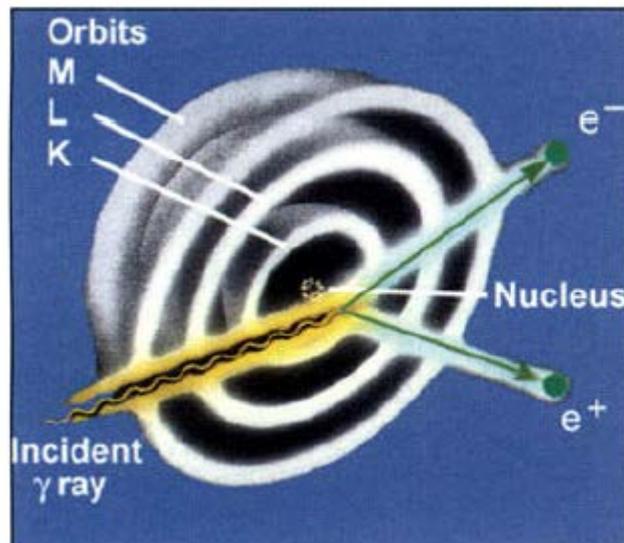


Figure 9-5 - Schematic of pair production at a nucleus (courtesy of Schlumberger).

# Compton scattering

- When the incident photon collides with an electron its energy is divided between the kinetic energy  $E = mv^2$  given to the electron ejected from its atom with initial velocity  $v$  and a photon "scattered" in a direction making an angle with the original incident direction (energy is between 1.022 MeV and 150 KeV).
- This type of reaction is called Compton scattering and it is the reaction figuring mainly in density measurements. The scattering effect is sensitive to the electron density of the formation (number of electrons per unit volume). The macroscopic cross section in a material consisting of atoms of mass  $A$ , and atomic number  $Z$ , is expressed by:

$$\Sigma_{C_0} = \sigma_{C_0} (N_{Av}/A) \rho_b Z \quad (9-5)$$

where:

$\Sigma_{C_0}$  is the macroscopic Compton cross section

$\sigma_{C_0}$  is the Compton cross section

$N_{Av}$  is the Avogadro's number ( $6.022 \times 10^{23} \text{ mol}^{-1}$ )

$\rho_b$  the material density.

$Z$  represents the number of electrons per atom.

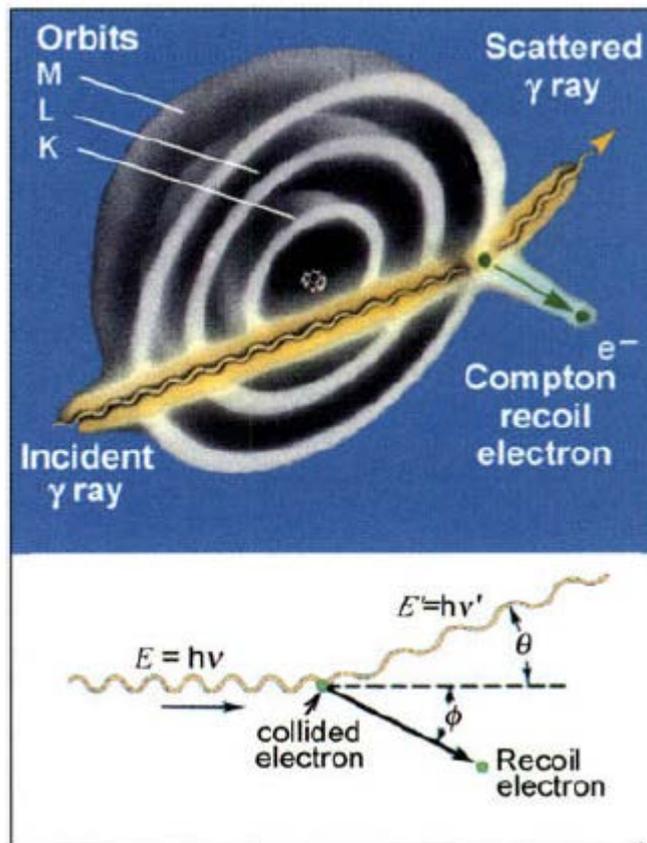


Figure 9-7 - Schematic of the Compton process. Geometrical relations in the Compton process. (courtesy of Schlumberger).

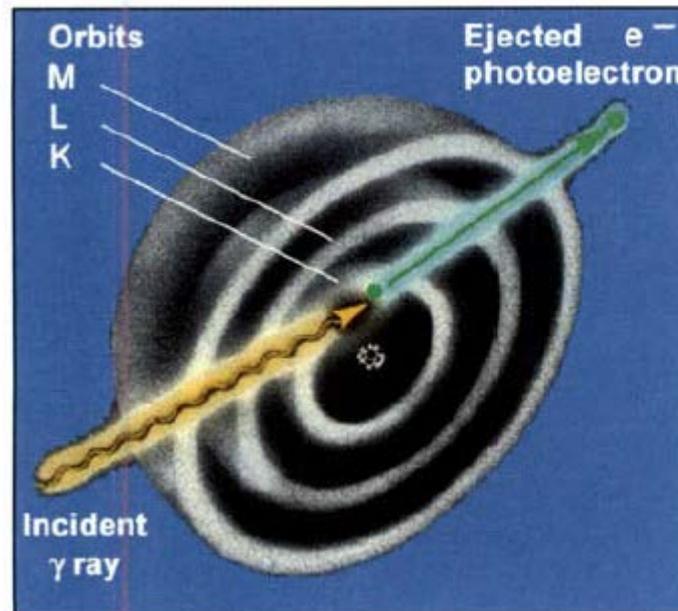
# Photoelectric effect

- In the course of a collision with an electron a photon loses part of its initial energy and for a certain energy level it can transfer all its remaining energy to the electron in the form of kinetic energy. The electron is ejected from its atom and the photon disappears. The gamma ray is absorbed (energy is less than 150 KeV).
- The microscopic cross-section of this reaction,  $\tau$ , has been found to be related to the atomic number of the target atom,  $Z$ , and the energy of the incident gamma ray,  $E_\gamma$ , by the following relation:

$$\tau_{\text{atom}} = 12.1 [(Z)^{4.6} / (E_\gamma)^{3.15}]$$

The unit is the barns / atom

- The photoelectric effect is highest when the gamma ray energy is small and the atomic number of the element high. For the most abundant rocks composing the Earth's crust, it becomes the dominant process for gamma ray energies below about 100 keV. It is at the origin of a measurement that is sensitive to the average atomic number of the formations and so to the lithology.



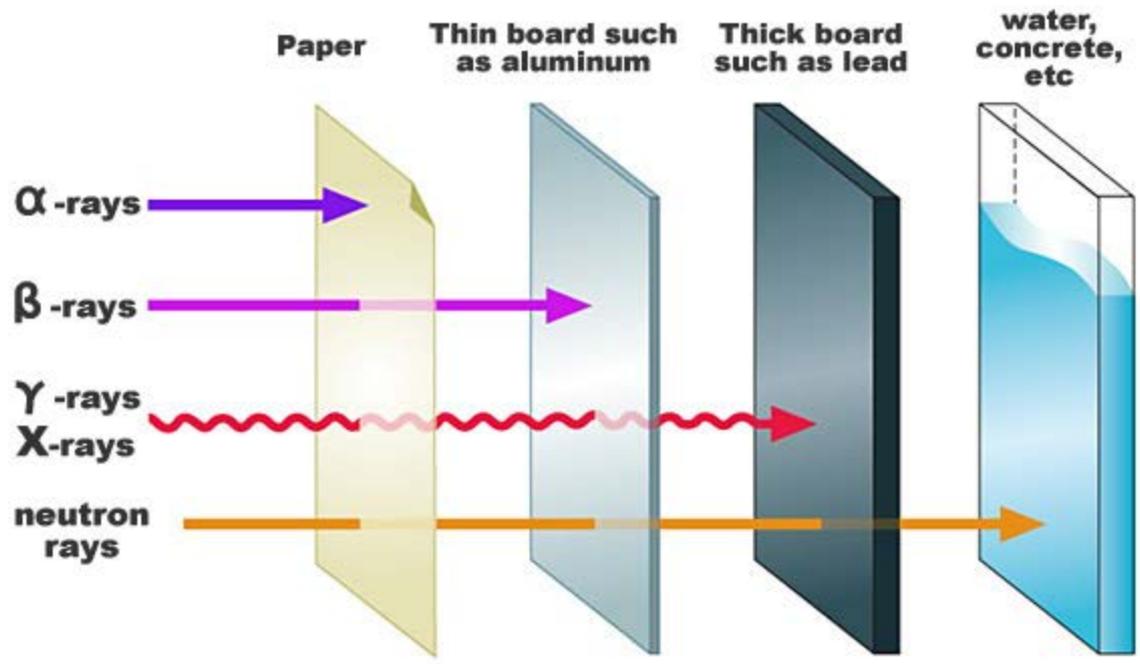
*Figure 9-8 -  
Schematic of the  
photoelectric process  
(courtesy of  
Schlumberger).*

# Neutron radiation

- Neutron radiation is a kind of ionizing radiation which consists of free neutrons. A result of nuclear fission or nuclear fusion, it consists of the release of free neutrons from atoms, and these free neutrons react with nuclei of other atoms to form new isotopes, which, in turn, may produce radiation.

| <b>Neutron energy</b> | <b>Energy range</b>   |
|-----------------------|-----------------------|
| 0.0–0.025 eV          | Cold neutrons         |
| 0.025 eV              | Thermal neutrons      |
| 0.025–0.4 eV          | Epithermal neutrons   |
| 0.4–0.6 eV            | Cadmium neutrons      |
| 0.6–1 eV              | EpiCadmium neutrons   |
| 1–10 eV               | Slow neutrons         |
| 10–300 eV             | Resonance neutrons    |
| 300 eV–1 MeV          | Intermediate neutrons |
| 1–20 MeV              | Fast neutrons         |
| > 20 MeV              | Relativistic neutrons |

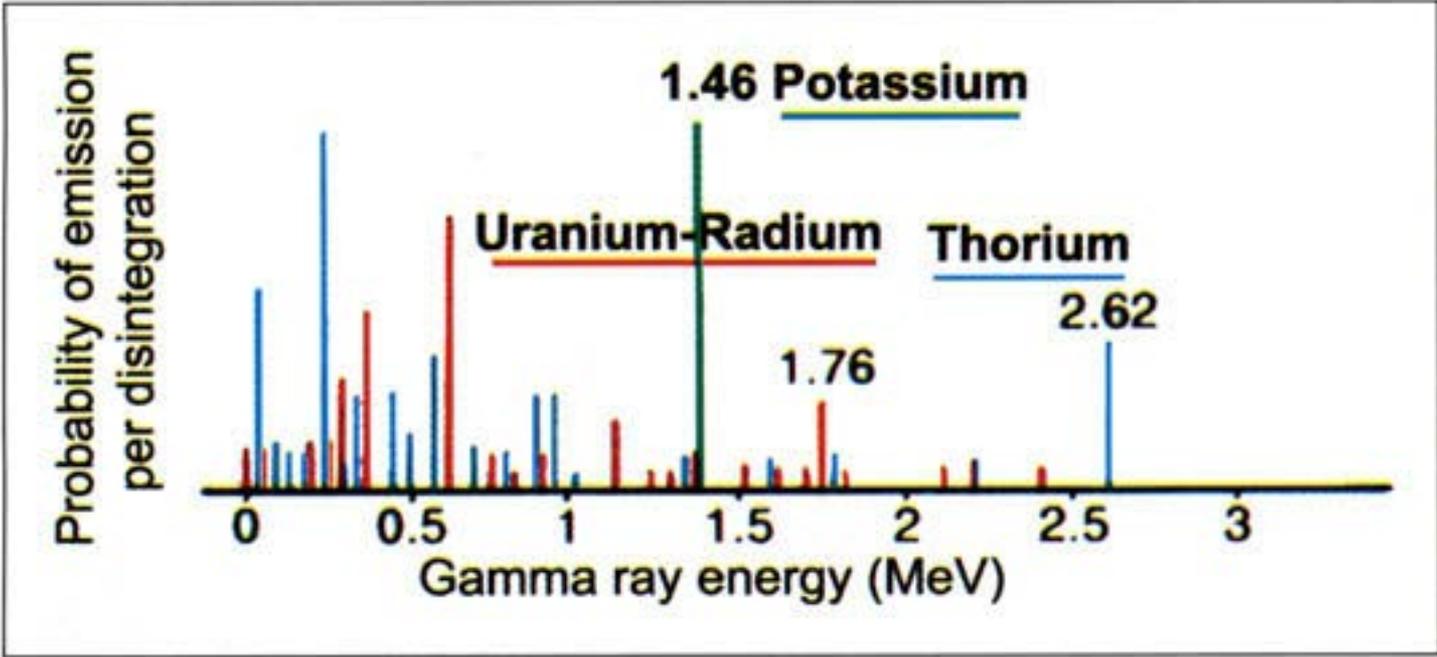
## Radiation types and the degree of penetration

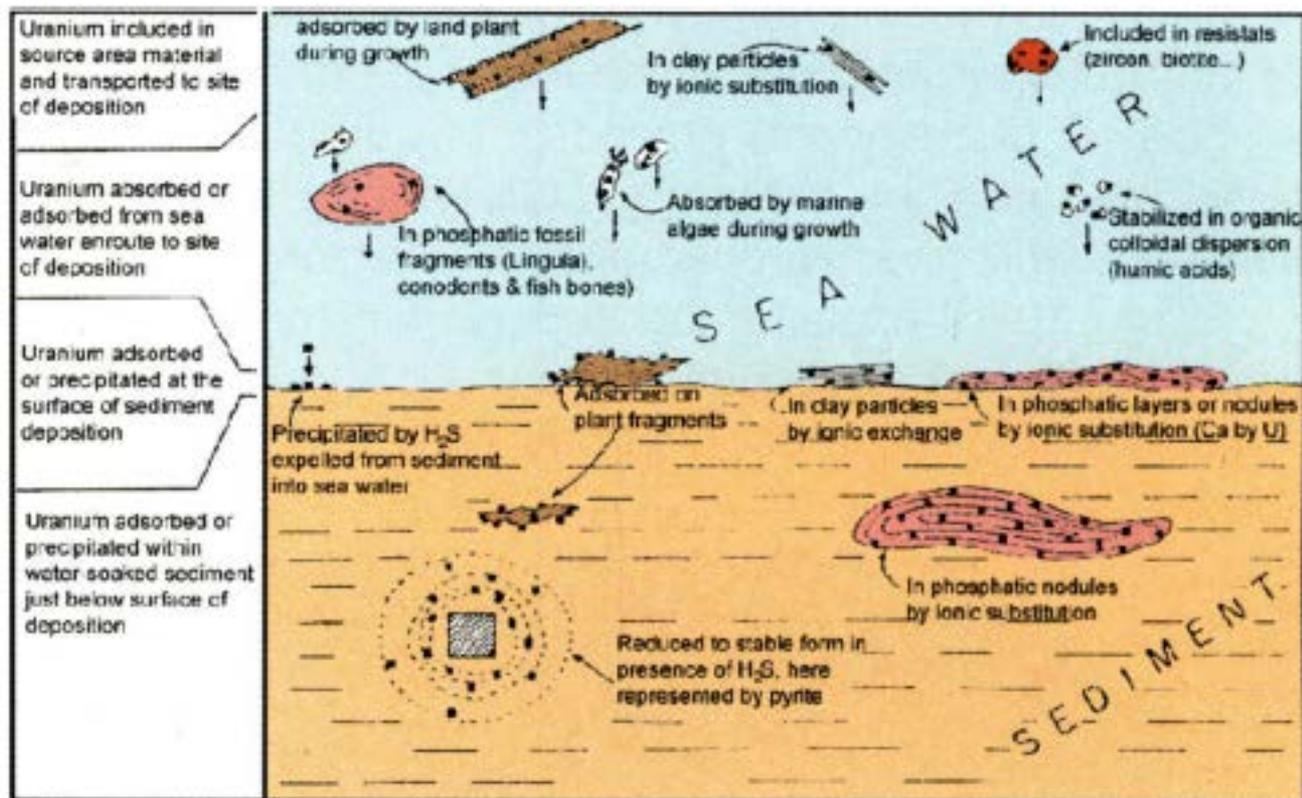


# Minerals and rocks containing radioactive elements

Main radioactive elements

| Element   | Isotope           | Percentage of the total element (%) | Emissions      |                |          | Half life (year)     | Relative abundance in Earth's crust (ppm) |
|---|-------------------|-------------------------------------|----------------|----------------|----------|----------------------|---|
|   |                   |                                     | $\alpha$       | $\beta$        | $\gamma$ |                      |   |
| Primeval natural gamma -ray emitters            |                   |                                     |                |                |          |                      |   |
| Potassium                                       | $^{40}\text{K}$   | 0.0118                              |                | 1              | 1        | $1.3 \times 10^9$    | 2.5                                       |
| Uranium <sup>d</sup>                            | $^{235}\text{U}$  | 0.72                                | 8 <sup>d</sup> | 5 <sup>d</sup> | a        | $7.1 \times 10^8$    | 0.02                                      |
| Secondary gamma-ray emitters by their daughters |                   |                                     |                |                |          |                      |   |
| Uranium series                                  | $^{238}\text{U}$  | 99.27                               | 8 <sup>d</sup> | 6 <sup>d</sup> | b        | $4.5 \times 10^9$    | 3   |
| Thorium series                                  | $^{232}\text{Th}$ |                                     | 7 <sup>d</sup> | 5 <sup>d</sup> | b        | $1.4 \times 10^{10}$ | 12  |





*Figure 10-10 - Diagrammatic sketch showing possible association and time of emplacement of uranium with common constituents of marine black shales. Uranium is represented by black squares (from Swanson, 1960).*

# Total Natural Radioactivity Measurement

- The measurement of the total natural radioactivity of the formations crossed by a well is known as the gamma ray log.
- The gamma-ray sonde contains generally one detector of scintillation-counter type. This type of counter is more efficient than the Geiger-Mueller counters previously used in older tools. Its dimension is shorter allowing a better vertical resolution.
- The detector records all the gamma rays emitted by the formation above some practical lower energy limit (on the order of 100 keV).

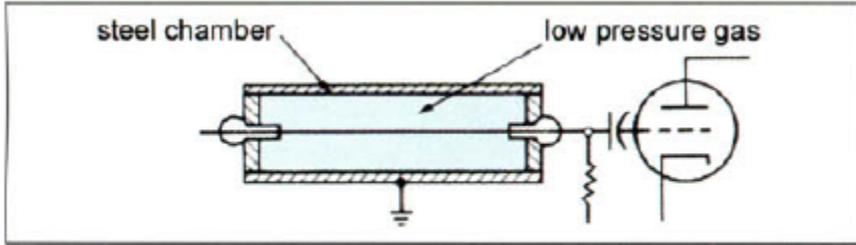


Figure 9-11 - Typical ionization chamber.

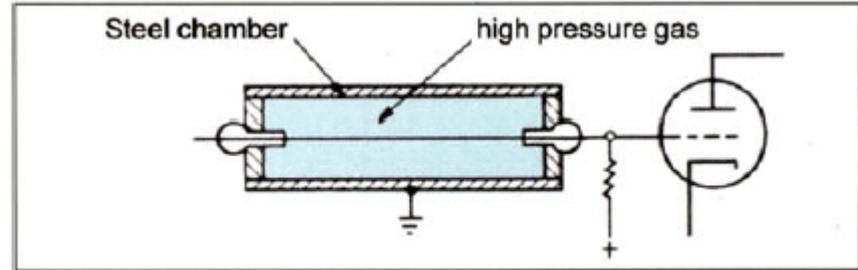
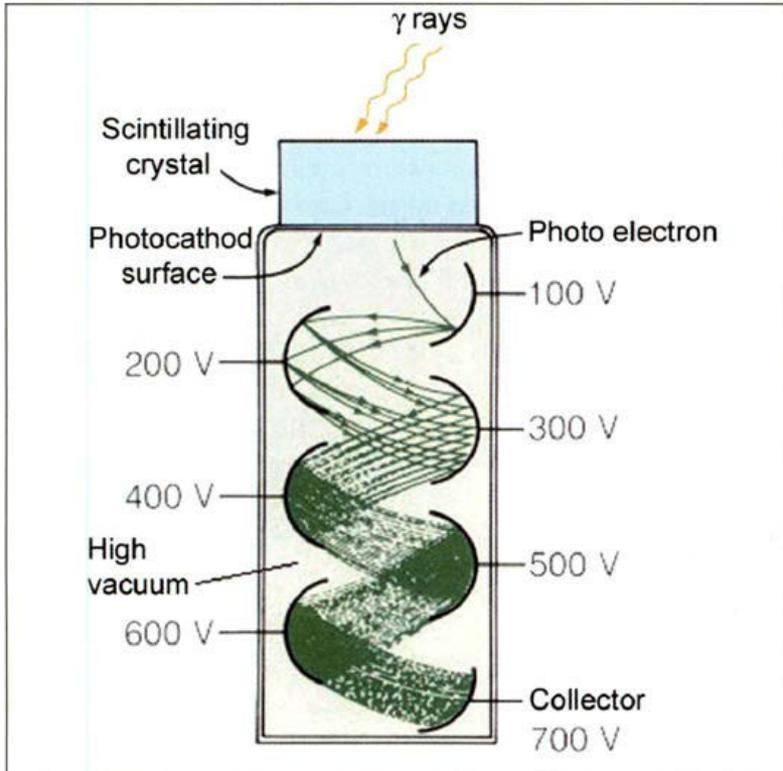


Figure 9-10 - Typical Geiger-Mueller counter.



- Any gamma-ray flux generated in a formation at a distance  $x$  from the borehole wall must cross the thickness  $x$  of this formation of density and a thickness  $h$  of the hole filled of mud of density  $\rho_m$  before reaching the detector. From this fact it is easy to understand that the borehole environment will affect the GR measurement. In addition, one must take into account that the mud can itself be radioactive due to its content in bentonite and sometimes in KCl, and in barite which makes the mud denser. Consequently, to evaluate the actual radioactivity of the formation corrections for borehole influence must be previously achieved.

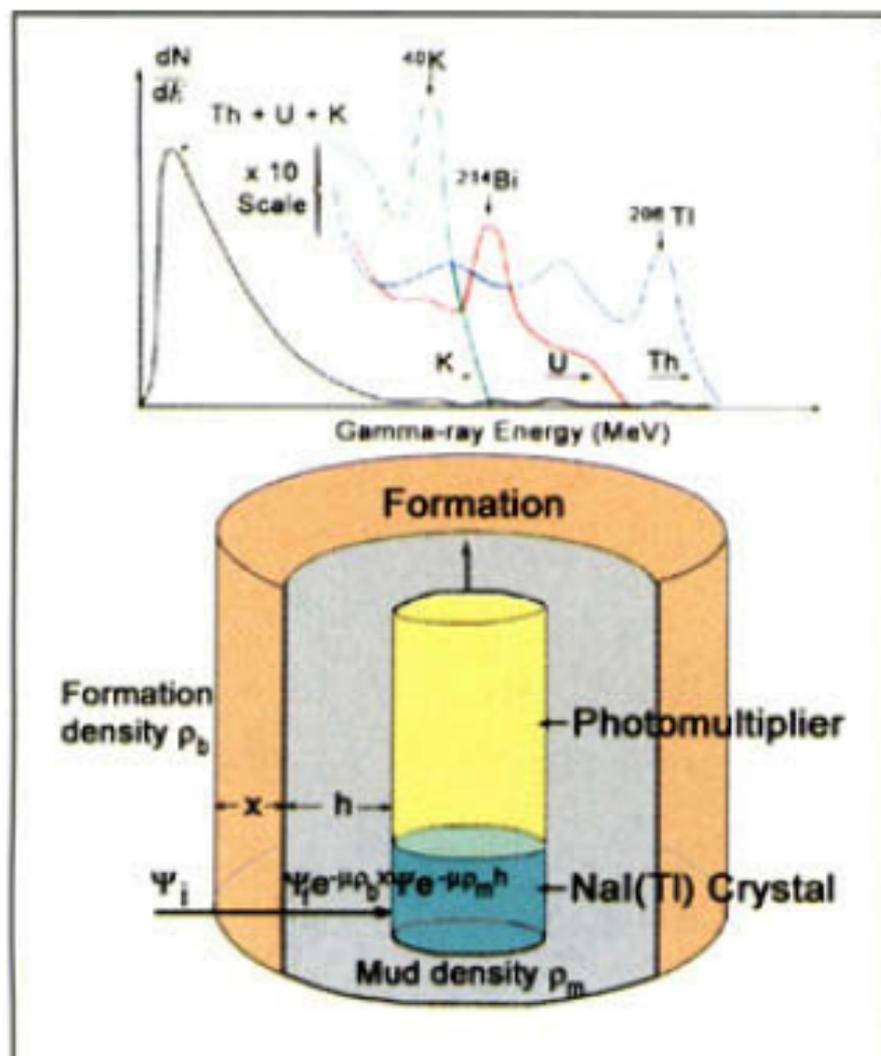


Figure 11-2 - The initial gamma-ray flux,  $\Psi_i$ , generated at distance  $x$  from the borehole wall and crossing a section  $h$  in the borehole filled by non-radioactive mud of density  $\rho_m$  has a reduced intensity when reaching the detector located in the well. The total spectrum recorded is reproduced on the top.

- Units:
- The global radioactivity was originally expressed in  $\mu\text{g Ra}$  equivalent /tonne. Now the unit is the A.P.I. (for American Petroleum Institute).
- The definition of the API unit comes from an artificially radioactive formation, constructed at the Houston University (see further the paragraph on Calibrations) to simulate about twice the radioactivity of a shale. This artificial formation contains approximately **4%** of potassium, 24 ppm of thorium and 12 ppm of uranium (Belknap *eta/.*, 1959). This mixture generates 200 API units.

- **Depth of investigation:**

- Gamma rays are absorbed or attenuated by the medium through which they travel, particularly when their energy is low or the medium dense. Consequently, a natural gamma-ray tool only detects radiation originating from a relatively small volume surrounding the detector.
- Consequently, one can speak about a geometrical factor and compute for each lithology type a radius of investigation.

- **Vertical resolution:**

- Vertical resolution is equal to the diameter of the "sphere" of investigation, and varies accordingly with formation and densities, and gamma-ray energies.

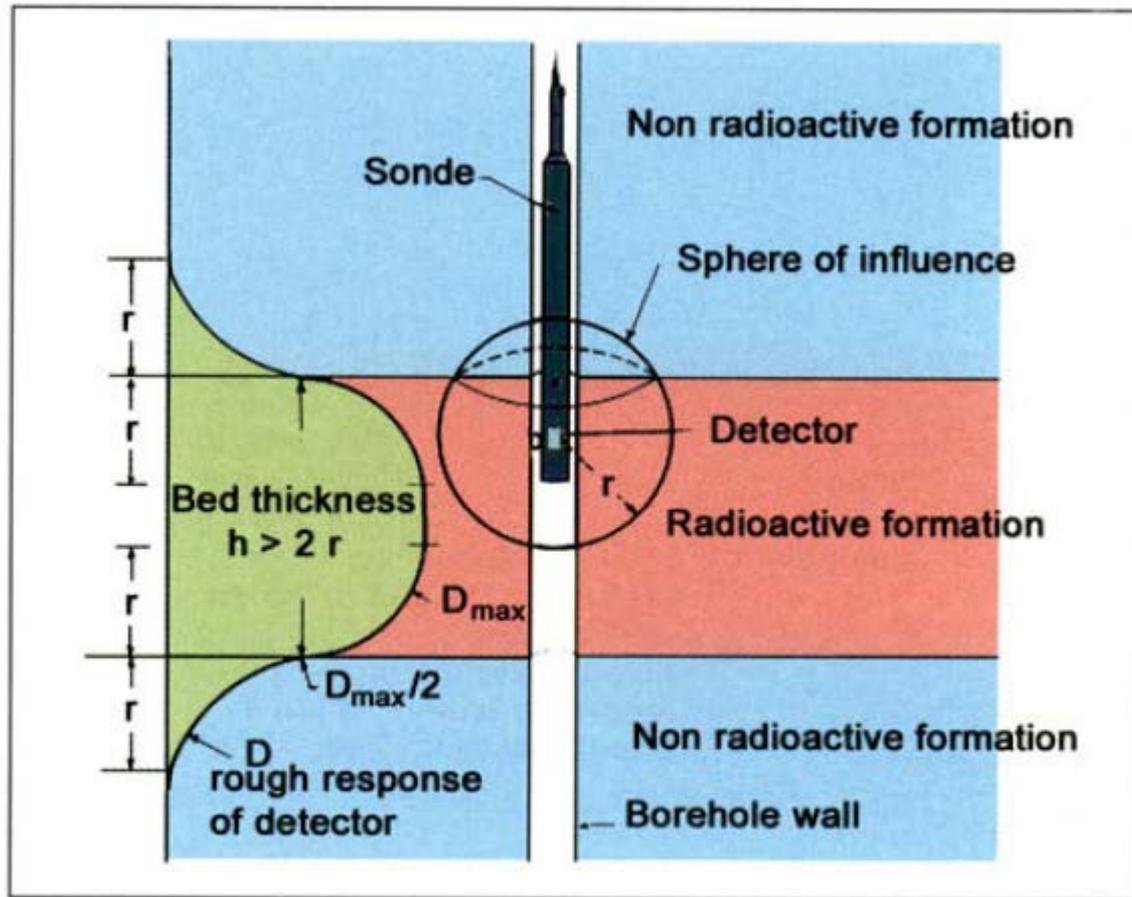


Figure 11-8 - Sphere of influence for a detector compared to the bed thickness, and shape of the curve (adapted from Hallenborg, 1973).

- **Factors affecting the gamma-ray response:**

1. Statistical variations
2. Logging speed
3. Hole condition effects
  1. Hole fluid
  2. Tubing. casina etc.
  3. Cement
  4. Bed thickness

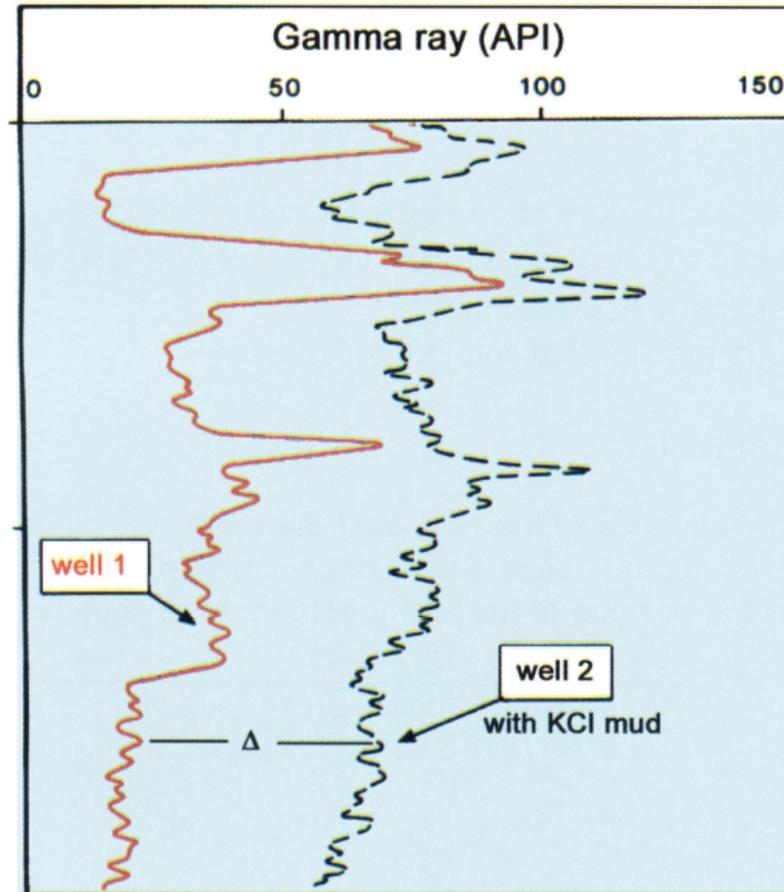


Figure 11-12 - Example illustrating the influence of mud with KCl on the gamma ray measurement. Well 2 is situated 3 km apart from well 1. The curve shape allows the correlation of formations between wells. The difference,  $\Delta$ , between the two readings is approximately equal to 50 API. This difference is less important in front of more radioactive peaks due probably to non invasion of the shale beds (adapted from Rider, 1986).

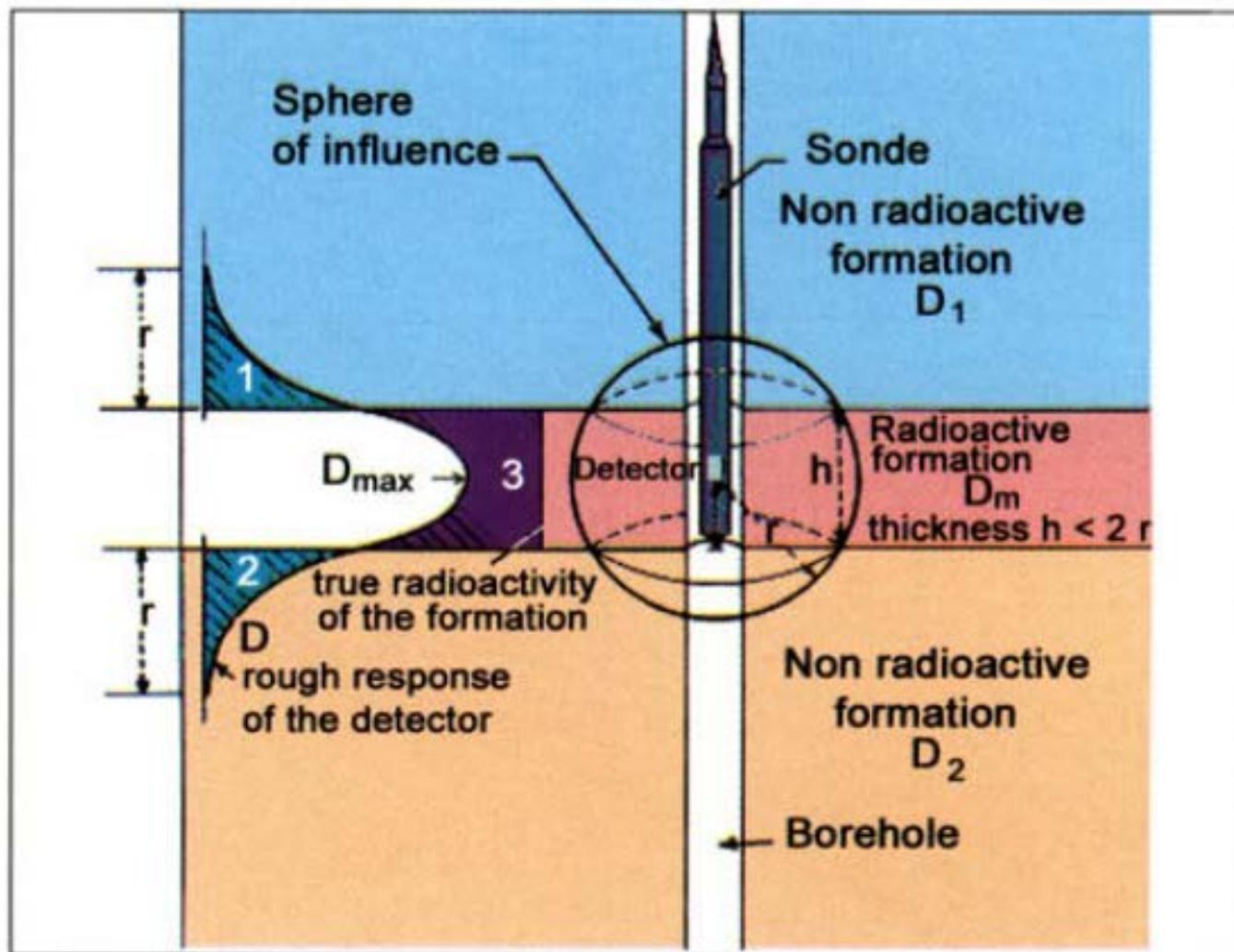


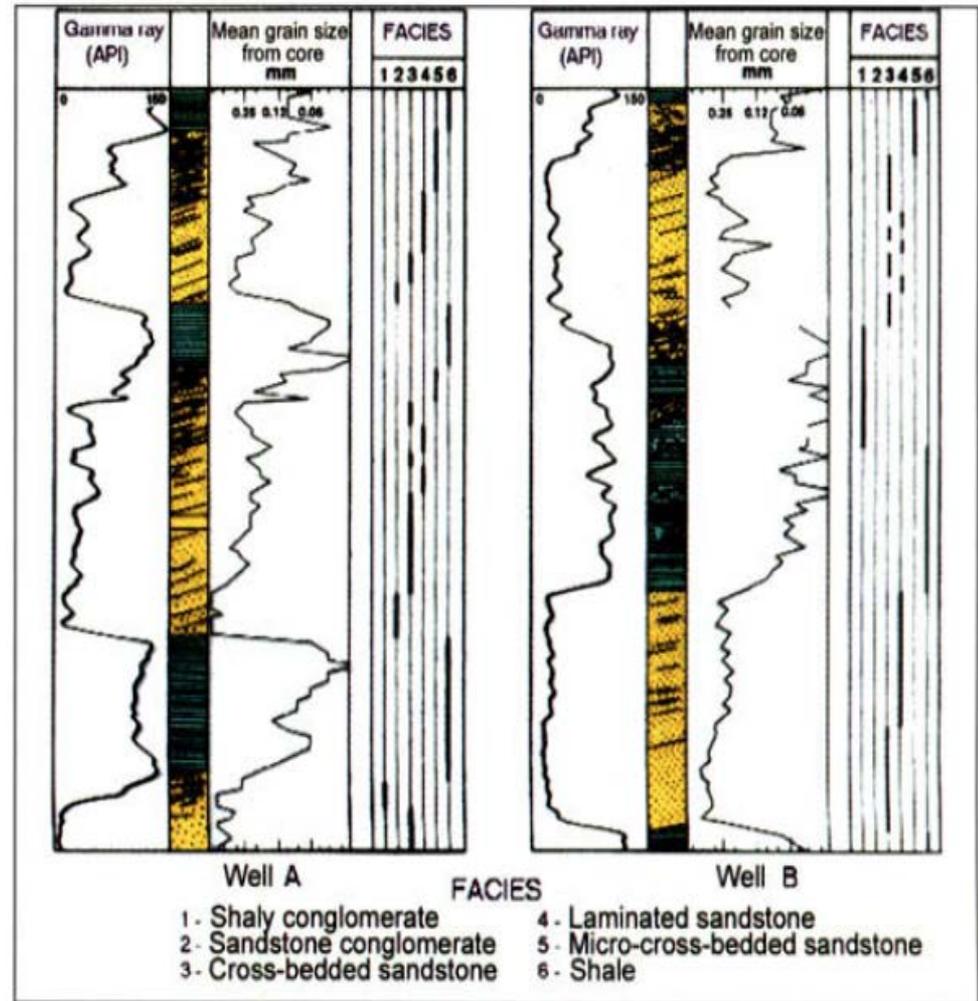
Figure 11-13 - Response in a thin bed (from Hallenborg, 1973).

# Applications of the total Gamma-Ray

| Applications        | Qualitative  | Quantitative   | Knowing   |
|---------------------|--|--|---|
| <b>Petrophysics</b> | "Clean" formations   | Computation of $V_{sh}$<br>Location of testing<br>Location of perforations | $GR_{min}$ and $GR_{max}$   |
| <b>Geology</b>      | <p><b>Lithology:</b><br/>shaly formations<br/>feldspathic sandstones<br/>glaucconitic sandstones<br/>potassium salts</p> <p>Radioactive silts<br/>Uranium ores</p> <p><b>Sedimentology:</b><br/>Facies determination<br/>Sequences<br/>Grain size evolution</p> <p><b>Stratigraphy:</b><br/>Correlations<br/>Unconformity detection<br/>Transgressions</p> <p><b>Tectonics:</b><br/>Overtuned series<br/>Reverse or thrust fault detection</p> <p><b>Core and fluid sampling</b></p> | <p>Shale percentage</p> <p>Potassium percentage<br/>15 API # 1% K</p>      | <p><math>GR_{min}</math> and <math>GR_{max}</math></p> <p>Combination with other log data</p> |

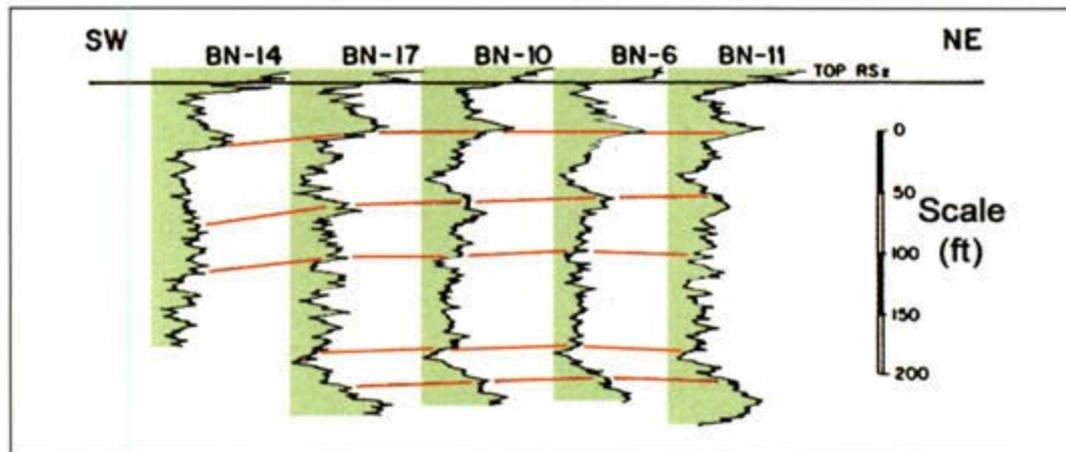
- Lithology determination:
- The gamma-ray measurement is essentially used to detect shale beds especially if SP curve is not useful. Evaporites can also be detected and their potassium content evaluated using charts. In first approximation 15 API corresponds to 1% of In combination with other log data, such as resistivity, neutron, density and sonic, one can determine the main lithologies. Silty formations can be recognized as soon as the gamma-ray curve is compared to other logs.

- Sedimentology:
- The gamma-ray curve can reflect typical grain size evolutions with depth - fining or coarsening up sequences - which may reflect typical facies as illustrated by Figure. This application requires a calibration on core data (cf. Chapters 3 to 5 of Well Logging and Geology from O.& L. Serra, 2003).





- Well-to-well correlations:
- Correlations between wells are better achieved and accurate using gamma-ray curves. This is linked to the fact that the gamma ray measurement is practically not affected by change in porosity or fluid content



- Detection of unconformities or transgressions:
- A sudden important change in the gamma-ray value may indicate either an unconformity or a transgression (cf. Chapter 11 of Well Logging and Geology, O. & L. Serra, 2003).

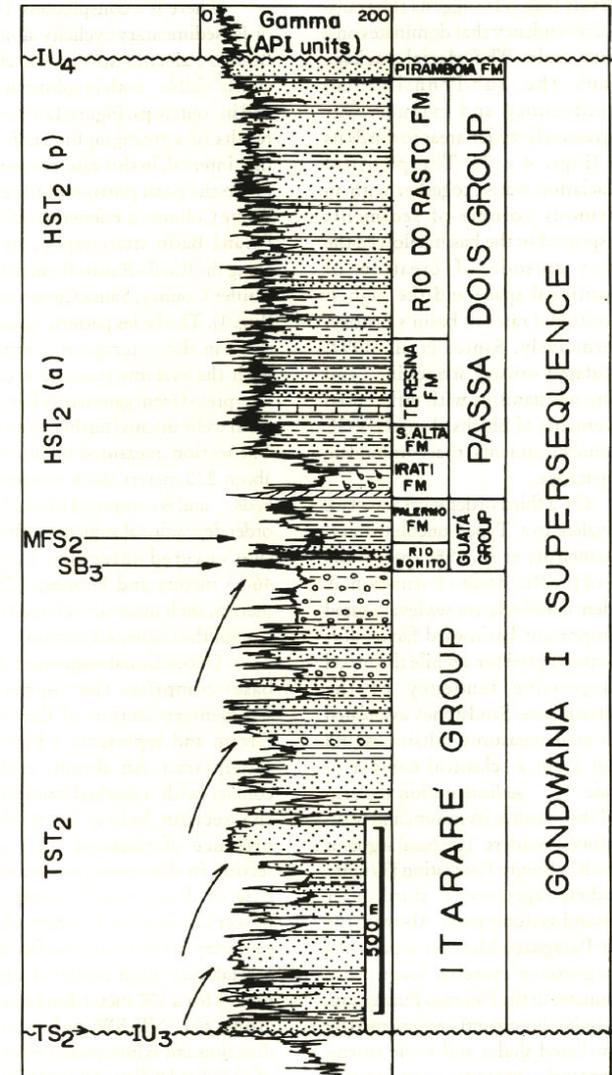


Figura 11 - Gamma and lithologic profiles showing a subsurface section of the Gondwana I supersequence. Location on Fig. 14. Legends: see Fig. 6.

- Tectonic applications:
- As just mentioned above, the gamma -ray curves are not affected by the fluid and porosity and when analyzed carefully they allow the detection of overturned or repeat intervals (cf. Chapter 8 of Well Logging and Geology, O. & L. Serra, 2003).

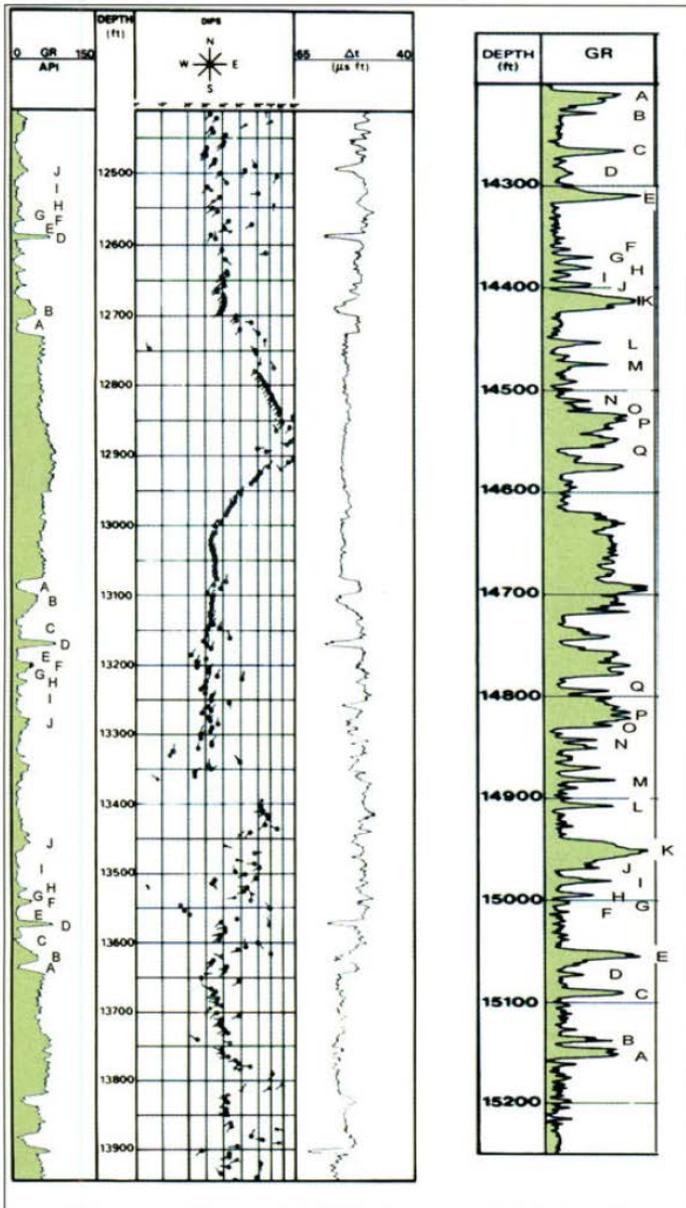


Figure 11-19 - Two examples of overturned folds very well detected thanks to gamma-ray curve analysis. The repeated peaks are indicated by letters (courtesy of Schlumberger).

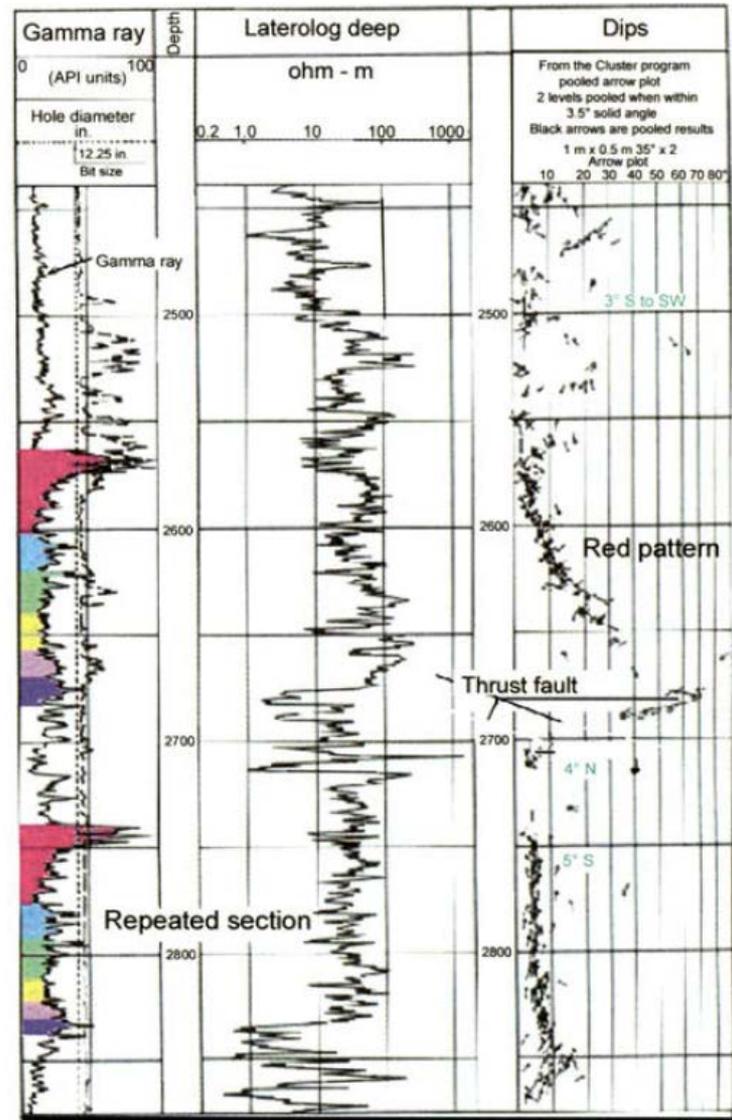
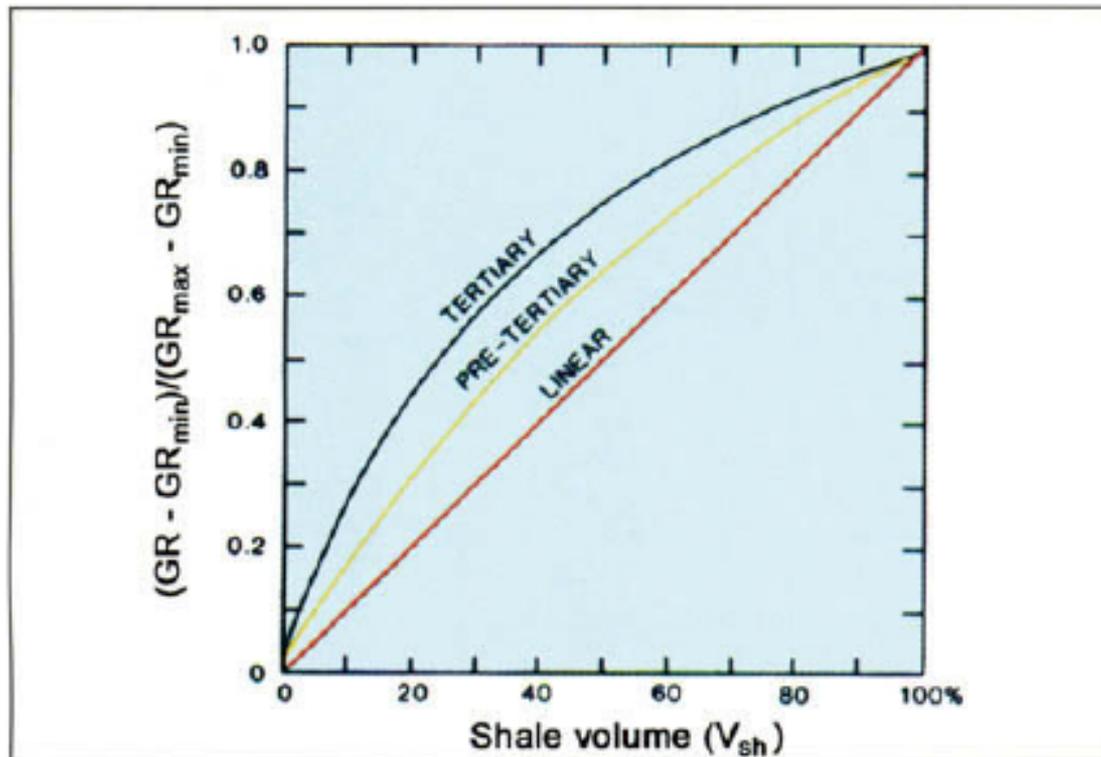


Figure 11-20 - Example of reverse fault perfectly detected by analysis of the gamma-ray curve (from Schlumberger, Well Evaluation Conference, Iran, 1976).

- Estimation of shale fraction of reservoir rocks:
- In sedimentary rocks, shales are the most common radioactive rocks (if we ignore potassium salts), with the radiation arising primarily from the clay fraction. To a reasonable approximation we can consider that the GR level is related to shaliness by:

$$V_{sh} < (V_{sh})_{GR} = [(GR - GR_{min}) / (GR_{sh} - GR_{min})] \quad (11-17)$$

- It must be understood that the GR response may include radioactivity from sources other than shale, for instance from orthoclase, microcline or micas often present in chemically immature sandstones, or from heavy radioactive minerals such as zircon and monazite. For this reason, the right side of the equation is an upper limit to  $V_{sh}$ . Relationships between gamma-ray values and shale content must be adapted to typical formations or calibrated on core data

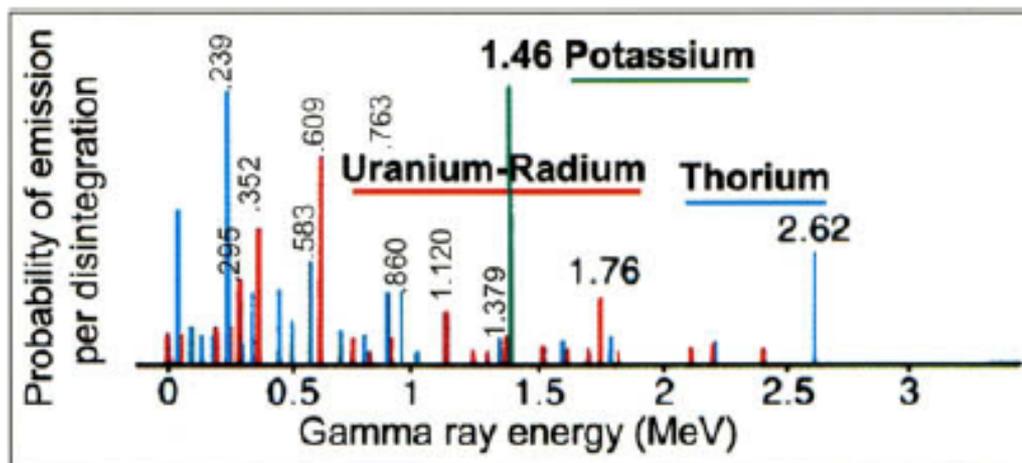


*Figure 11-21 - Evaluation of the shale content from the gamma-ray values as a function of the age of the shaly formations (from Dresser Atlas document).*

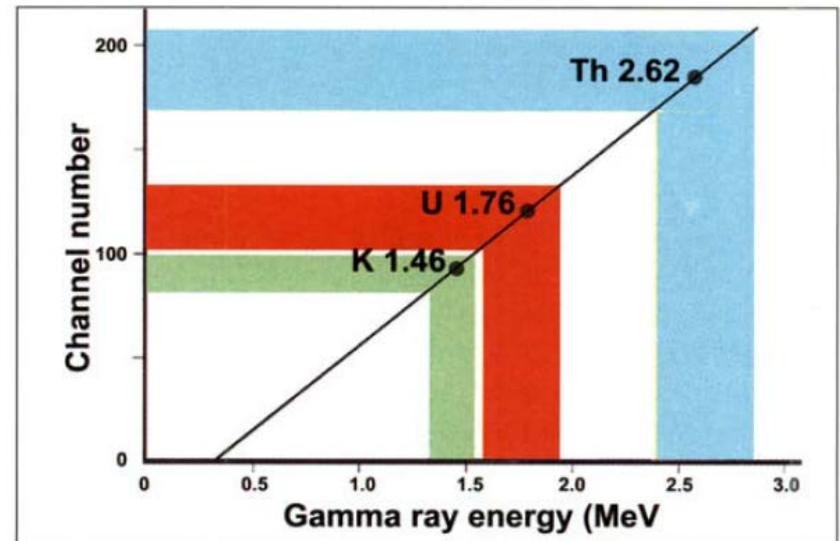
- **Depth control of sampling, perforating and testing equipment:**
- Positioning wireline testers, sidewall core sampling, or perforations is better achieved using gamma ray curves in open holes, or even through tubing or casing.
- **The evaluation of injection profiles:**
- The gamma ray is sometimes used in connection with radioactive tracers operations.

# Natural Gamma Ray Spectrometry Tool (NGT)

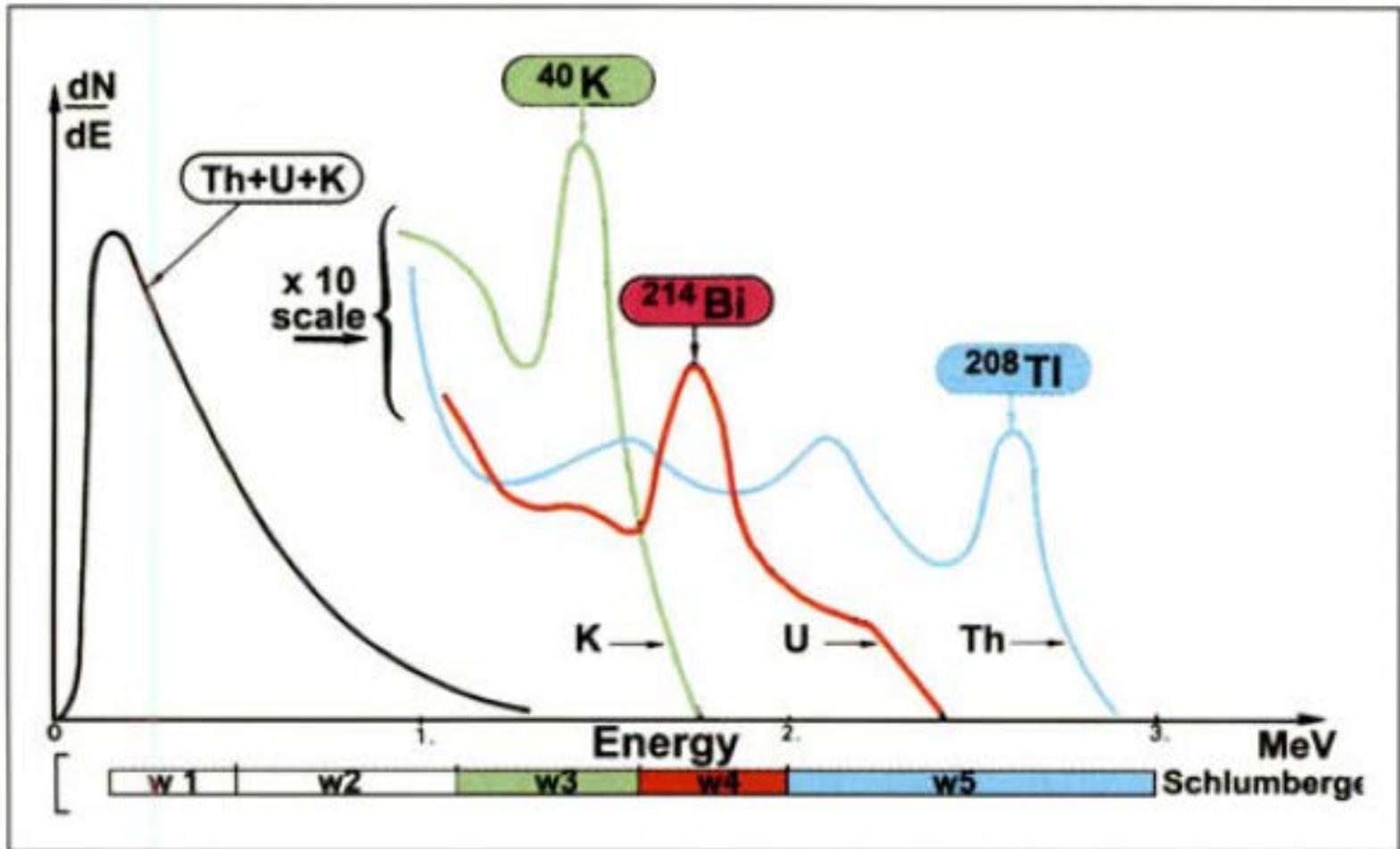
- The gamma rays emitted by the three decay series have a number of discrete energies. In Figure are shown the three corresponding theoretical gamma-ray emission spectra. Each spectrum characterizes a decay series, each series has a spectral "signature" that enables its presence to be discerned.

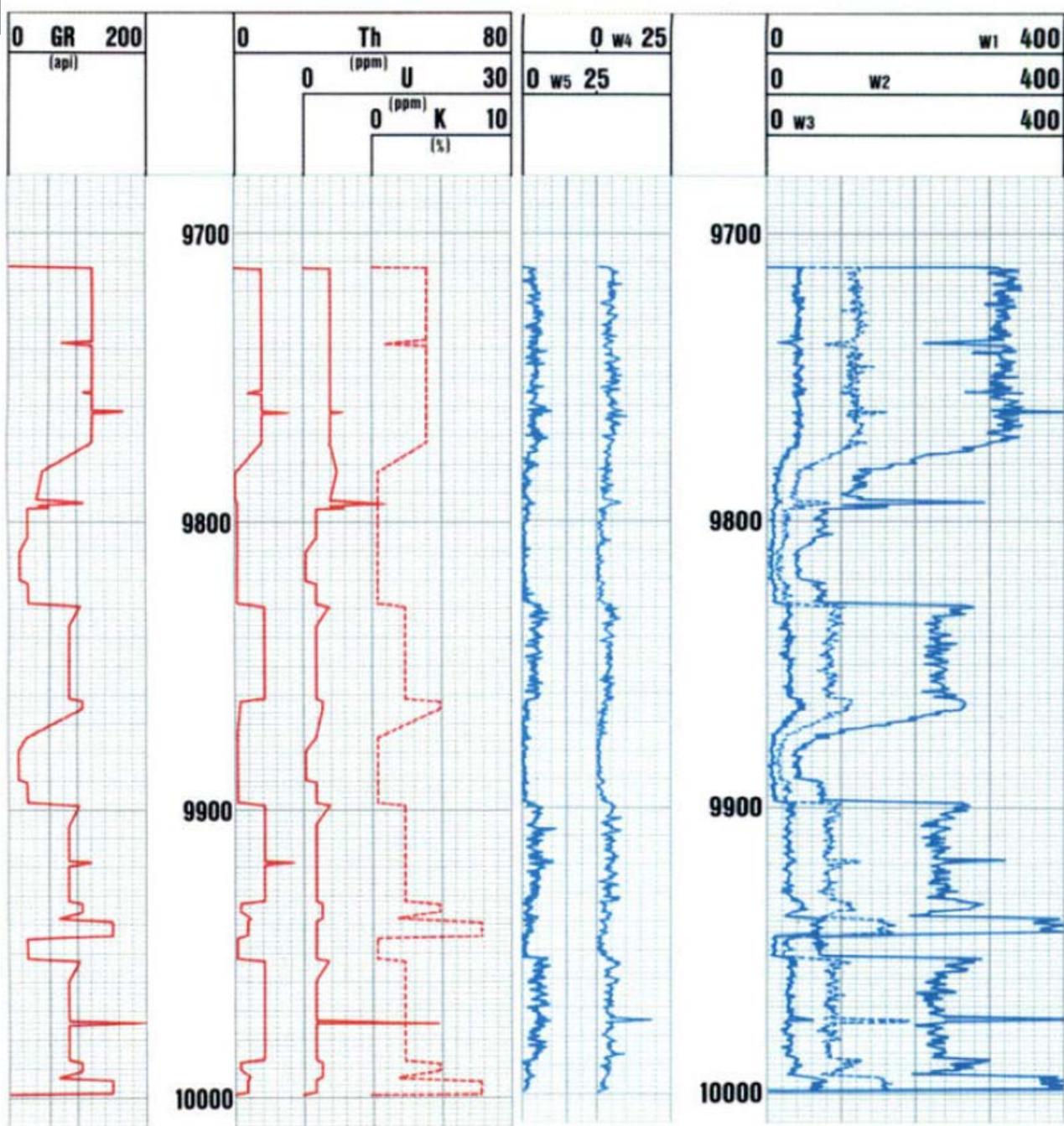


- To obtain a quantitative evaluation of thorium, uranium and potassium from an analysis of the total energy distribution, it is helpful to divide the spectrum into two regions:
  1. the high-energy region, with the three main peaks: Thallium 208Tl at 2.62 MeV (from the  $^{232}\text{Th}$  family), Bismuth 214Bi at 1.76 MeV (from the  $^{238}\text{U}$  family), and Potassium 40K at 1.46 MeV;
  2. the low-energy region, covering the energy range of the gamma rays resulting from Compton scattering in the formation, plus lower-energy emissions from the thorium and uranium series.



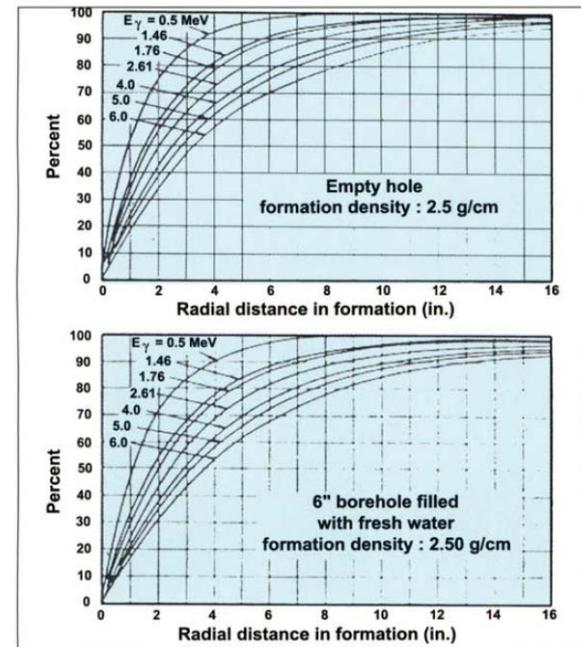
- The Schlumberger Natural Gamma ray Spectrometry tool (NGS or NGT) uses five windows.





- **Depth of investigation:**

- The depth of investigation depends not only on hole size, mud-density and formation bulk density, but on the energies of the gamma rays themselves Higher-energy radiation can reach the detector from deeper in the formation.



- Vertical resolution:
- In average, for 90% of the signal, it corresponds to approximately three times the size of the detector crystal, so close to 36 in. But, once again it depends on the rock density and the energy of the gamma ray. Enhancement techniques can be used to improve the vertical resolution. In that case one can expect a vertical resolution close to 18 in.



- **Environmental and other effects on the measurement:**
  1. Time constant (vertical smoothing), logging speed, dead time
  2. The borehole
  3. Tool position
  4. Casing
  5. Bed thickness

# Applications

| Application  | Qualitative  |   | Quantitative  | Knowing   |
|--------------|--|---|---|---|
| Petrophysics | Separation between shaly formations and radioactive reservoirs |   | Computation of the shale content<br>Computation of the percentage of the minerals composing the rocks | $Th_{min}$ , $K_{min}$ , $Th_{max}$ , $K_{max}$ .<br>The mineralogical model and the logging parameters of the minerals - Other log data. |
| Geology      | Lithology  | Lithological type<br>Nature of radioactive minerals | Mineral admixture   | The mineralogical model and the logging parameters of the minerals - Other log data.  |
|              | Sedimentology  | Clay type<br>Facies<br>Environment                  | Clay mineral admixture  | The mineralogical model and the logging parameters of the minerals - Other log data.  |
|              | Geochemical  | Source-rock evaluation                              |   | Uranium percentage in source-rock.  |
|              | Stratigraphy   | Correlations<br>Unconformities                      |   |   |
|              | Tectonics  | Repeated formations<br>Overturned formations        |   |   |

- **Lithology:**

- 1- Evaporitic environment:

- Differentiate between shales and potassium salts; these last minerals having a much higher potassium content than the clay minerals, and no thorium content since thorium is insoluble and can be considered as an indicator of detrital origin. So in front of potassium evaporates, the Th curve will be flat and near zero while the K curve will show a high percentage of potassium and a shape generally very similar to that of the total gamma ray, at least if at the same time the uranium curve is flat and near zero (showing little organic material in the rock)

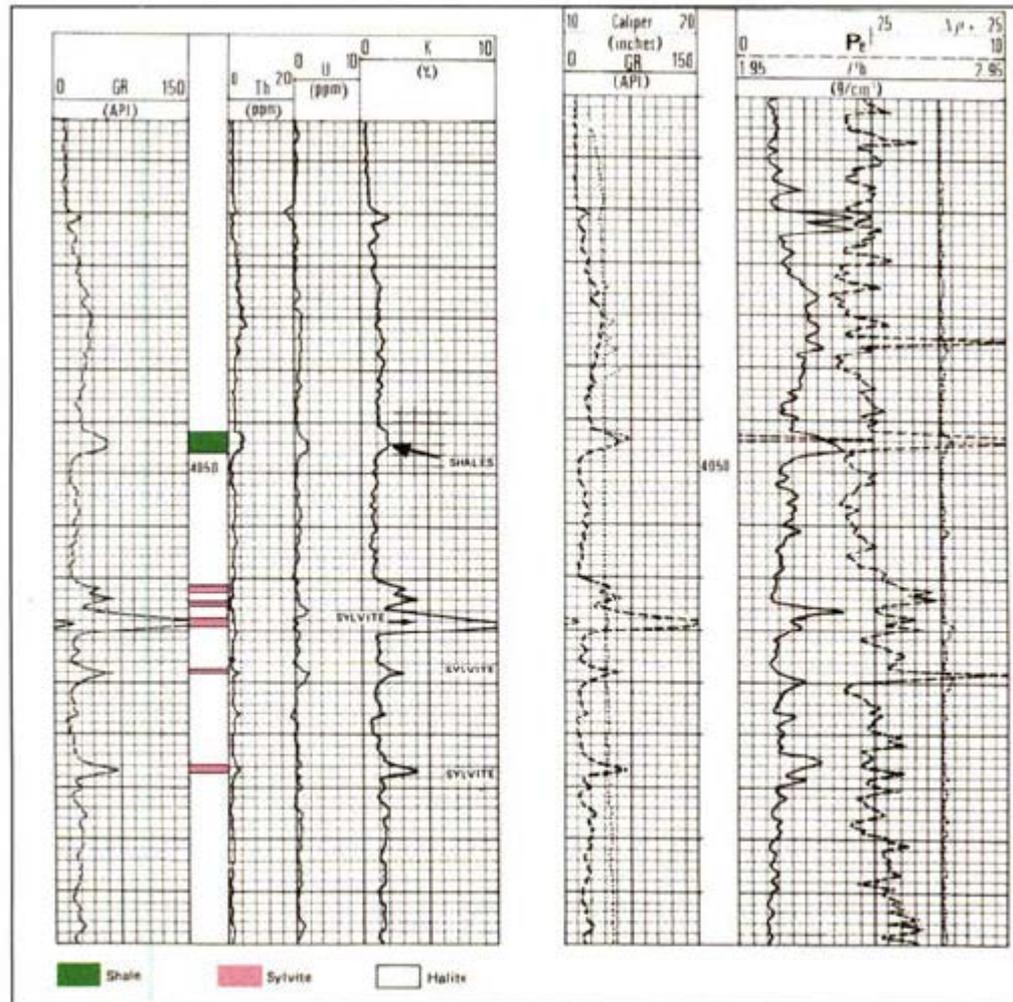
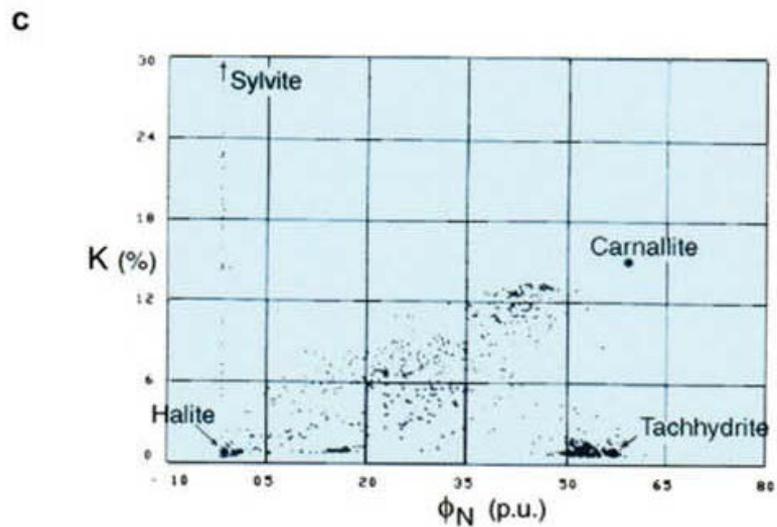
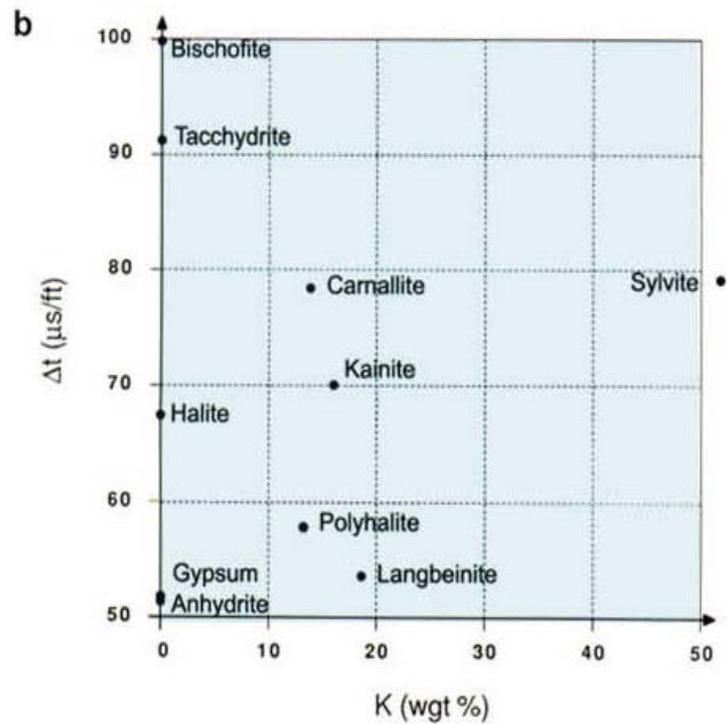
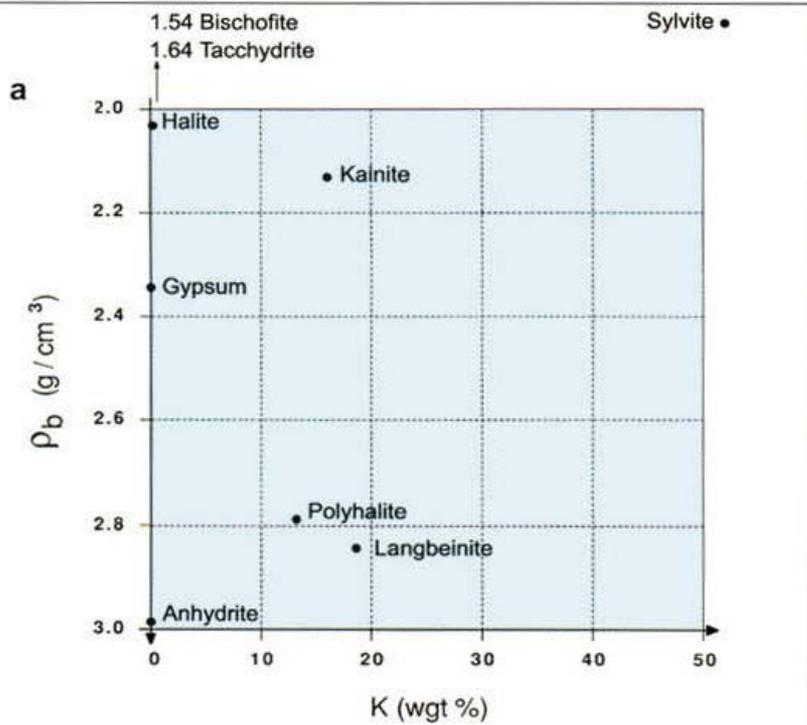


Figure 12-26 - Example of response in evaporite. Observe at 4065 the high potassium value (higher than 10%). It indicates the existence of sylvite in this halite interval. The sylvite presence is confirmed by the value of Pe in the uncaved zone.



- 2- Sand-shale series:
- Very often pure clean sands or sandstones exhibit very low radioactivity; because their thorium, uranium and potassium contents are very low too. They correspond to orthoquartzites.
- But sometimes sands or sandstones contain significant percentages of clay, are radioactive. In these cases, To compute a better shale percentage by using the shale indicators derived from the thorium or the potassium, or from their sum (CGR):

$$(V_{sh})_{Th} = (Th - Th_{min}) / (Th_{sh} - Th_{min})$$

$$(V_{sh})_K = (K - K_{min}) / (K_{sh} - K_{min})$$

$$(V_{sh})_{CGR} = (CGR - CGR_{min}) / (CGR_{sh} - CGR_{min})$$

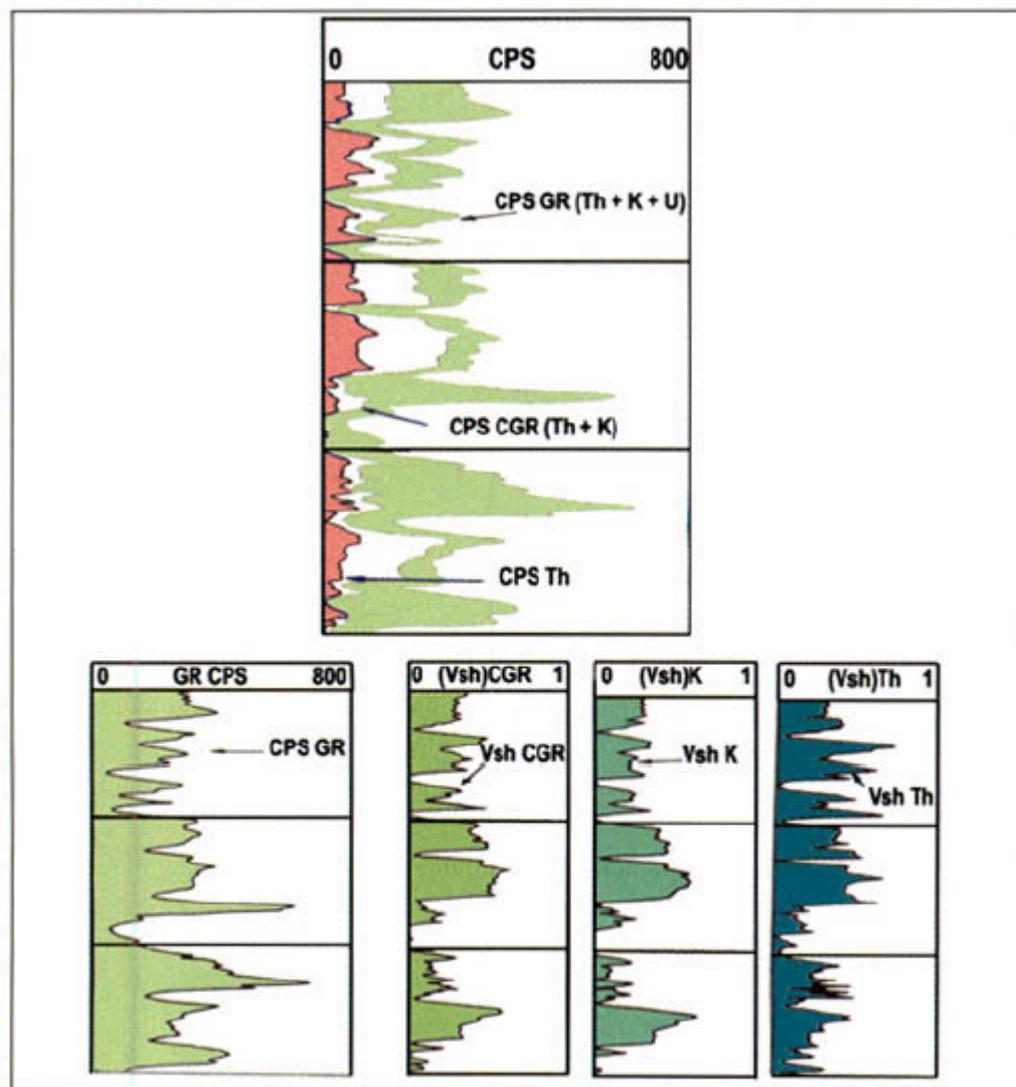


Figure 12-29 - (a) Formation response due to thorium, thorium and potassium; thorium, potassium and uranium. (b) Comparison of the three shale indicators with the total gamma ray (from Serra et al., 1980).

- *3- Feldspathic sandstones or arkoses:*
- They will show some potassium content – dependent on the feldspar percentage in the sands - due to the high percentage of potassium in feldspars.
- *4- Heavy minerals within sandstones:*
- Very often heavy minerals like zircon, allanite, monazite, and sphene are thorium and uranium-bearing, which give rise to some radioactivity in pure sandstones. This case is easy to recognize because the potassium level is generally very low, only the thorium and uranium curves being active. Consequently, this type of sandstone shows a very high Th/K ratio. At the same time  $\rho_b$  and the apparent matrix density ( $\rho_{ma}$ ) generally increase owing to the denser minerals present.

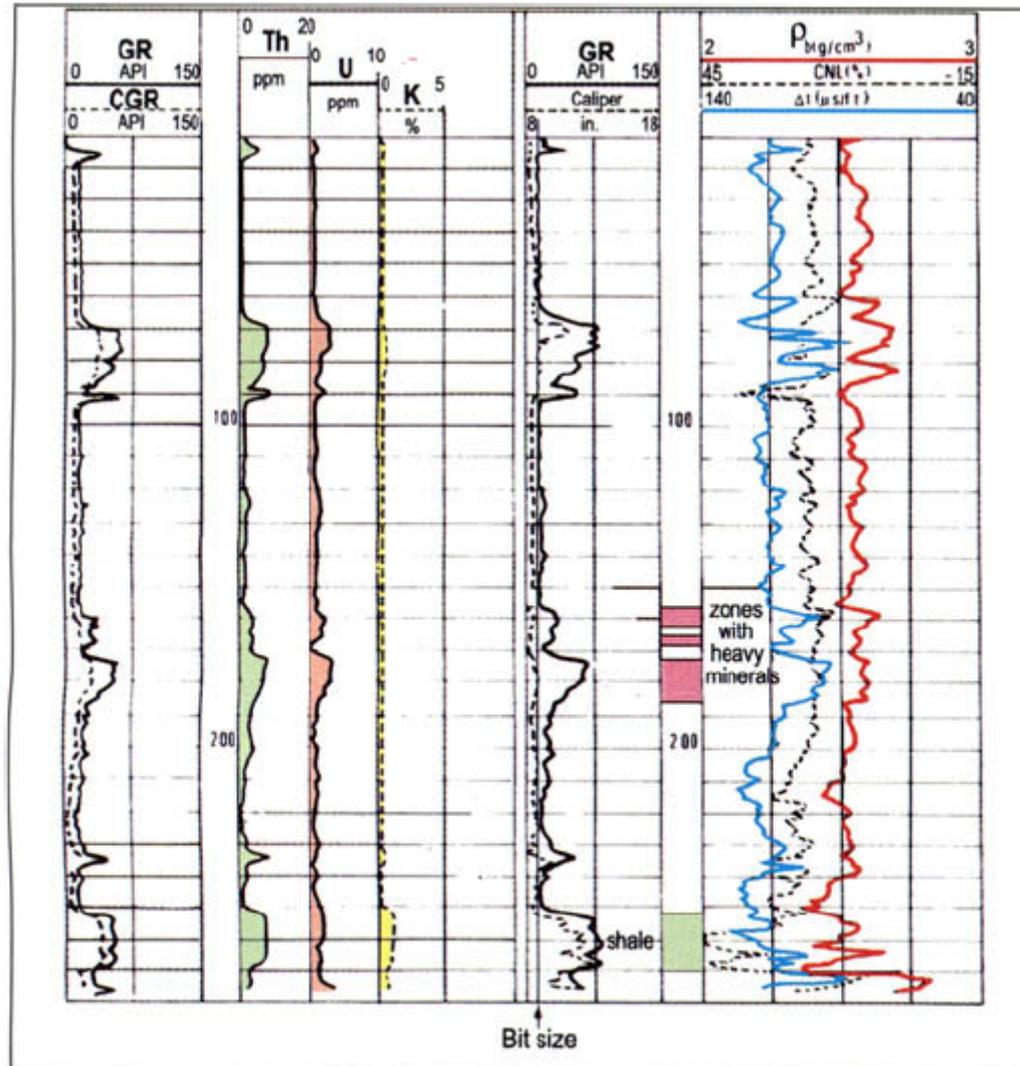


Figure 12-36 - Example of heavy mineral influence on thorium and uranium. Observe the very low potassium content and the increase of density while neutron does not change.

- 5- Shaly sands and sandstones:
- The combination of NGS and LDT\* data (P, or Uma) allows the determination of the clay mineral types present within the sands.

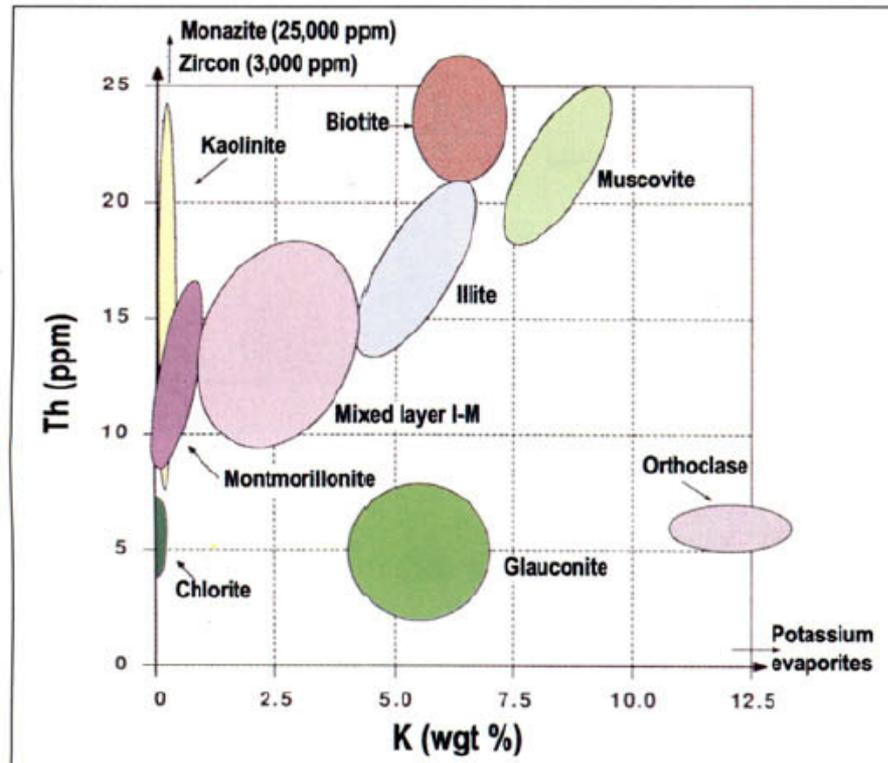


Figure 12-37 - Thorium vs potassium cross-plot with the position of the main radioactive minerals. These minerals are represented by ellipses to indicate that their elemental composition can vary in relation with the importance of the weathering.

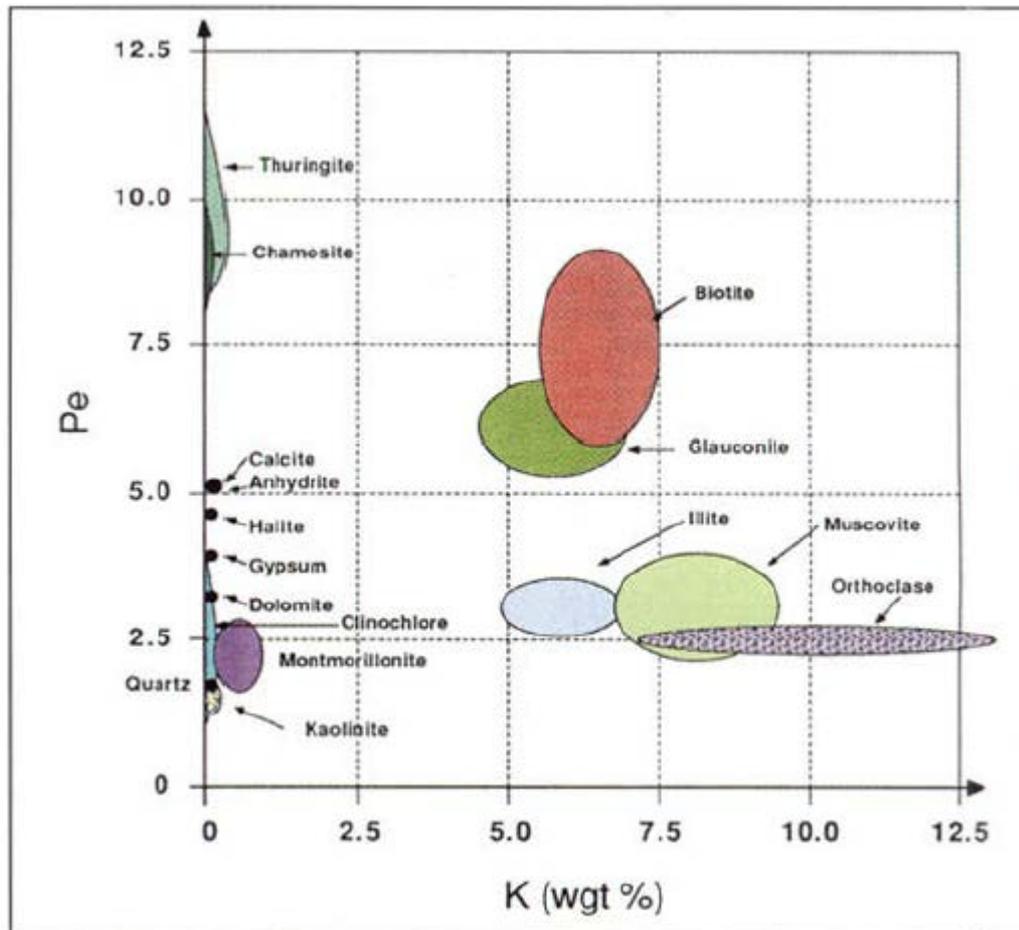


Figure 12-38 - Pe vs potassium with the position of the main minerals.

- 6- Carbonate series:
- In these rocks the standard gamma ray is very often a poor clay indicator, because the observed radioactivity is not related to clay content of the rock, but to the presence of uranium. In a pure carbonate of a chemical origin, the thorium will be absent, since it is insoluble. So, if the spectrometry measurement shows a carbonate level with thorium and potassium near zero this corresponds to a pure carbonate. If at the same time the uranium is zero too, this carbonate was precipitated in an oxidizing environment

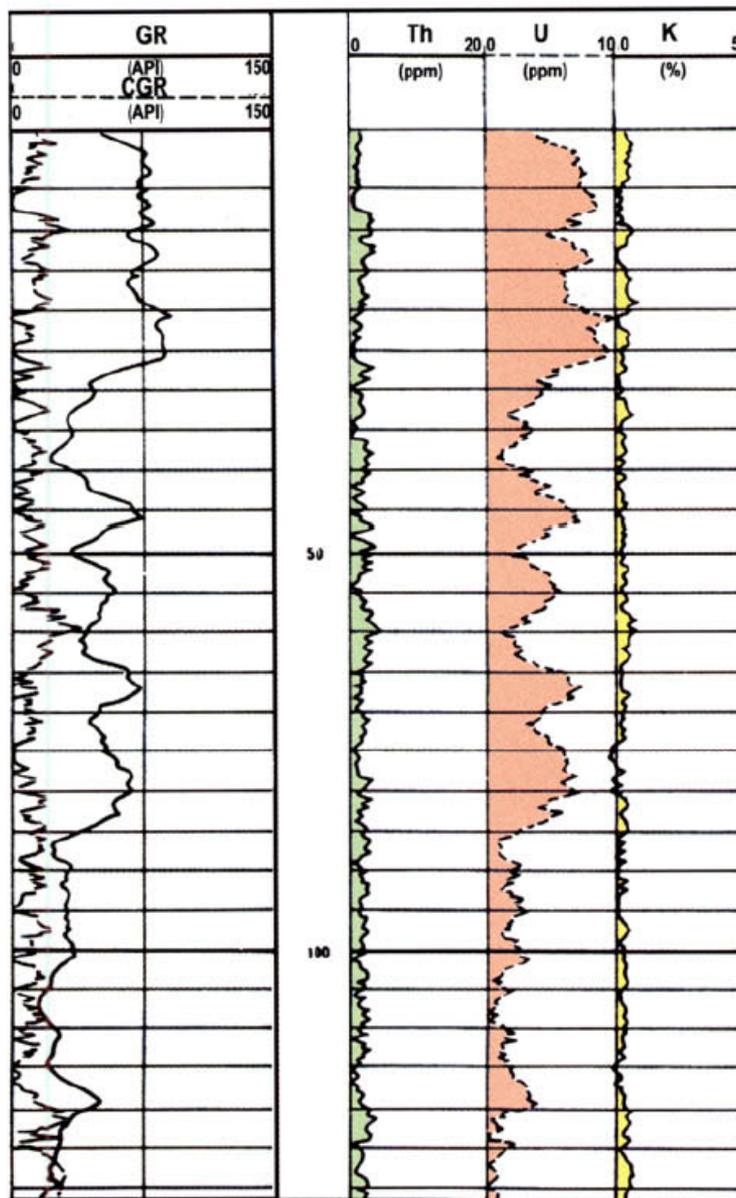


Figure 12-40 - Example of NGS response in a carbonate series showing that the radioactivity is mainly due to uranium. The thorium/uranium ratio is in many places lower than 2.

- If the levels show a variable percentage of uranium, the corresponding carbonate can either have been deposited in a reducing environment (restricted), generally favorable also to the conservation of organic material and to its transformation into hydrocarbon; or, if it is compact (low porosity) it corresponds to a carbonate with stylolites, in which impurities such as uranium, organic matter and even clay minerals, are concentrated. Peaks of uranium can also correspond to phosphate-bearing levels. If Th and K are present with uranium, this indicates the presence of clays in the carbonate (clayey carbonates to mark). If K is present with or without uranium it can correspond to a carbonate of algal origin or a carbonate with glauconite.

- Well-to-well correlations:
- As the gamma ray, the natural radioactivity spectrometry is very usefull for correlations either of facies or chronostratigraphic. Particularly, peaks on thorium curves are often used for well to well correlations. as they correspond generally to volcanic ashes (or bentonitic levels) and, consequently, can be considered as deposited at exactly the same time over a wide area (Lock & Hoyer, 1971).

- Detection **of** unconformities:
- Abrupt changes in the mean thorium/potassium ratio are generally indicative of important variations in the proportion of radioactive minerals which occur when there are changes in geological conditions of deposition. These correspond to unconformities.

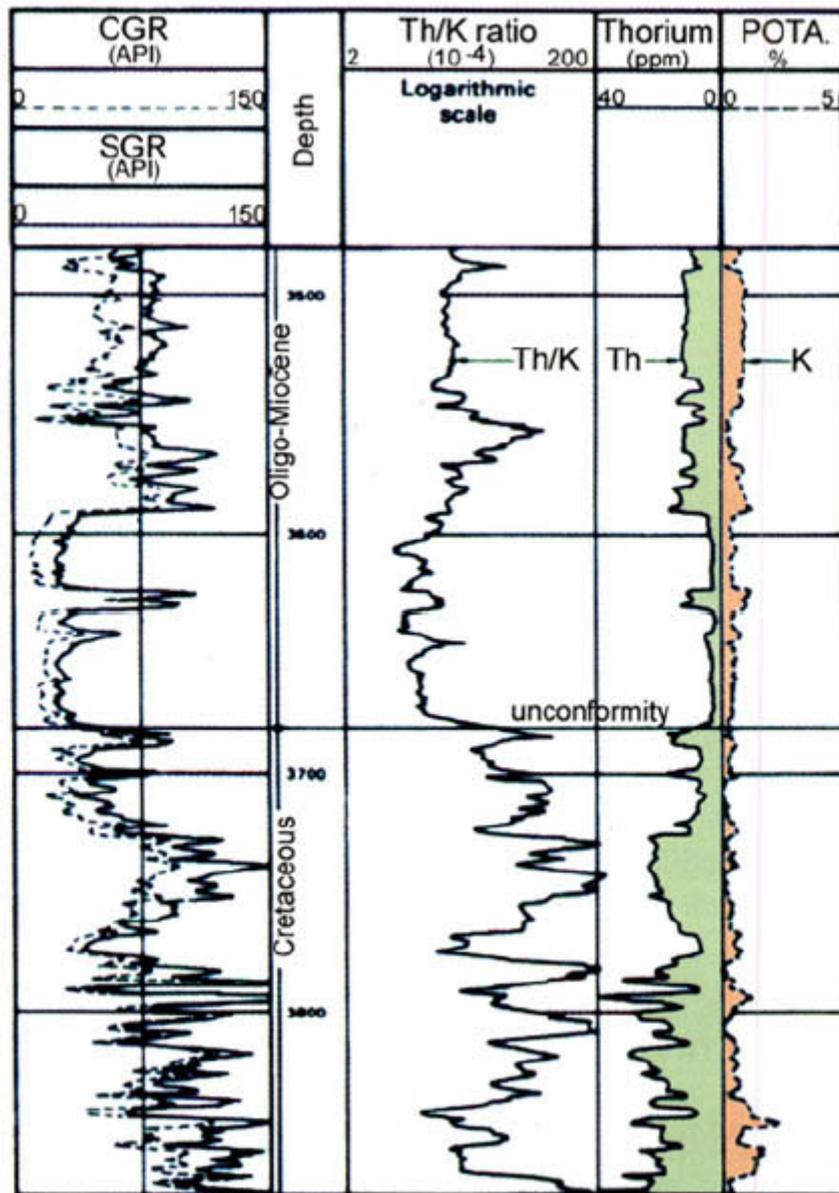


Figure 12-41 - Unconformity detected by the NGS and not easily seen on other logs (from WEC, Venezuela, 1980).

- **Fracture and stylolite detection:**
- In reducing conditions the circulation of hydrothermal or underground waters in fractures may cause precipitation of the uranium salt, uraninite. So fractures can be recognized by peaks of uranium. The presence of fractures must be confirmed by other methods because uranium is often associated with stylolites: during compaction, insoluble impurities (clay minerals, organic matter, iron oxides ... ) are often concentrated in very thin layers called stylolites, which can also give radioactive peaks

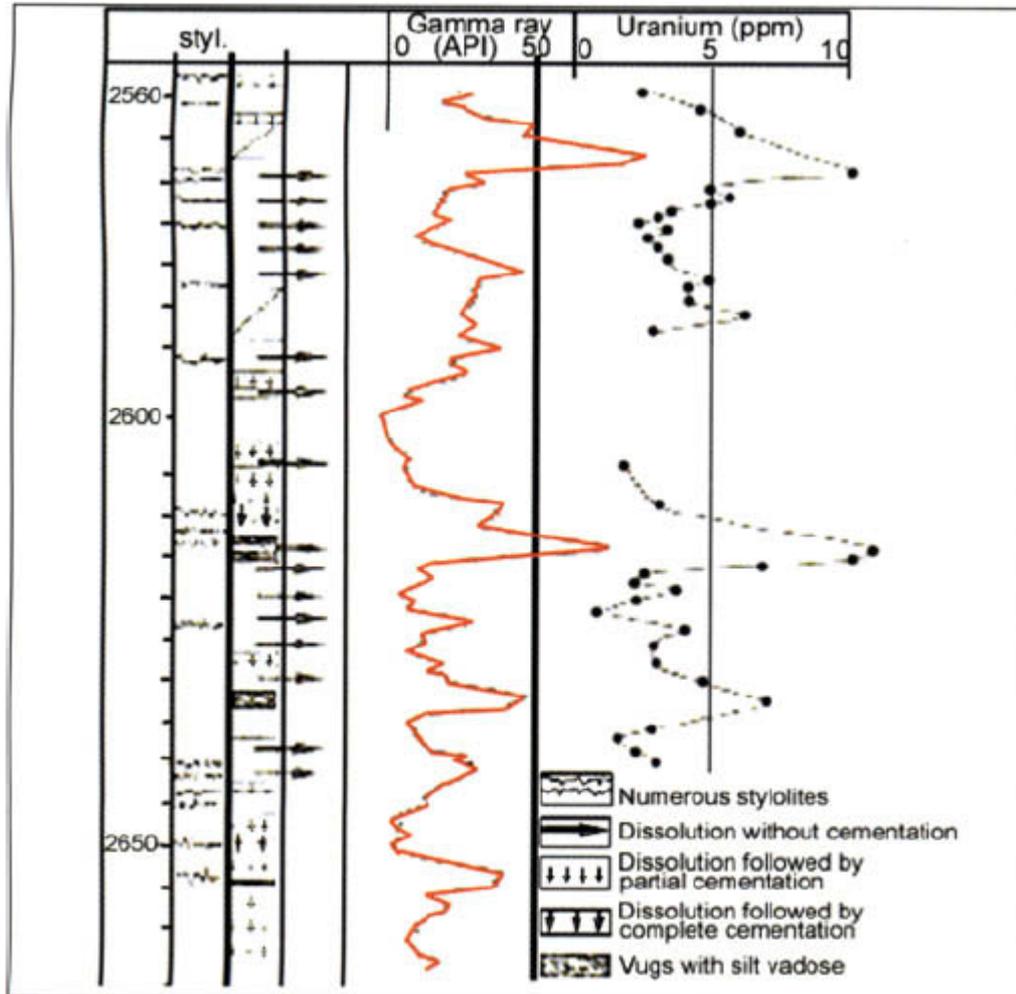


Figure 12-42 - Example of stylolites detected by uranium peaks confirmed by measurements realized on core (from Hassan et al., 1976).

- Igneous rock recognition:
- Except for syenite, most of the intrusive igneous rocks show a Th/U ratio close to 4. Deviations from this value seem to indicate weathering effects during which uranium is dissolved and eliminated by rain and running waters; or oxidizing conditions before crystallization of magma; or intrusions of basic igneous rocks.

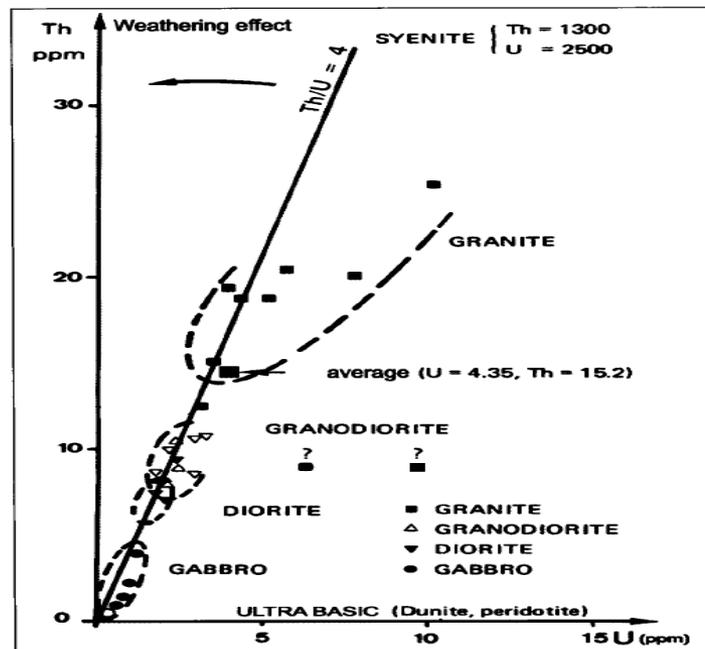


Figure 12-46 - Thorium vs uranium cross-plot for the main igneous rocks.

- **Diagenesis:**

- Under compaction, montmorillonite is transformed into illite, passing through an intermediate mixed-layer illitemontmorillonite phase (Hassan *et al.*, 1976). This results in a decrease of the Th/K ratio with depth. In undercompacted shales this trend will be reversed.

# Logging & source rock

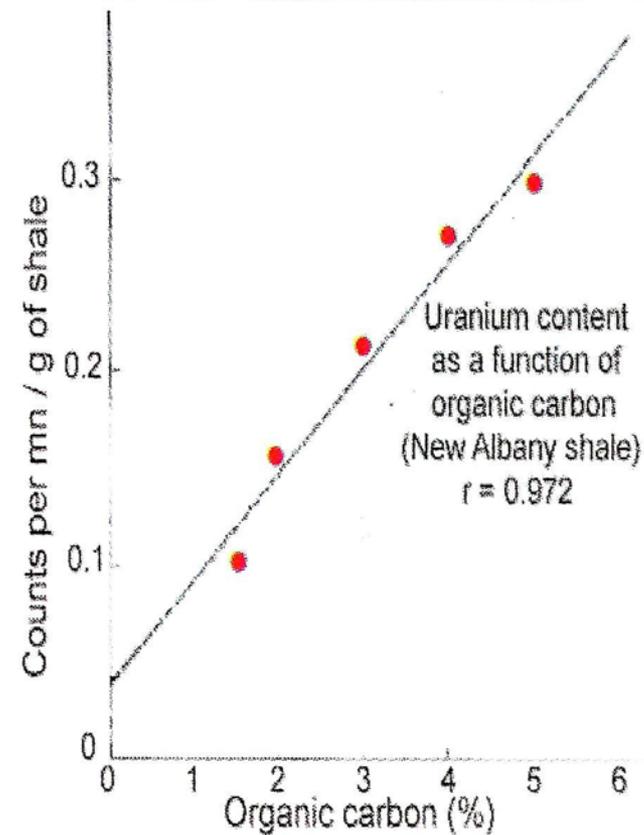
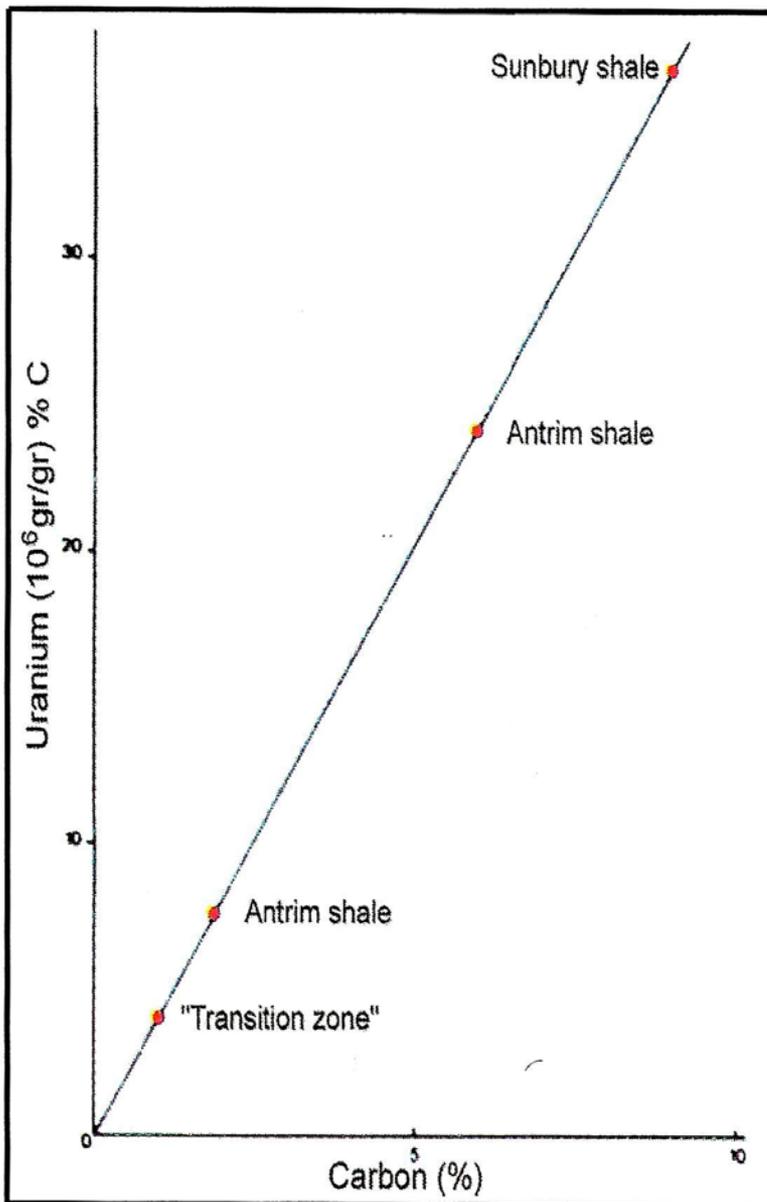
- در این جا ما می خواهیم پتانسیل هیدروکربن زایی حوضه رسوبی را آنالیز کنیم.
- این آنالیز با مشخص کردن محل سنگ منشا و ارزیابی خواص ژئوشیمیایی آن آغاز می شود.
- معمولا سنگ های مادر شیلی می باشند و متاسفانه نمی توان از آنها **core** تهیه کرد ولی **side wall**
- **core** می توان تهیه کرد که نقاط اطلاعاتی است و طیف اطلاعاتی نمی باشد.
- در ادامه ما به بررسی راه های گوناگونی که توسط **logging** برای رسیدن به سنگ مادر داریم می پردازیم.

# The carbolog method

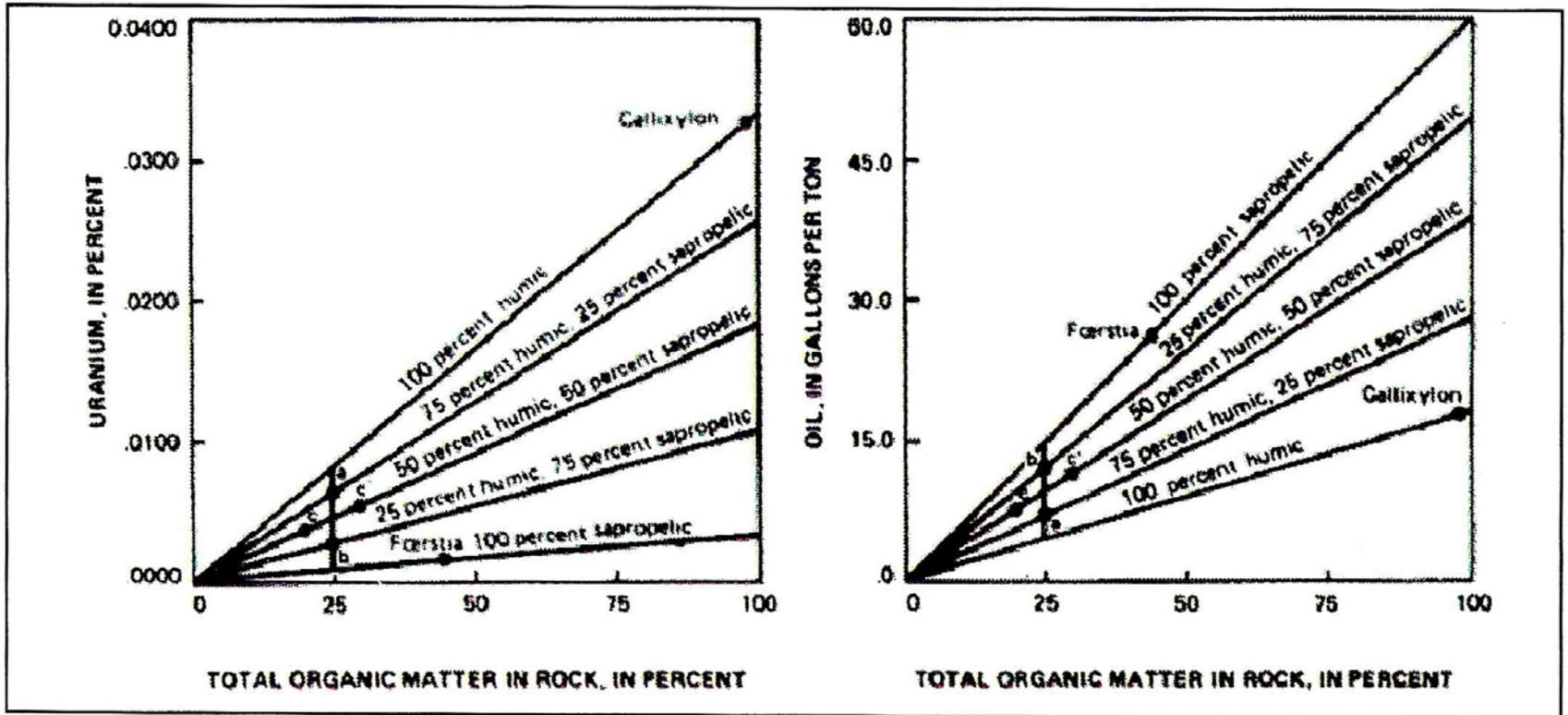
- این تکنیک در سال 1989 توسط carpenter و همکاران ابداع شد.
- این روش ، روشی سریع و با کیفیت می باشد.
- این روش نیاز دارد که برای هر حوضه رسوبی به طور جداگانه کالیبره شود.

# The uranium concentration

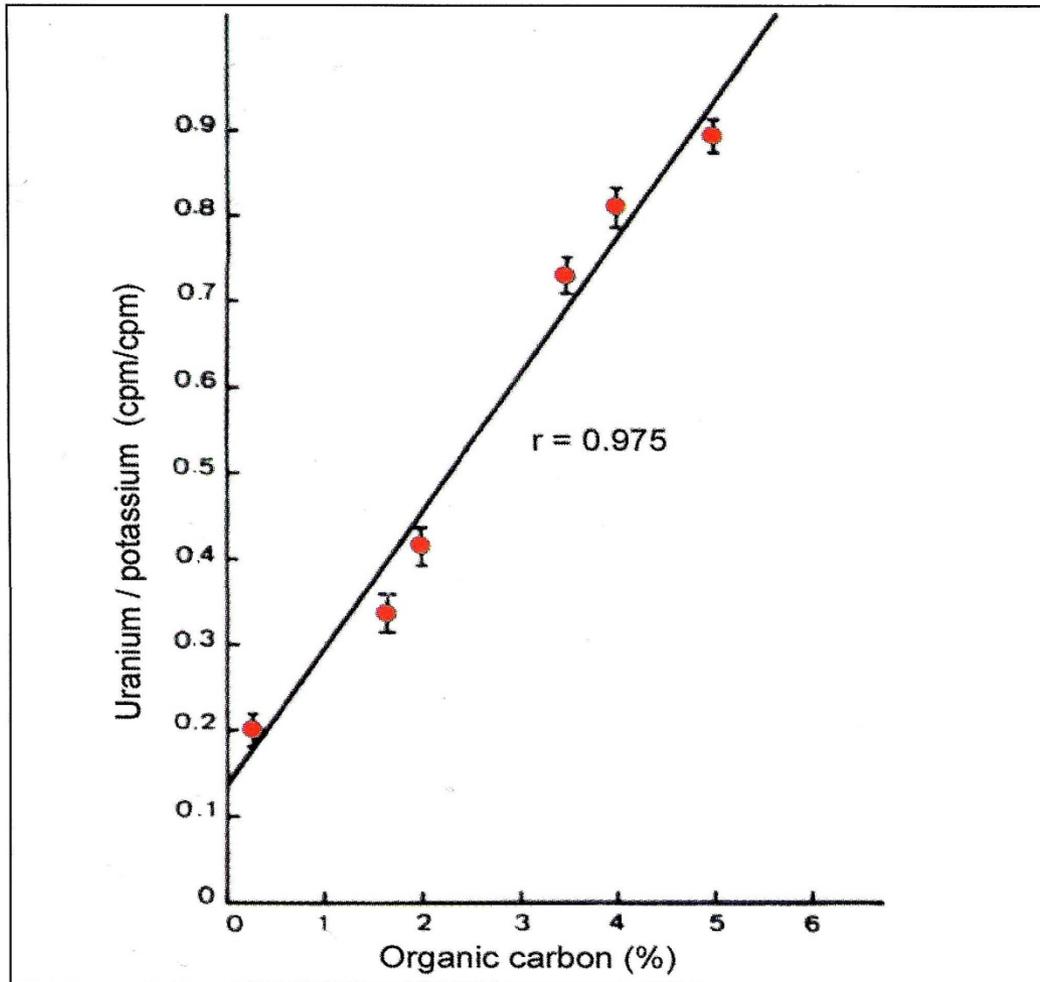
- محیط آبیایی که برای تبدیل مواد آلی به نفت لازم است ، محیطی مناسب هم برای تجمع اورانیوم می باشد.
- وجود باکتری و اسید هومیک باعث می شود که یون های محلول اورانیوم به مواد نامحلول تبدیل شود.
- بر اساس کارهای افراد بسیاری يك سري نمودار برای مشخص کردن مقدار مواد آلی براساس مقدار اورانیوم پیشنهاد شده که در زیر آنها را مشاهده می کنید.



*Relation between uranium and organic carbon in sedimentary rocks (from Beers & Goodman, 1944).*

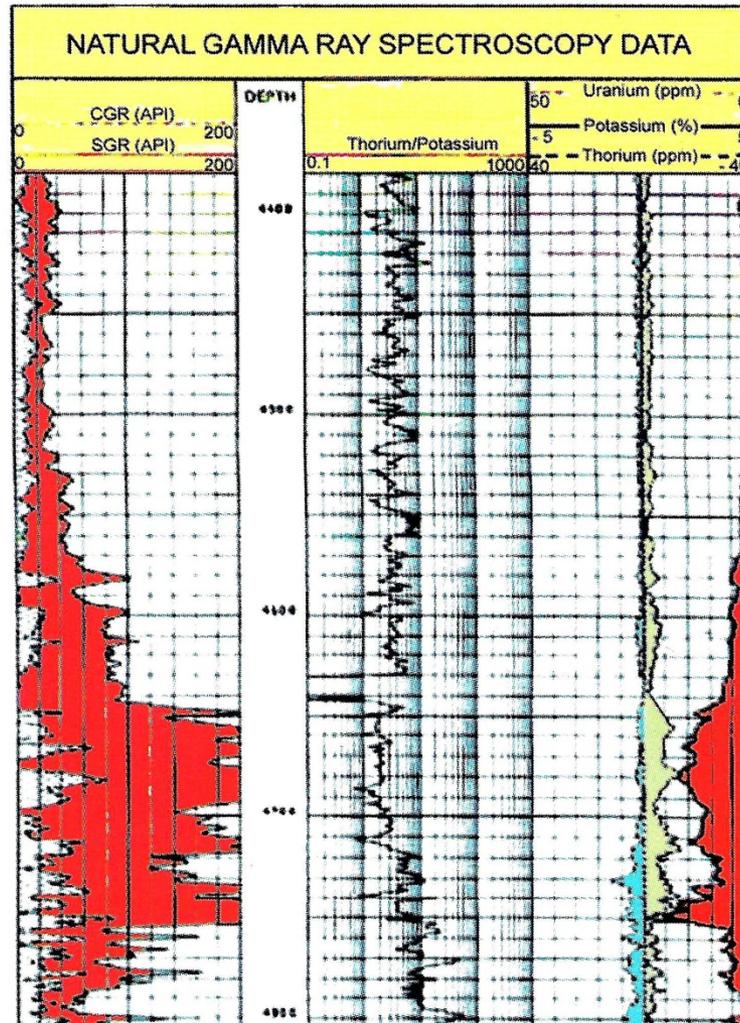


*On the left: diagram showing possible relation of uranium content to total organic matter as controlled by the proportion of humic and sapropelic material making up the organic matter. On the right: oil yield of a marine black shale as a function of the total organic matter (from Swanson, 1960).*



*Relation between uranium (expressed as a uranium/potassium ratio) and organic carbon (from Supernaw et al., 1978).*

- علاوه بر این می توان در روی نمودارها گفت که مقادیر بالای اورانیوم نشانه ی سنگ منشا می باشد.

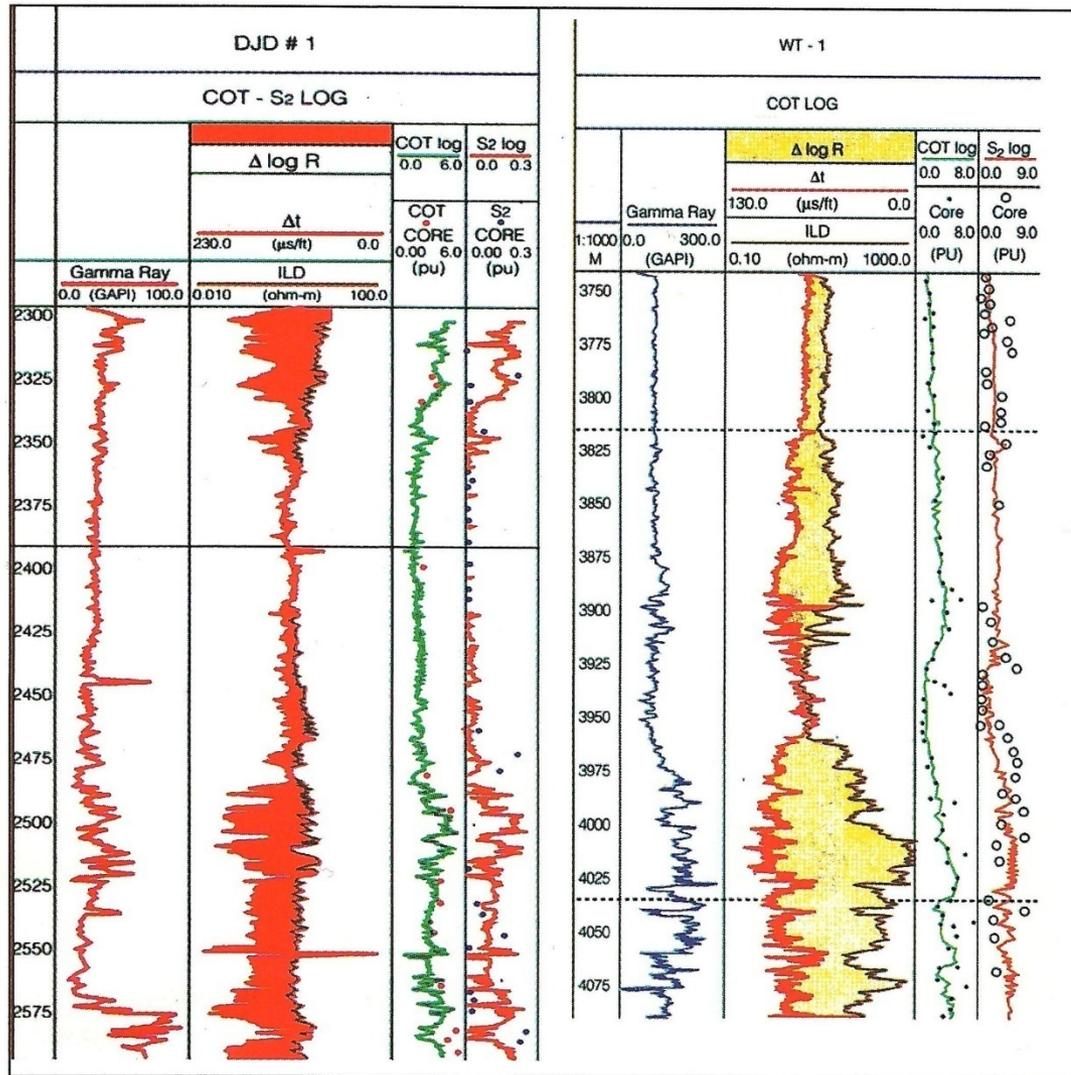


*Example of formation very rich in uranium as shown by the natural gamma ray spectrometry data. It may correspond to a potential source rock (courtesy of Schlumberger).*

# The $\Delta\log R$ method

- این متد توسط ژئولوژیست های Exxon پیشنهاد شد.
- این نمودار ترکیبی از نمودار صوتی و نمودار مقاومت می باشد که نتایج با توجه به Level of organic metamorphism units (LOM) تفسیر می شود.
- نمودار  $\Delta\log R$  وقتی حاصل می شود که نمودار صوتی را در مقیاس لگاریتمی رسم کرده و در همان ستون نمودار مقاومت را به صورت خطی رسم کرده ، حال جدایش بین این دو نمودار ، نمودار  $\Delta\log R$  می باشد.
- مناطقی که این دو نمودار روی هم قرار بگیرند (base line) ناحیه ی non – source می باشد.
- مقدار  $\Delta\log R$  از رابطه ی زیر محاسبه می شود.

$$\Delta\log R = \log_{10} (R/R_{\text{base line}}) + 0.025(\Delta t - \Delta t_{\text{base line}})$$



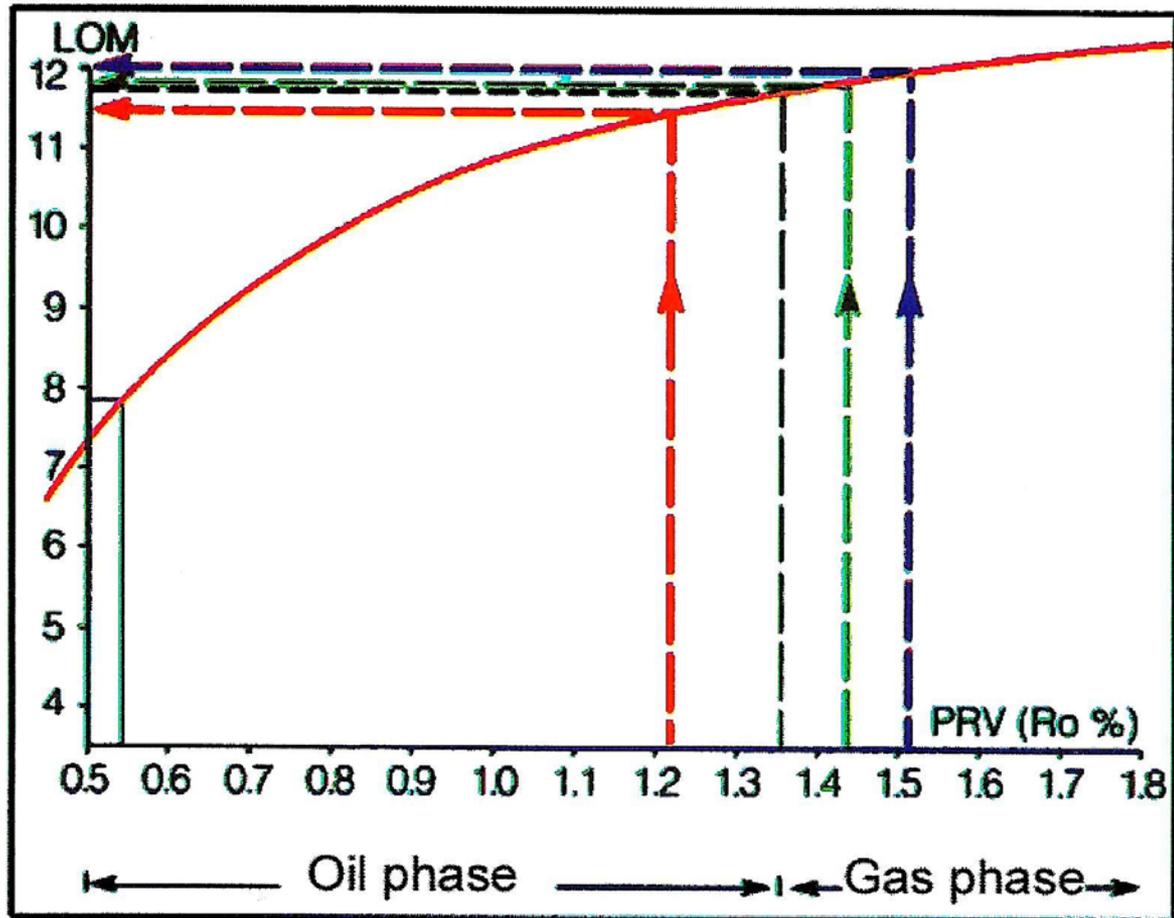
Two example of  $\Delta \log R$ , TOC and  $S_2$  curves determined on 2 wells of Algeria (from Malla & Baci, 1995).

- براي مشخص کردن TOC از نمودار  $\Delta \log R$  بايد مقدار LOM مشخص باشد.
- براي يافتن LOM نياز به دانستن  $R_o$  داريم و با دانستن  $R_o$  مي توان توسط نمودار زير LOM را بدست آورد.
- مقدار  $R_o$  را توسط آزمایشگاه بدست مي آوريم و يا توسط ابزار nuclear fission trace بدست آورد.
- براي مقادير مختلف LOM داريم:

0 to 7.5 : immature

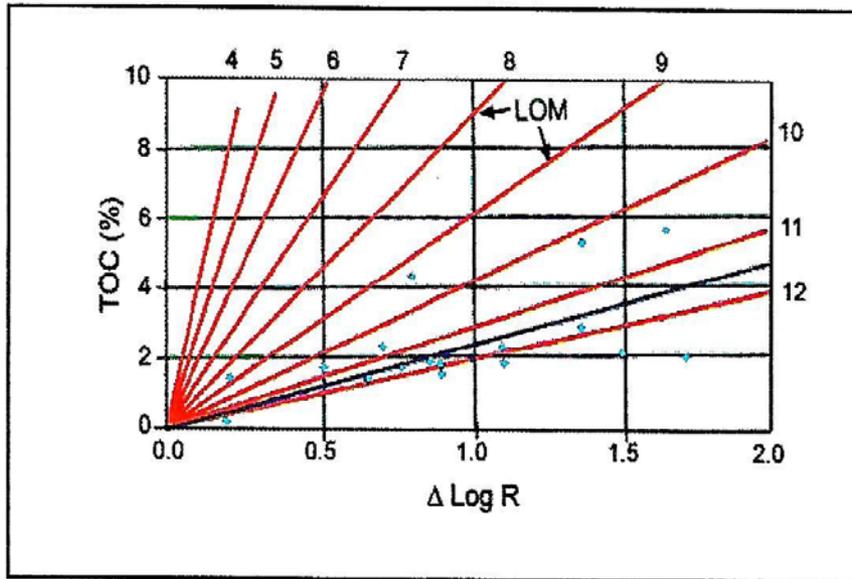
7.5 to 11.5 : oil phase

> 11.5 : gas phase



*The value of LOM, determined from measured PRV equivalents for well DJD-1, was calculated at 11.5 (from Malla & Baci, 1995).*

• با دانستن  $\Delta \log R$  و LOM ، TOC از نمودار زیر بدست مي آيد.

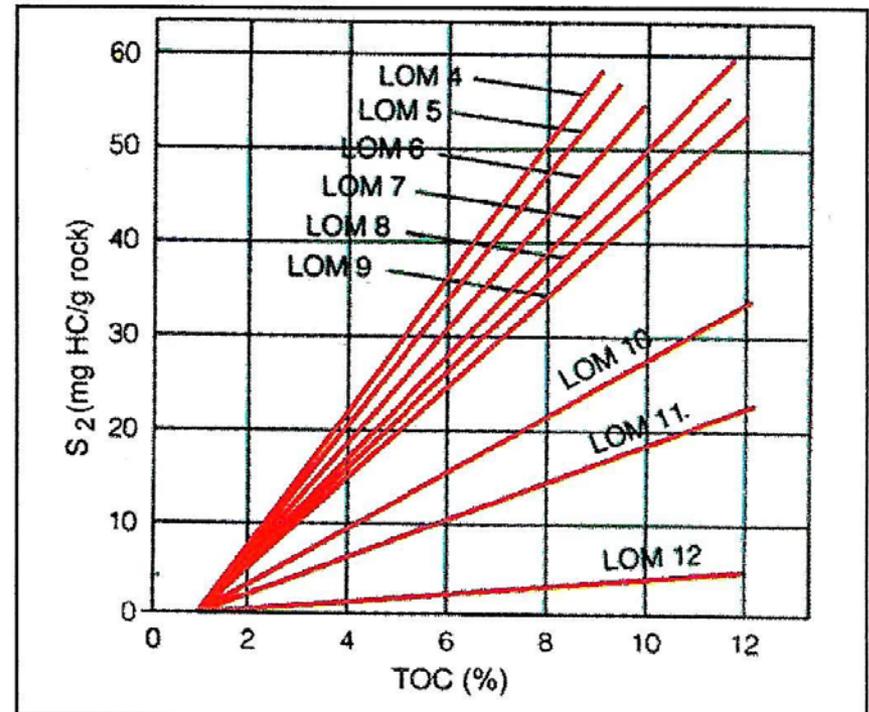


*Chart to allow the determination of TOC from  $\Delta \log R$  separation and LOM (from Malla & Baci, 1995).*

• پارامتر (S<sub>2</sub>) hydrocarbon generation potential را می توان از نمودار زیر بدست

آورد.

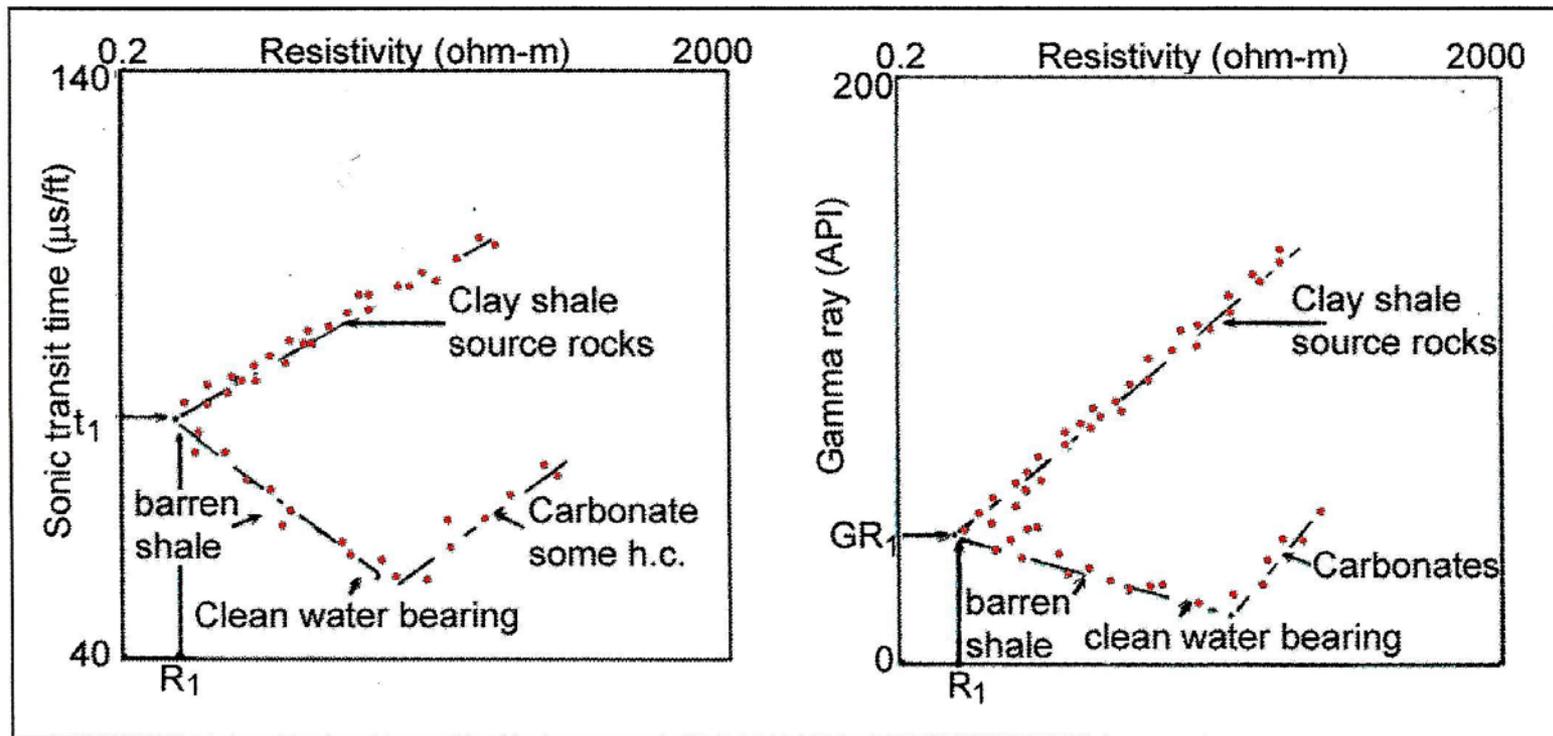
*Determination of S<sub>2</sub>  
from TOC and LOM for type II  
(oil-prone) kerogen  
(from Malla & Baci, 1995).*



# Method based on cross - plot

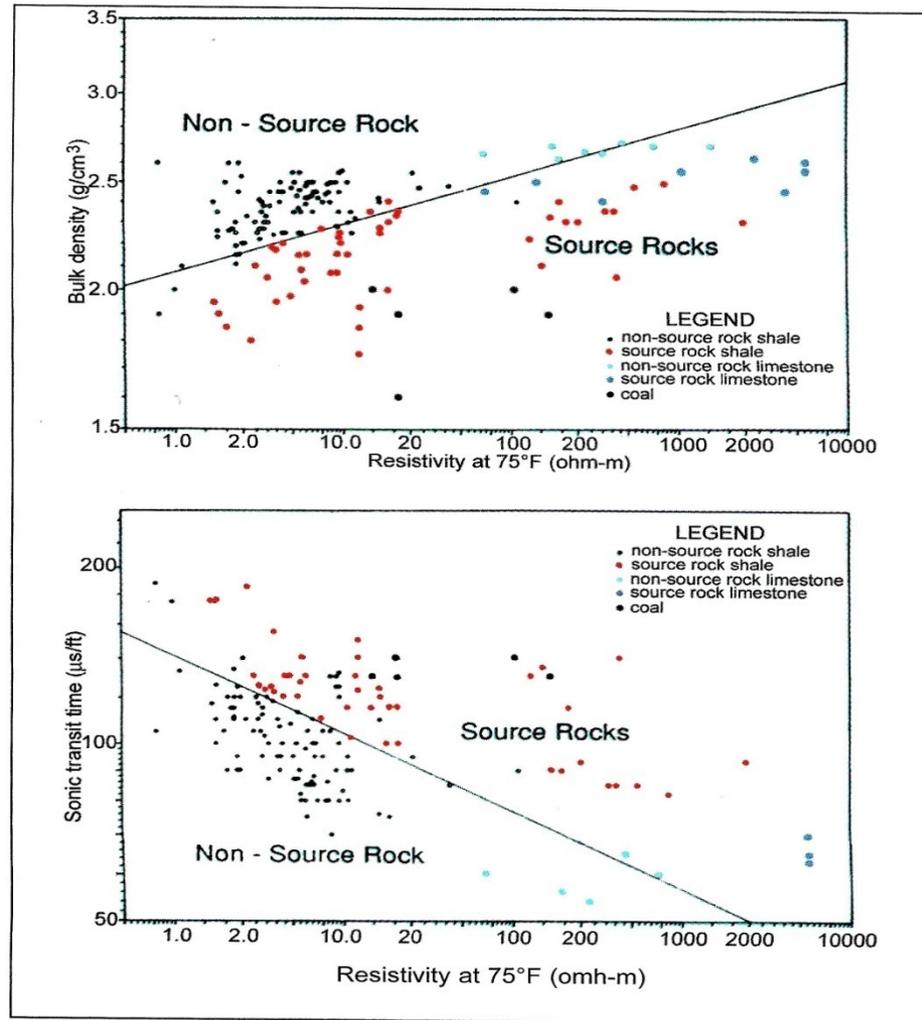
- این روش بر اساس اثر مواد آلی بر واکنش ابزار نسبت به مواد آلی بنا نهاده شده است.
- مواد آلی هادی نمی باشند ، در نتیجه باعث افزایش مقاومت می شوند.
- دانسیته مواد آلی بین 0.95 تا 1.05 است و با دانسیتهی سنگ ها متفاوت است.
- زمان عبور مواد آلی حدود 180 میکرو ثانیه است.
- واکنش نسبت به نوترون در مواد آلی حدود 67 p.u می باشد ولی در مینرال های شیل کمتر از 50 p.u می باشد.
- حضور مواد آلی باعث افزایش GR می شود.
- حال به ارائه ی cross – plot ها ی پیشنهادی می پردازیم.

• Dumesnil و Autric در سال 1985 از نمودار صوتي ويا گاما بر حسب مقاومت نمودارهاي زير را پيشنهاده کردند.



*Characterization of source rocks by cross-plots combining sonic transit time and resistivity (left diagram), or gamma ray and resistivity (right diagram) (from Autric & Dumesnil, 1985).*

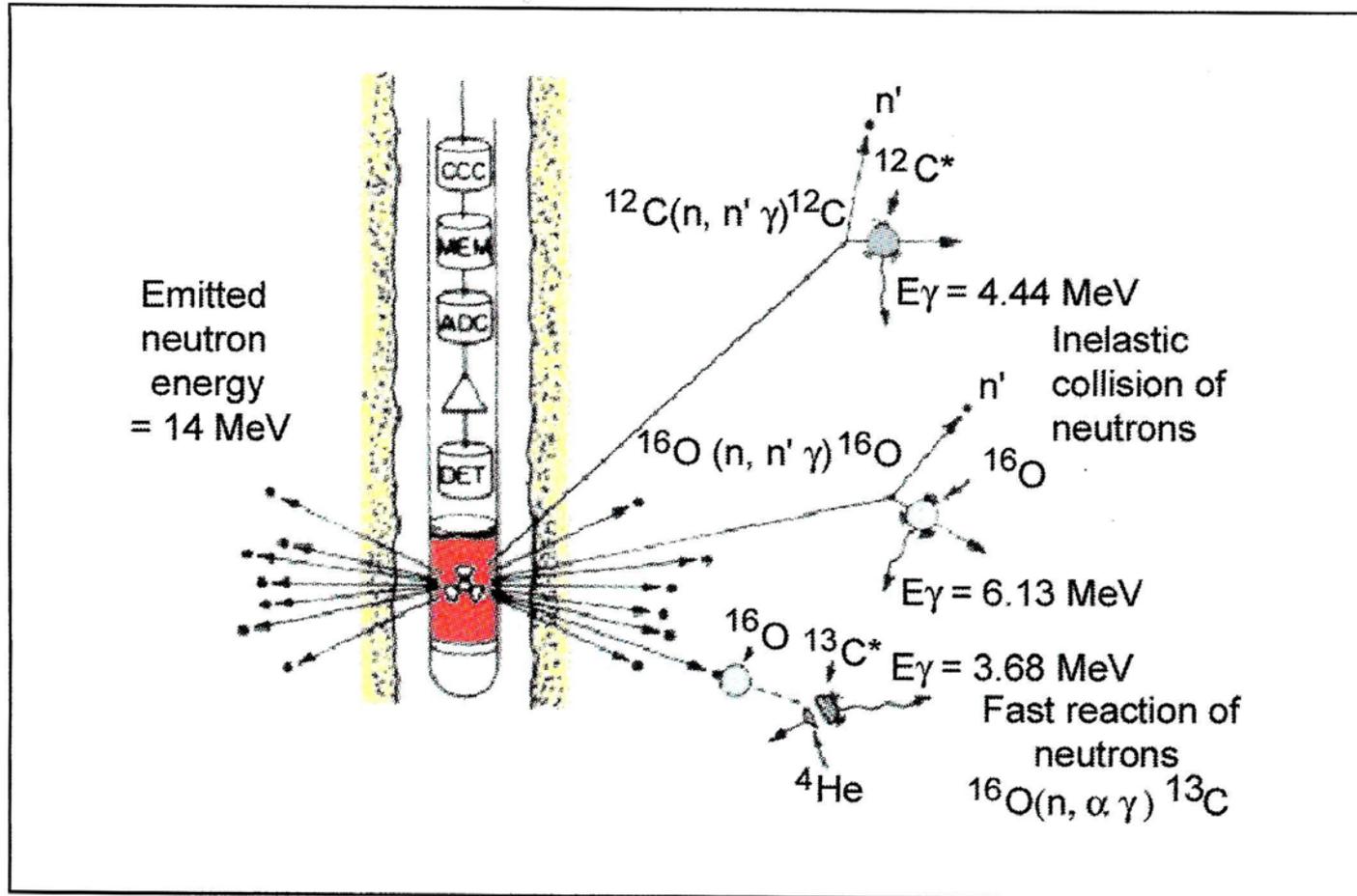
• Meyer و Nederlof در سال 1984 نمودارهایی زیر را پیشنهاد کردند.



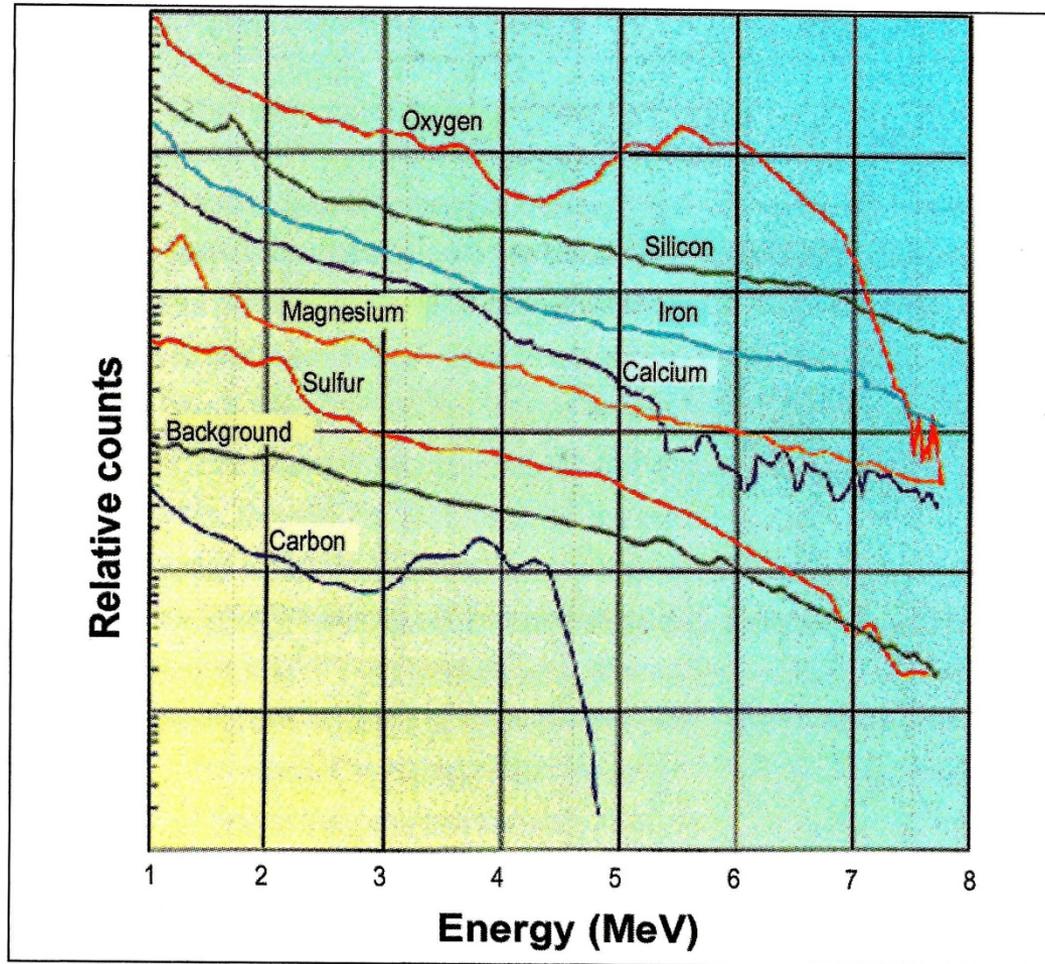
*Bulk density-resistivity cross-plot and sonic-resistivity cross-plots allowing the identification of source rocks (from Meyer & Nederlof, 1984).*

# Method based on nuclear measurement

- این روش براساس محاسبه ی  $C/O$  می باشد.
- رفتار هر عنصر در برخورد نوترون پرنرژی با خودش متفاوت می باشد و بر این اساس می توان کربن و هیدروژن موجود در سازند را بر این اساس مشخص کرد.
- در زیر این واکنش را برای چند عنصر مشاهده می کنید.



*Example of interactions between high energy neutrons and C and O atoms (courtesy of Schlumberger).*



*Typical Inelastic collision spectrum. Observe the peaks of Oxygen and Carbon. They are more characteristic and so can be easily detected by window energy detection collimated around these peaks (courtesy of Schlumberger).*

- این روش توسط Herron در سال 1986 بیان شد و برای یافتن **total organic carbon** باید دو موضوع زیر را اصلاح کرد.

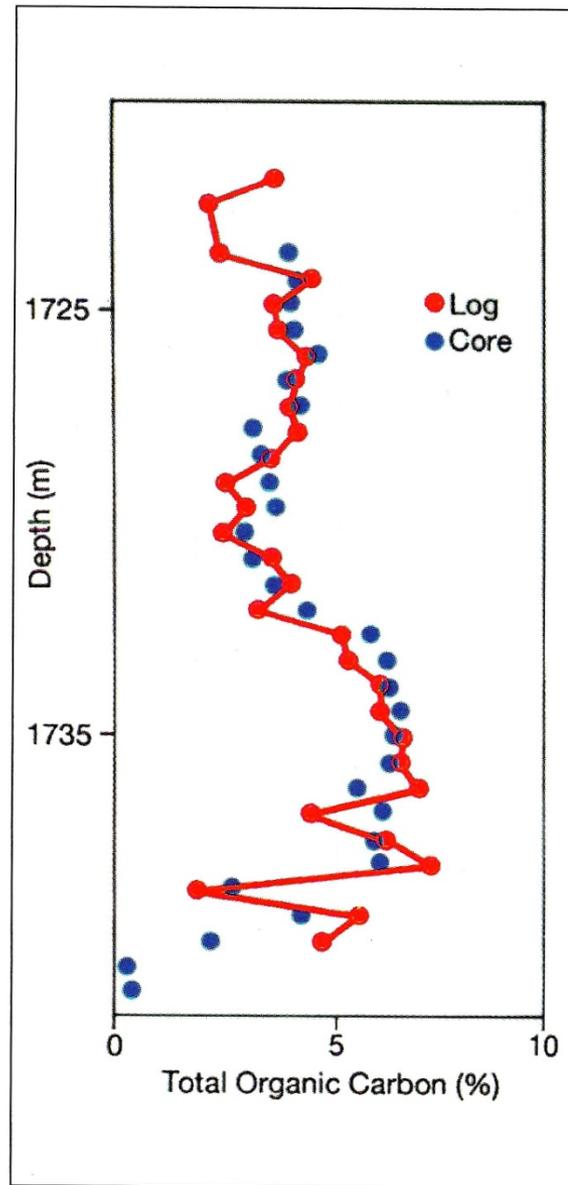
1. مقدار  $O$  موجود در سنگ ، این موضوع راحت حل می شود در صورت این که لیتولوژی به طور کامل شناخته شده باشد.

2. اصلاح کربن غیر آلی موجود در سازند همانند کربن کلسیت یا دولومیت.

- با اصلاح دو موضوع بالا می توان به راحتی کربن آلی موجود در سازند را مشخص کرد.

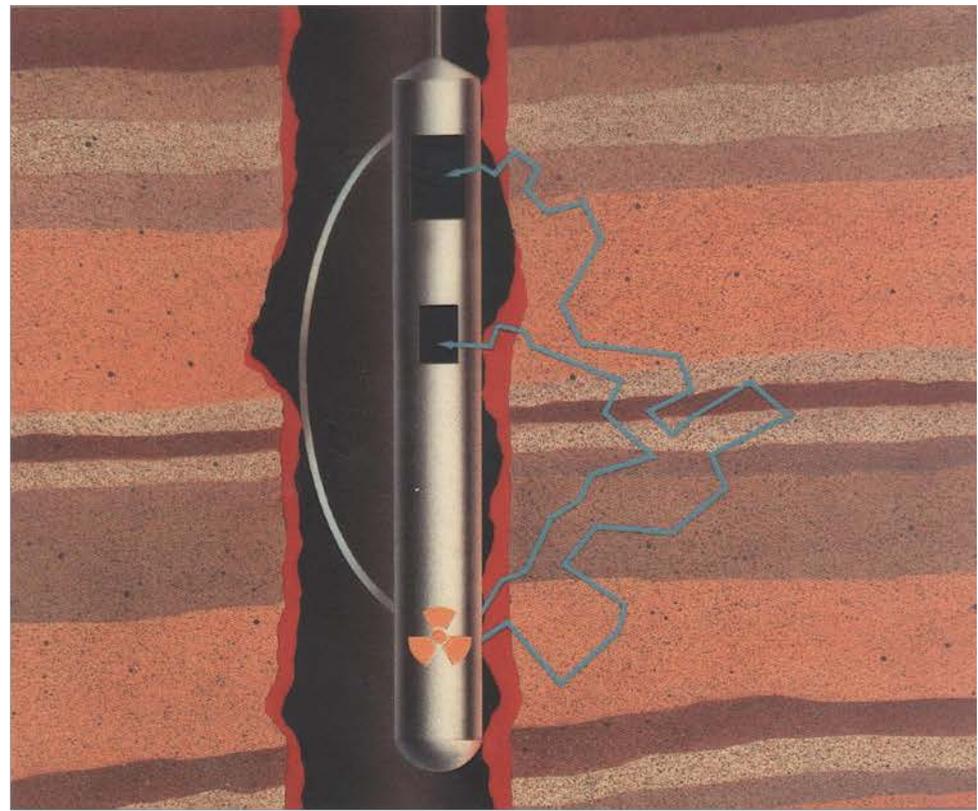
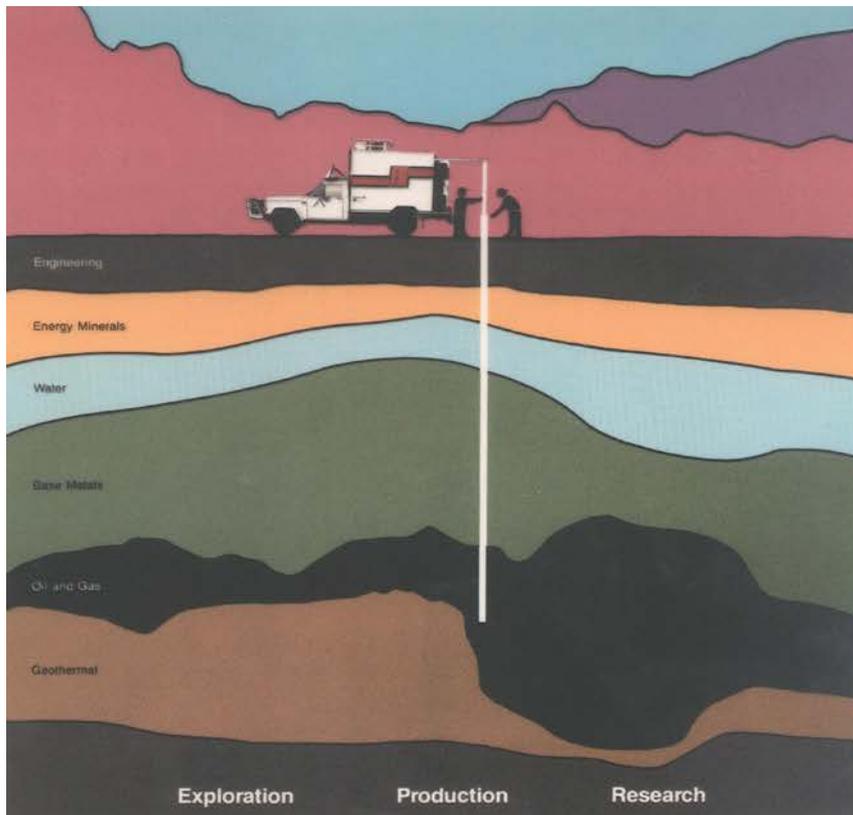
- در شکل زیر این موضوع را برای نمونه ای مشاهده می کنید و نتایج را با نتایج **core** مقایسه کرده ایم . مشاهده می کنید که این نتایج بسیار به هم نزدیک می باشد.

- این روش نیاز به کالیبره شدن توسط نتایج **core** را ندارد ، ولی متأسفانه هزینه ی زیادی دارد در نتیجه خیلی استفاده نمی شود.



*Evaluation of the organic carbon content through the measurement of the carbon-oxygen ratio (from Herron et al., 1988).*

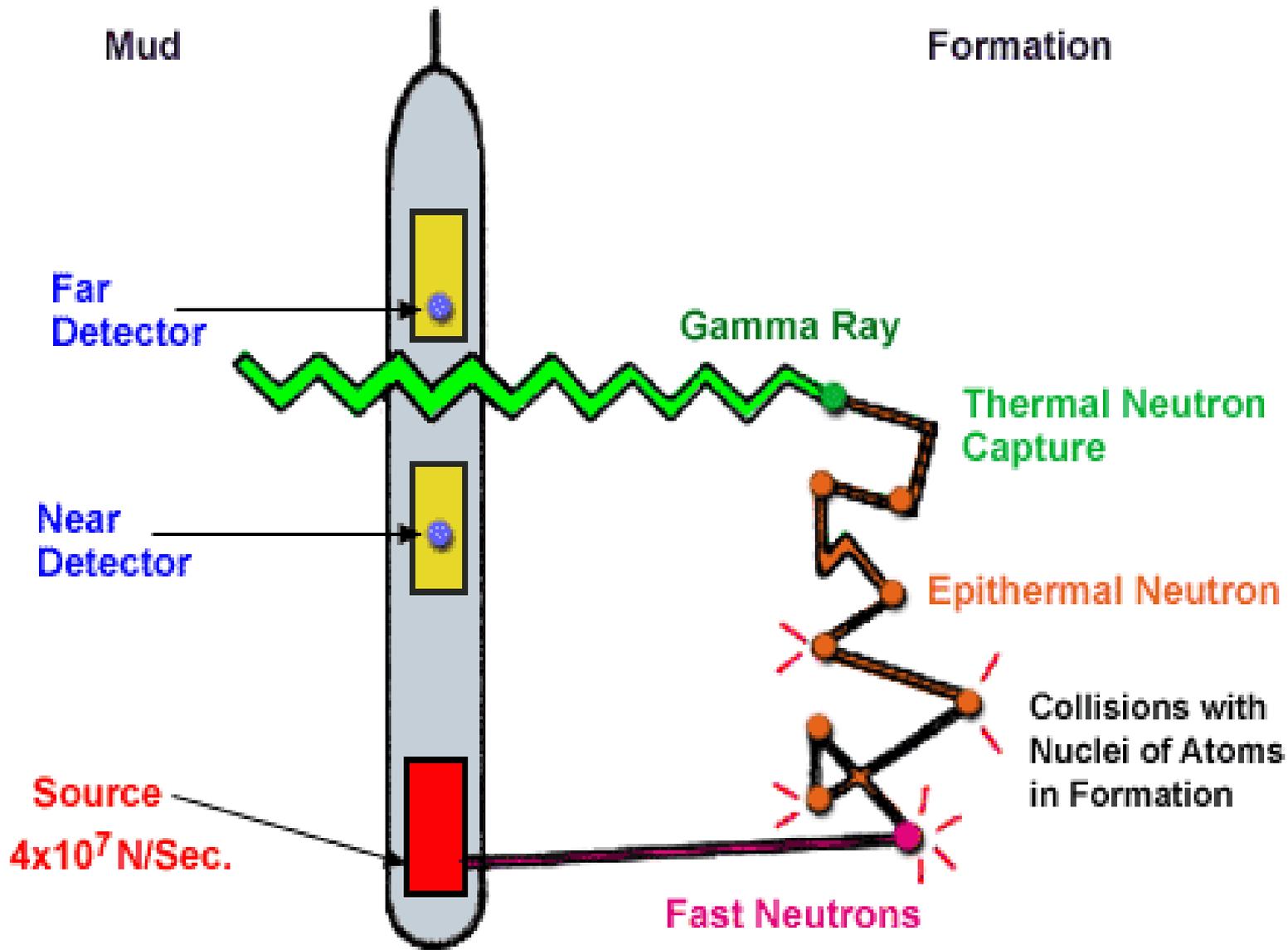
# Neutron Log



## Definition

Neutron tools were the first logging instruments to use radioactive sources for determining the porosity of the formation. After the later introduction of the gamma-gamma density tool, the neutron measurement was applied in conjunction with the density porosity reading in order to recognize and correct for effects of shale and gas.

Neutron tool response is dominated by the concentration of hydrogen atoms in the formation. In clean reservoirs containing little or no shale, the neutron log response will provide a good measure of formation porosity if liquid-filled pore spaces contain hydrogen, as is the case when pores are filled with oil or water (hydrogen index =1). By contrast, when logging shaly or gas-bearing formations, a combination of Neutron and Density readings will often be required for accurate porosity assessment.

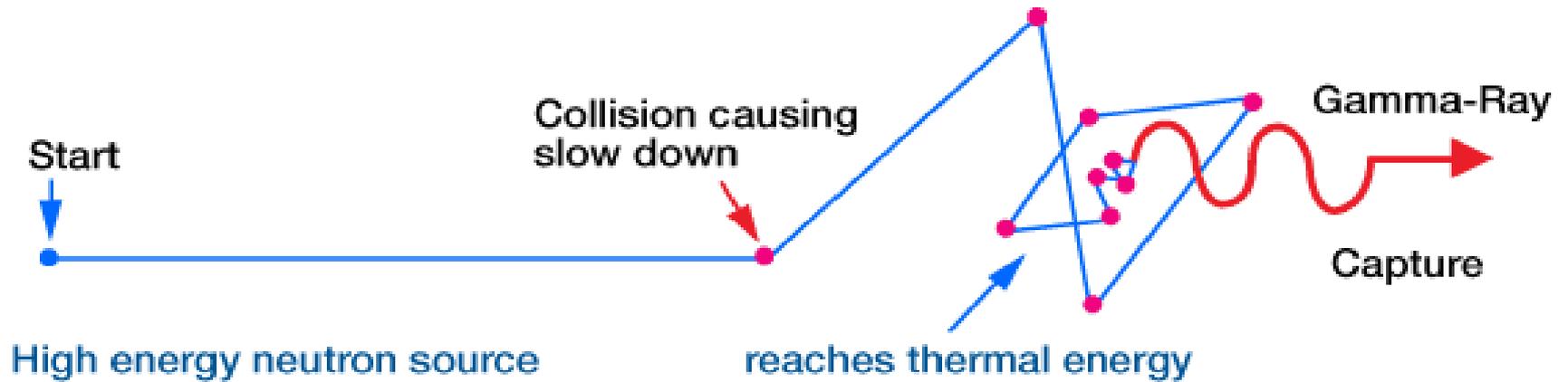


*Generalized Neutron Logging Tool* illustrates a typical neutron logging tool.

## Basic Principles

The electrically neutral neutron has a mass that is practically identical to that of the hydrogen atom. The neutrons that are emitted from a neutron source have a high energy of several million electron volts (MeV). After emission, they collide with the nuclei within the borehole fluid and formation materials. With each collision, the neutrons lose some of their energy. The largest loss of energy occurs when the neutrons collide with hydrogen atoms. The rate at which the neutrons slow-down depends largely on the amount of hydrogen in the formation.

With each collision the neutrons slow down, until the neutrons reach a lower (epithermal) energy state and then continue to lose energy until they reach an even lower (thermal) energy state of about 0.025 eV. At this energy the neutrons are in thermal equilibrium with other nuclei in the formation. At thermal speeds, the neutrons will eventually be captured by a nucleus. When a nucleus captures a thermal neutron, a gamma ray (called a gamma ray of capture) is emitted to dissipate excess energy within the atom.



*Emission, Traveling and Collisions of a Neutron in a Formation*

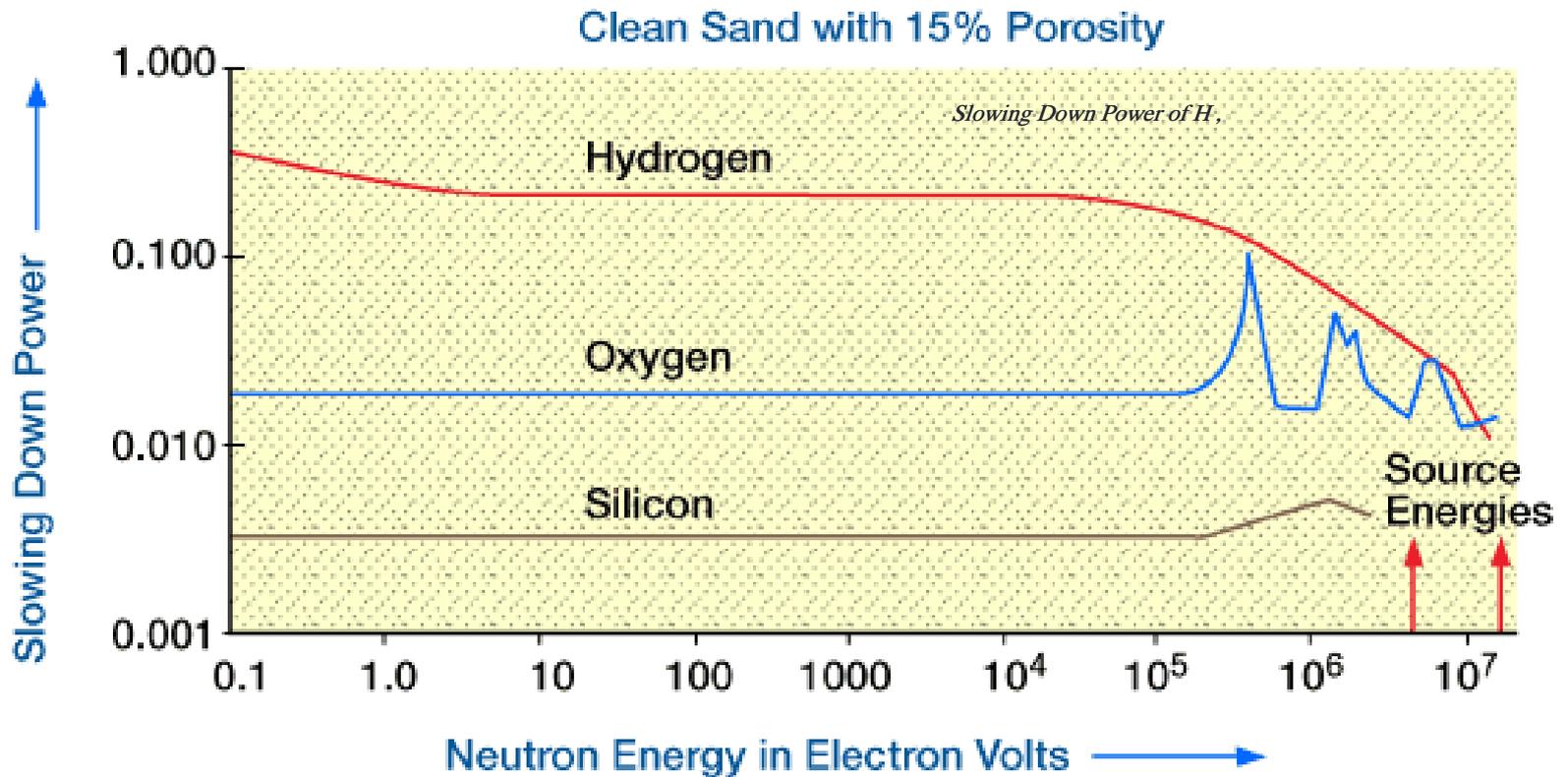
The amount of energy lost at each collision depends on the relative mass of the target nucleus, and the scattering cross section. (At the nuclear level, the term *cross section* is defined as the effective area within which a neutron must pass in order to interact with an atomic nucleus. Such interactions are typically classified either as neutron capture or as neutron scatter. The cross-section is a probabilistic value dependent on the nature and energy of the particle, as well as the nature of the capturing or scattering nucleus.

Depending on the type of tool being used, either the gamma rays emitted after neutron capture, the epithermal neutrons or the thermal neutrons will be counted.

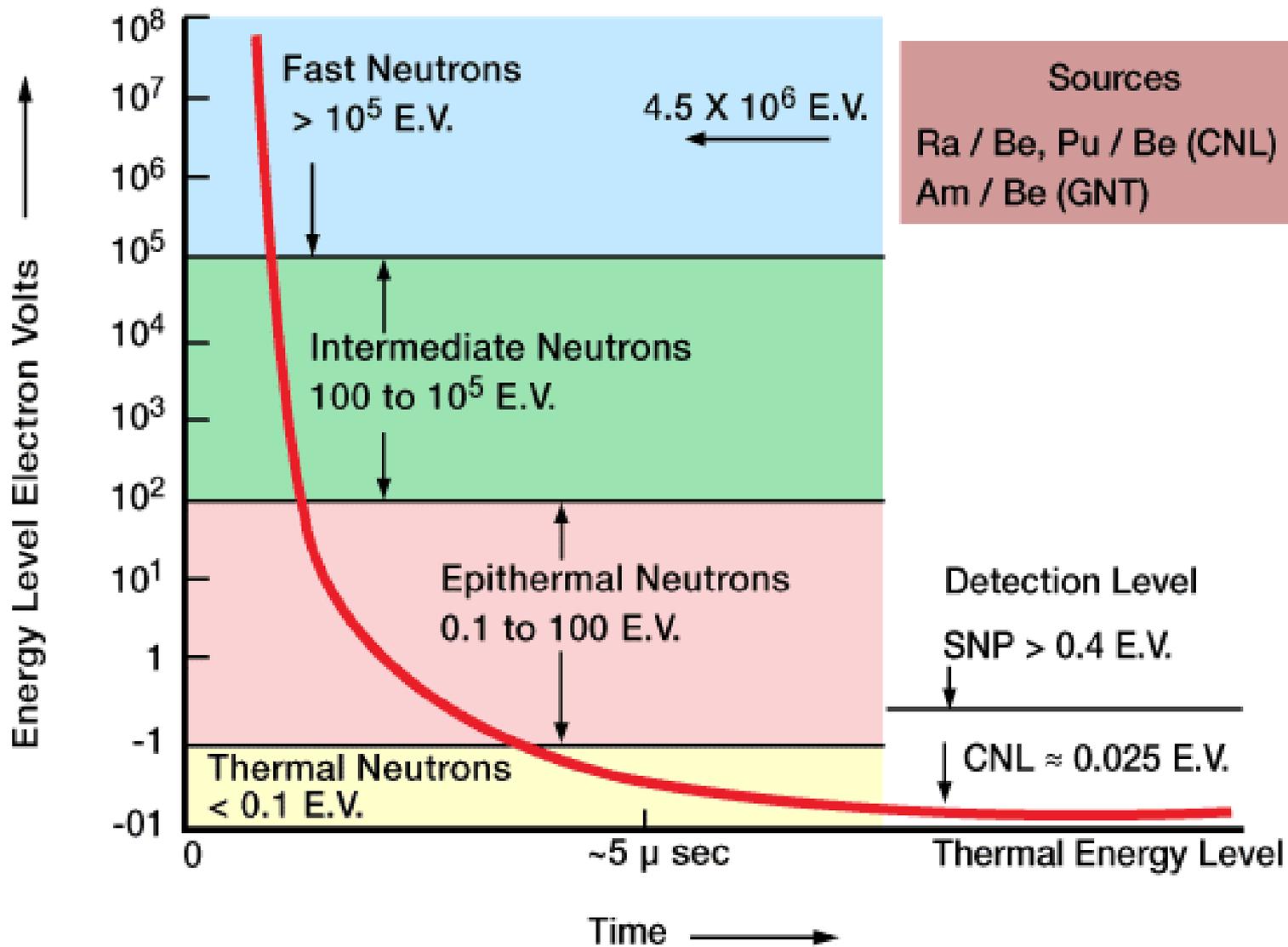
The principles of neutron logging are summarized below:

- A neutron source emits a continuous flux of high-energy neutrons.
- Collisions with formation nuclei reduce the neutron energy -thereby slowing it down.
- At thermal energy levels (approximately 0.025 eV), neutrons are captured.
- Neutron capture results in an emission of gamma rays.
- Depending on the type of tool, the detector measures the slowed down neutrons and/or emitted gamma rays.

Neutron logging devices contain one or more detectors and a neutron source that continuously emits energetic (fast) neutrons.



Slowing down power of H, O, Si for different neutron energies



Neutron energy level versus time after leaving the source illustrates the slow down process

Porosity (or the hydrogen index) can be determined by measuring epithermal or thermal neutron populations, or by measuring capture gamma rays, or any combination thereof.

Neutron logs that detect epithermal neutrons are referred to as *sidewall neutron* logs. By contrast, the compensated neutron log, in widespread use today, detects thermal neutrons, using two neutron detectors to reduce borehole effects. Single thermal neutron detector tools, of poorer quality, are also available in many areas of the world.

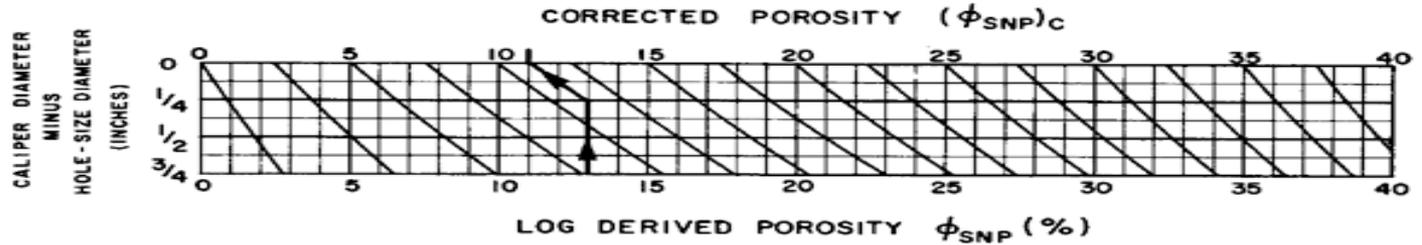
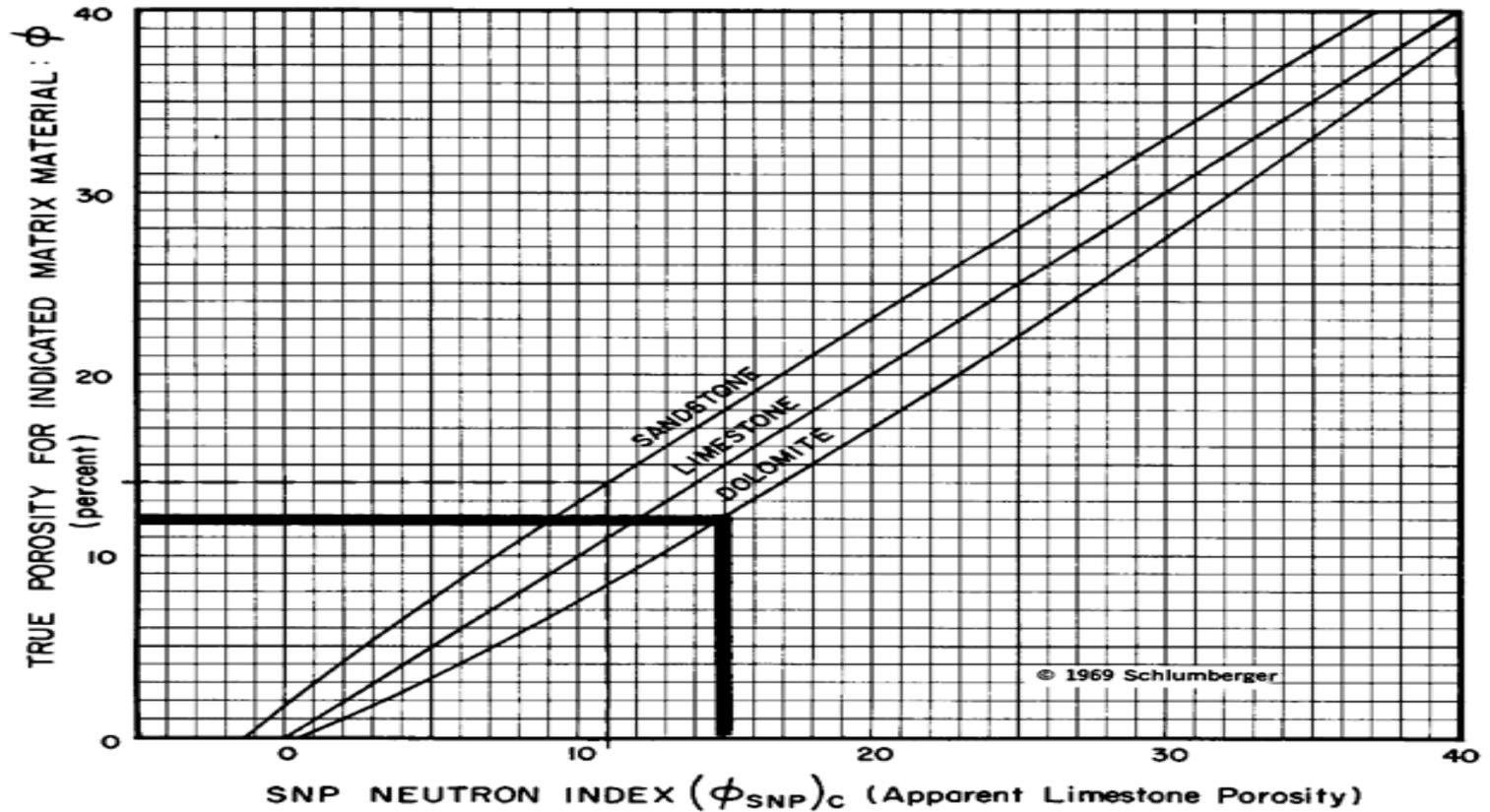
Capture gamma rays are used for porosity determination, and logs of this type are referred to as *neutron-gamma* logs. The responses of these devices are dependent upon such variables as porosity, lithology, hole size, hole rugosity, fluid type, and temperature.

Compensated and sidewall logs use corrections from their electronic panels to account for some of these variables, while neutron-gamma logs require departure curves (provided in chart books) to make corrections.

# NEUTRON POROSITY EQUIVALENCE CURVES

## SIDEWALL NEUTRON POROSITY LOG (SNP)

MAY ALSO BE USED FOR GNT NEUTRON LOGS



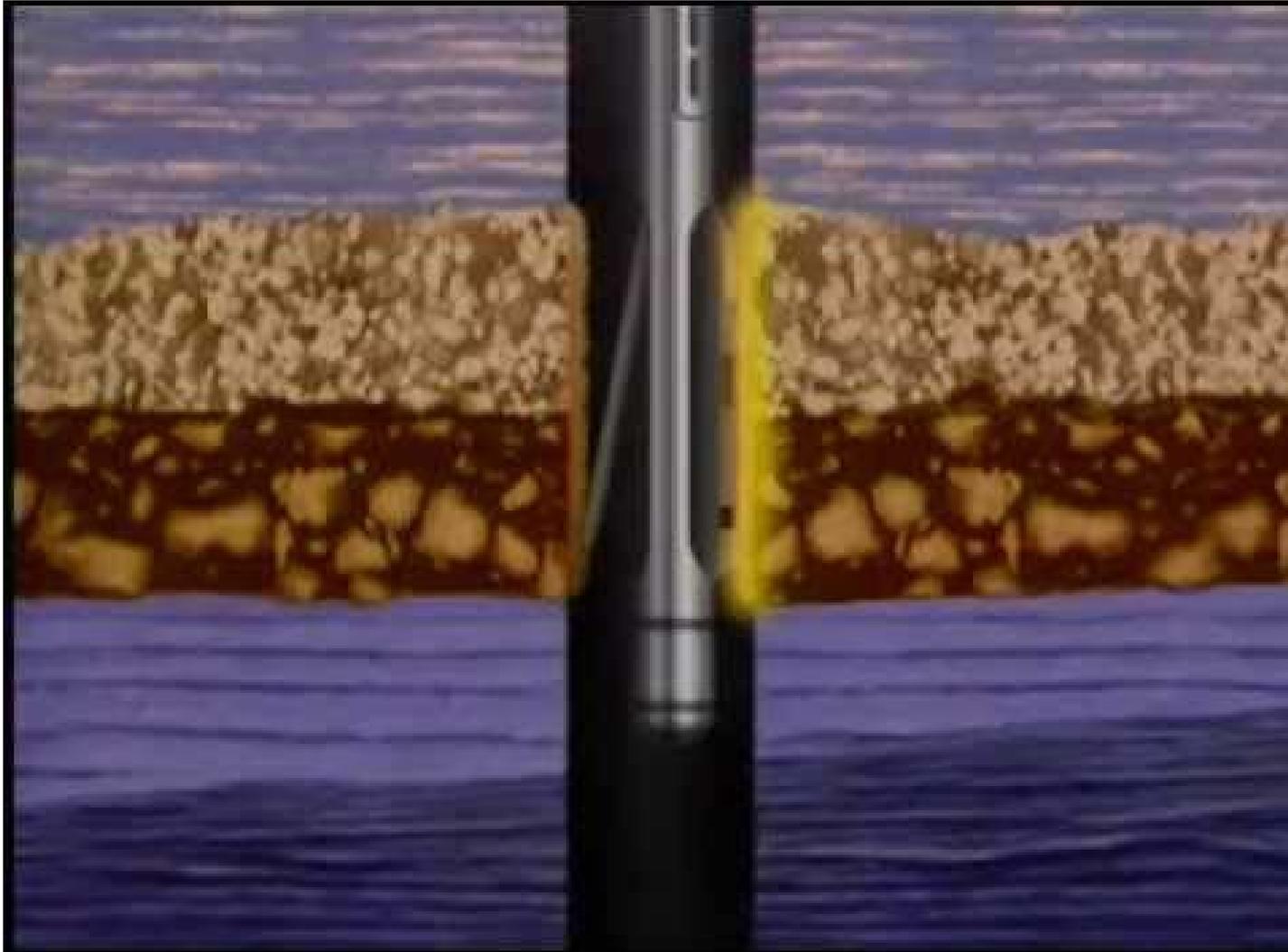
# *NEUTRON LOGGING APPLICATIONS*

Neutron tools are used primarily to determine:

- porosity, usually in combination with the density tool
- gas detection, usually in combination with the density tool, but also with a sonic tool
- shale volume determination, in combination with the density tool
- lithology indication, again in combination with the density log and/or sonic log
- formation fluid type.

Depending on the device, these applications may be made in either open or cased holes. Additionally, because neutrons are able to penetrate steel casing and cement, these logs can be used for depth tie-in as well as providing information on porosity and hydrocarbon saturations in cased holes

# Density log



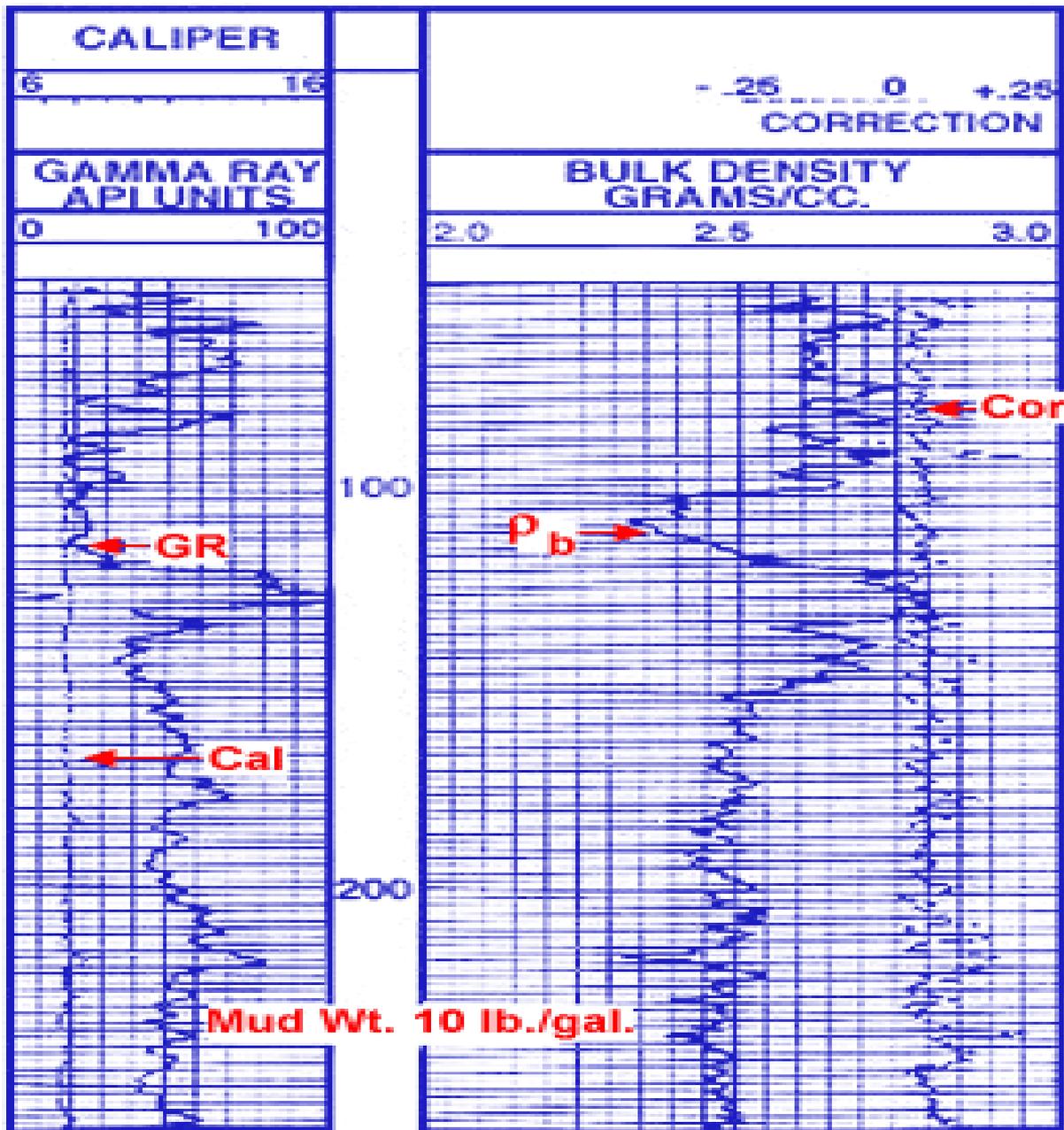
## Density Log

The formation density log is a porosity log that measures *electron density* of a formation.

The density logging device is a contact tool which consists of a medium-energy gamma ray source that emits gamma rays into a formation. The gamma ray source is either Cobalt-60 or Cesium-137.

A density derived porosity curve is sometimes presented in tracks #2 and #3 along with the bulk density and correction curve . The most frequently used scales are a range of 2.0 to 3.0 gm/cc or 1.95 to 2.95 gm/cc across two tracks. Track #1 contains a gamma ray log and caliper

Formation bulk density is a function of matrix density, porosity, and density of the fluid in the pores (salt, mud, fresh mud, or hydrocarbons). Density is one of the most important pieces of data in formation evaluation. In the majority of the wells drilled, density is the primary indicator of porosity. In combination with other measurements, it may also be used to indicate lithology and formation fluid type.

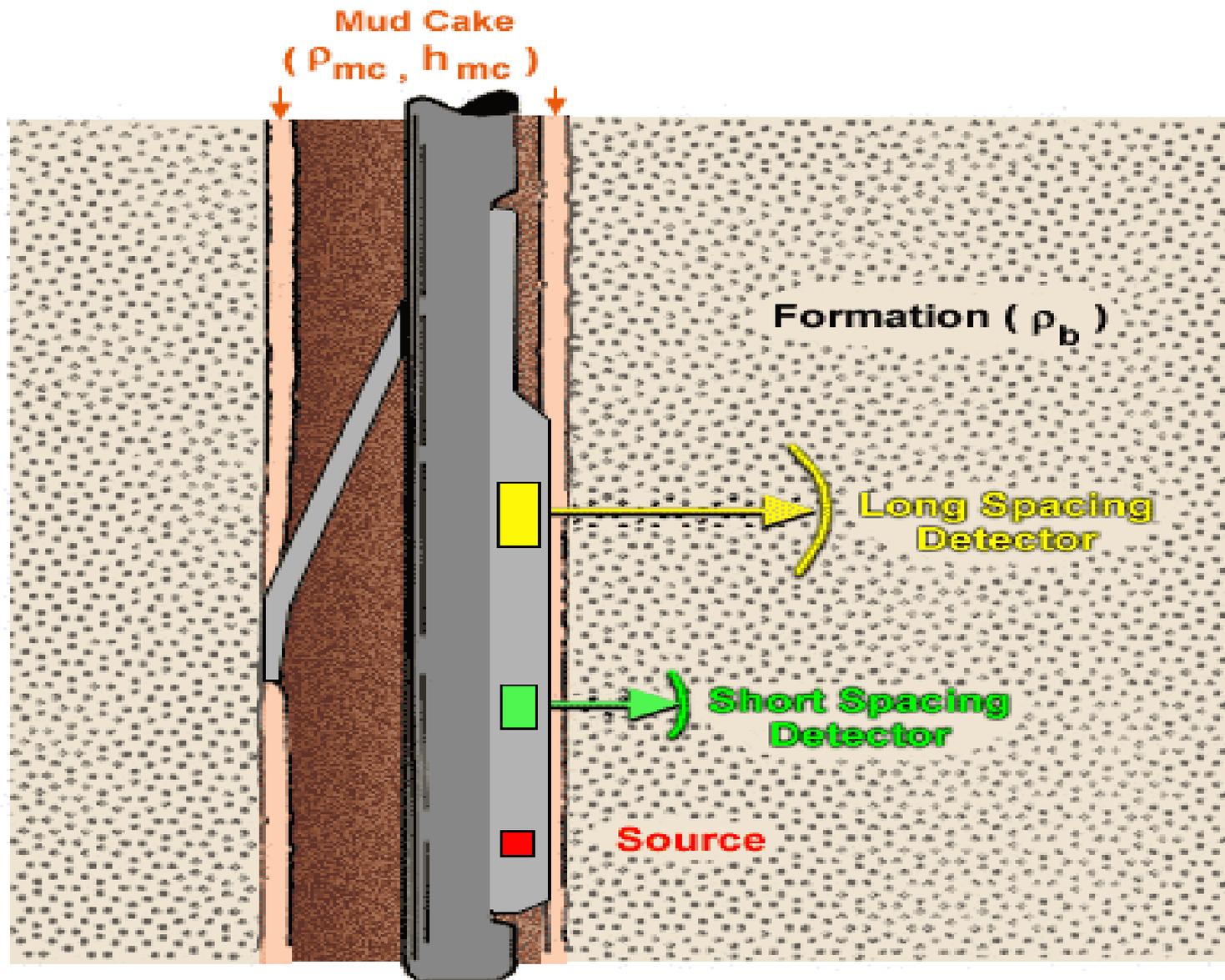


Courtesy Schlumberger Well Services

The tool can be used by itself, but is typically run in combination with other tools, such as the compensated neutron and resistivity tools. The formation density skid device, *Schematic of the Dual-Spacing Formation Density Logging Device (FDC)* carries a gamma ray source and two detectors, referred to as the short-spacing and long-spacing detectors

The tool employs a radioactive source which continuously emits gamma rays. These pass through the mudcake and enter the formation, where they progressively lose energy until they are either completely absorbed by the rock matrix or they return to one of the two gamma ray detectors in the tool

Dense formations absorb many gamma rays, while low-density formations absorb fewer. Thus, high-count rates at the detectors indicate low-density formations, whereas low count rates at the detectors indicate high-density formations. For example, in a thick anhydrite bed the detector count rates are very low, while in a highly washed-out zone of the hole, simulating an extremely low-density formation, the count rate at the detectors is extremely high.



Courtesy Schlumberger Well Services

This tool is a contact-type tool; i.e., the skid device must ride against the side of the borehole to measure accurately.

Gamma rays can react with matter in three distinct manners:

- *Photoelectric effect*, where a gamma ray collides with an electron, is absorbed, and transfers all of its energy to that electron. In this case, the electron is ejected from the atom.
- *Compton scattering*, where a gamma ray collides with an electron orbiting some nucleus. In this case, the electron is ejected from its orbit and the incident gamma ray loses energy.
- *Pair production*, where a gamma ray interacts with an atom to produce an electron and positron. These will later recombine to form another gamma ray.

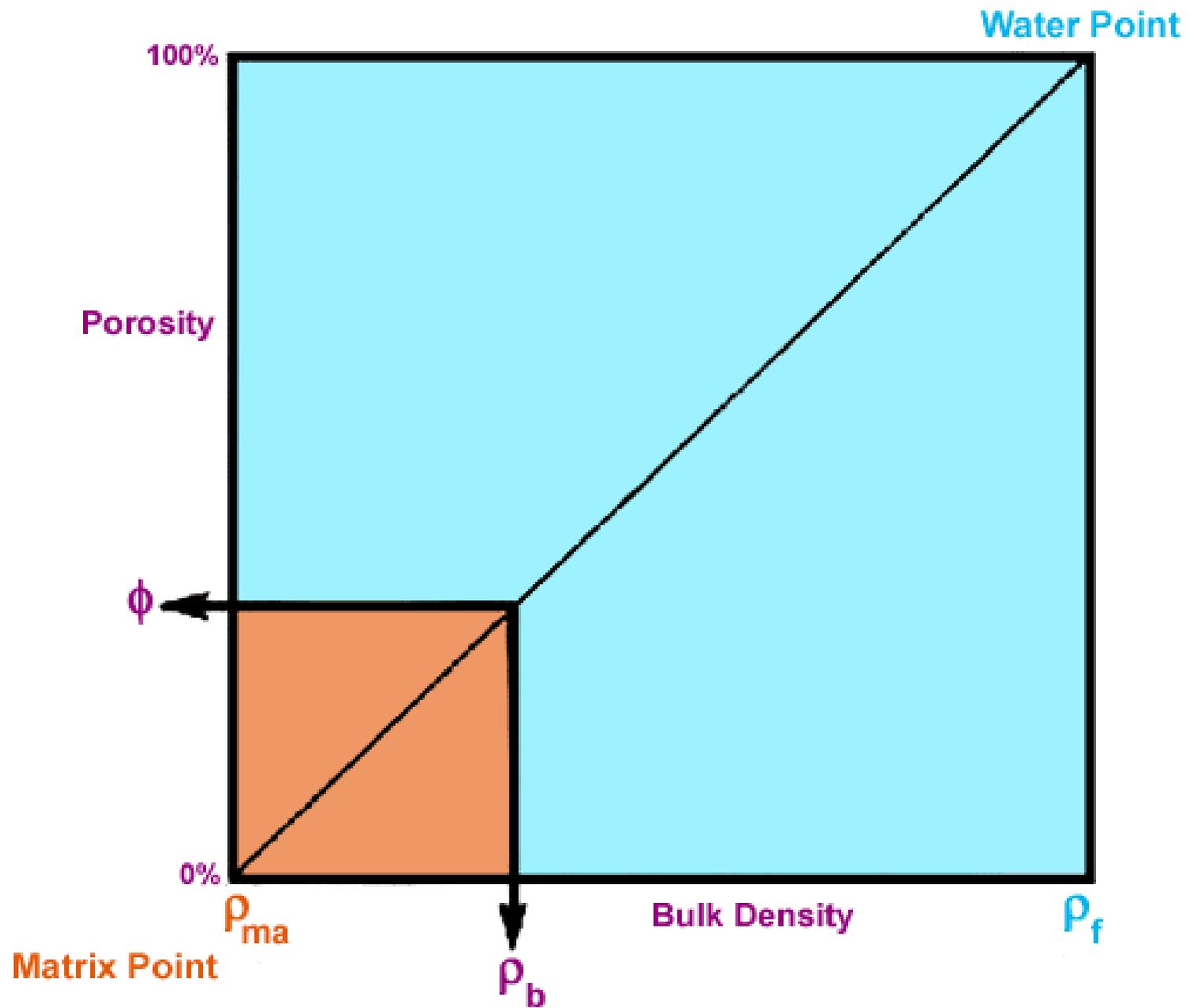
Photoelectric interaction can be monitored to find the lithology-related parameter,  $P_e$ . For the conventional density measurement, only the Compton scattering of gamma rays is of interest. Conventional logging sources do not emit gamma rays with sufficient energies to induce pair production, therefore pair production will not be a topic of this discussion.

To determine density porosity, either by chart or by calculation, the matrix density and type of fluid in the borehole must be known. The formula for calculating density porosity is:

$$\Phi = \frac{\rho_{ma} - \rho_b}{\rho_{ma} - \rho_f}$$

Where invasion of formation is shallow, low density of the formation's hydrocarbon will increase density porosity. Oil does not significantly affect density porosity, but gas does (gas affect). Hilchie (1978) suggests using a gas density of 0.7 gm/cc for fluid density ( $\rho_f$ ) in the density porosity formula if gas density is unknown.

The density log gives reliable porosity values, provided the borehole is smooth, the formation is shale-free, and the pore space does not contain gas. In shaly formations and/or gas-bearing zones, it is necessary to refine the interpretative model to make allowances for these additions or substitutions to the rock system.

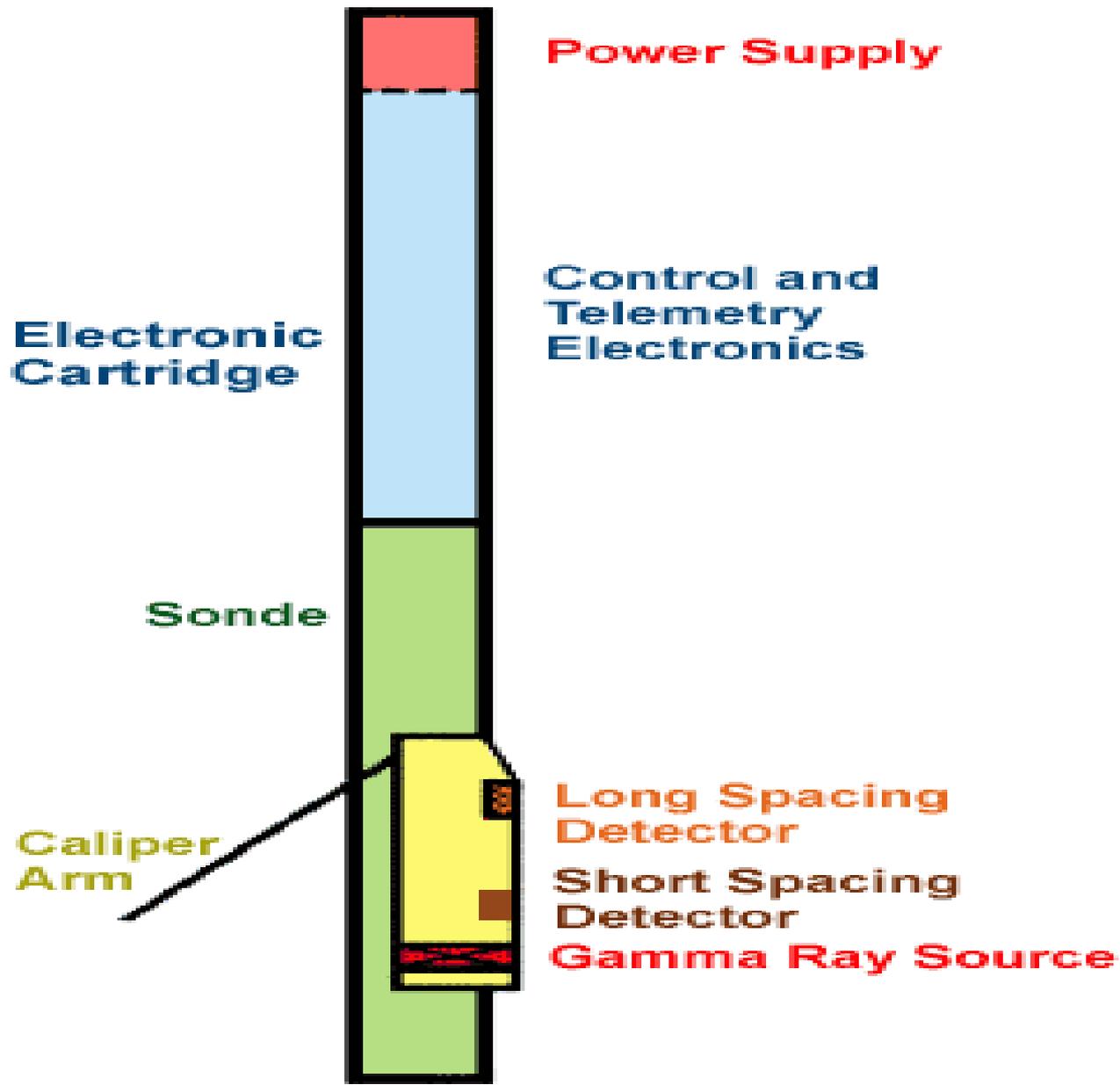


## LITHOLOGIC DENSITY TOOL

The Pe, or lithodensity log, run with the lithodensity tool (LDT), is another version of the standard formation density log. In addition to the bulk density (rb), the tool also measures the **photoelectric absorption index (Pe)** of the formation. This new parameter enables a lithological interpretation to be made without prior knowledge of porosity.

The photoelectric effect occurs when a gamma ray collides with an electron and is absorbed in the process, so that all of its energy is transferred to the electron. The probability of this reaction taking place depends upon the energy of the incident gamma rays and the type of atom. The photoelectric absorption index of an atom increases as its atomic number, Z, increases.

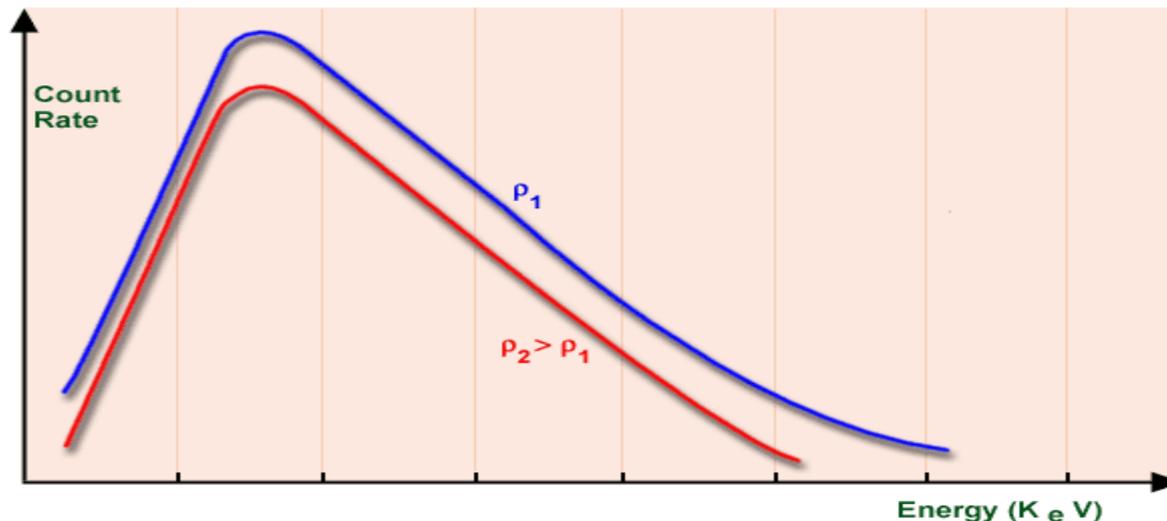
$$Pe = (0.1 \cdot Z_{eff})^{3.6}$$



Courtesy Schlumberger Well Services

The lithodensity tool is similar to a conventional density logging device, and uses a skid containing a gamma ray source and two gamma ray detectors held against the borehole wall by a spring-actuated arm. Gamma rays are emitted from the tool and are scattered by the formation, losing energy until they are absorbed via the photoelectric effect.

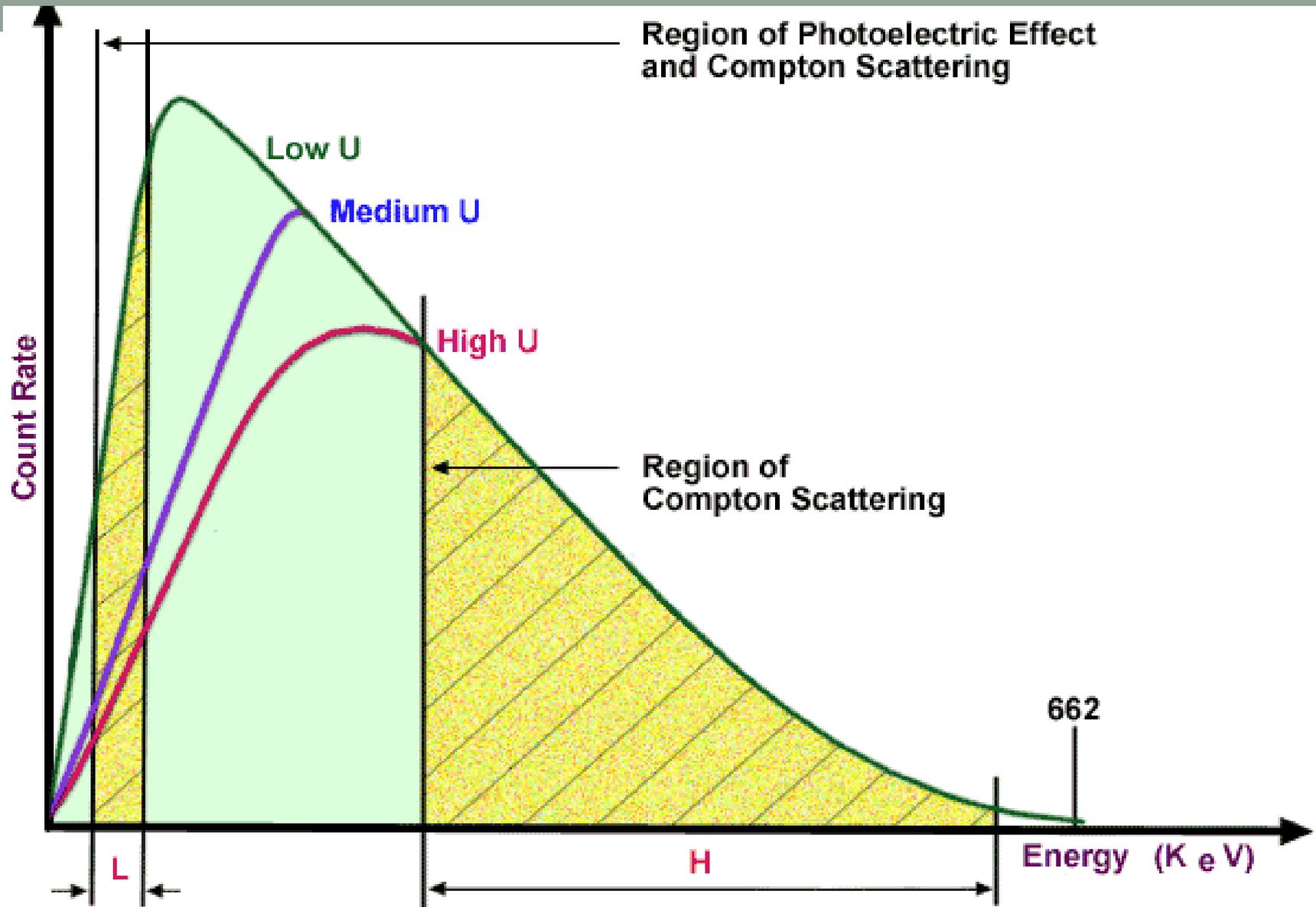
At a finite distance from the source, there is a gamma ray energy spectrum as shown in the figure given below. Variation in Gamma Ray Spectrum for Formations of Different Densities. This Figure also shows that an increase in the formation density results in a decrease in the number of gamma rays detected over the whole spectrum.



For formations of constant density but different photoelectric absorption coefficients, the gamma ray spectrum is only altered at lower energies, as indicated in the next figure .

Observing the gamma ray spectrum, we notice that region H only supplies information relating to the density of the formation, whereas region L provides data relating to both the electron density and the Pe value. By comparing the counts in the energy windows H and L, the Pe can be measured. The gamma ray spectrum at the short spacing detector is only analyzed for a density measurement, which is used to correct the formation density determined from the long spacing spectrum for effects of mud-cake and rugosity.

The photoelectric absorption coefficient is virtually independent of porosity, there being only a slight decrease in the coefficient as the porosity increases. Similarly, the fluid content of the formation has little effect. Simple lithologies, such as pure sandstone and anhydrite, can be read directly from logs using Pe curves. Look for the following readings in the most commonly occurring reservoir rocks and evaporites.



Region of Photoelectric Effect and Compton Scattering

Low U

Medium U

High U

Region of Compton Scattering

662

Energy (K e V)

L

H

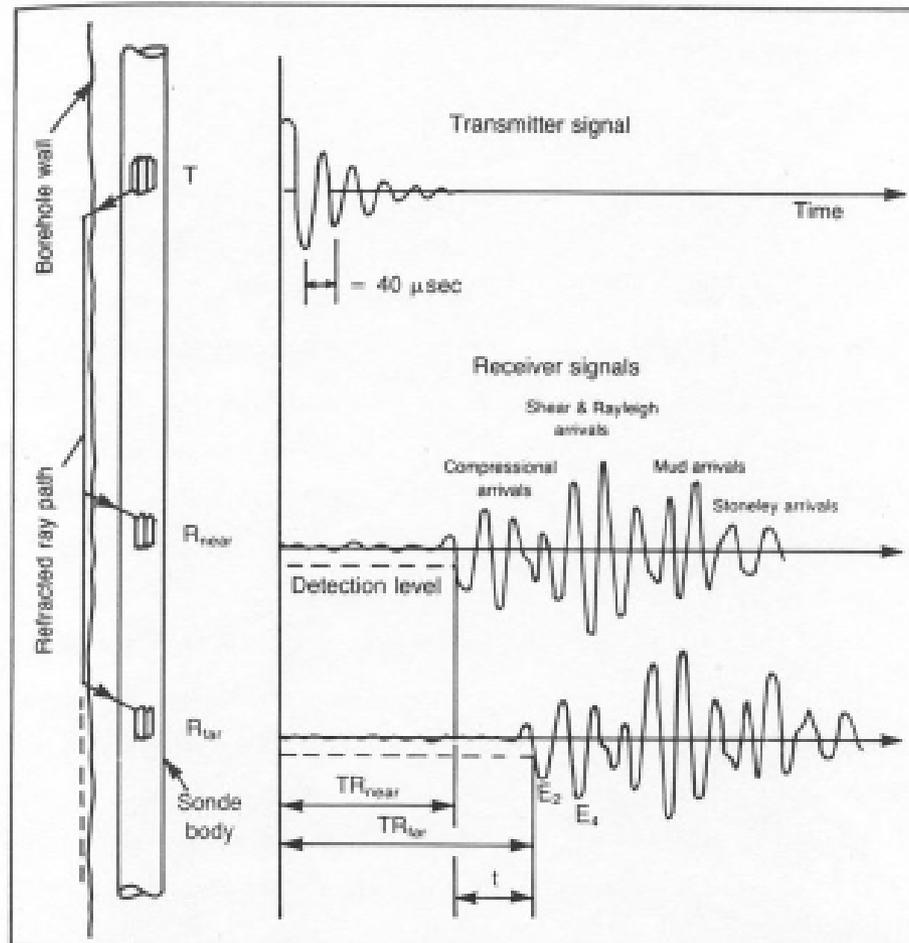
Courtesy Schlumberger Well Services

| <b>Material</b> | <b>Pe</b> |
|-----------------|-----------|
| Sand            | 1.81      |
| Shale           | 3-4       |
| Limestone       | 5.08      |
| Dolomite        | 3.14      |
| Salt            | 4.65      |
| Anhydrite       | 5.05      |

## Application of density log

It can assist the geologist to: (1) identify evaporite minerals, (2) detect gas-bearing zones, (3) determine hydrocarbon density, and (4) evaluate shaly sand reservoirs and complex lithologies.

# Sonic Log



Basic Sonic logging system (courtesy Schlumberger, © SPE)

# Uses

- 1) **Determine porosity of reservoir rock**
- 2) Improve correlation and interpretation of seismic records
- 3) Identify zones with abnormally high pressures
- 4) Assist in identifying lithology
- 5) Estimate secondary pore space
- 6) Indicate mechanical integrity of reservoir rocks and formations that surround them (in conjunction with density data)
- 7) Estimate rock permeability

# Principle

Transmitter emits sound waves

Receivers pick up and record the various waves

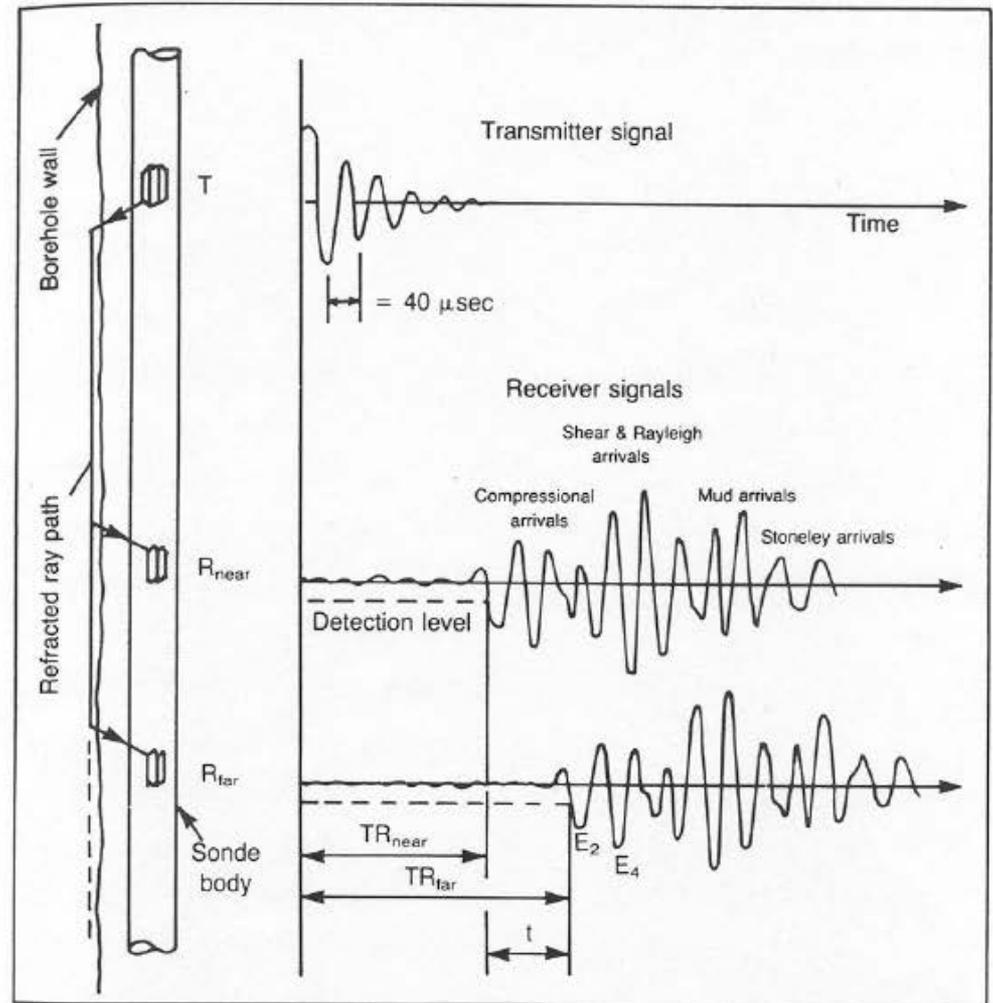
Measure the first arrival of the compressional wave

Travel time is the difference in arrival of the compressional wave at the receivers

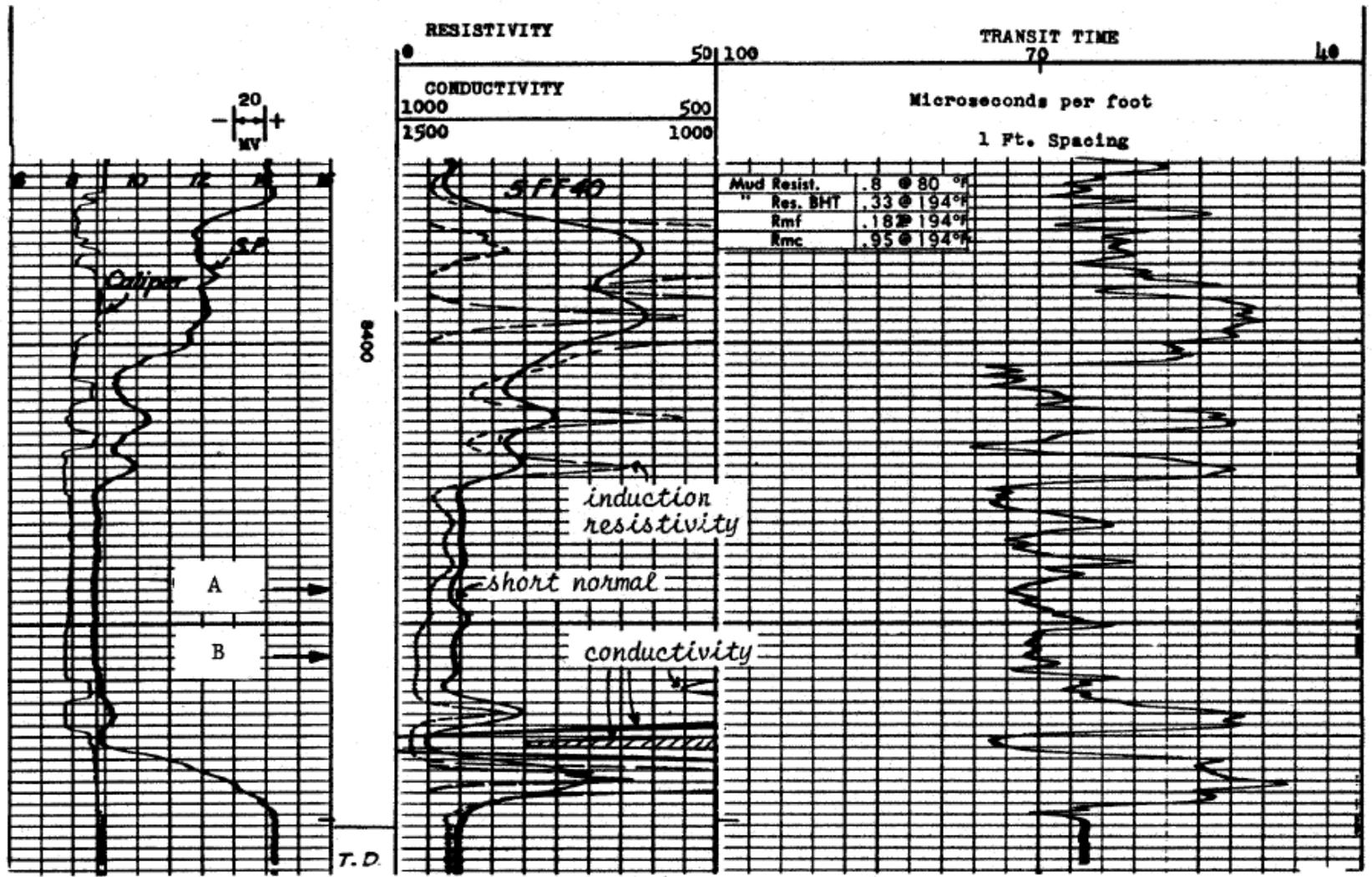
(1', 2', 3' Sonic)

$$\Delta t = (t_2 - t_1)/L_s$$

where  $L_s$  is span between receivers.



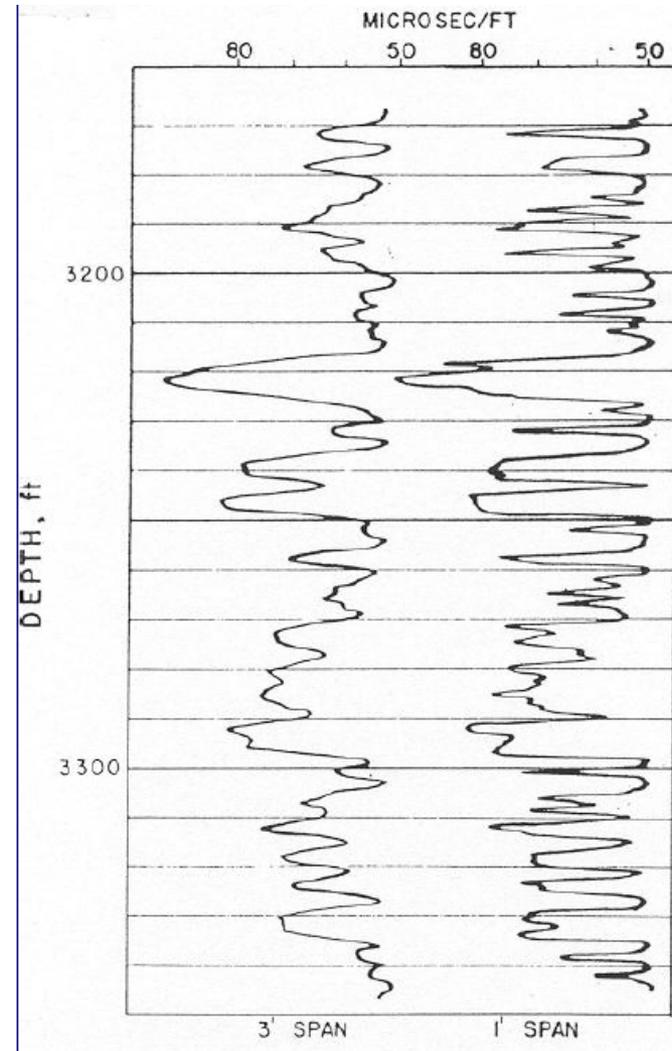
Basic Sonic logging system (courtesy Schlumberger, © SPE)



# Vertical Resolution

## Span

- defined as distance between receivers
- determines vertical resolution,  $h \sim \text{span}$



3 and 1-ft spacing sonic logs recorded in a west texas well  
(Bassiouni, 1994)

# Lateral Resolution

## Depth of investigation

- varies with wavelength,  $\lambda$ , which is related to formation velocity,  $v$ , and tool frequency,  $f$ .  $\lambda = v/f$
- Depth of investigation,  $D_i \sim 3 \lambda$
- Rule of thumb, 0.75 to 3.75 ft.
- indirectly related to T-R spacing

## Critical T-R Spacing

- short enough for pulse to be detected
- long enough to allow 1st arrival to be compressional wave and not mud wave
- $f(\text{standoff}, v_{\text{mud}}/v_{\text{fm}})$
- borehole enlargement effects

# Cycle Skipping

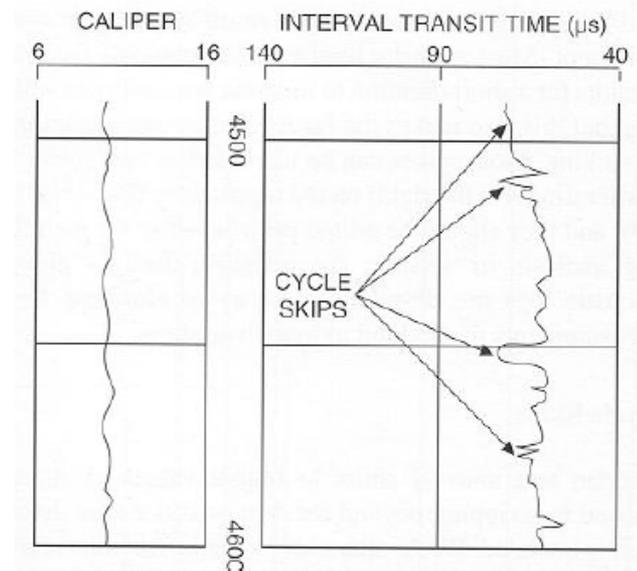
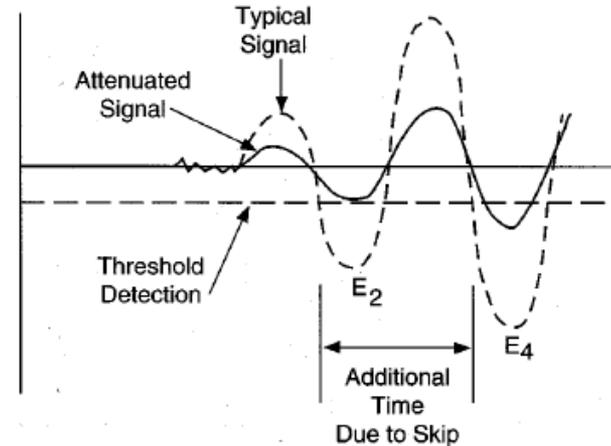
**Cause:** Dampening of first arrival at far receiver

**Effect:**

Sonic curve shows spiking or an abrupt change towards a higher travel time

**Occurs in:**

- Unconsolidated formations (particularly gas bearing);
- fractured formations;
- transmitter weak and/or receiver poor

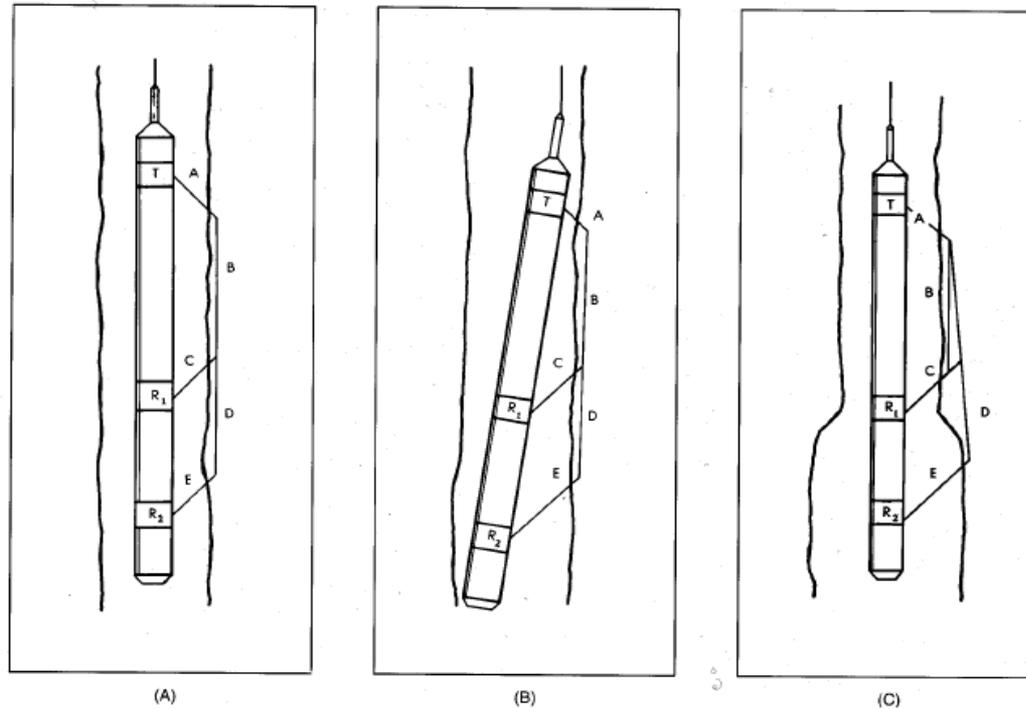


# Types

- Basic Sonic (obsolete)
- **BHC - borehole compensated sonic (most common)**
- LSS - Long spaced sonic
- Array Sonic or Full Waveform Sonic
- Dipole Shear Imager (DSI)

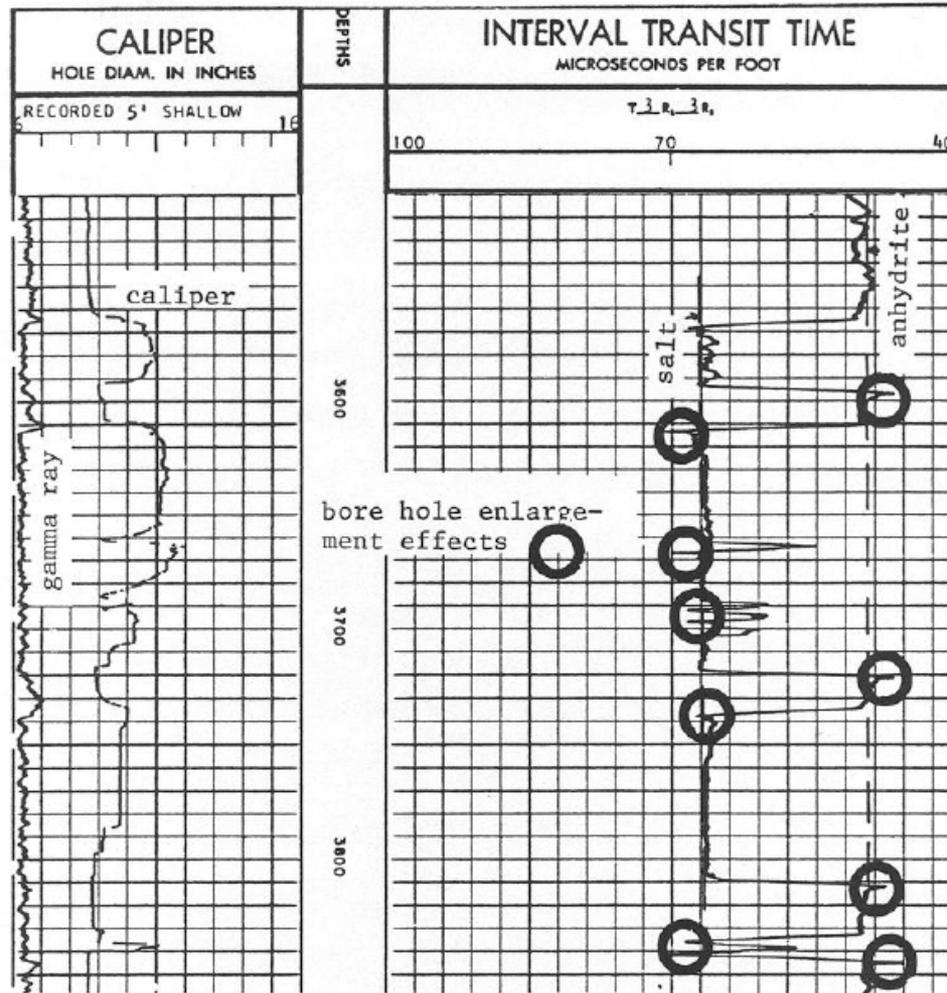
# Basic Sonic Log

- One transmitter and two or three receivers, T-R1-R2 -R3
- Borehole and sonde tilt problems



Single transmitter, two-receiver configuration  
Western Atlas (1993)

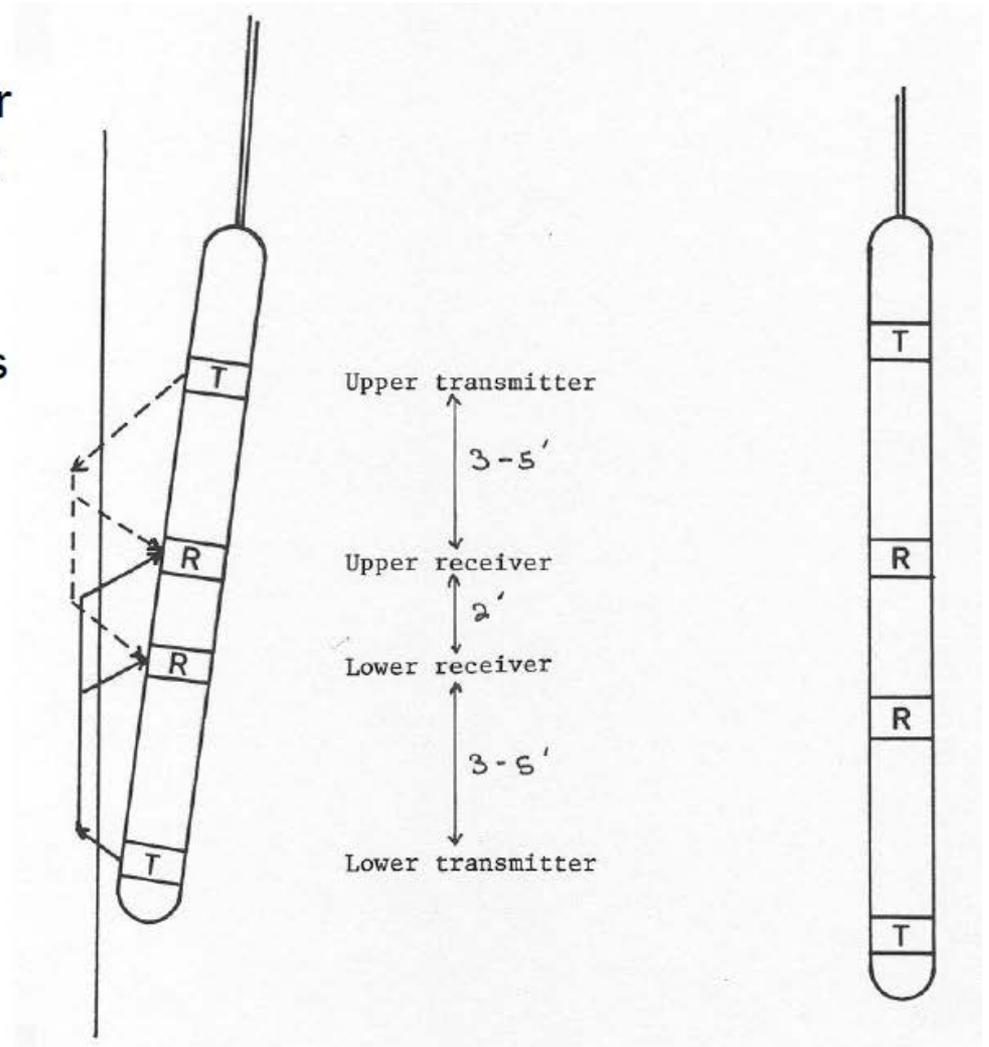
# Example-Borehole enlargement Effects



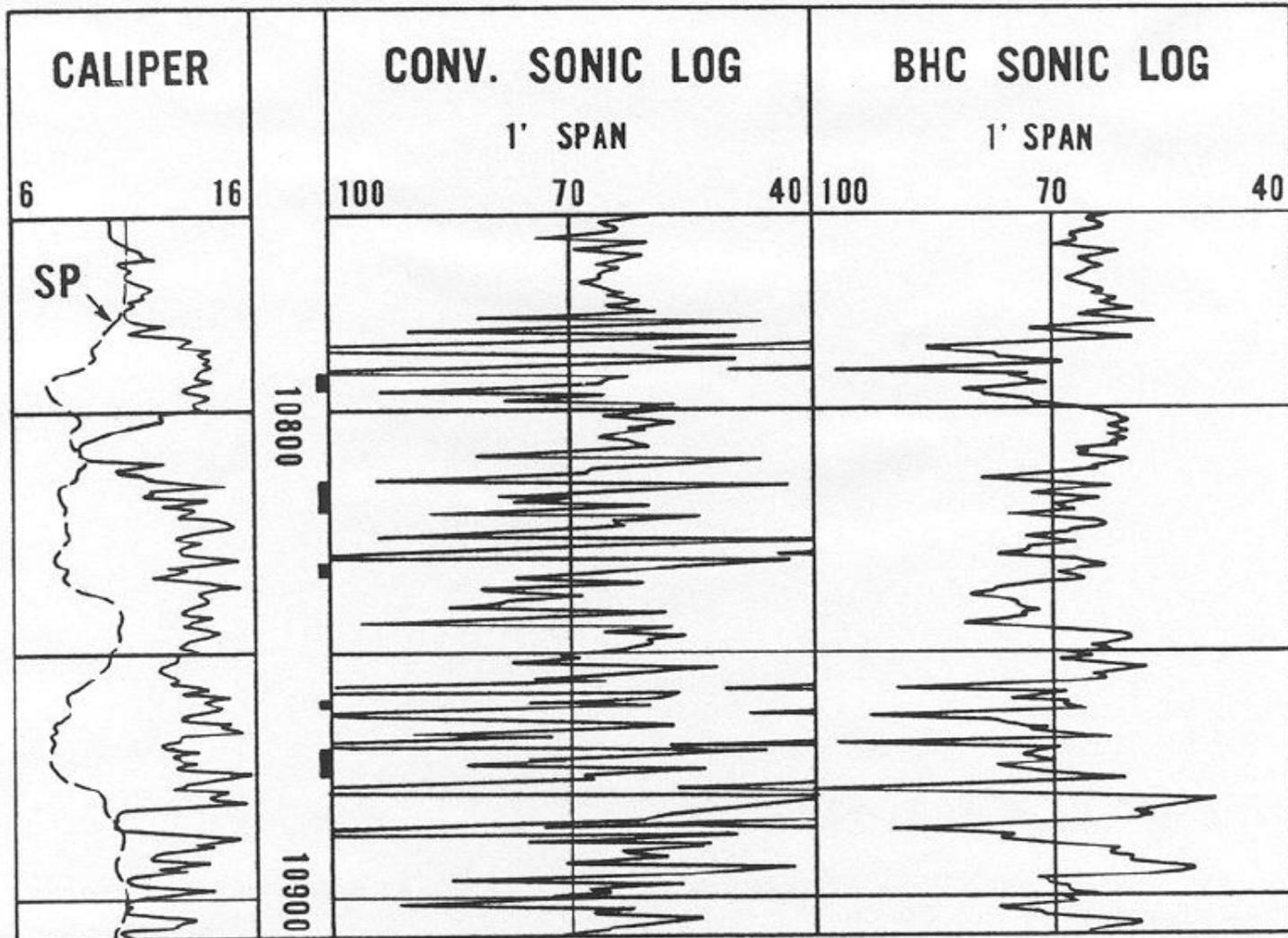
West Texas acoustic log  
Hilchie (1978)

# Borehole compensated Sonic (BHC)

- Automatically compensates for borehole effects and sonde tilt
- System of upper and lower transmitters bounding two sets of receivers.



# Comparison of BHC with Basic Sonic

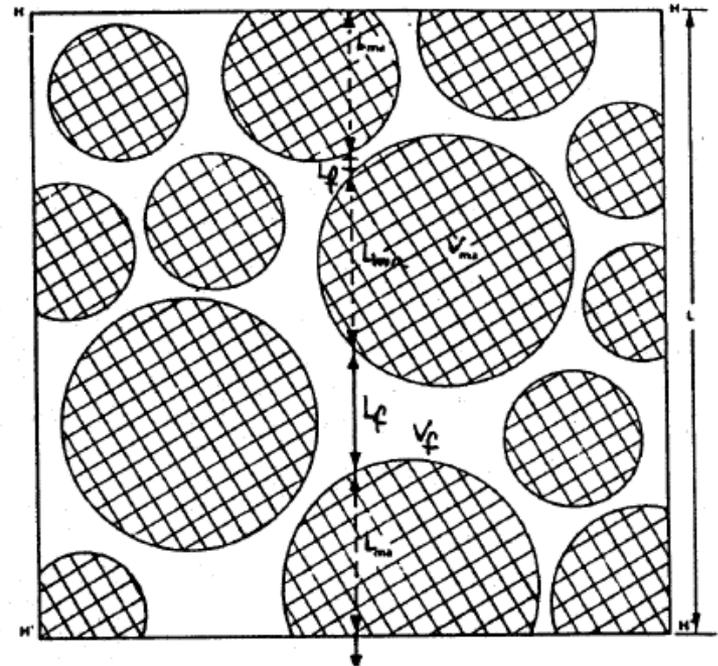


# Porosity

**Wyllie Eq.** - linear time averaged relationship

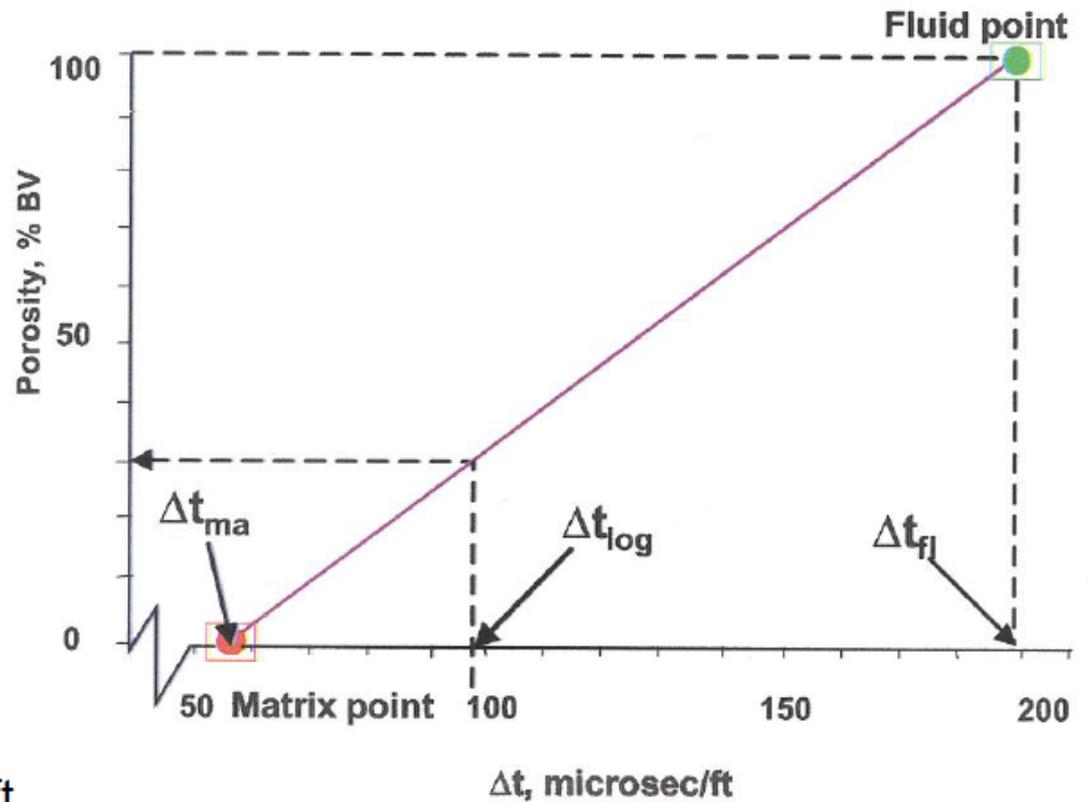
$$\Delta t = \frac{\sum \frac{L_f}{L}}{V_f} + \frac{\sum \frac{L_{ma}}{L}}{V_{ma}}$$

- empirically determined
- for clean and consolidated sandstones
- uniformly distributed small pores



# Wyllie Equation

$$\phi = \frac{\Delta t_{\log} - \Delta t_{ma}}{\Delta t_f - \Delta t_{ma}}$$



| $\Delta t_{ma}, \mu\text{sec/ft}$ | $\Delta t_f, \mu\text{sec/ft}$ |
|-----------------------------------|--------------------------------|
| ss 55.5                           | fresh 189                      |
| lms 47.6                          | salt 185                       |
| dol 43.5                          |                                |
| Anhy 50.0                         |                                |

# Porosity – uncompacteds sands

**Evidence:** when  $\Delta t_{log} > 100$  microsec/ft in overlying shale

**Result:** Estimated porosity too high

**Correction:** Observed transit times are greater in uncompacteds sands; thus apply empirical correction factor,  $C_p$

$$\phi = \frac{t_{log} - t_{ma}}{t_f - t_{ma}} \frac{1}{C_p}$$

Estimate  $C_p$  from overlying shale zone

$$C_p = c \frac{\Delta t_{sh}}{100}$$

where the shale compaction coefficient,  $c$ , ranges from  $0.8 < c < 1.3$ .

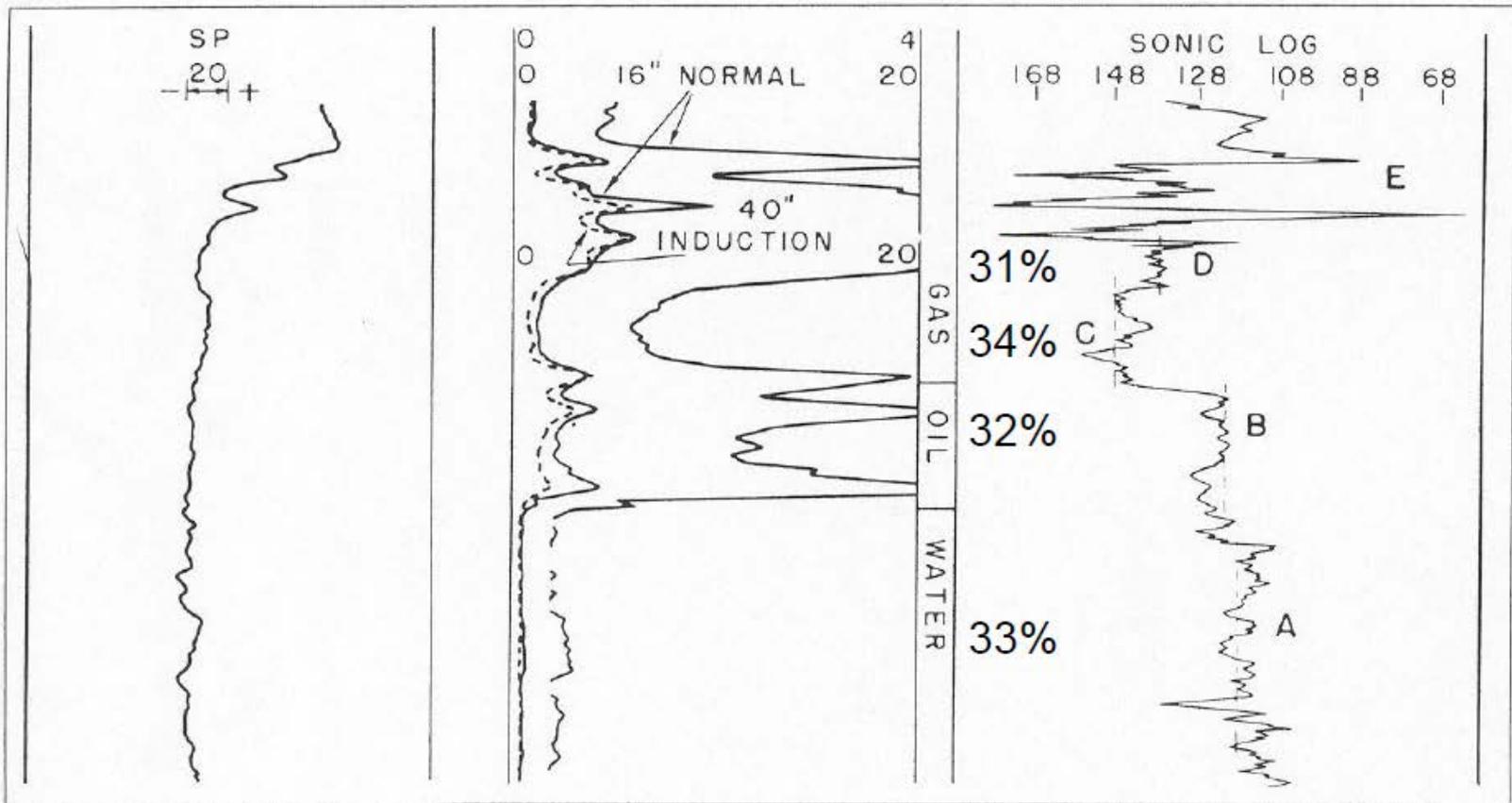
# Porosity – uncompactedsands-Fluid Effect

- Sonic primarily independent of fluid type
- Know lithology, can calculate porosity
- Fluid Effect in high porosity formations with high HC saturation.  
Correct by:

$$\text{oil: } \phi_{\text{corr}} = 0.9 * \phi_s$$

$$\text{gas: } \phi_{\text{corr}} = 0.7 * \phi_s$$

- Apply after compaction correction.



Cp = 1.44...from overlying shale

Ave zone  
Core  $\phi$

## Transit time - porosity transform (Raymer-Hunt)

- based on field observation
- yields slightly greater porosity in the 5 to 25% range
- does not require compaction correction

$$\phi = C \frac{t_{\log} - t_{ma}}{t_{\log}}$$

Where

C ranges from 0.625 to 0.700

Typical value used in practice is  $C = 0.67$

$C = 0.6$  for gas-saturated formations

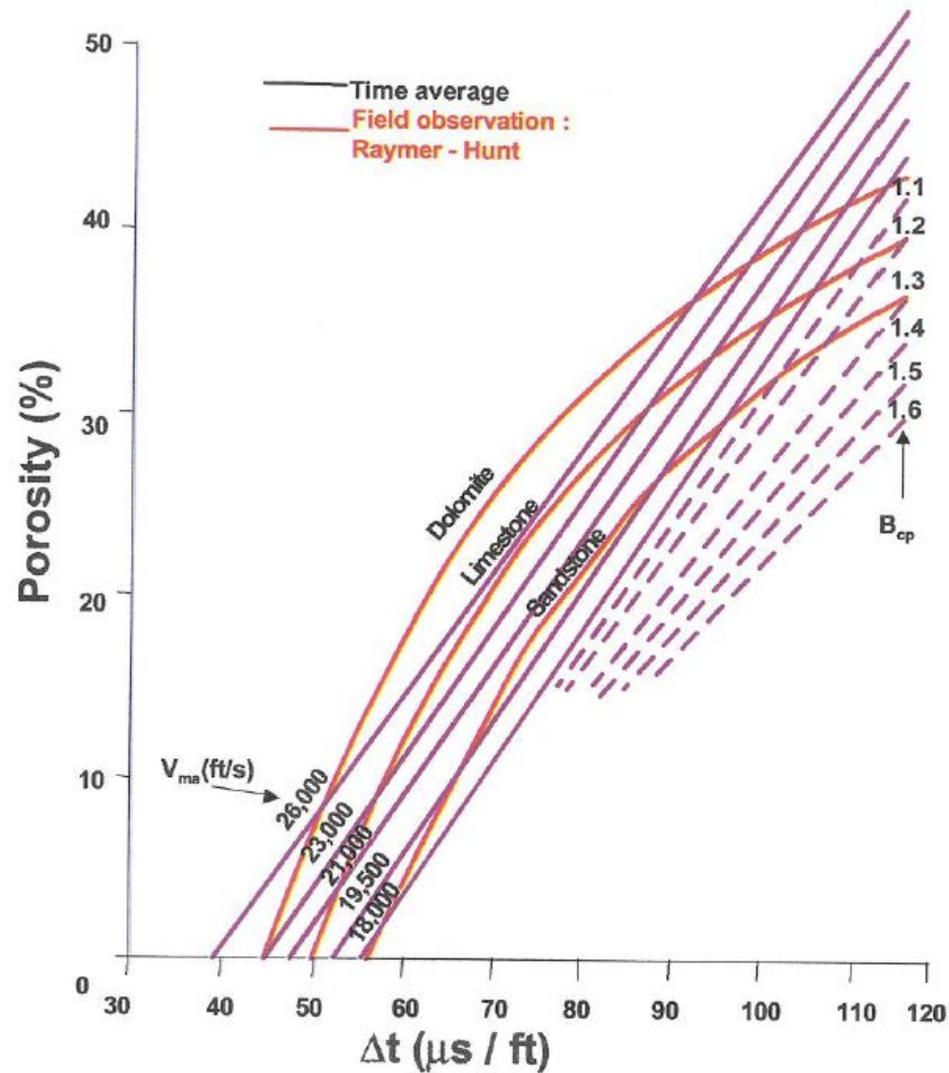
$\Delta t_{ma}$ ,  $\mu\text{sec}/\text{ft}$

Ss 56.0

Lms 49.0

Dolo 44.0

# Porosity comparison

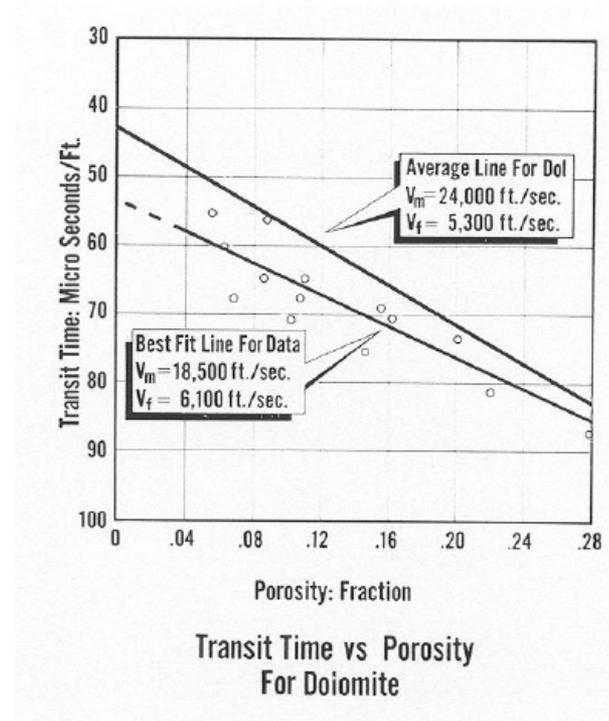


# Secondary Porosity

- Sonic ignores secondary porosity; i.e, vugs and fractures
- Result: Measured transit time < than would be calculated for given porosity
- Estimate Secondary porosity by:

$$\phi_2 = \phi_t - \phi_s$$

- Alternative: Develop specific empirical relationships for heterogeneous systems



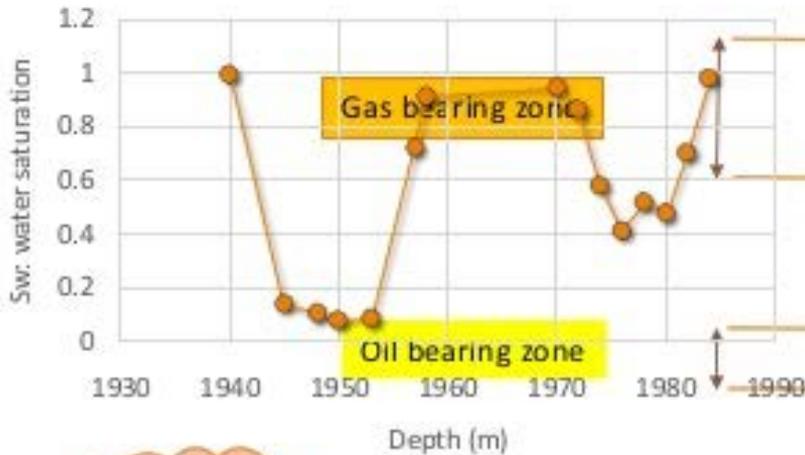
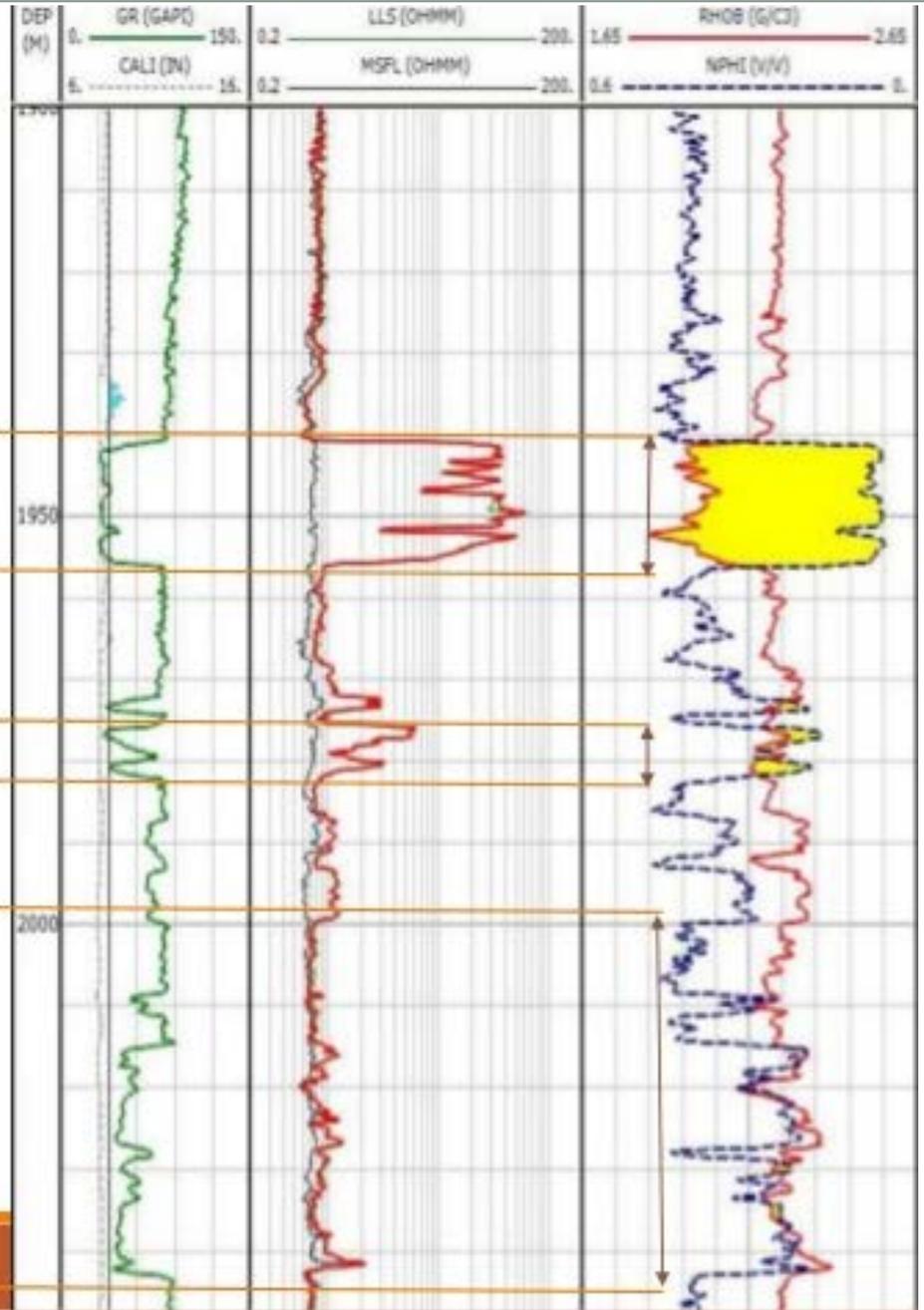
Example of Porosity – Velocity Correlation in Dolomite  
The example illustrates travel times which are consistently greater than predicted by the “time-average equation”. (Corelab)

# Combination Neutron Density Log

The Combination Neutron-Density Log is a combination porosity log. Besides its use a porosity device, it is also used to determine lithology and to detect gas-bearing zones. The Neutron-Density Log consists of neutron and density curves recorded in tracks #2 and #3 and a caliper and gamma ray log in track #1.

Where an *increase* in density porosity occurs along with a *decrease* in neutron porosity in a gas-bearing zone, it is called *gas effect*. Gas effect is created by gas in the pores. Gas in the pores causes the density log to record too high a porosity (i.e. gas is lighter than oil or water), and causes the neutron log to record too low a porosity (i.e. gas has a lower concentration of hydrogen atoms than oil or water). The effect of gas on the Neutron-Density Log is a very important log response because it helps a geologist to detect gas-bearing zones.

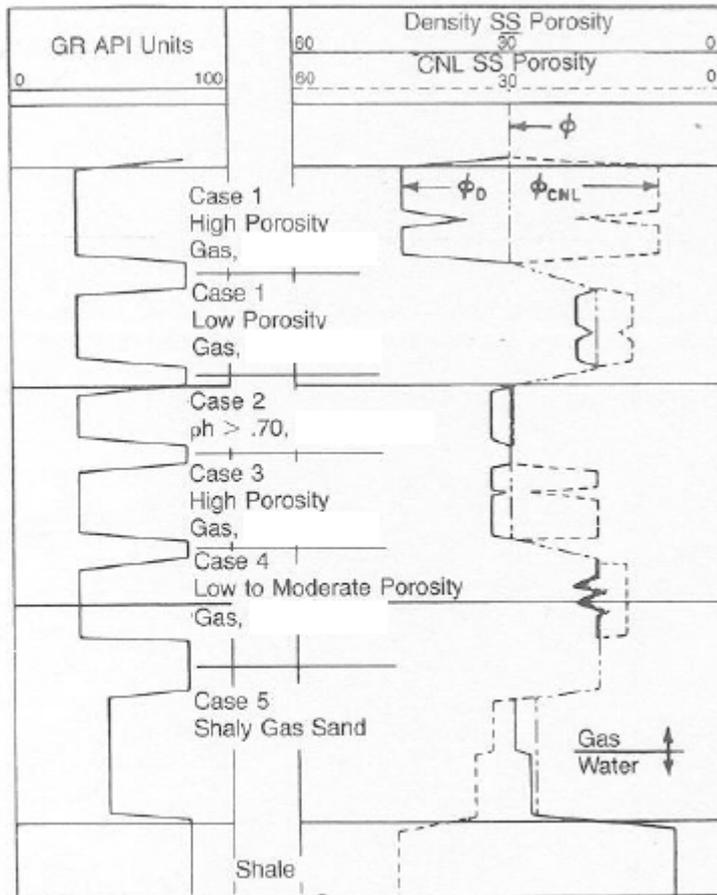
Qualitative Interpretation  
V/s  
Quantitative Interpretation



Water bearing zone

# Gas Bearing Formation Interpretation

- **Effect of gas on neutron log response**
  - lower hydrogen content than calibrated value, thus higher count rate resulting in low  $\phi_a$ .
  - Shale effect is opposite to the gas effect, makes detection extremely difficult
- **Effect of gas on density log response**
  - presence of gas reduces bulk density, resulting in a high apparent porosity.
  - shale effect can increase or decrease bulk density, dependent on shale's bulk density.
- **Effect of gas on sonic log response**
  - increase in sonic log porosity in poorly-consolidated sands.
  - not quantitative or predictable



Type I: mirror image,  
gas crossover  
(both FDC and CNL investigate same  
Saturation profile)

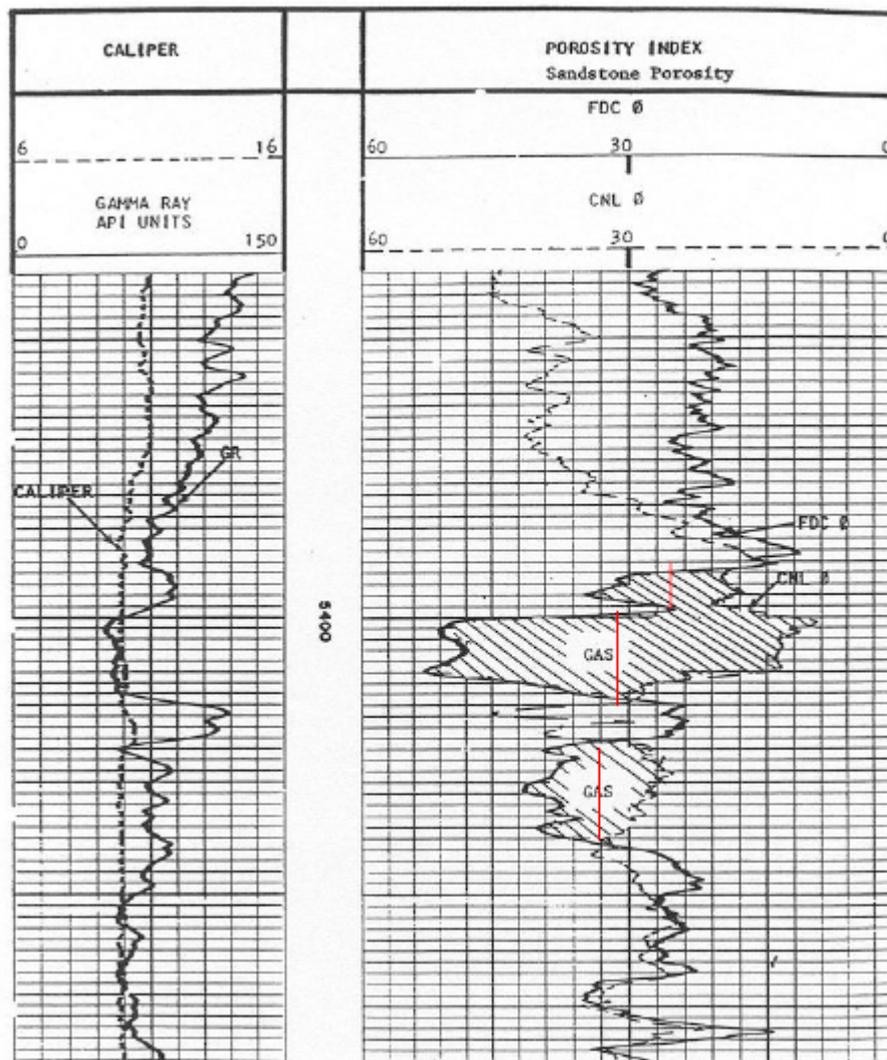
Type II: asymmetric  
gas crossover

Type III: Shaly gas sand

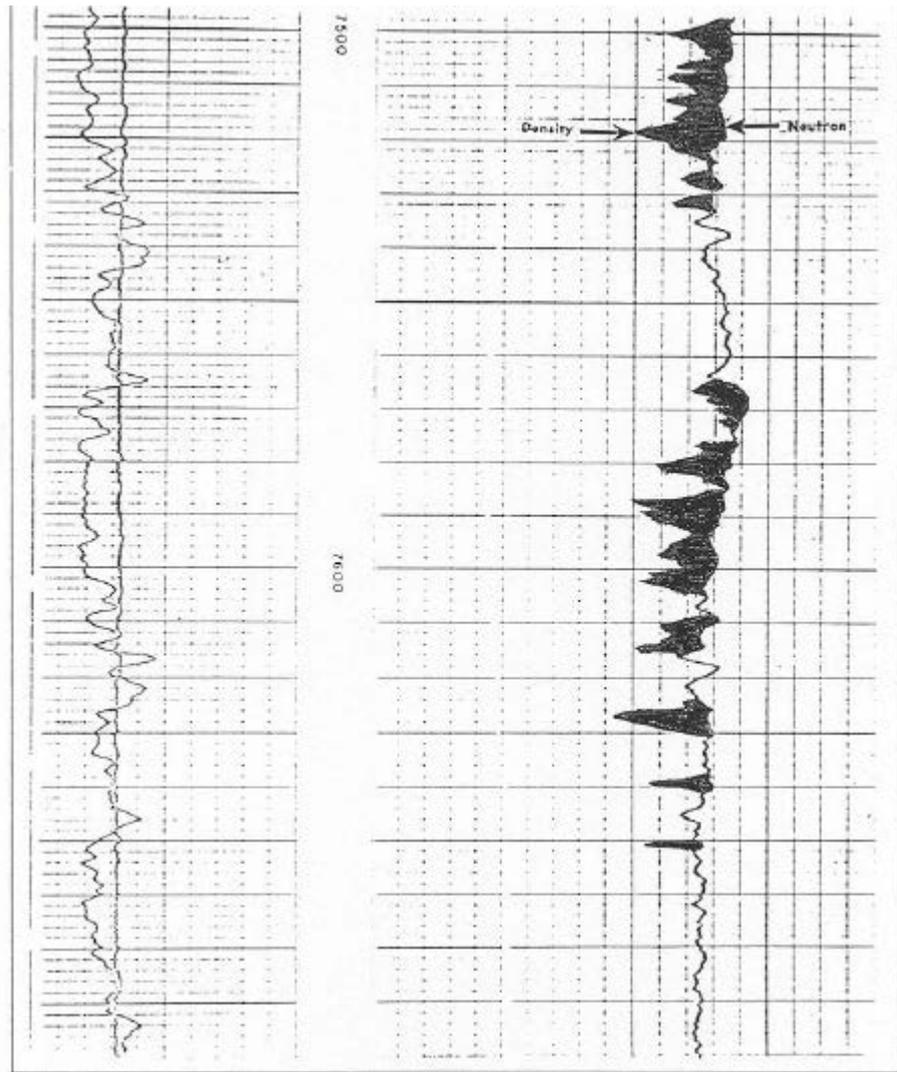
Idealized example of saturation effects on density and neutron logs.  
(Helander, 1983)

Density – neutron log  
 illustrating Type I gas effect  
 (Hilchie, 1978)

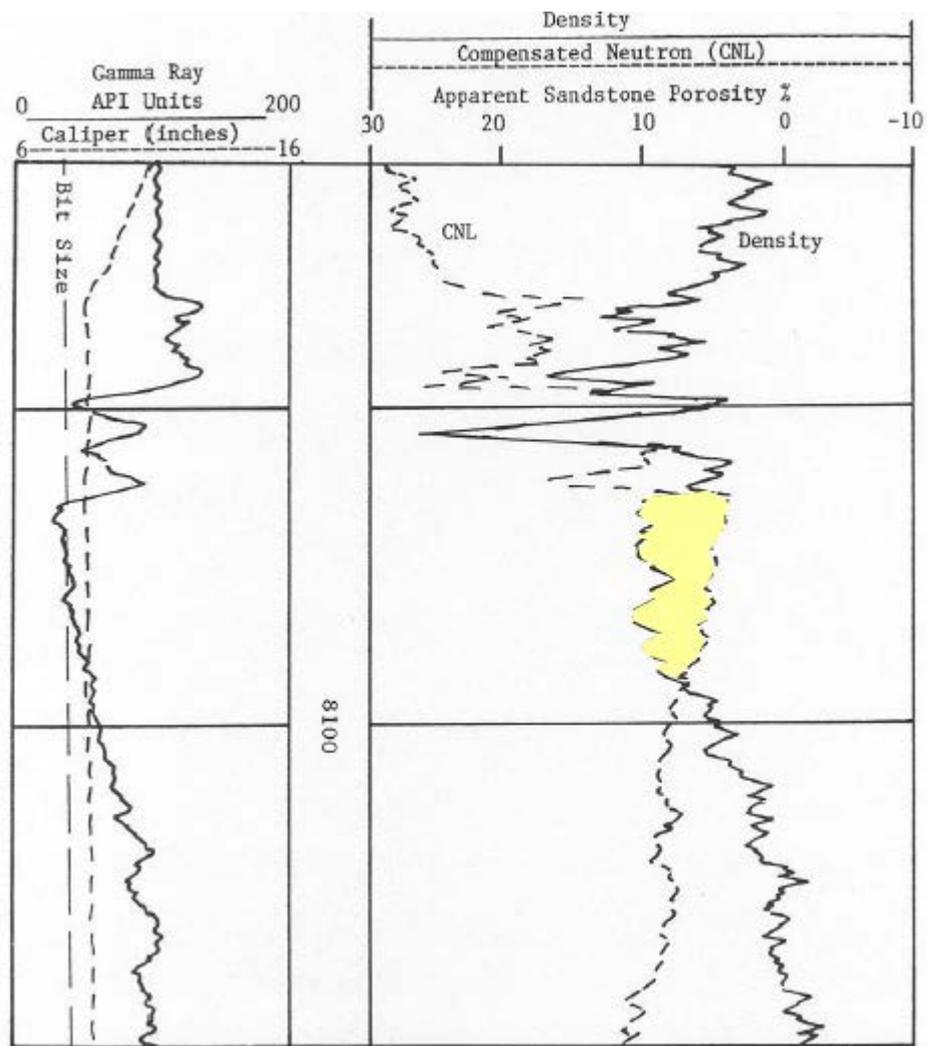
- deep invasion, or
- Extremely shallow invasion



Density – neutron log illustrating the effect of shallow to moderate invasion. (Type II)  
(Bassiouni, 1994)



Density – neutron log illustrating a gas-bearing shaly sand. (Type III) (Hilchie, 1978)



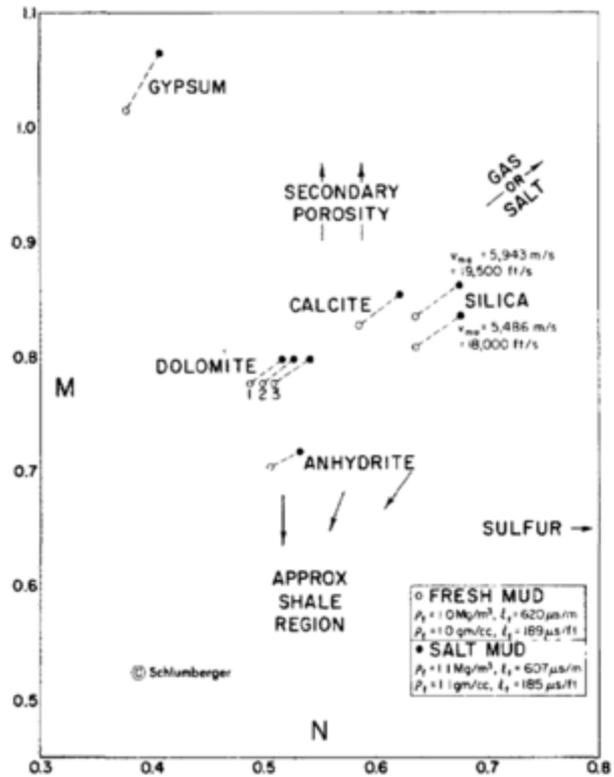
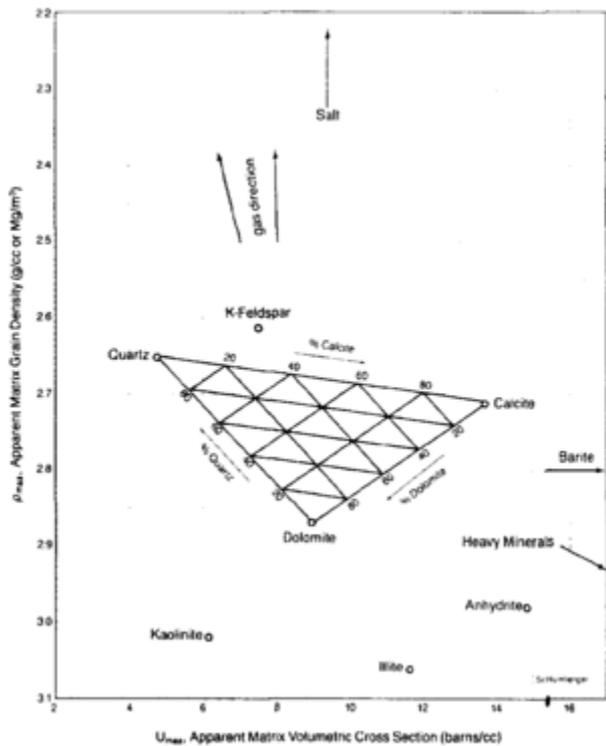
The gamma ray log measures the natural radiation of a formation, and primarily functions as a lithology log. It helps differentiate shales (high radioactivity) from sands, carbonates, and anhydrites (low radioactivity). The neutron log is a porosity device that is used to measure the amount of hydrogen in a formation. The density log is a porosity device that measures electron density. When these three logs are used together (i.e. Combination Gamma Ray Neutron-Density log), lithologies can be determined.

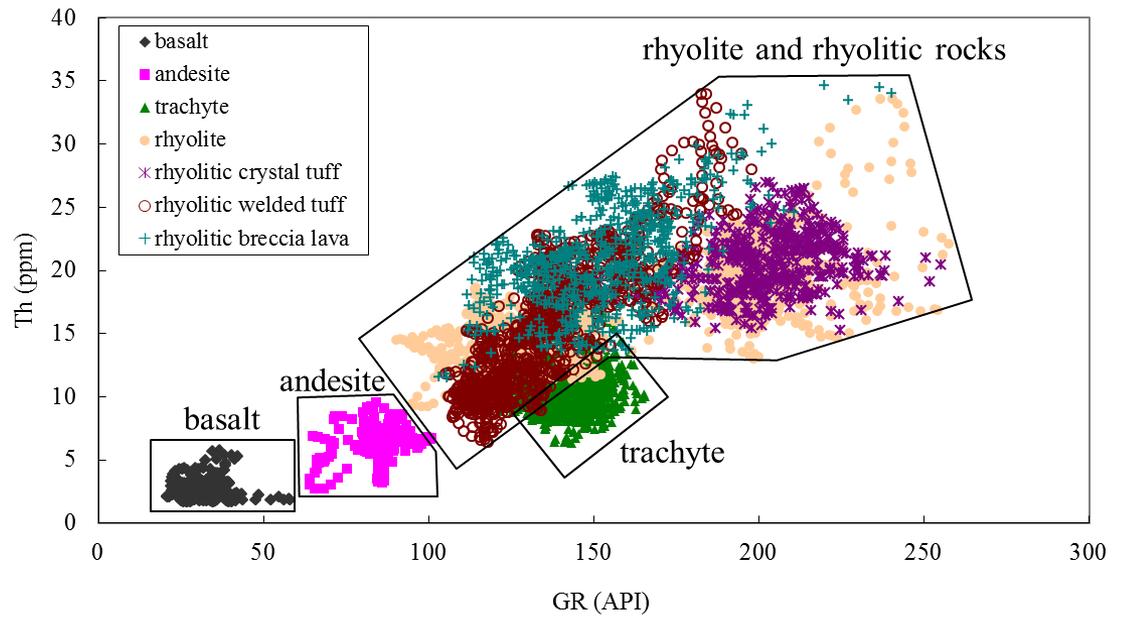
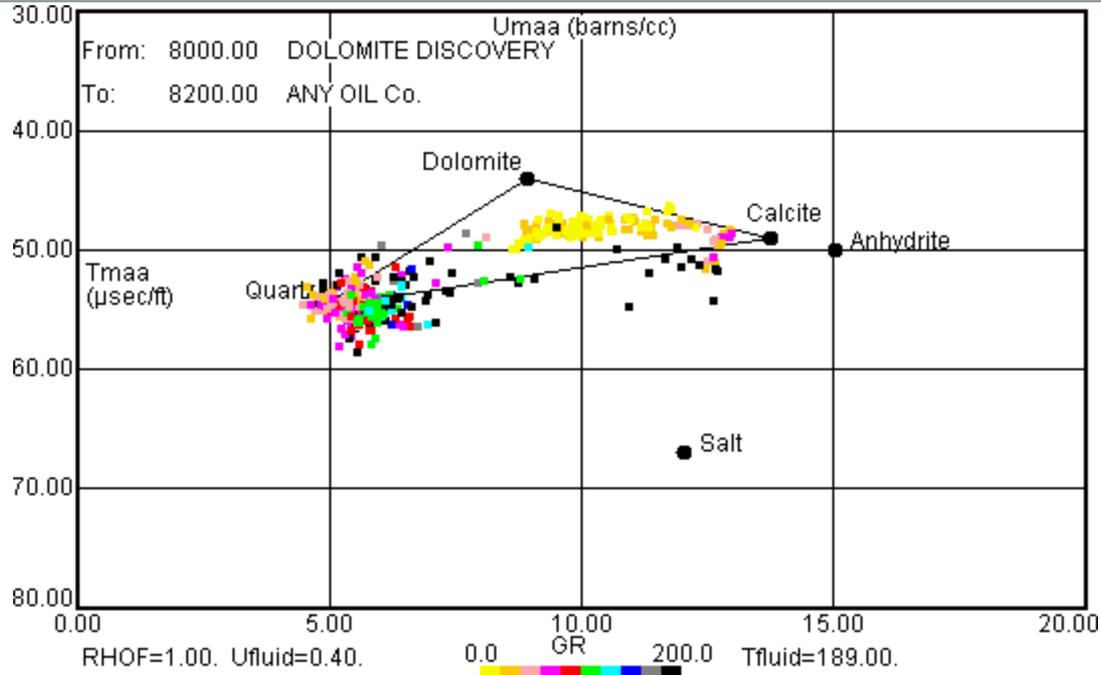
### **M-N\* Lithology Plot**

The M-N\* plot requires a sonic log along with neutron and density logs. The sonic log is a porosity log that measures interval transit time. A sonic log, neutron log, and density log are all necessary to calculate the lithology dependent variables M\* and N\*. M\* and N\* values are essentially independent of matrix porosity (sucrosic and intergranular).

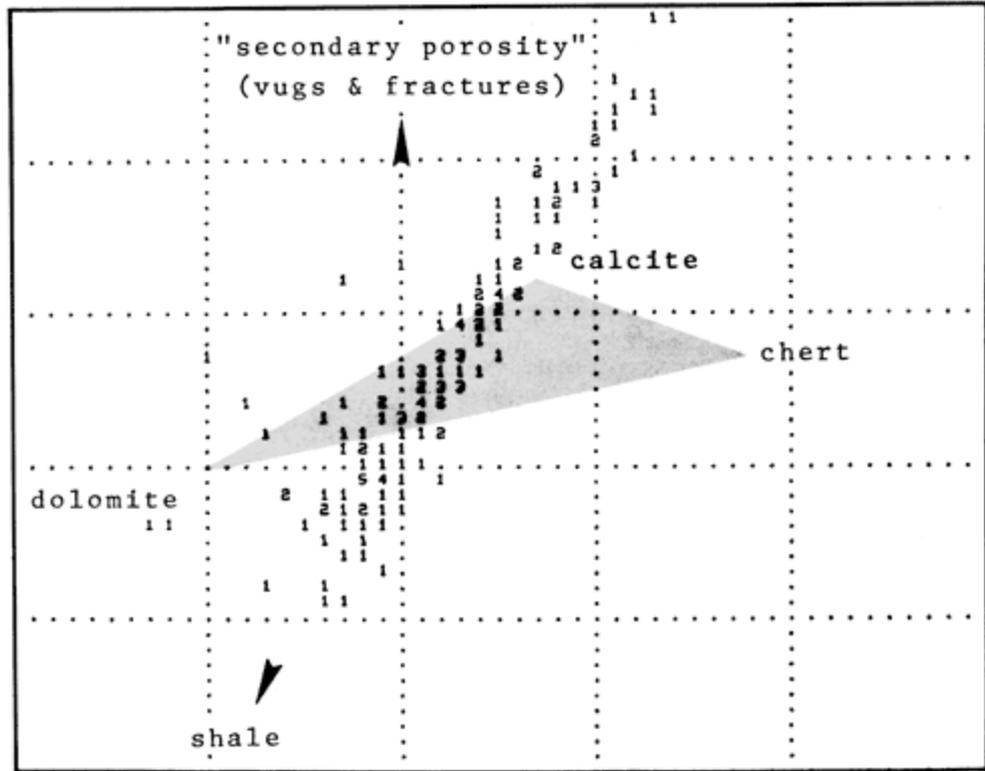
### **MID\* Lithology Plot**

The MID\* (Matrix Identification) plot, like the M-N\* is a crossplot technique which helps identify lithology and secondary porosity. Also, like M-N\* plot, the MID\* plot requires data from neutron, density, and sonic logs.





$$M = \frac{(\Delta_1)_f - \Delta_1}{\rho_b - \rho_f} \times .01$$

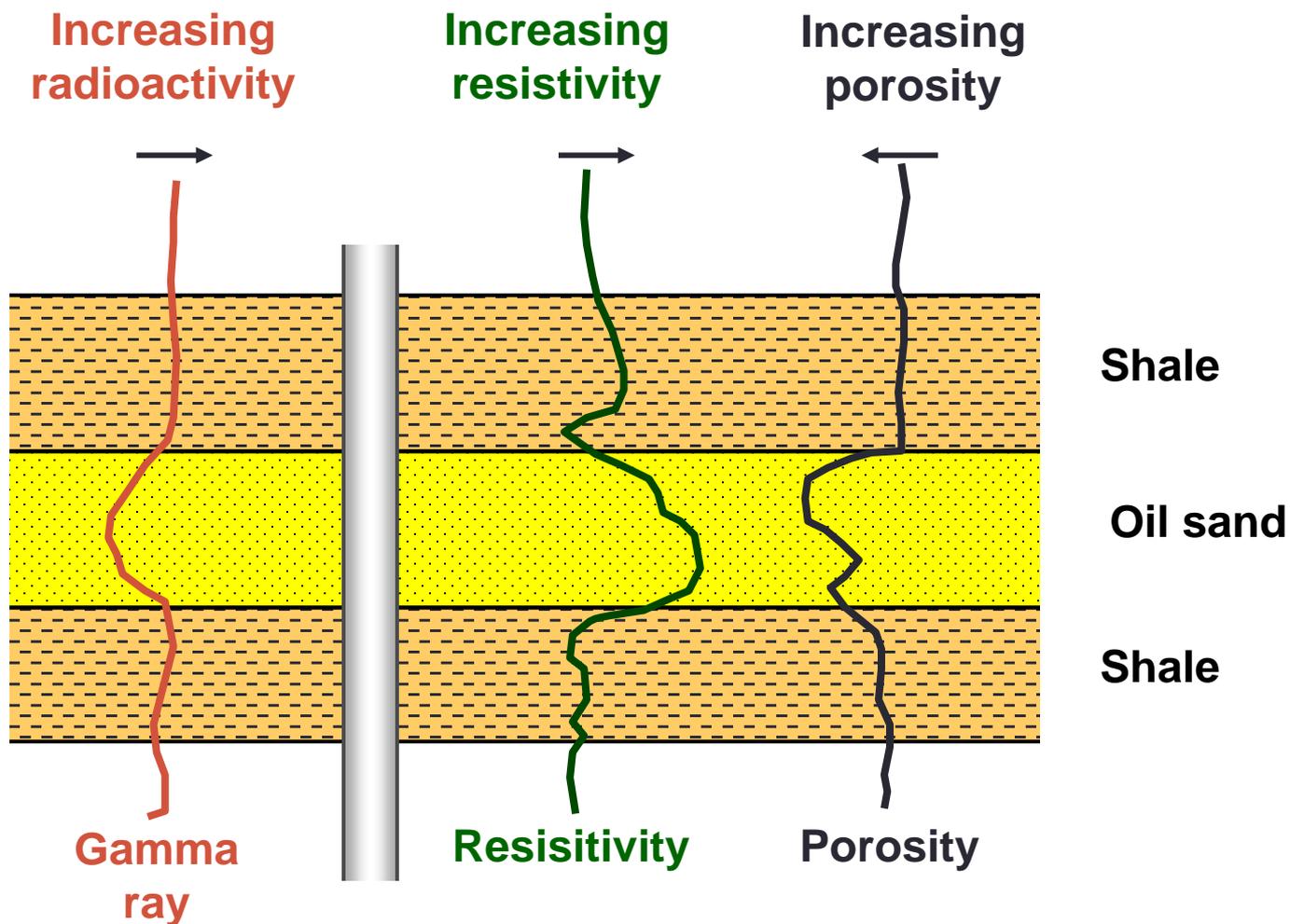


$$N = \frac{(\Phi_N)_f - \Phi_N}{\rho_b - \rho_f}$$

# **POROSITY DETERMINATION FROM LOGS**



# POROSITY DETERMINATION BY LOGGING





# POROSITY LOG TYPES

## 3 Main Log Types

- Bulk density
- Sonic (acoustic)
- Compensated neutron

These logs do not measure porosity directly. To accurately calculate porosity, the analyst must know:

- Formation lithology
- Fluid in pores of sampled reservoir volume

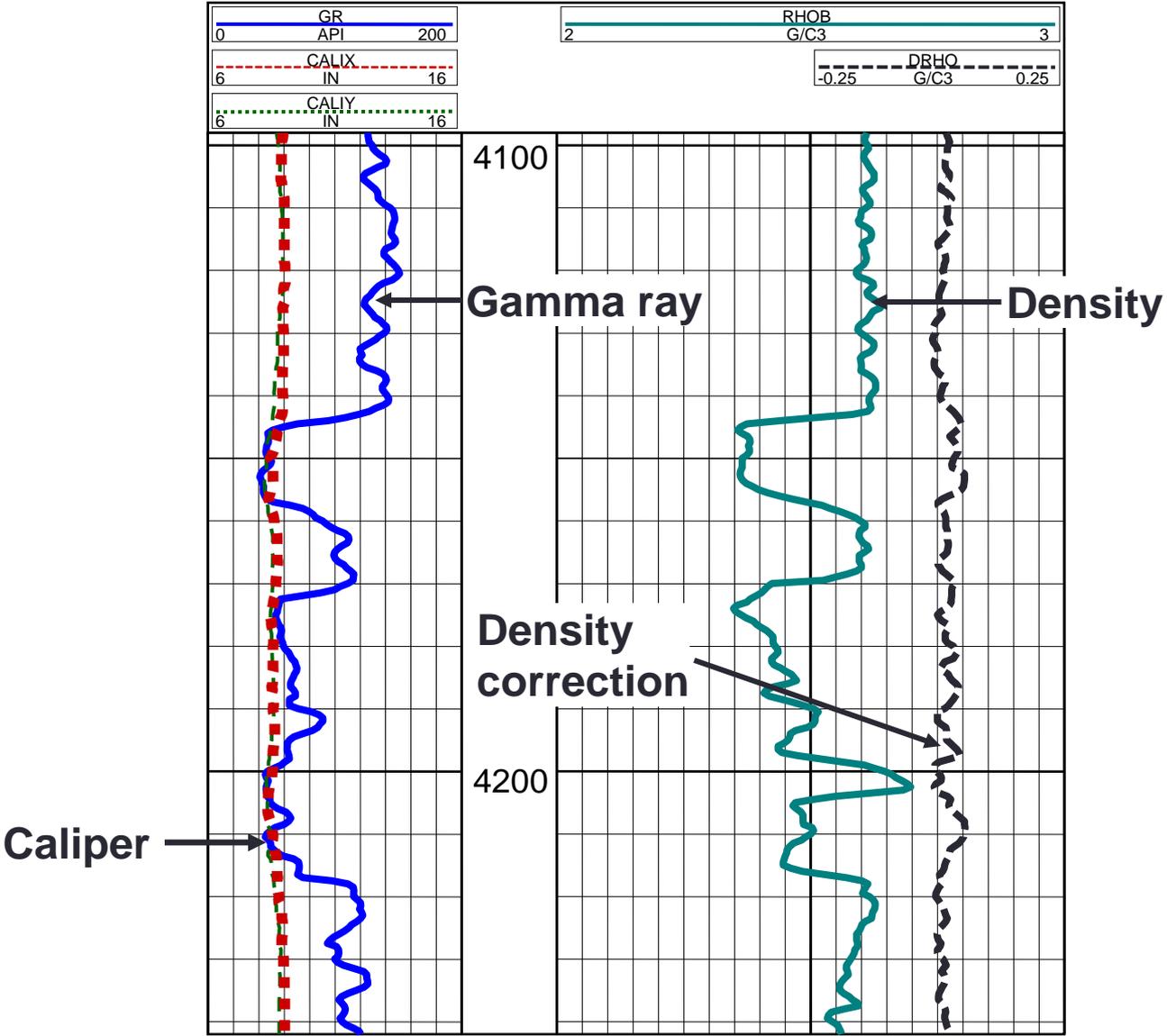
# DENSITY LOGS

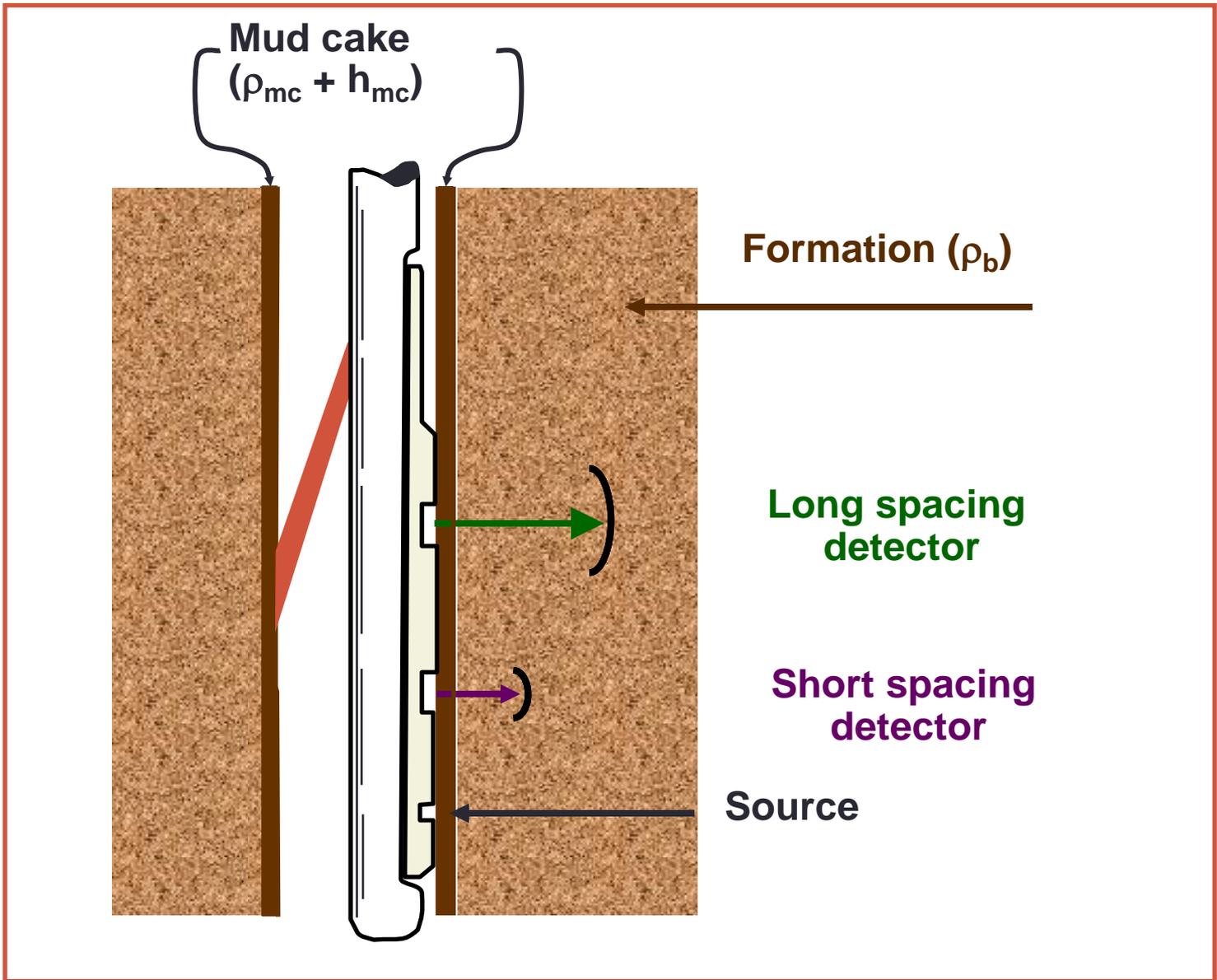
- Uses radioactive source to generate gamma rays
- Gamma ray collides with electrons in formation, losing energy
- Detector measures intensity of back-scattered gamma rays, which is related to electron density of the formation
- Electron density is a measure of bulk density

# DENSITY LOGS

- Bulk density,  $\rho_b$ , is dependent upon:
  - Lithology
  - Porosity
  - Density and saturation of fluids in pores
    - Saturation is fraction of pore volume occupied by a particular fluid (intensive)

# DENSITY LOG





# BULK DENSITY

$$\rho_b = \underbrace{\rho_{ma} (1 - \phi)}_{\text{Matrix}} + \underbrace{\rho_f \phi}_{\text{Fluids in flushed zone}}$$

- Measures electron density of a formation
- Strong function of formation bulk density
- Matrix bulk density varies with lithology
  - Sandstone 2.65 g/cc
  - Limestone 2.71 g/cc
  - Dolomite 2.87 g/cc



# POROSITY FROM DENSITY LOG

## Porosity equation

$$\phi = \frac{\rho_{ma} - \rho_b}{\rho_{ma} - \rho_f}$$

## Fluid density equation

$$\rho_f = \rho_{mf} S_{xo} + \rho_h (1 - S_{xo})$$

We usually assume the fluid density ( $\rho_f$ ) is between 1.0 and 1.1. If gas is present, the actual  $\rho_f$  will be  $< 1.0$  and the calculated porosity will be too high.

- $\rho_{mf}$  is the mud filtrate density, g/cc
- $\rho_h$  is the hydrocarbon density, g/cc
- $S_{xo}$  is the saturation of the flush/zone, decimal

# DENSITY LOGS

Working equation (hydrocarbon zone)

$$\rho_b = \phi S_{xo} \rho_{mf} + \phi (1 - S_{xo}) \rho_{hc}$$

$$+ V_{sh} \rho_{sh} + (1 - \phi - V_{sh}) \rho_{ma}$$

|                               |   |                                  |
|-------------------------------|---|----------------------------------|
| $\rho_b$                      | = | Recorded parameter (bulk volume) |
| $\phi S_{xo} \rho_{mf}$       | = | Mud filtrate component           |
| $\phi (1 - S_{xo}) \rho_{hc}$ | = | Hydrocarbon component            |
| $V_{sh} \rho_{sh}$            | = | Shale component                  |
| $1 - \phi - V_{sh}$           | = | Matrix component                 |

# DENSITY LOGS

- If minimal shale,  $V_{sh} \approx 0$
- If  $\rho_{hc} \approx \rho_{mf} \approx \rho_f$ , then
- $\rho_b = \phi \rho_f - (1 - \phi) \rho_{ma}$

$$\phi = \phi_d = \frac{\rho_{ma} - \rho_b}{\rho_{ma} - \rho_f}$$

$\phi_d$  = Porosity from density log, fraction  
 $\rho_{ma}$  = Density of formation matrix, g/cm<sup>3</sup>  
 $\rho_b$  = Bulk density from log measurement, g/cm<sup>3</sup>  
 $\rho_f$  = Density of fluid in rock pores, g/cm<sup>3</sup>  
 $\rho_{hc}$  = Density of hydrocarbons in rock pores, g/cm<sup>3</sup>  
 $\rho_{mf}$  = Density of mud filtrate, g/cm<sup>3</sup>  
 $\rho_{sh}$  = Density of shale, g/cm<sup>3</sup>  
 $V_{sh}$  = Volume of shale, fraction  
 $S_{xo}$  = Mud filtrate saturation in zone invaded by mud filtrate,

# BULK DENSITY LOG

001) BONANZA 1

GRC  
0 150

TLDC  
0.2 200

RHOC  
1.95 2.95

SPC  
-160 MV 40

SNC  
0.2 200

CNLLC  
0.5

ACAL  
6 16

MLLCF  
0.2 200

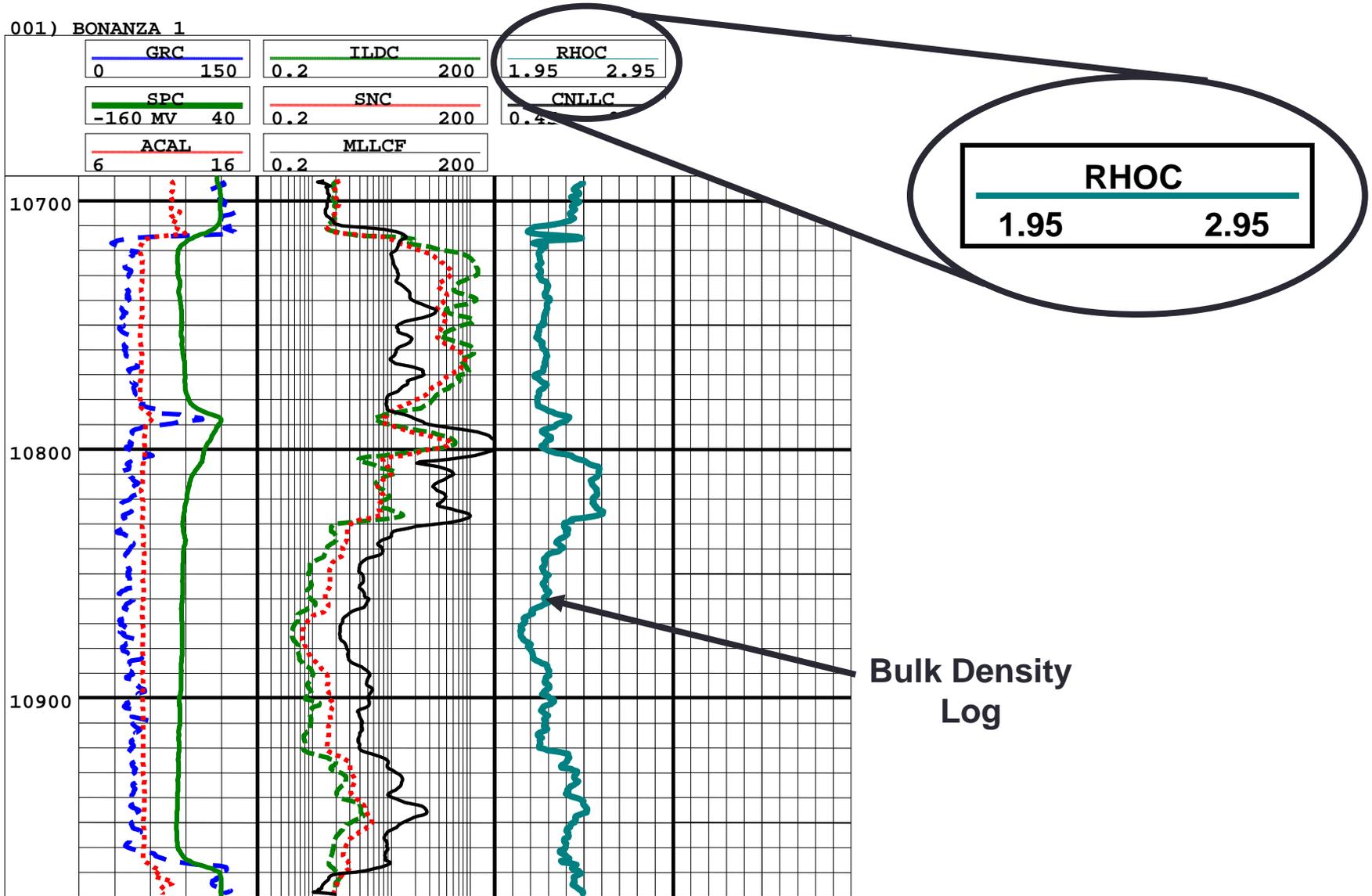
10700

10800

10900

RHOC  
1.95 2.95

Bulk Density Log



# NEUTRON LOG

- Logging tool emits high energy neutrons into formation
- Neutrons collide with nuclei of formation's atoms
- Neutrons lose energy (velocity) with each collision

# NEUTRON LOG

- The most energy is lost when colliding with a hydrogen atom nucleus
- Neutrons are slowed sufficiently to be captured by nuclei
- Capturing nuclei become excited and emit gamma rays

# NEUTRON LOG

- Depending on type of logging tool either gamma rays or non-captured neutrons are recorded
- Log records porosity based on neutrons captured by formation
- If hydrogen is in pore space, porosity is related to the ratio of neutrons emitted to those counted as captured
- Neutron log reports porosity, calibrated assuming calcite matrix and fresh water in pores, if these assumptions are invalid we must correct the neutron porosity value

# NEUTRON LOG

## Theoretical equation

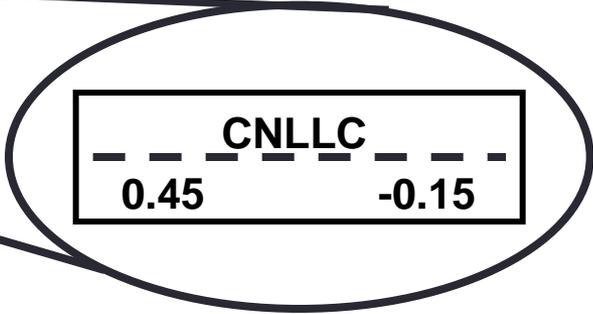
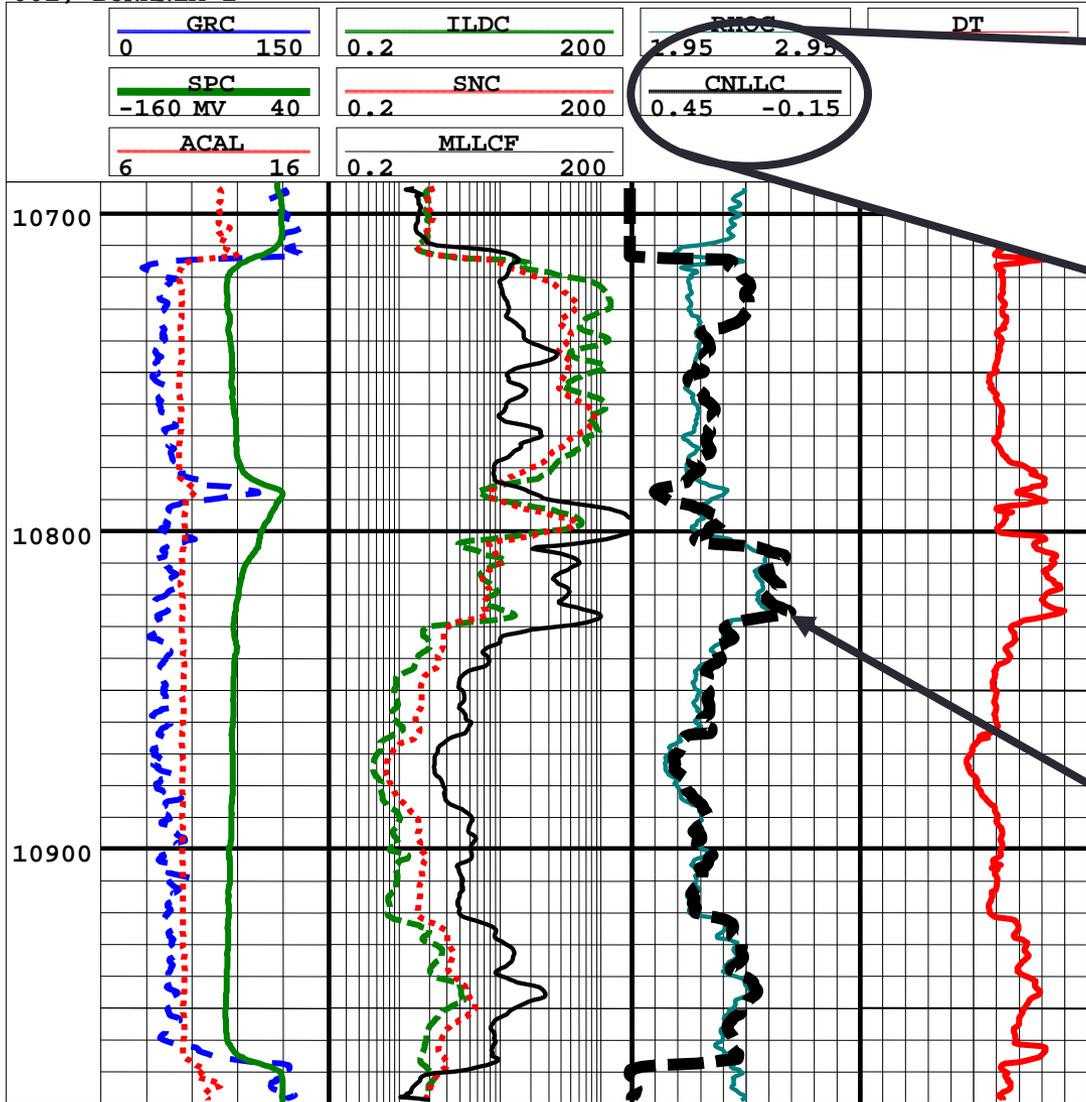
$$\phi_N = \phi S_{xo} \phi_{Nmf} + \phi (1 - S_{xo}) \phi_{Nhc} \\ + V_{sh} \phi_{sh} + (1 - \phi - V_{sh}) \phi_{Nma}$$

$\phi_N$  = Recorded parameter  
 $\phi S_{xo} \phi_{Nmf}$  = Mud filtrate portion  
 $\phi (1 - S_{xo}) \phi_{Nhc}$  = Hydrocarbon portion  
 $V_{sh} \phi_{Nsh}$  = Shale portion  
 $(1 - \phi - V_{sh}) \phi_{Nhc}$  = Matrix portion where  $\phi$  = True porosity of rock  
 $\phi_N$  = Porosity from neutron log measurement, fraction

$\phi_{Nma}$  = Porosity of matrix fraction  
 $\phi_{Nhc}$  = Porosity of formation saturated with hydrocarbon fluid, fraction  
 $\phi_{Nmf}$  = Porosity saturated with mud filtrate, fraction  
 $V_{sh}$  = Volume of shale, fraction  
 $S_{xo}$  = Mud filtrate saturation in zone invaded by mud filtrate, fraction

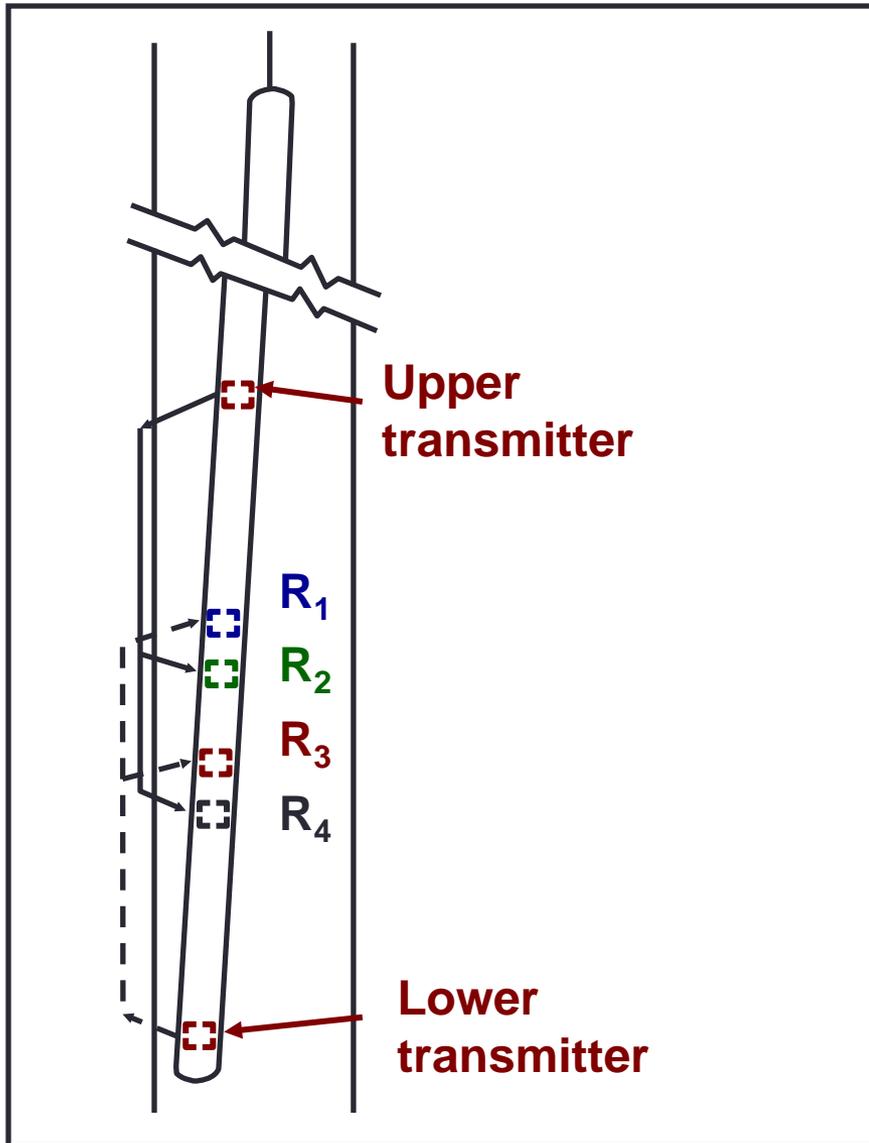
# POROSITY FROM NEUTRON LOG

001) BONANZA 1

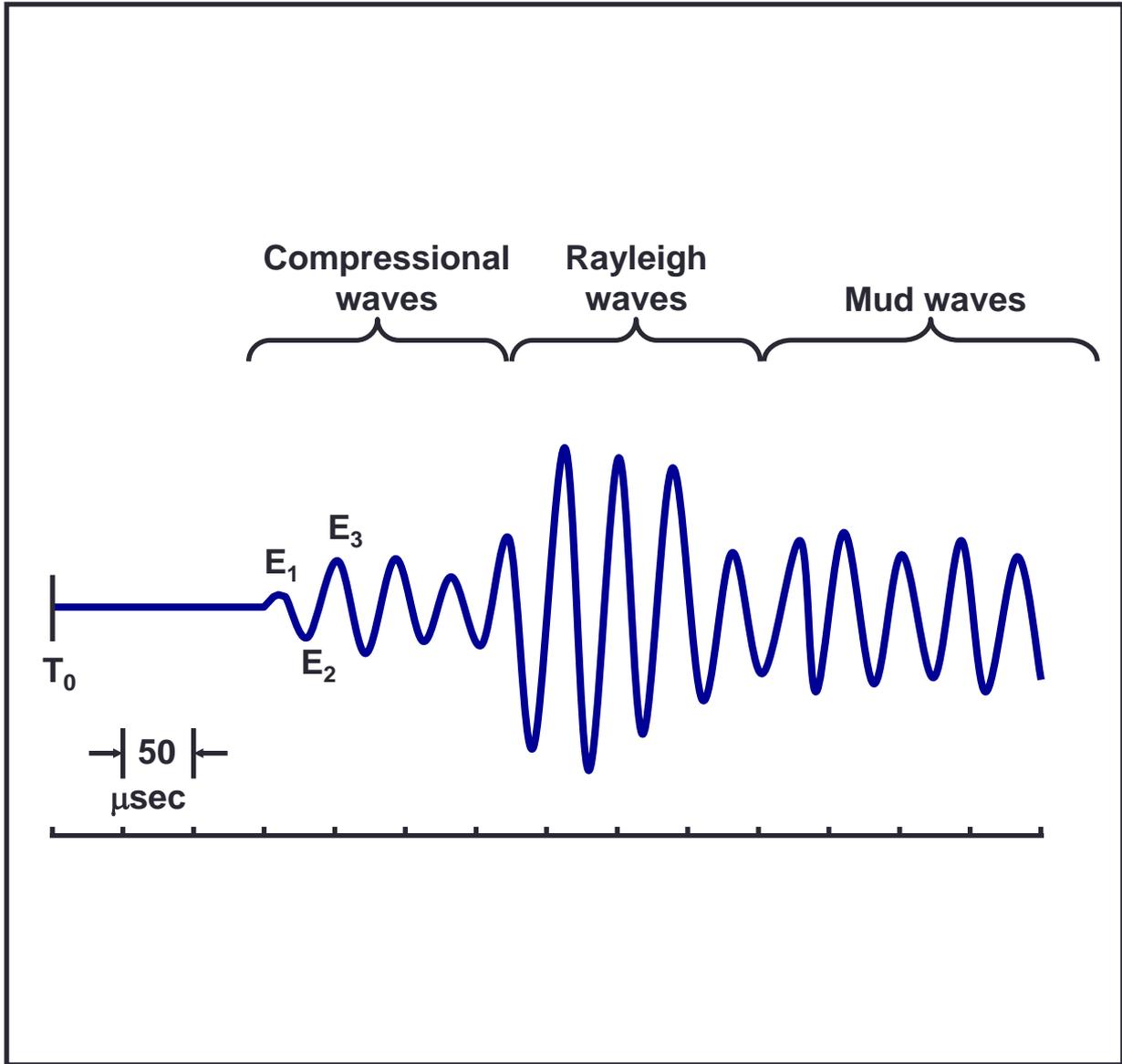


Neutron Log

# ACOUSTIC (SONIC) LOG



- Tool usually consists of one sound transmitter (above) and two receivers (below)
- Sound is generated, travels through formation
- Elapsed time between sound wave at receiver 1 vs receiver 2 is dependent upon density of medium through which the sound traveled



# COMMON LITHOLOGY MATRIX TRAVEL TIMES USED

| <b>Lithology</b> | <b>Typical Matrix Travel Time, <math>\Delta t_{ma}</math>, <math>\mu\text{sec}/\text{ft}</math></b> |
|------------------|---|
| <b>Sandstone</b> | <b>55.5</b>   |
| <b>Limestone</b> | <b>47.5</b>   |
| <b>Dolomite</b>  | <b>43.5</b>   |
| <b>Anhydrite</b> | <b>50.0</b>   |
| <b>Salt</b>      | <b>66.7</b>   |

# ACOUSTIC (SONIC) LOG

## Working equation

$$\Delta t_L = \phi S_{xo} \Delta t_{mf} + \phi (1 - S_{xo}) \Delta t_{hc} \\ + V_{sh} \Delta t_{sh} + (1 - \phi - V_{sh}) \Delta t_{ma}$$

$\Delta t_L$  = Recorded parameter, travel time read from log

$\phi S_{xo} \Delta t_{mf}$  = Mud filtrate portion

$\phi (1 - S_{xo}) \Delta t_{hc}$  = Hydrocarbon portion

$V_{sh} \Delta t_{sh}$  = Shale portion

$(1 - \phi - V_{sh}) \Delta t_{ma}$  = Matrix portion

# ACOUSTIC (SONIC) LOG

- If  $V_{sh} = 0$  and if hydrocarbon is liquid (i.e.  $\Delta t_{mf} \approx \Delta t_f$ ), then
- $\Delta t_L = \phi \Delta t_f + (1 - \phi) \Delta t_{ma}$

or

$$\phi_s = \phi = \frac{\Delta t_L - \Delta t_{ma}}{\Delta t_f - \Delta t_{ma}}$$

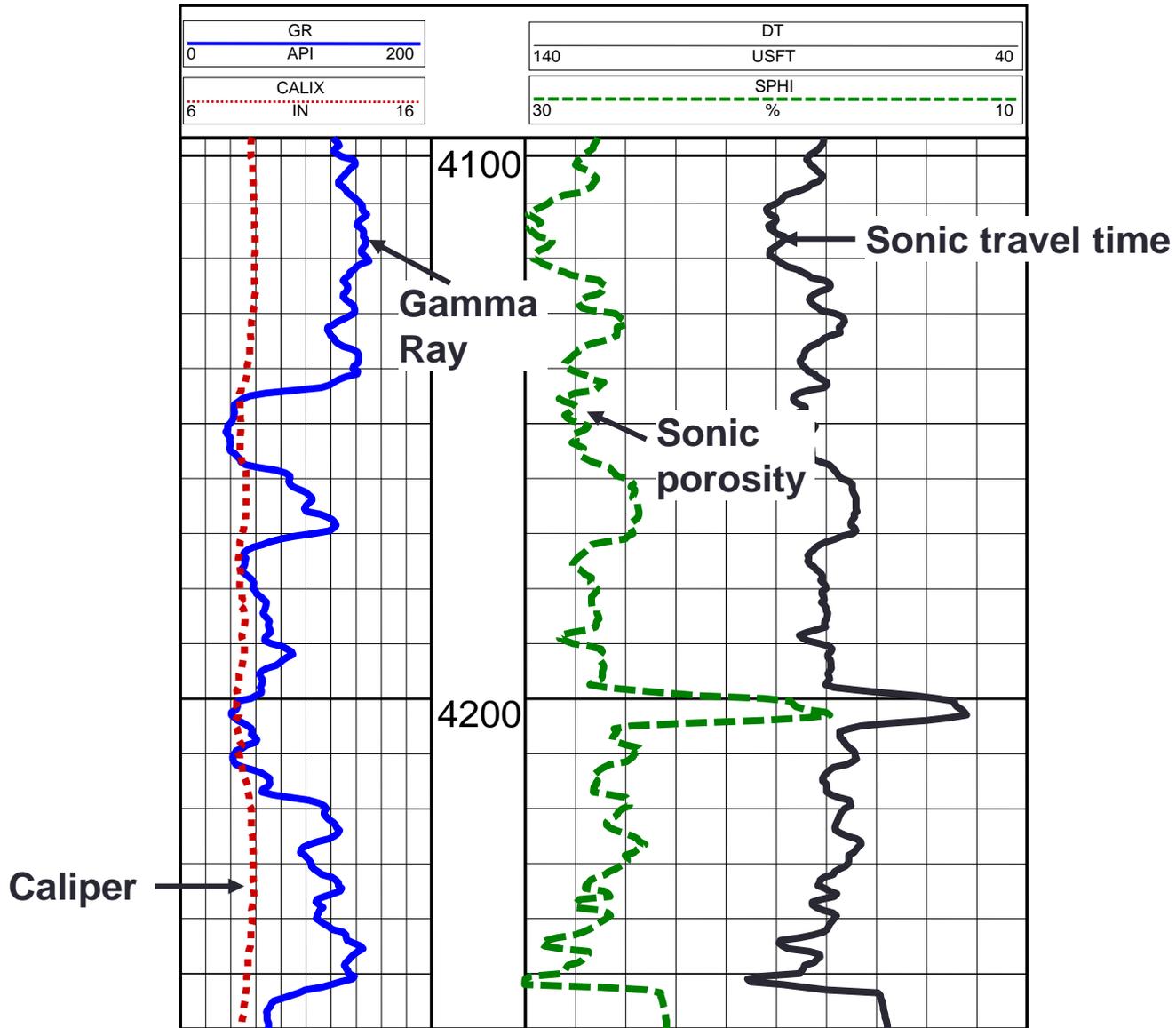
$\phi_s$  = Porosity calculated from sonic log reading, fraction

$\Delta t_L$  = Travel time reading from log, microseconds/ft

$\Delta t_{ma}$  = Travel time in matrix, microseconds/ft

$\Delta t_f$  = Travel time in fluid, microseconds/ft

# ACOUSTIC (SONIC) LOG



# SONIC LOG

The response can be written as follows:

$$t_{\log} = t_{ma} (1 - \phi) + t_f \phi$$

$$\phi = \frac{t_{\log} - t_{ma}}{t_f - t_{ma}}$$

$t_{\log}$  = log reading,  $\mu\text{sec}/\text{ft}$

$t_{ma}$  = the matrix travel time,  $\mu\text{sec}/\text{ft}$

$t_f$  = the fluid travel time,  $\mu\text{sec}/\text{ft}$

$\phi$  = porosity

# SONIC LOG

001) BONANZA 1

GRC  
0 150

TLDC  
0.2 200

RHOC  
1.95 2.95

DT  
150 us/f 50

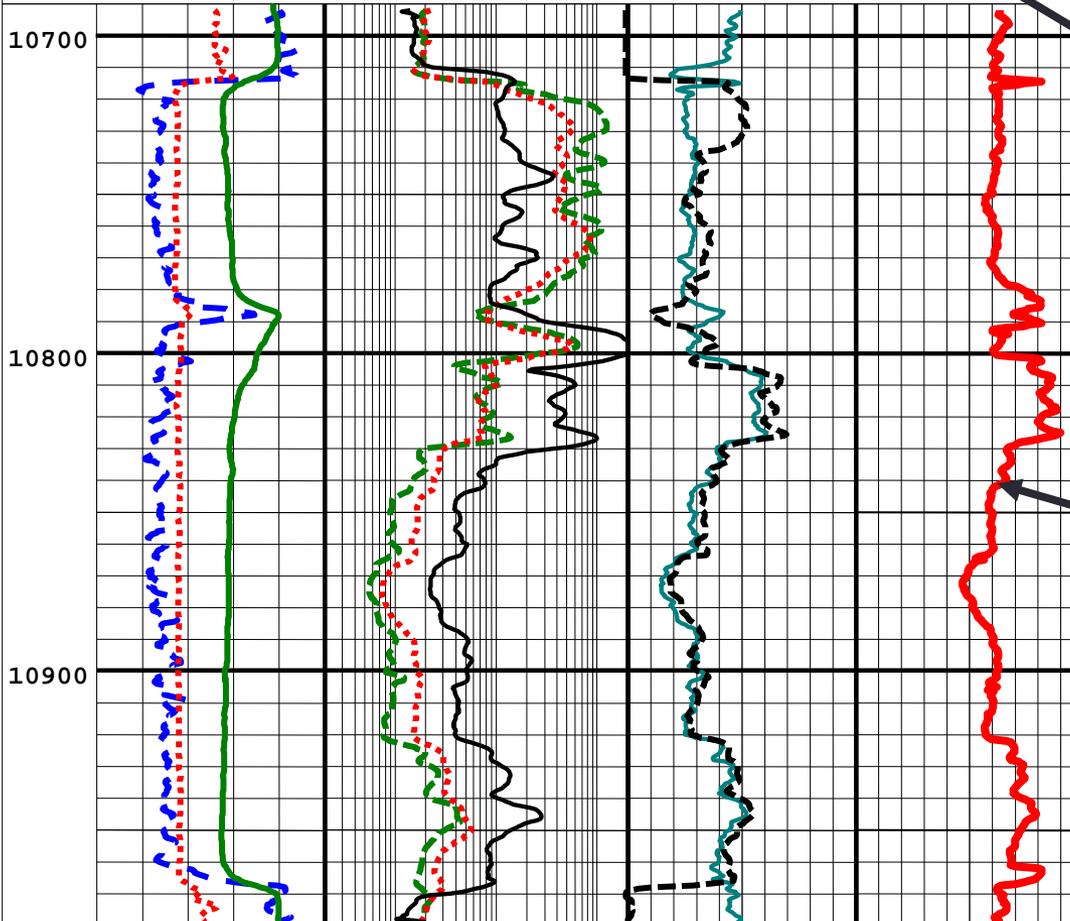
SPC  
-160 MV 40

SNC  
0.2 200

CNLLC  
0.45 -0.15

ACAL  
6 16

MLLCF  
0.2 200



Sonic  
Log



# EXAMPLE

## Calculating Rock Porosity Using an Acoustic Log

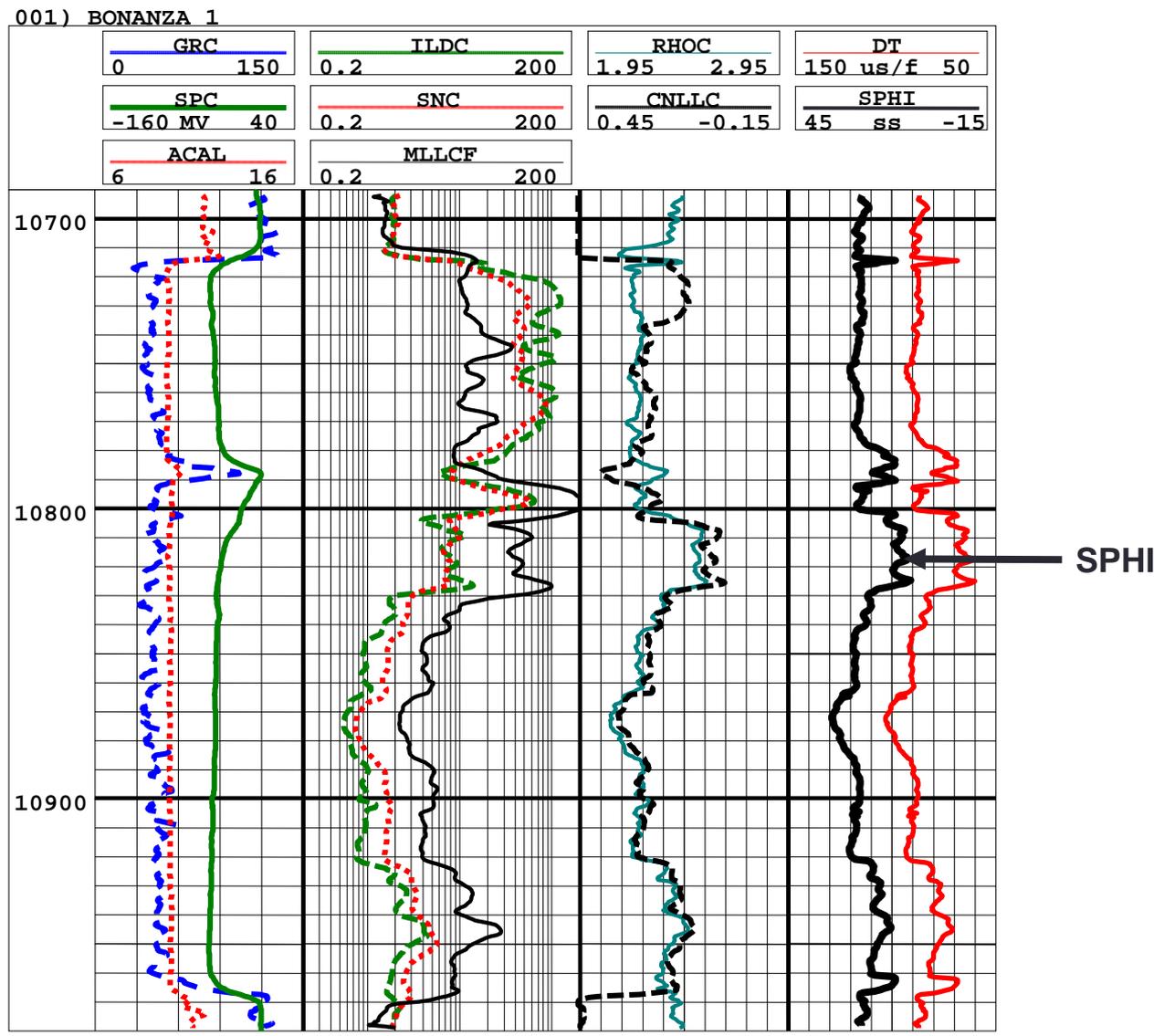
Calculate the porosity for the following intervals. The measured travel times from the log are summarized in the following table.

At depth of 10,820', acoustic log reads travel time of  $65 \mu\text{s}/\text{ft}$ .

Calculate porosity. Does this value agree with density and neutron logs?

Assume a matrix travel time,  $\Delta t_m = 51.6 \mu\text{sec}/\text{ft}$ . In addition, assume the formation is saturated with water having a  $\Delta t_f = 189.0 \mu\text{sec}/\text{ft}$ .

# EXAMPLE SOLUTION SONIC LOG



# FACTORS AFFECTING SONIC LOG RESPONSE

- Unconsolidated formations
- Naturally fractured formations
- Hydrocarbons (especially gas)
- Rugose salt sections

# RESPONSES OF POROSITY LOGS

## The three porosity logs:

- Respond differently to different matrix compositions
- Respond differently to presence of gas or light oils

## Combinations of logs can:

- Imply composition of matrix
- Indicate the type of hydrocarbon in pores



# GAS EFFECT

- Density -  $\phi$  is too high
- Neutron -  $\phi$  is too low
- Sonic -  $\phi$  is not significantly affected by gas



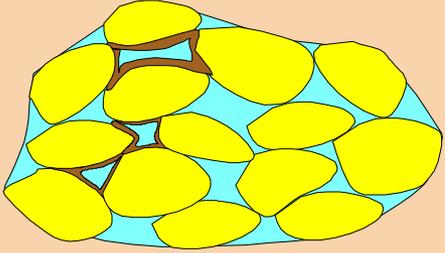
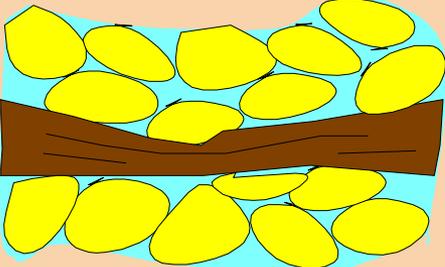
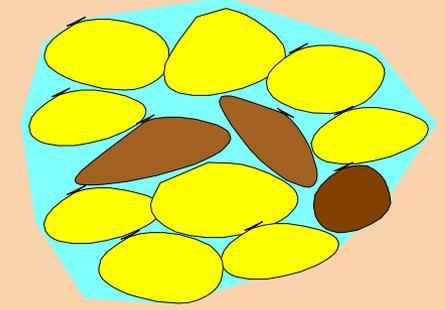
# ESTIMATING POROSITY FROM WELL LOGS

Openhole logging tools are the most common method of determining porosity:

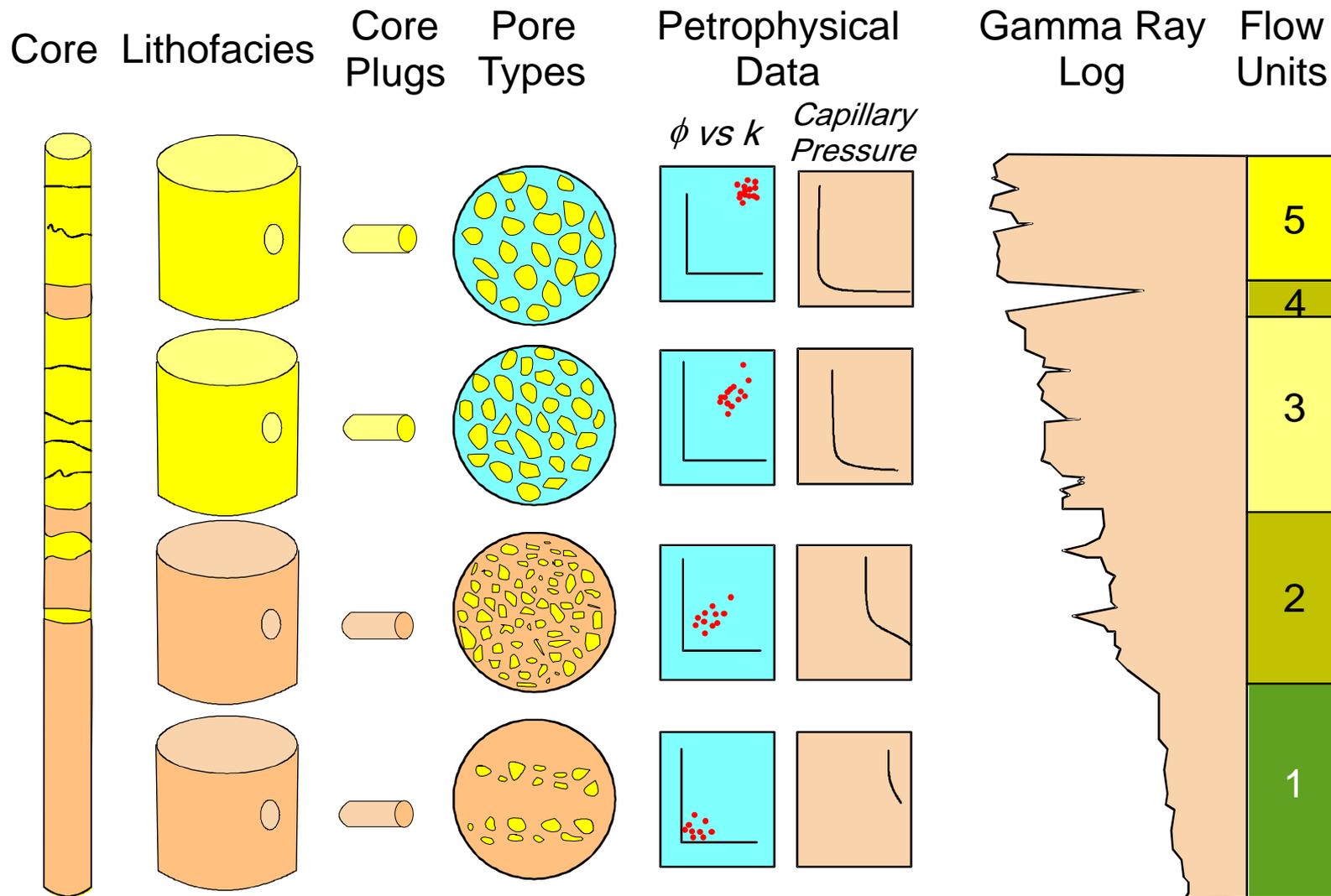
- Less expensive than coring and may be less risk of sticking the tool in the hole
- Coring may not be practical in unconsolidated formations or in formations with high secondary porosity such as vugs or natural fractures.

If porosity measurements are very important, both coring and logging programs may be conducted so the log-based porosity calculations can be used to calibrated to the core-based porosity measurements.

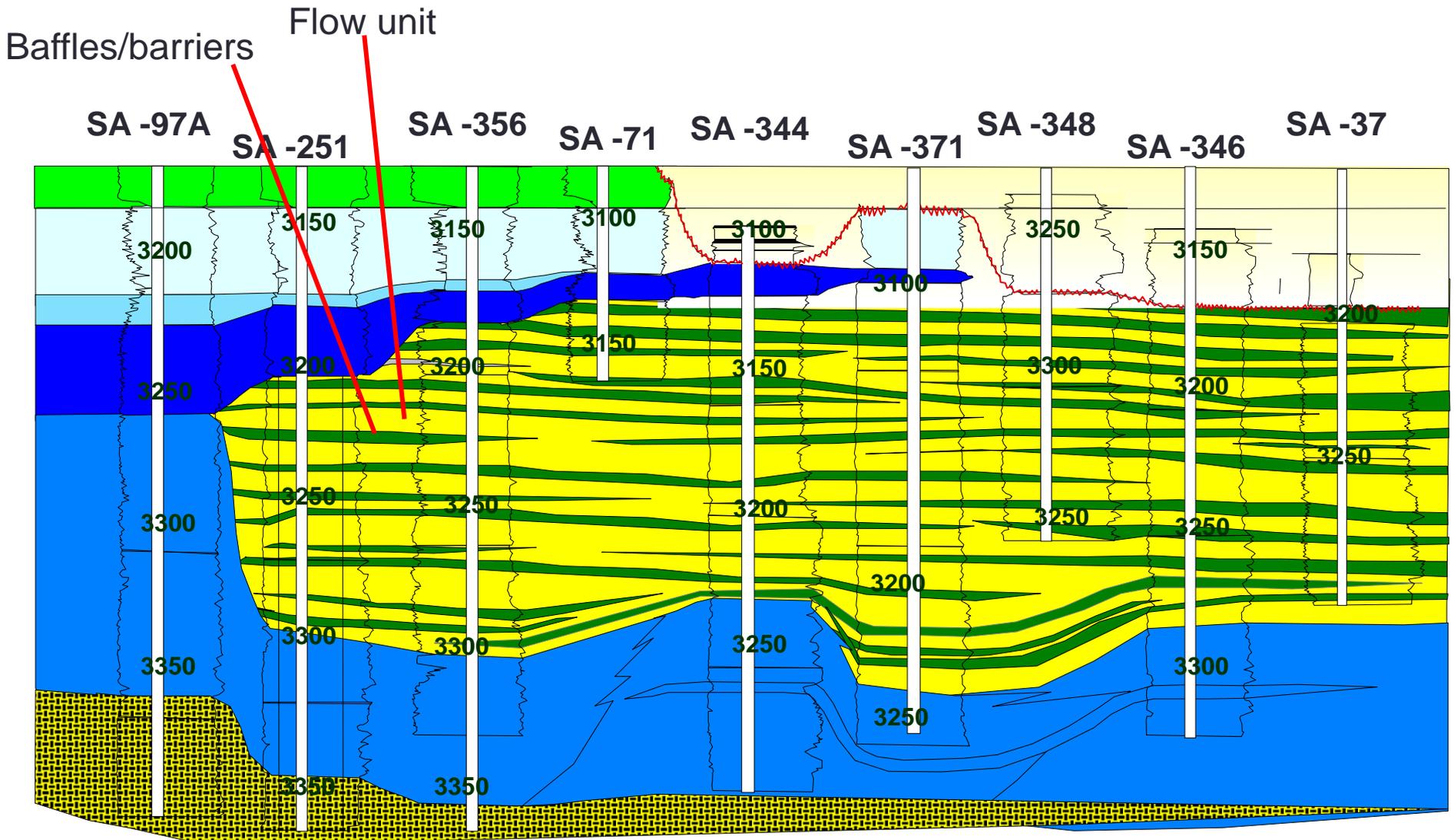
# Influence Of Clay-Mineral Distribution On Effective Porosity

|  |   |  |
|--|---|--|
|   | <p><b>Dispersed Clay</b></p> <ul style="list-style-type: none"> <li>• Pore-filling</li> <li>• Pore-lining</li> <li>• Pore-bridging</li> </ul> | <div style="display: flex; align-items: center; justify-content: center;"> <div style="background-color: cyan; padding: 5px; margin-right: 10px;"><math>\phi_e</math></div> <div style="background-color: brown; padding: 5px; text-align: center;">Clay Minerals</div> </div> |
|   | <p><b>Clay Lamination</b></p>   | <div style="display: flex; align-items: center; justify-content: center;"> <div style="background-color: cyan; padding: 5px; margin-right: 10px;"><math>\phi_e</math></div> <div style="background-color: brown; padding: 5px; text-align: center;">Clay Minerals</div> </div> |
|  | <p><b>Structural Clay<br/>(Rock Fragments,<br/>Rip-Up Clasts,<br/>Clay-Replaced Grains)</b></p>   | <div style="display: flex; align-items: center; justify-content: center;"> <div style="background-color: cyan; padding: 5px; margin-right: 10px;"><math>\phi_e</math></div> <div style="background-color: brown; padding: 5px; text-align: center;">Clay Minerals</div> </div> |

# GEOLOGICAL AND PETROPHYSICAL DATA USED TO DEFINE FLOW UNITS

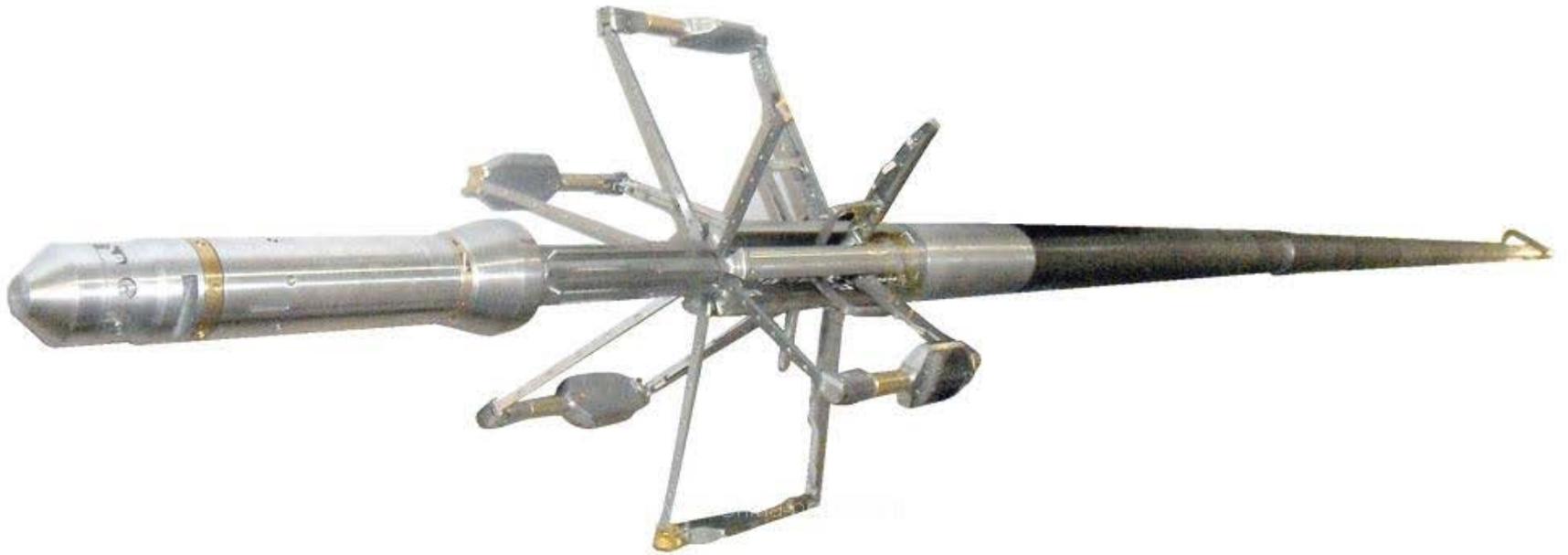


# Schematic Reservoir Layering Profile in a Carbonate Reservoir



From Bastian and others

# Resistivity Log

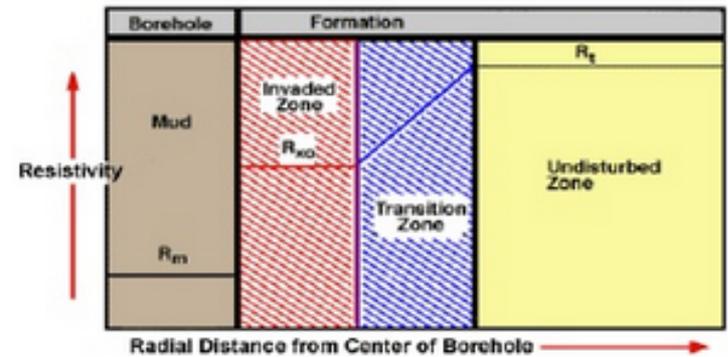


- Resistivity logging is a method of well logging that works by characterizing the rock or sediment in a borehole by measuring its electrical resistivity. Resistivity is a fundamental material property which represents how strongly a material opposes the flow of electric current. In these logs, resistivity is measured using 4 electrical probes to eliminate the resistance of the contact leads. The log must run in holes containing electrically conductive mud or water.
- Resistivity logging is sometimes used in mineral exploration (especially exploration for iron and potassium) and water-well drilling, but most commonly for formation evaluation in oil- and gas-well drilling. Most rock materials are essentially insulators, while their enclosed fluids are conductors. Hydrocarbon fluids are an exception, because they are almost infinitely resistive. When a formation is porous and contains salty water, the overall resistivity will be low. When the formation contains hydrocarbon, or contains very low porosity, its resistivity will be high. High resistivity values may indicate a hydrocarbon bearing formation.

- Usually while drilling, drilling fluids invade the formation, changes in the resistivity are measured by the tool in the invaded zone. For this reason, several resistivity tools with different investigation lengths are used to measure the formation resistivity. If water based mud is used and oil is displaced, "deeper" resistivity logs (or those of the "virgin zone") will show lower conductivity than the invaded zone. If oil based mud is used and water is displaced, deeper logs will show higher conductivity than the invaded zone. This provides not only an indication of the fluids present, but also, at least qualitatively, whether the formation is permeable or not.

## Basics about the Resistivity:

- Resistivity measures the electric properties of the formation,
- Resistivity is measured as,  $R$  in  $\Omega$  per  $m$ ,
- Resistivity is the inverse of conductivity,
- The ability to conduct electric current depends upon:
  - The **Volume** of water,
  - The **Temperature** of the formation,
  - The **Salinity** of the formation



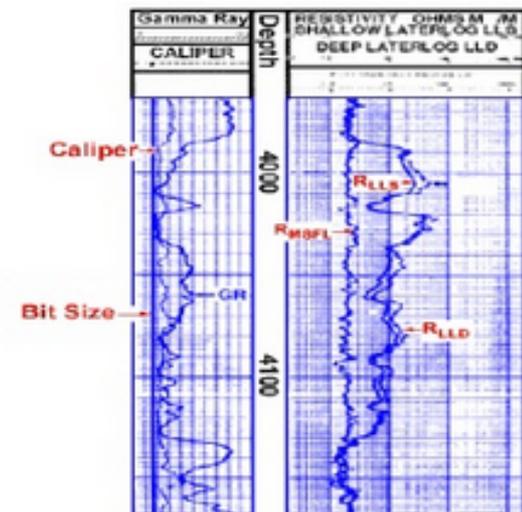
## The Resistivity Log:

**Resistivity logs** measure the ability of rocks to conduct electrical current and are scaled in units of ohm-meters.

## The Usage:

Resistivity logs are electric logs which are used to:

- Determine Hydrocarbon versus Water-bearing zones,
- Indicate Permeable zones,
- Determine Resistivity Porosity.



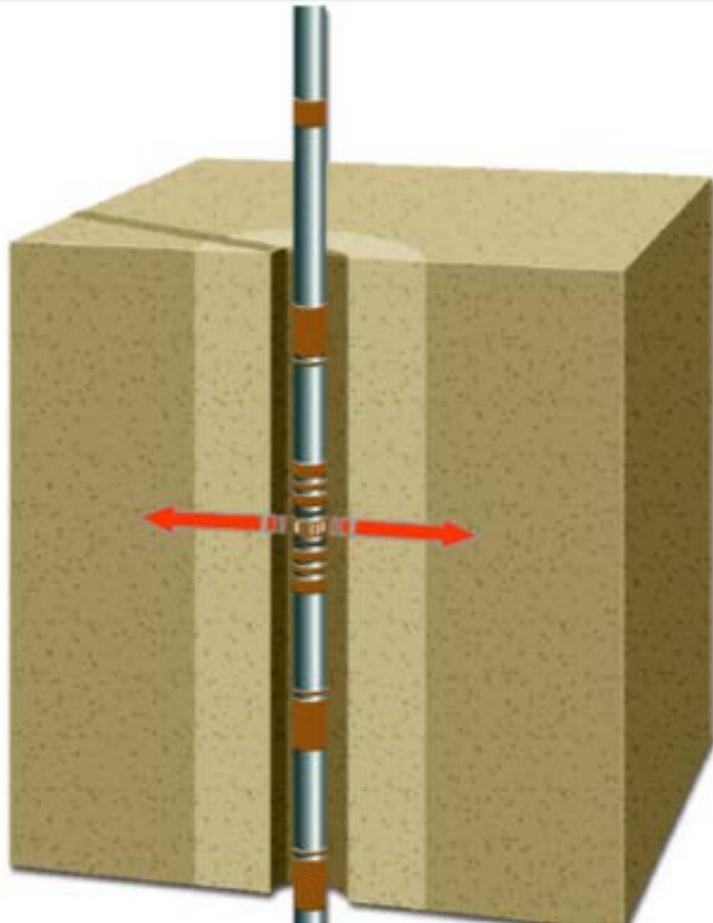
## Resistivity Logging

There are two types of resistivity logging tools:

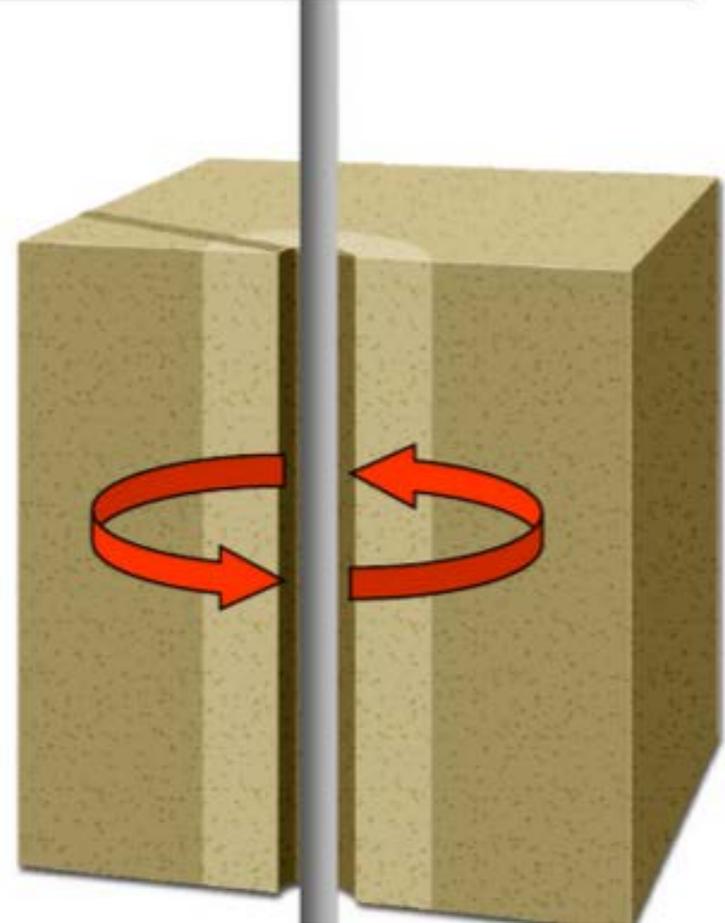
- Laterolog tools send a current from electrodes on the logging tool, through the formation, to a return electrode located either at surface or downhole.
  - Laterolog tools need a conductive path between the logging tool and the formation
- Induction tools generate current loops in the formation and measure the strength of the electromagnetic signal created by these current loops.
  - Induction tools do not require a conductive path in the borehole. They work in oil-base muds and air-filled holes.

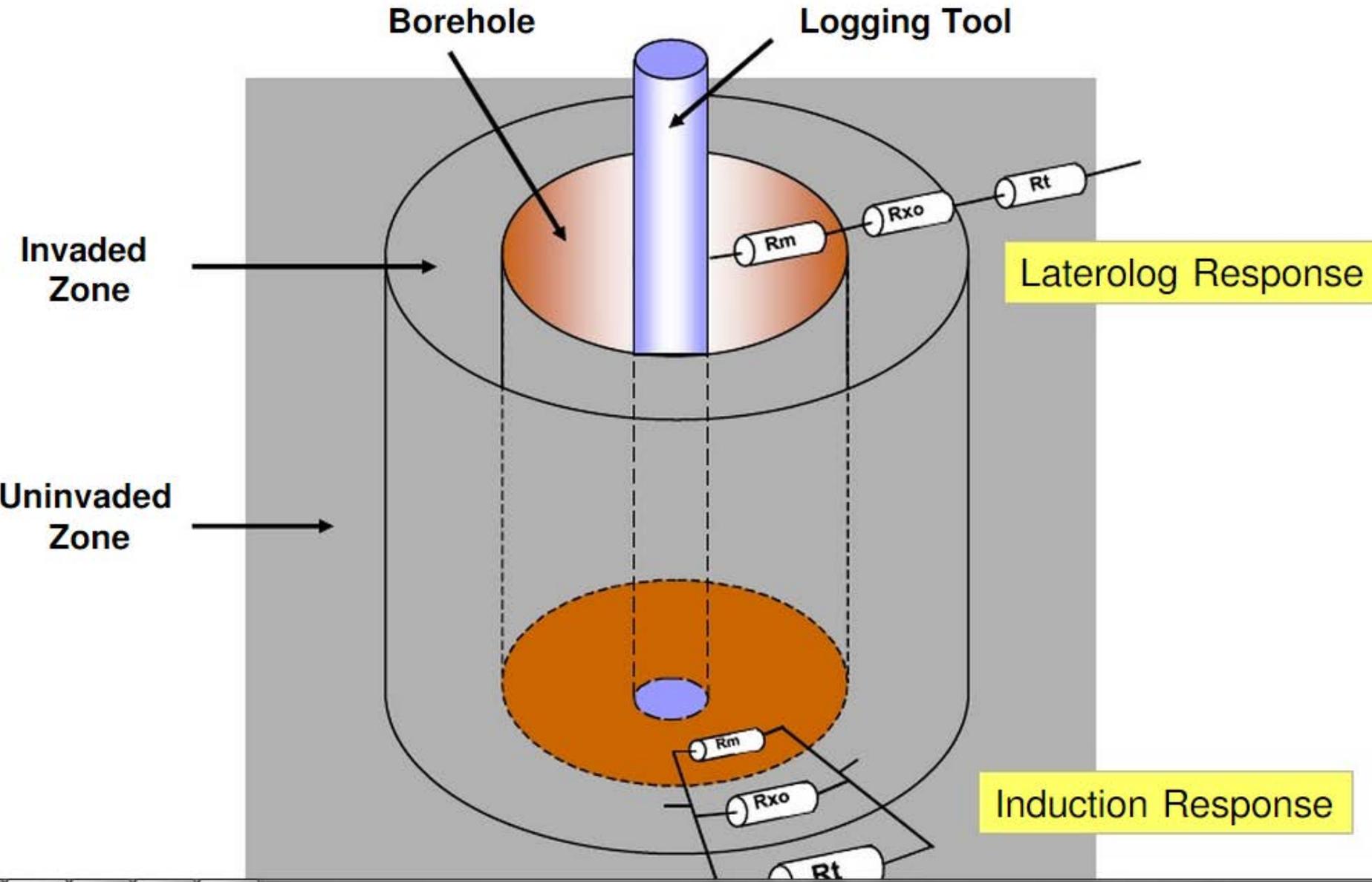
## Basic Resistivity tool types

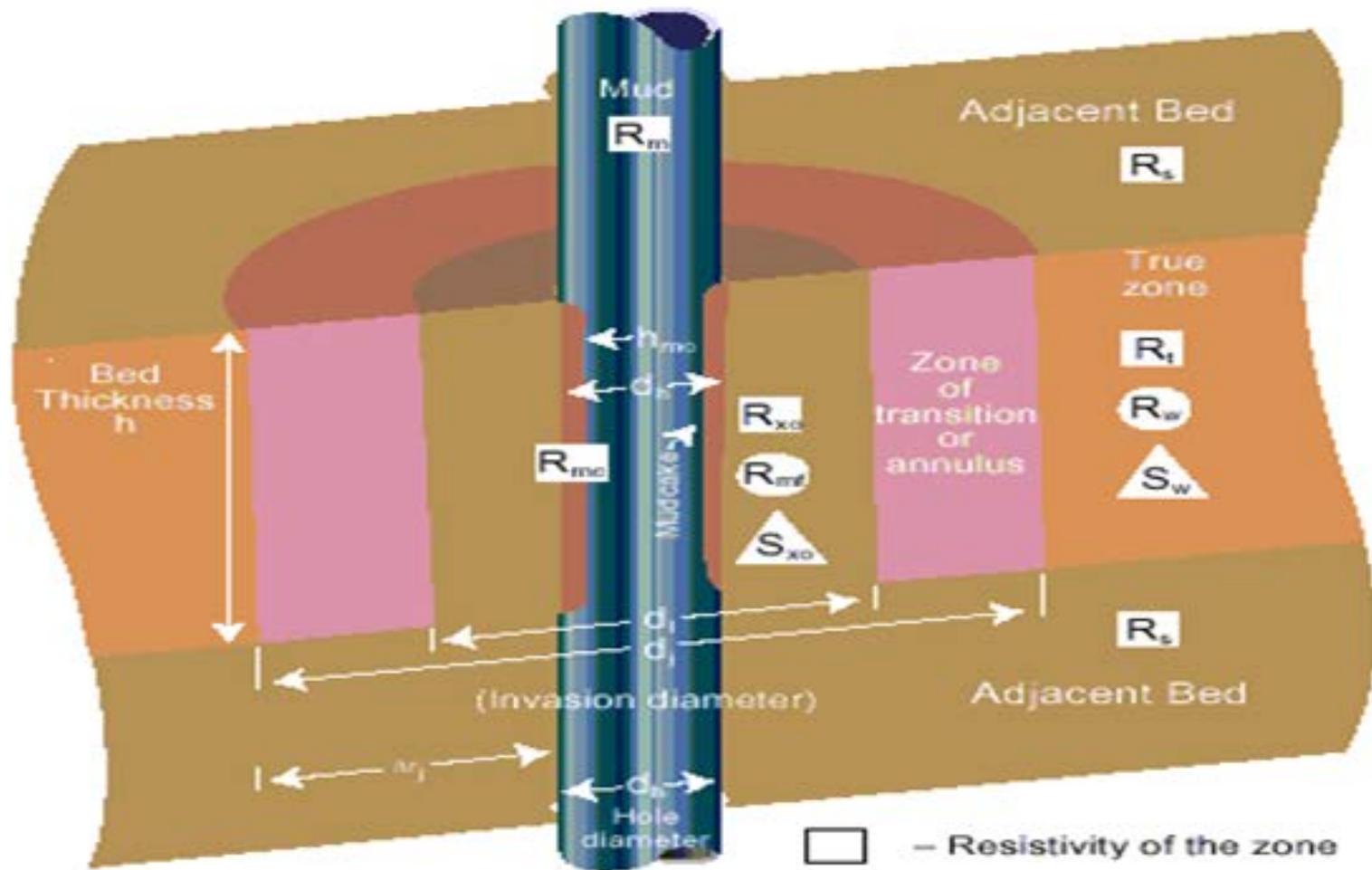
Laterolog Logging Tools



Induction Logging Tools





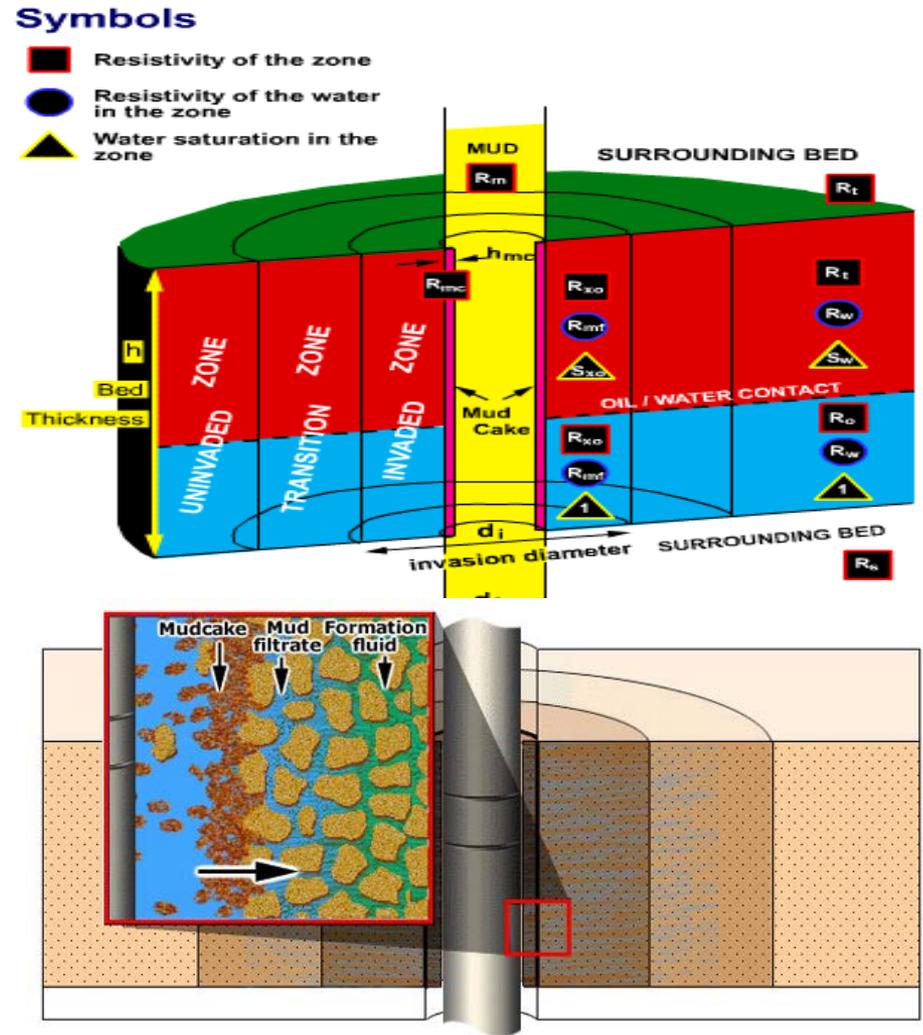


- Resistivity of the zone
- Resistivity of the water in the zone
- Water saturation in the zone

# R<sub>t</sub> – True Formation Resistivity

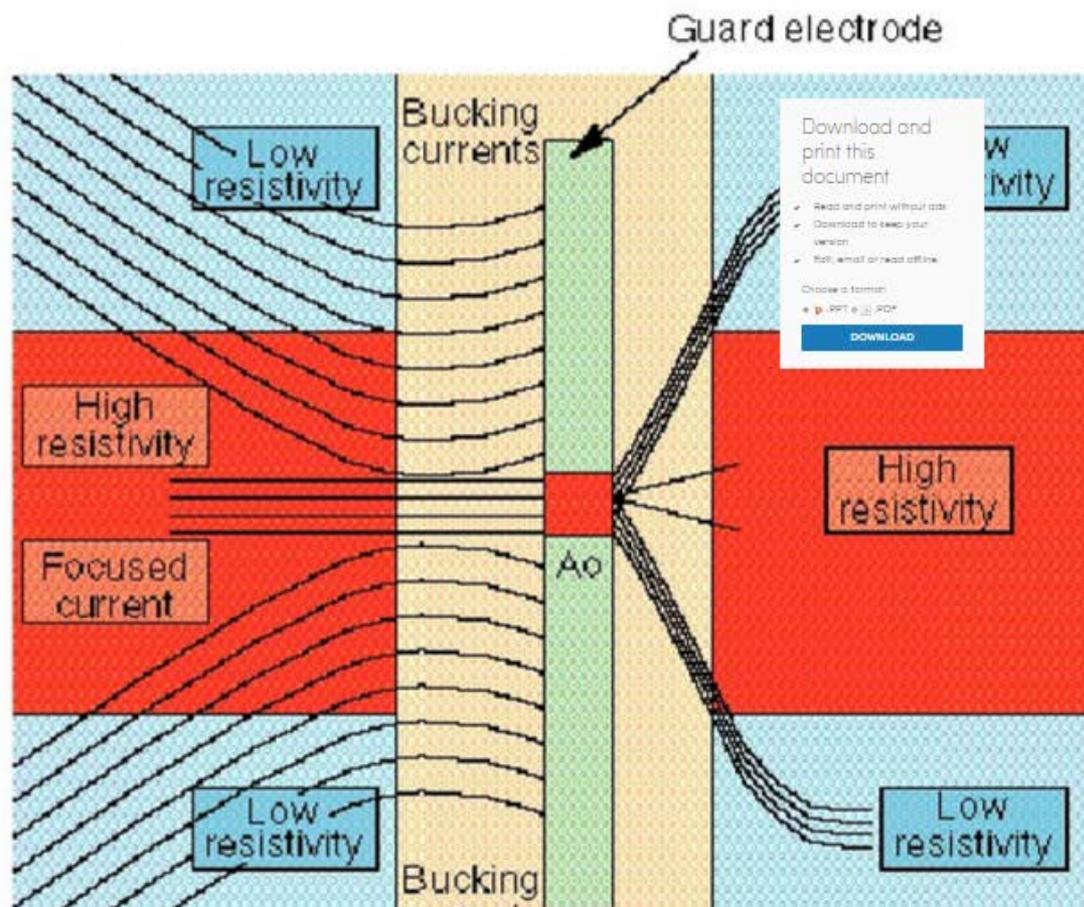
- R<sub>t</sub> is the True Resistivity of the formation
- Client performs reservoir analysis using R<sub>t</sub>
- Incorrect R<sub>t</sub> = Incorrect Analysis = Incorrect production decision
- Symbols: R<sub>w</sub>, R<sub>m</sub>, R<sub>t</sub>, R<sub>xo</sub>, R<sub>mc</sub>, R<sub>o</sub>

S<sub>w</sub>, S<sub>xo</sub>

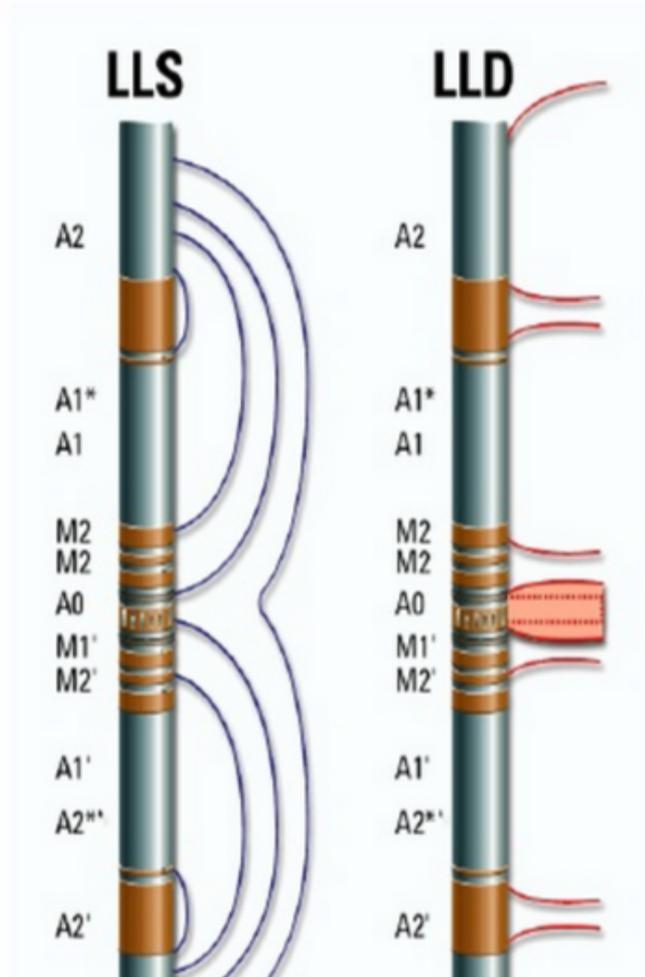


## Resistivity : Laterolog

Current is forced through the mud into the formation

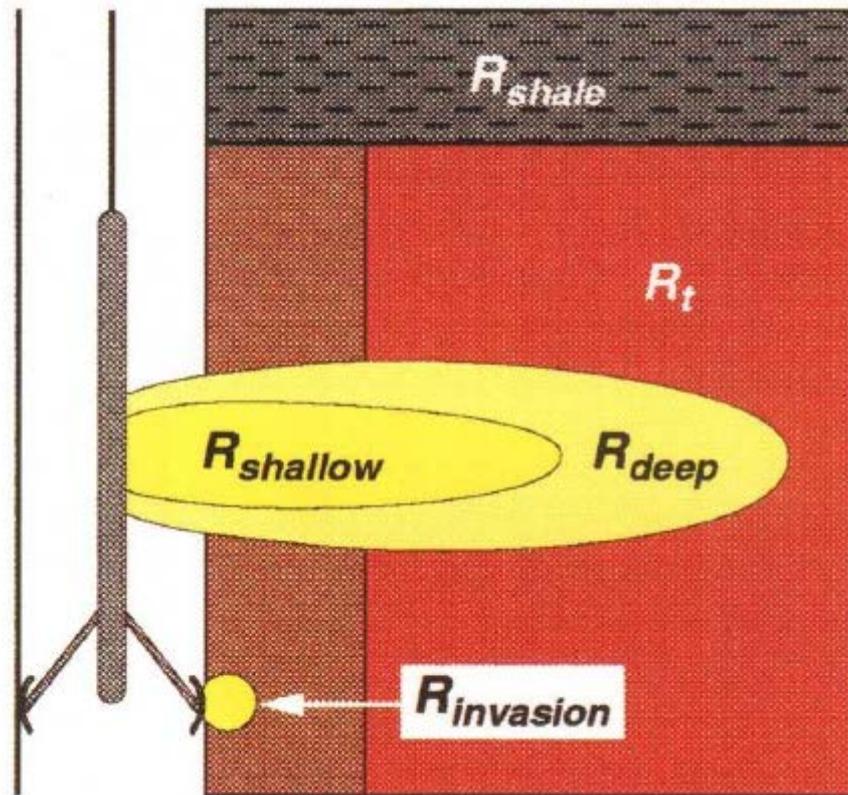


# Dual Laterolog Measurement



LLD: deep measurement, current returns to surface.

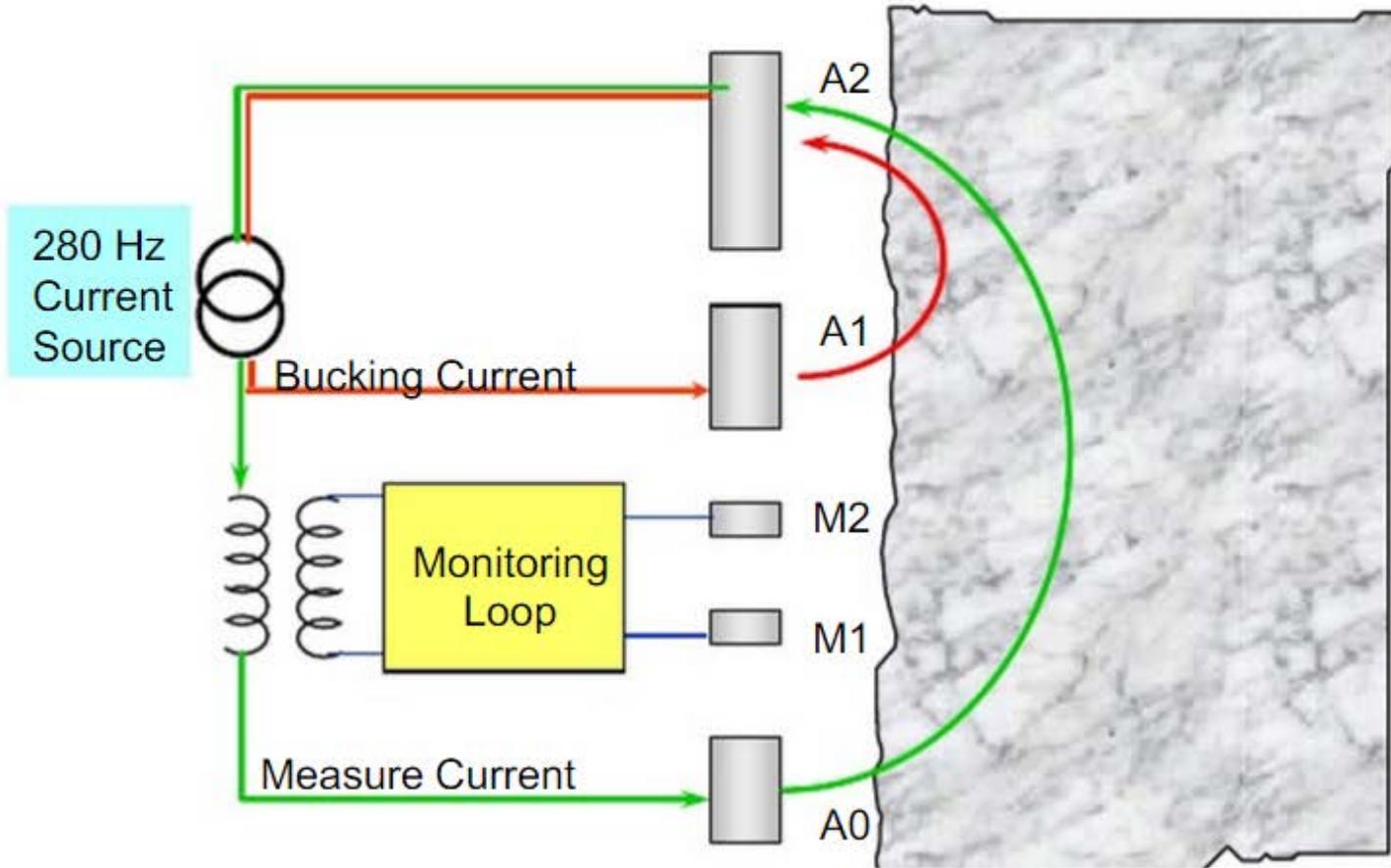
LLS: shallow measurement, current returns to the tool itself.



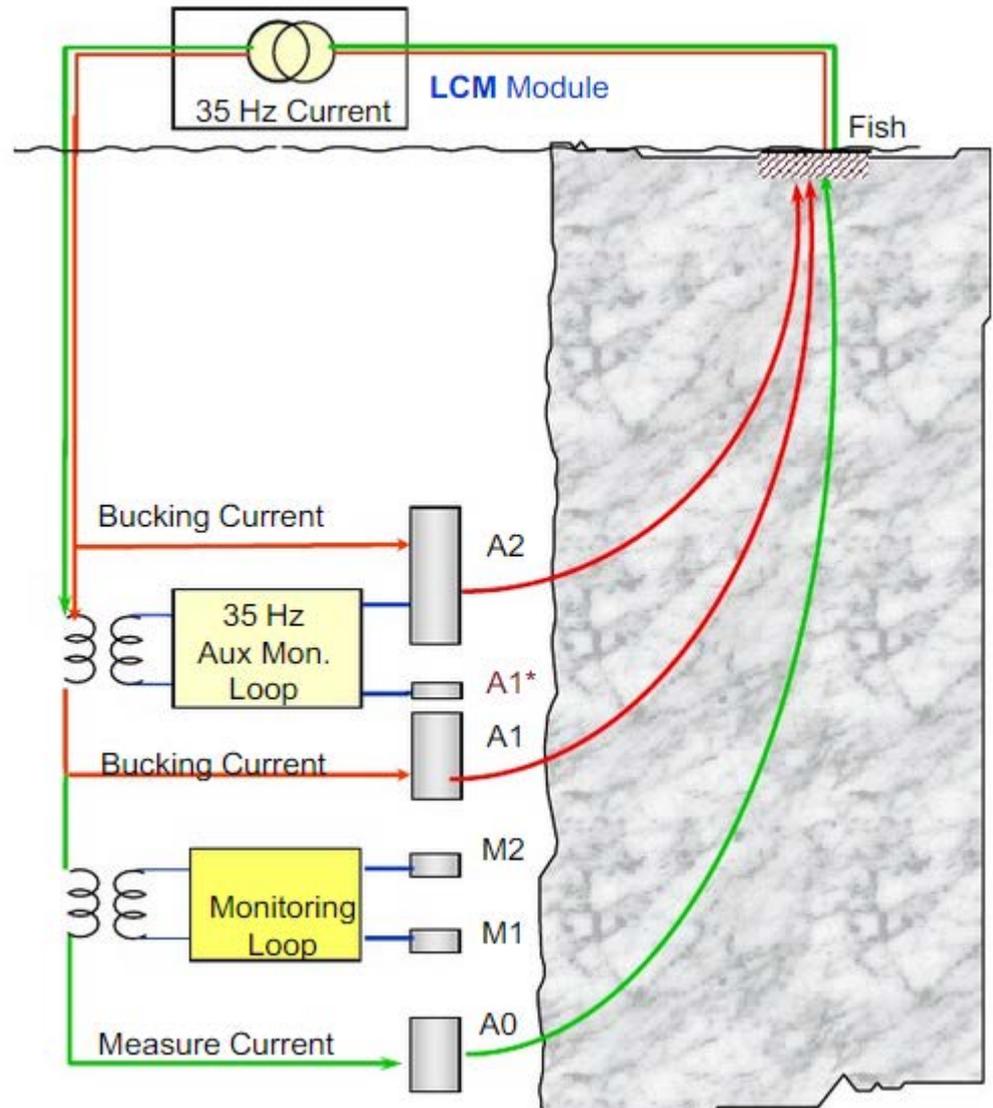
(after van Ditzhuijzen, 1994)

= Uninvaded reservoir
  = Invaded reservoir

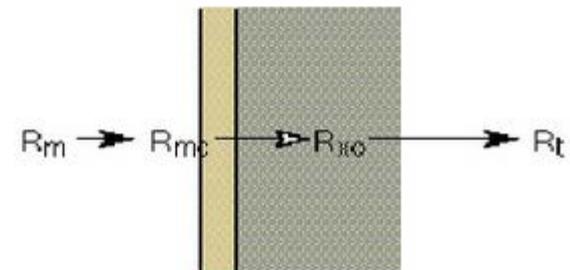
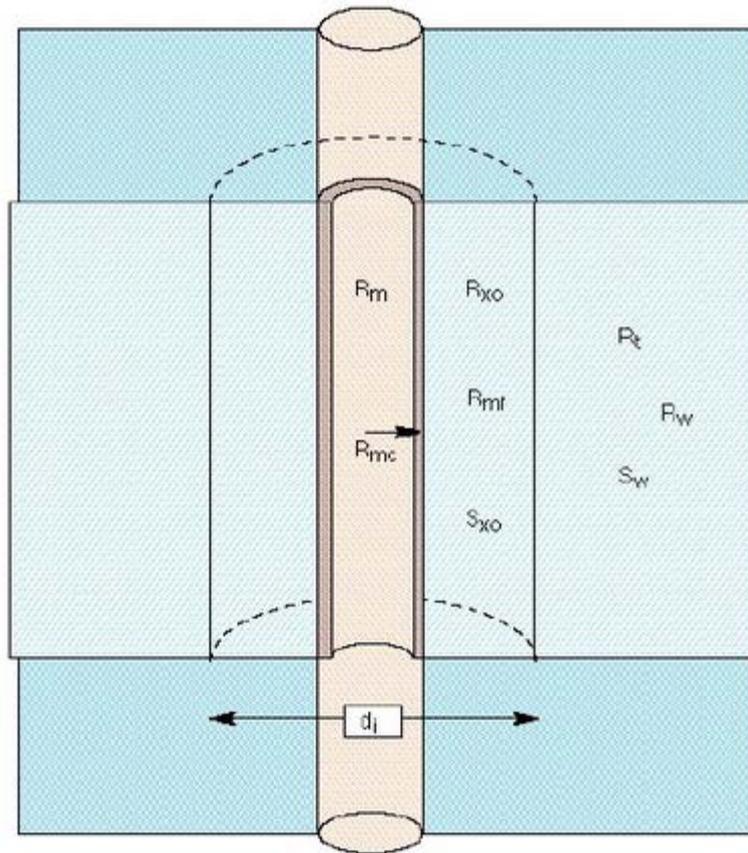
# Resistivity : Laterolog Shallow (LLS)



# Resistivity : Laterolog Deep (LLD)

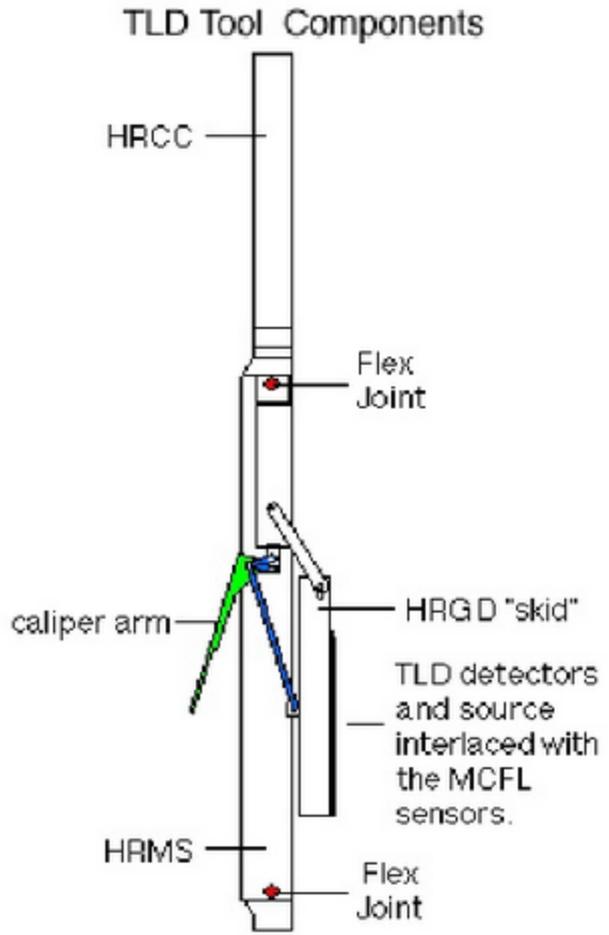


## Resistivity : Laterolog invasion effects

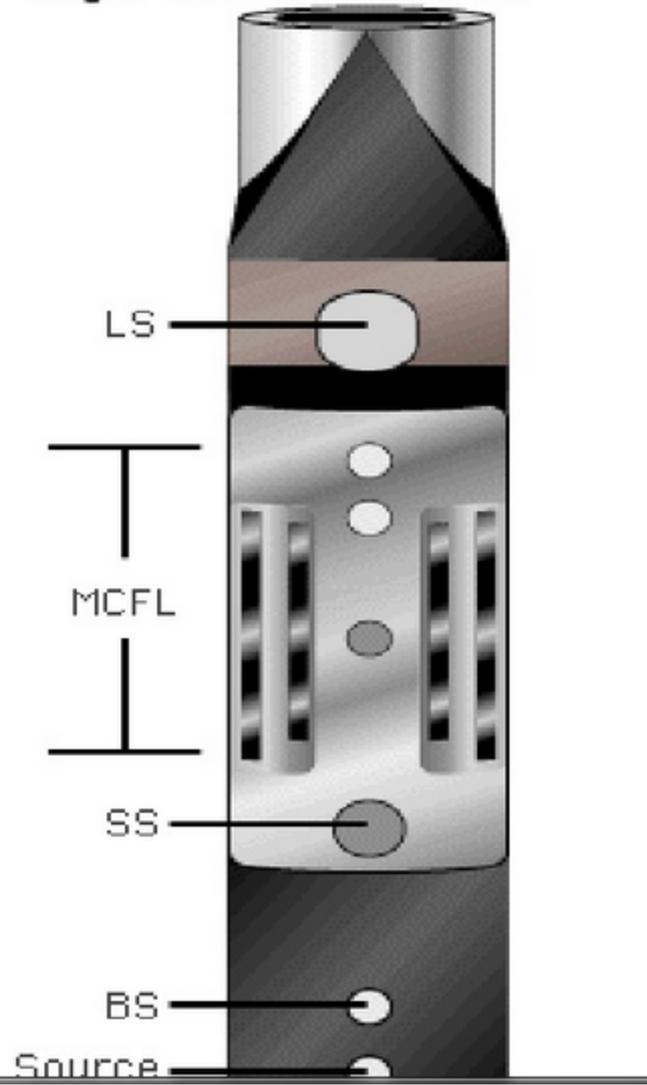


$$RLL = V_m R_m + V_{mc} R_{mc} + V_{xo} R_{xo} + (1 - V_m - V_{mc} - V_{xo}) R_t$$

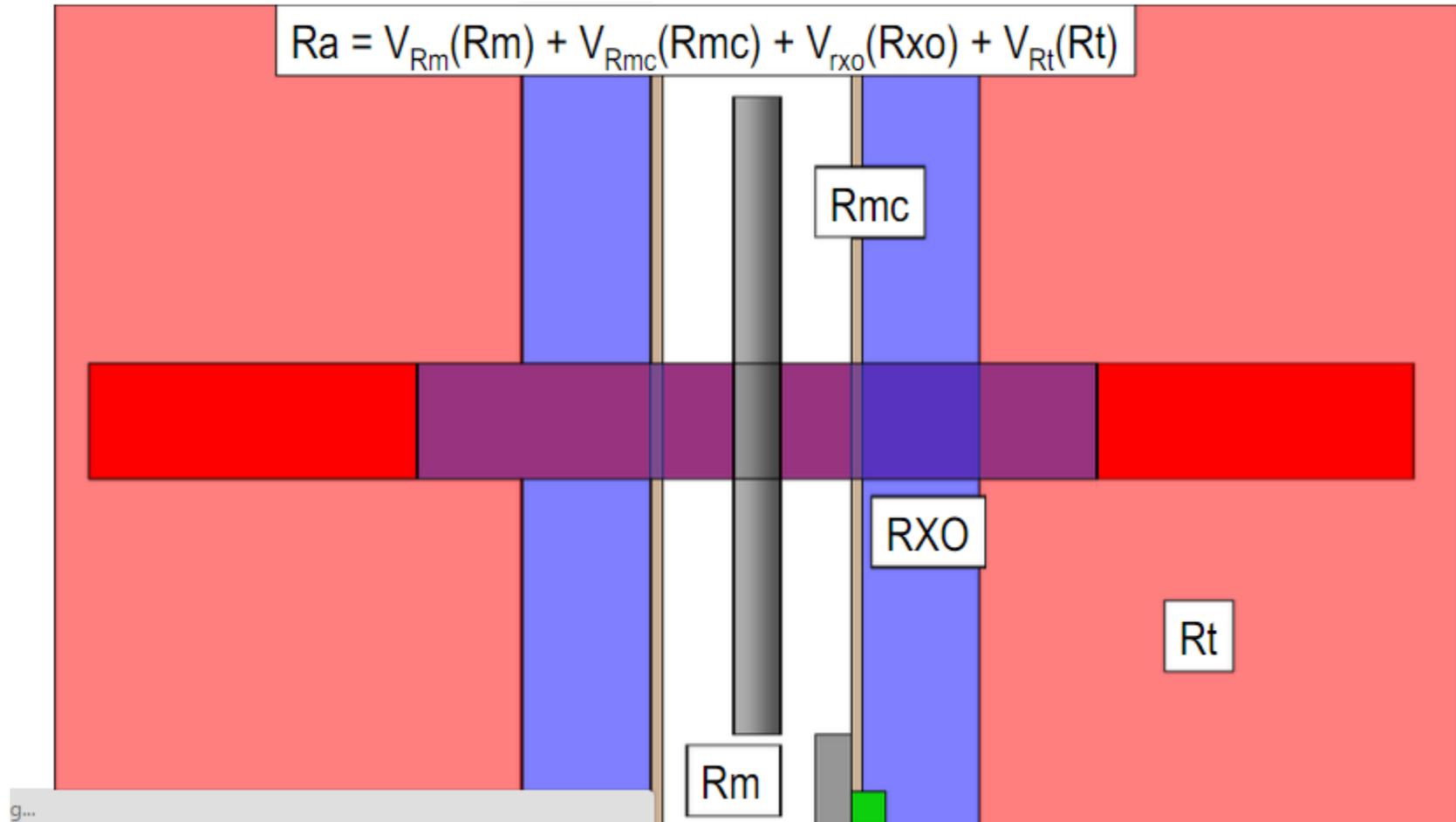
# Resistivity : Laterolog



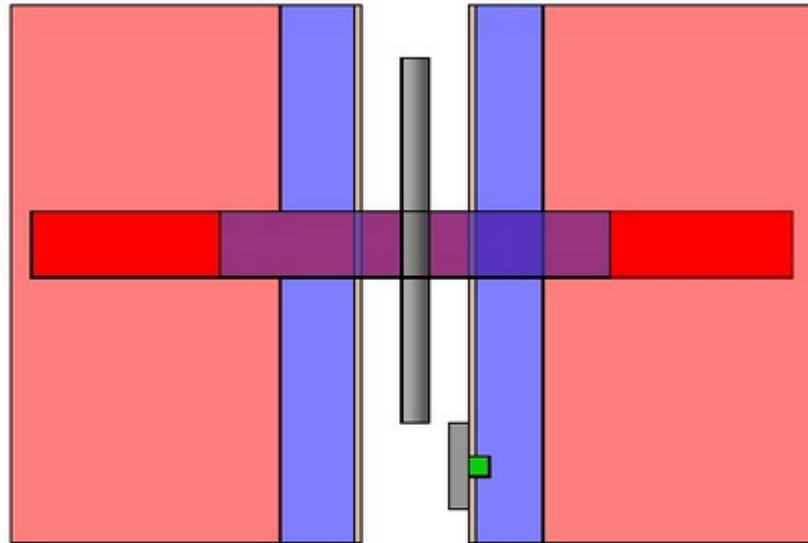
# High - Resolution Skid



## Resistivity : Laterolog invasion effects



## Resistivity : Laterolog invasion effects

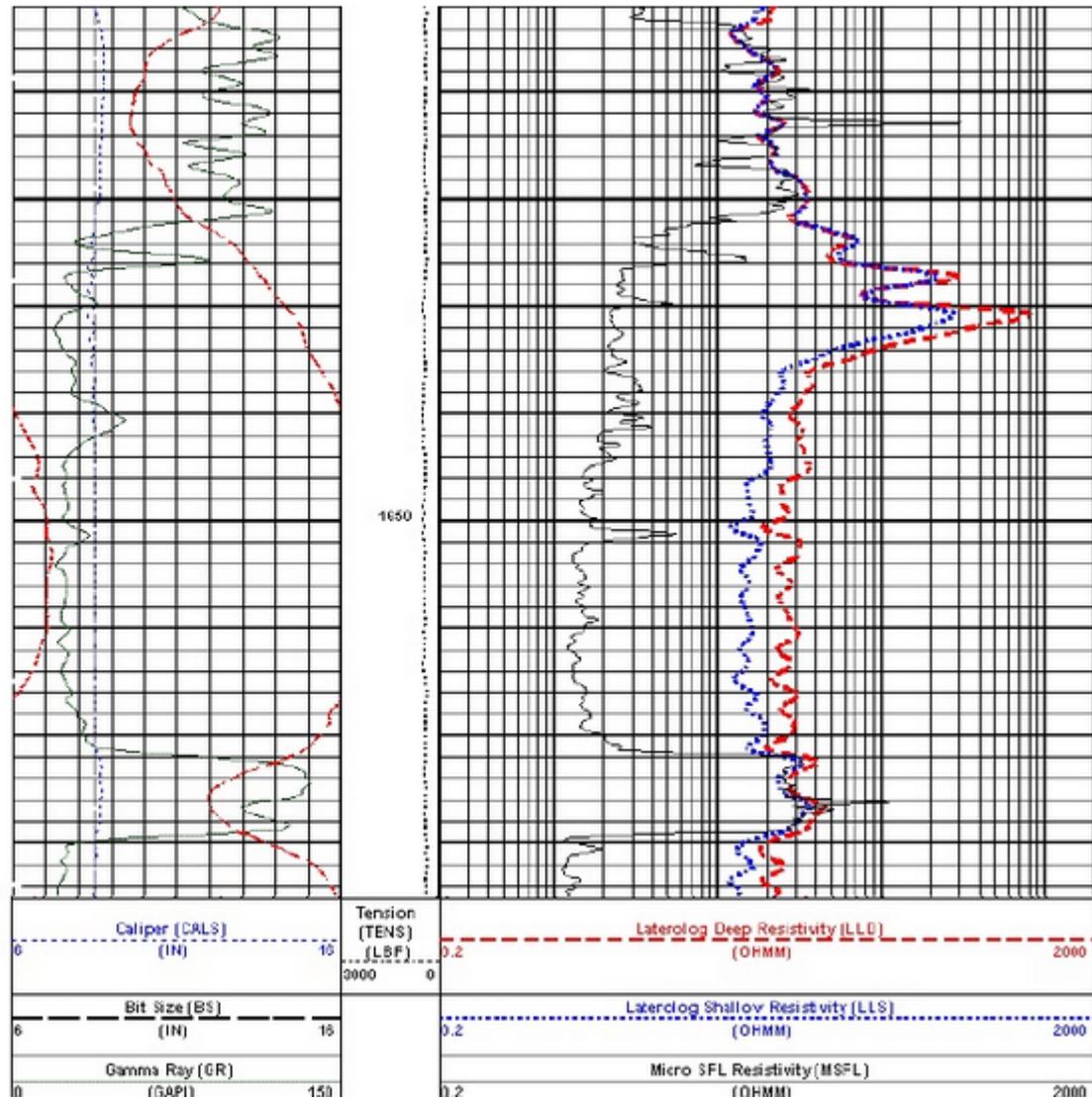


If  $R_{mf} < R_w$  then  $R_{xo} < LLS < LLD < R_t$

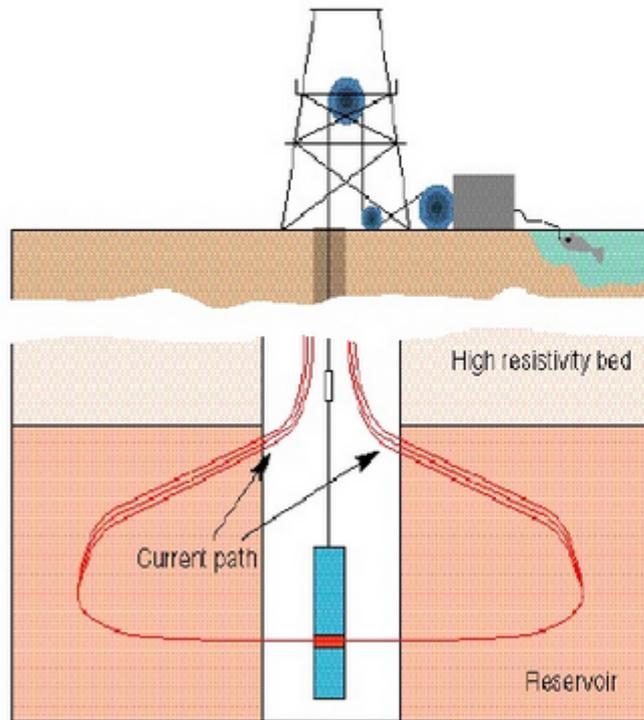
If  $R_{mf} > R_w$  then  $R_{xo} > LLS > LLD > R_t$

Using  $R_{xo}$ ,  $LLS$  &  $LLD$ ,  $R_t$  and  $D_i$  can be computed

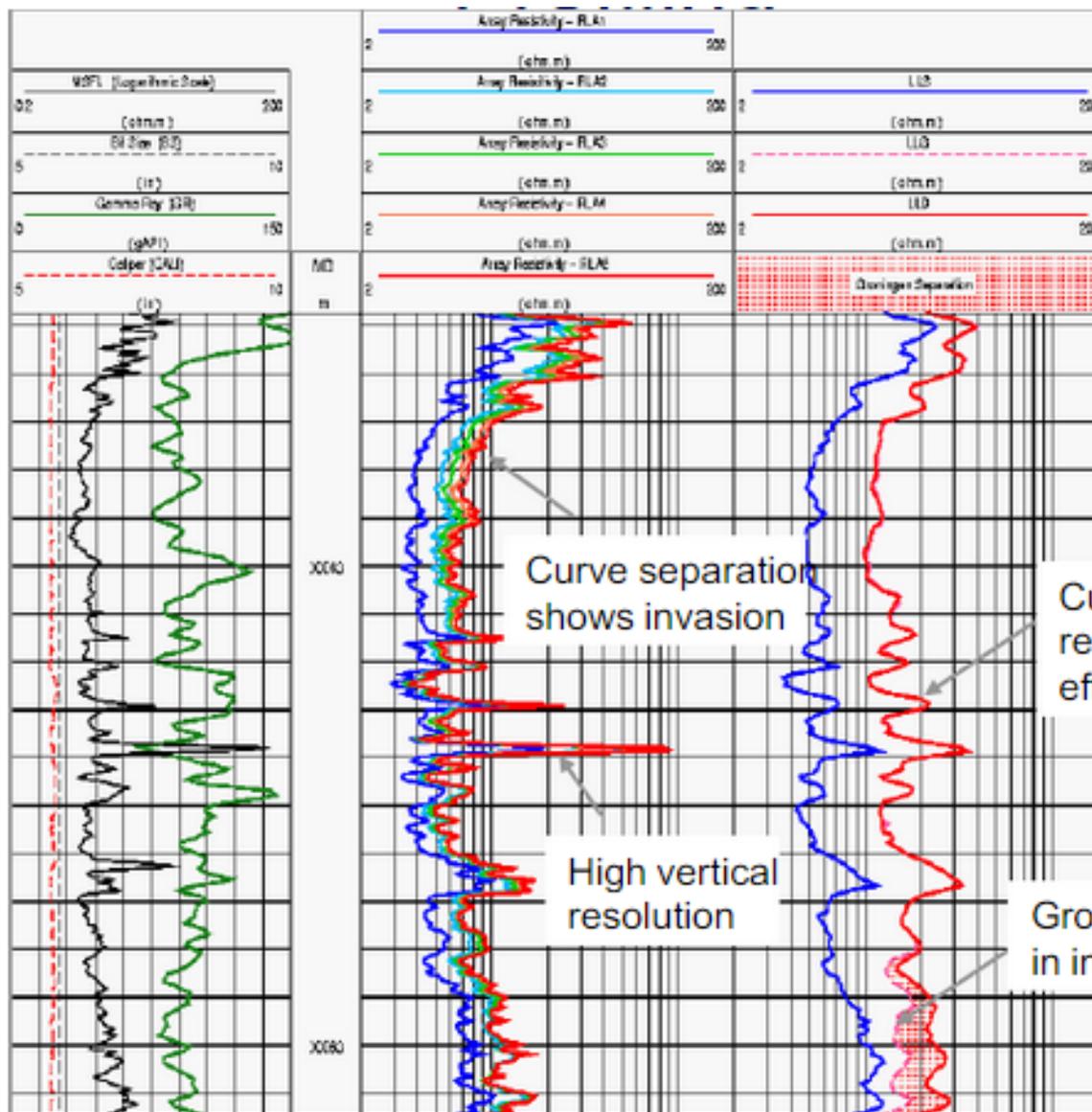
# Resistivity : Laterolog invasion effects



## Groningen Effect

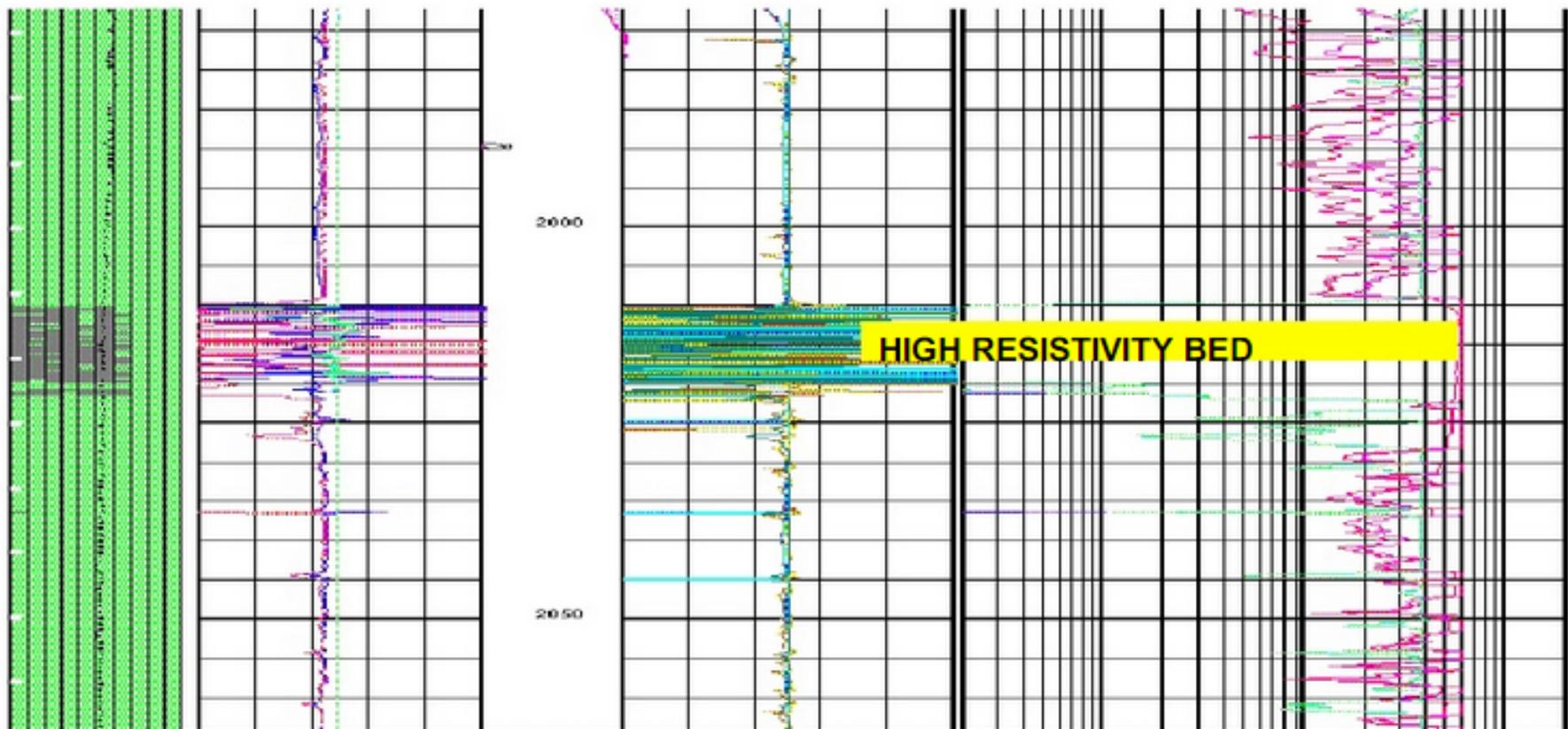


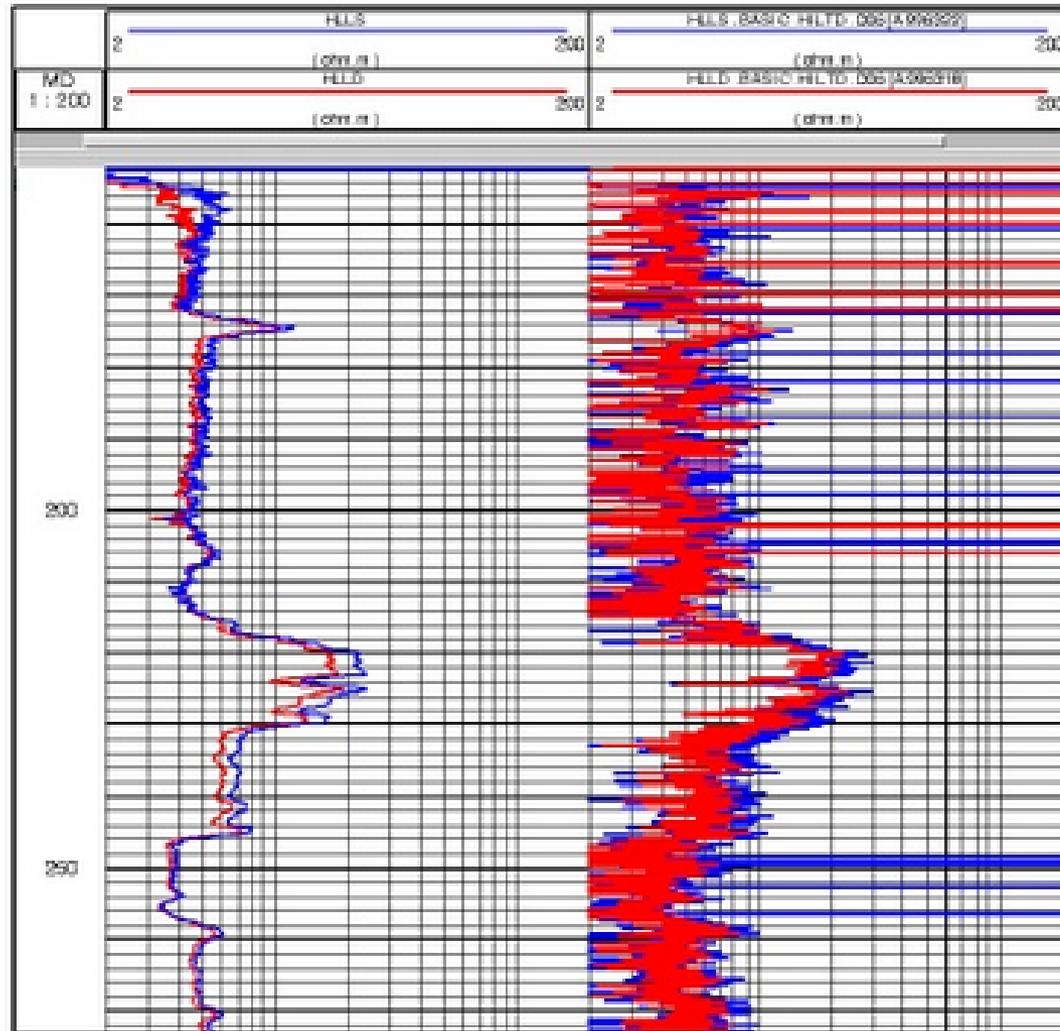
- Caused by highly resistive beds overlying the formation that is being measured.
- This forces the deep current into the mud column.
- This is caused by the voltage reference (cable-torpedo) becoming non-zero.
- LLD reads too high
- More pronounced at low resistivity



HRLA tool

DLL tool

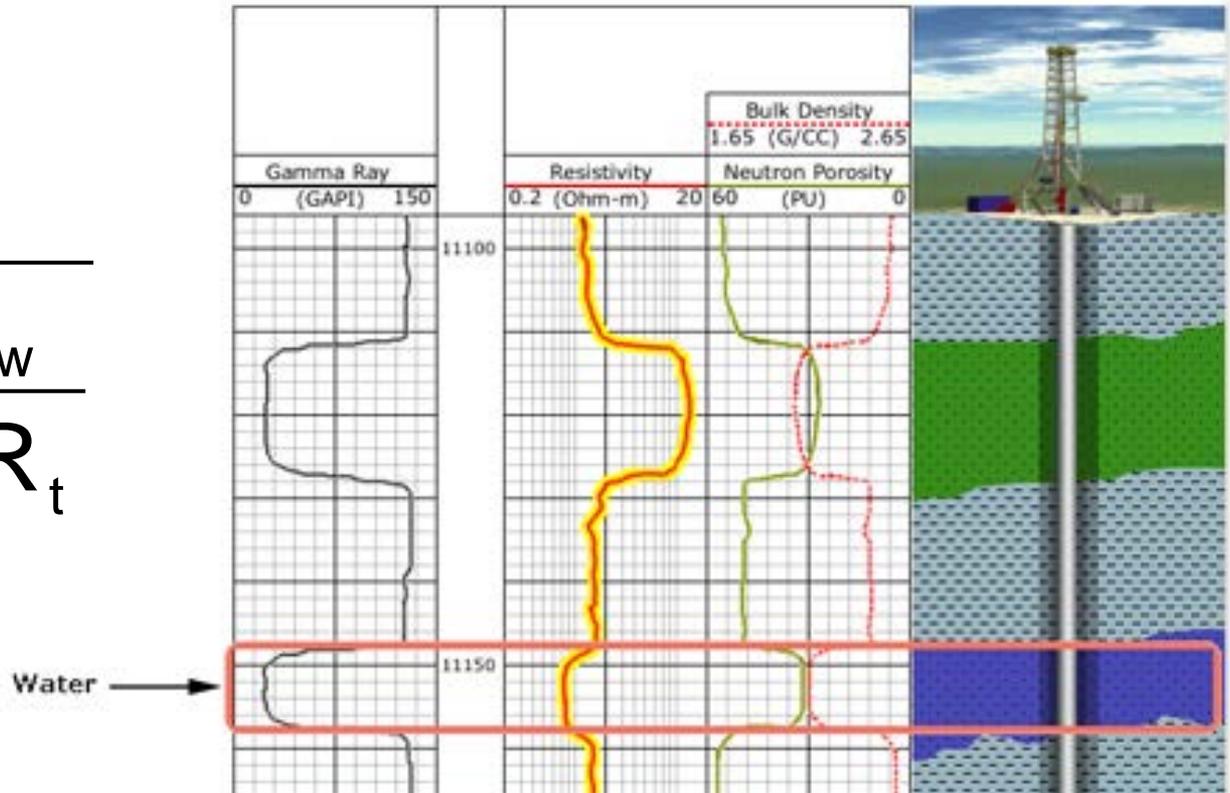


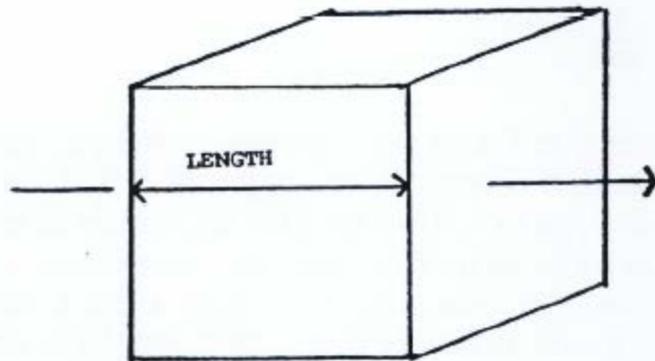


Rig Generator OFF

Rig Generator ON

$$S_w = \sqrt[n]{\frac{aR_w}{\phi_{\text{eff}}^m R_t}}$$

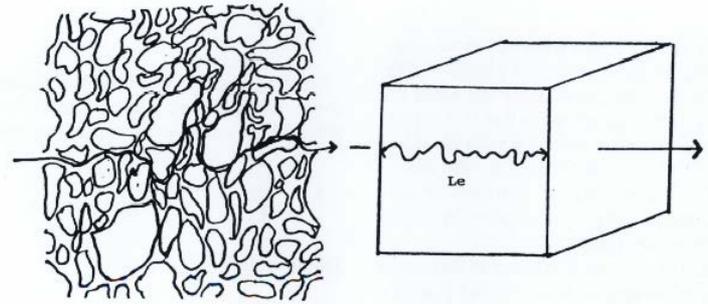




$$r = \frac{R \times L}{A}$$

**Figure 4-12.** Illustration of ionic current through an unimpeded path.

where R = resistivity of the water  
 r = resistance of the cube  
 L = length of the cube  
 A = area of the cube perpendicular to the direction of measurement, L



**Figure 4-13.** Illustration of ionic current through a formation.

If R has a value of 0.05 ohm-meters and L and A are 1 meter, then the resistance of the sample is 0.05 ohms.

If we replaced some of the water with a cubic meter of rock composed of straight capillary tubes, the resistivity of the water and the length of the sample would not change. The rock matrix takes no active part in the conduction of ionic current, being for all practical purposes an insulator, so the total conducting

We see that reducing the conductive area of the sample's face effectively increases its resistance. The exposed conductive area of the sample just discussed is proportional to the porosity of the rock, and for our cubic meter, the equation may be restated as:

$$r = \frac{R \times L}{\Phi}$$

Formation factor =

$$\frac{\text{resistivity of rock saturated with fluid}}{\text{resistivity of the saturating fluid}}$$

or

$$F = \frac{R_o}{R_w}$$

$R_o$ , the resistivity of the fluid saturated rock, was given by the expression:

$$r = \frac{R \times L_c}{\Phi}$$

and  $R_w$ , the resistivity of the saturating fluid, was given by:

$$r = \frac{R \times L}{A}$$

Thus

$$F = r \times L_c / \Phi / r \times L / A = \frac{A \times L_c}{\Phi \times L}$$

The area of the cube is one meter, so our expression for F now becomes:

$$F = \frac{(L_c/L)}{\Phi}$$

Porosity can also be expressed in terms of formation factor. By plotting formation factor versus porosity determined from laboratory data for many different rocks and reducing to equations the curves generated on such graphs, a general relationship was found of the form:

$$F = \frac{a}{\Phi^m}$$

The values  $a$  and  $m$  in this expression relate porosity to F in much the same manner as the ratio  $(L_c/L)$  related resistivity to F. They describe the texture of the rock. The value  $m$  is often called the cementation exponent, since its value tends to increase as the extent to which a rock is cemented increases, but this is not the only factor controlling its value. Both  $a$  and  $m$  depend upon properties of the original sediment, and upon whatever processes converted the sediment to rock. The values of  $a$  and  $m$  will vary from one rock to the next.

This is the so-called *Archie Equation*, named after G.E. Archie, an early pioneering analyst. It works well in carbonate reservoirs, whose porosity and permeability are mainly secondary.

$$F = \frac{0.62}{\Phi^{2.15}}$$

The *Humble Equation*, mainly the work of W.O. Winsauer and his colleagues, adequately describes sandstones and other granular structures whose porosity is mainly primary. Because of earlier calculating tools incapable of handling the complex power of the Humble Equation, a simple version of it yields similar values. This is the *Tixier Relationship*:

$$F = \frac{.81}{\Phi^2}$$

To relate these rather idealized models to the resistivities measured by well logs of real rock/fluid systems, let us return to an earlier expression:

$$F = \frac{R_o}{R_w}$$

Transposing it:

$$R_o = FR_w$$

as  $R_{wa}$ , or apparent water resistivity. We may now state:

$$R_t = FR_{wa}$$

where  $R_t$  = the system resistivity recorded by the log

Hydrocarbon presence in the rock pores serves to increase the measured value of  $R_t$  by increasing the length  $L_c$  of the ionic path. Oil and gas behave exactly as the rock matrix does in their effect on conductivities, i.e., they are insulators. Normally hydrocarbons exist in the rock pores as suspended droplets, acting like fine grains of rock inserted in the spaces between the larger grains. The apparent resistivity of the water in the pore space increases, as it has been shown that  $F$  is independent of fluid resistivities.

## Calculating Water Saturation

Earlier we sought to calculate water saturation by comparing the resistivity of a zone to an idealized resistivity of the same rock containing only water. This poses certain difficulties, as logs do not directly measure  $R_o$ . Short of actually sampling the rock and its fluids some means must be found to determine  $R_o$  from the logs. Recalling two of our earlier statements:

$$S_w \propto \frac{R_o}{R_t} \text{ and } R_o = FR_w$$

By substituting:

$$S_w \propto \frac{FR_w}{R_t}$$

F may be found from a porosity log and the appropriate  $F-\Phi$  relationship.  $R_w$  may be obtained by measuring produced samples or calculating it from the SP.  $R_t$ , of course, is directly measured by the logging instruments. We have a workable means of calculating the ratio  $R_o/R_t$ . But in what way is it proportional to  $S_w$ ? Archie showed that the constant of proportionality, for resistivity comparisons, is a power of  $S_w$  by

reducing graphs of measured laboratory data to equations. The relationship becomes:

$$S_w^n = \frac{FR_w}{R_t}$$

where  $n$ , the constant of proportionality, is the resistivity index exponent, commonly referred to as the saturation exponent.

In totally oil wet rocks,  $n$  can have a value as high as 3.0, 4.0, or greater. Such rocks are extremely rare. In water-wet rocks,  $n$  has a value of 2.0. In shaly un-compacted coastal sands, it has a value of 1.8. These two values will suffice for virtually all situations.

The use of  $n$  as a basis of comparison works equally well for other resistivity contrasts. Since we know that  $R_o = FR_w$  and  $R_t = FR_{wa}$ , substituting these expressions for  $R_o$  and  $R_t$  enables us to say:

$$S_w^n = \frac{R_w}{R_{wa}}$$

The quantity  $R_{wa}$ , although not directly measured, is commonly computed by the surface computer and printed directly on the log as an auxiliary curve. It is computed using the equation:

$$R_{wa} = \frac{R_t \Phi^m}{a}$$

Obviously, we must have both a resistivity and a porosity log in addition to some feel for the appropriate values of  $a$  and  $m$  in order to perform the computation.

The contrasts  $R_o/R_t$  and  $R_w/R_{wa}$  are useful in the field as a quick-look interpretation method for reducing the number of zones to consider. Clean salt water zones generally exhibit  $R_t$  and  $R_{wa}$  values lower than those found in shales. These  $R_t$  and  $R_{wa}$  values, when read in a water-bearing zone near the zone of interest, are arbitrarily assumed to be  $R_o$  and  $R_w$ . It is easily observed that when  $R_t$  and  $R_{wa}$  exceed three times the values of  $R_o$  and  $R_w$ , the calculated water saturations will be less than 60%. This is usually considered to be the upper limit of commercial producibility. Chapter 6 will cover the technique in greater detail.

- All water saturation determinations from resistivity logs in clean (nonshaly) formations with homogeneous intergranular porosity are based on Archie's water saturation equation, or variations thereof. The equation is

$$S_w^n = \frac{F R_w}{R_t} \dots\dots\dots(1)$$

- $R_w$  is the formation water resistivity,  $R_t$  is the true formation resistivity, and  $F$  is the formation resistivity factor.  $F$  is usually obtained from the measured porosity of the formation through the relationship

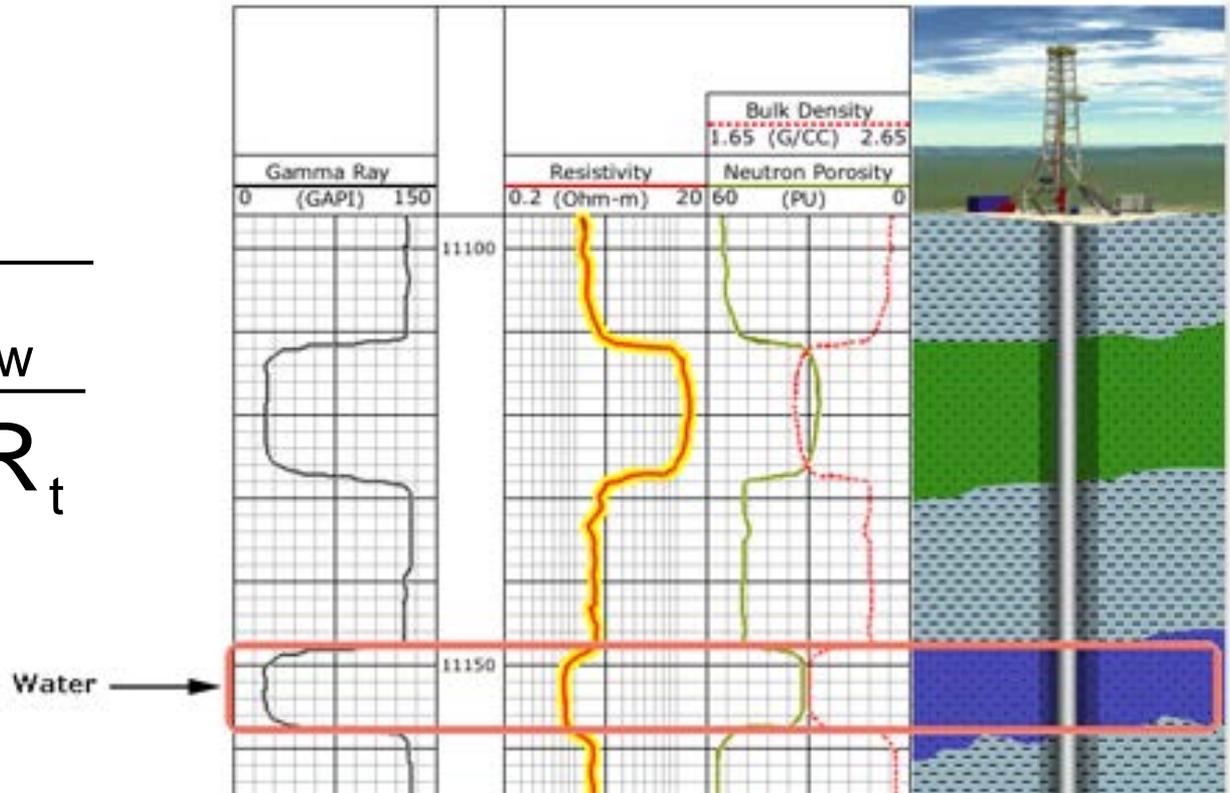
$$F = a / \phi^m \dots\dots\dots(2)$$

- For  $S_{xo}$ , the water saturation in the flushed zone, a similar expression exists:

$$S_{xo}^n = \frac{F R_{mf}}{R_{xo}} \dots\dots\dots(3)$$

- where  $R_{mf}$  is the mud filtrate resistivity and  $R_{xo}$  is the flushed zone resistivity.

$$S_w = \sqrt[2]{\frac{aR_w}{\phi_{\text{eff}}^m R_t}}$$





# Why Do We Need to Know This?

- Determining  $R_t$  is not simple
- Many things prevent our tool from reading  $R_t$ :
  - Wellbore effects
  - Tool physics effects
  - Formation effects
- Curve separation can help us to determine  $R_t$  if we understand why the curves are reading different values.

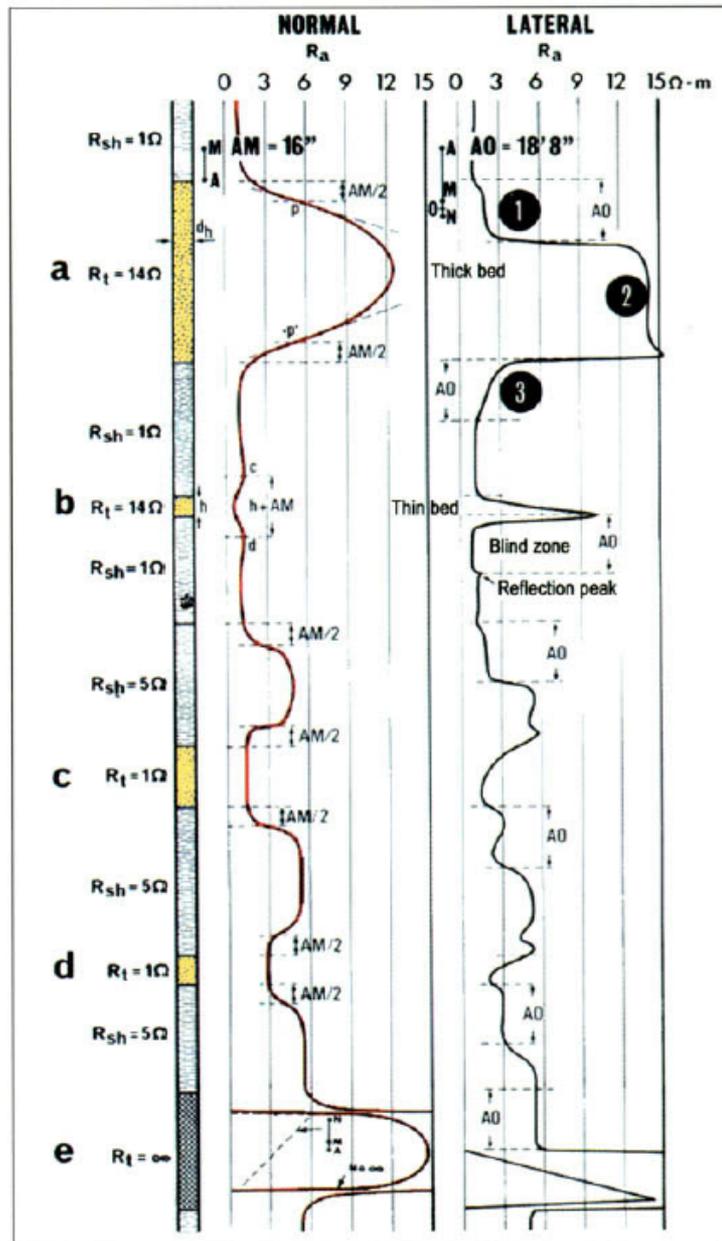
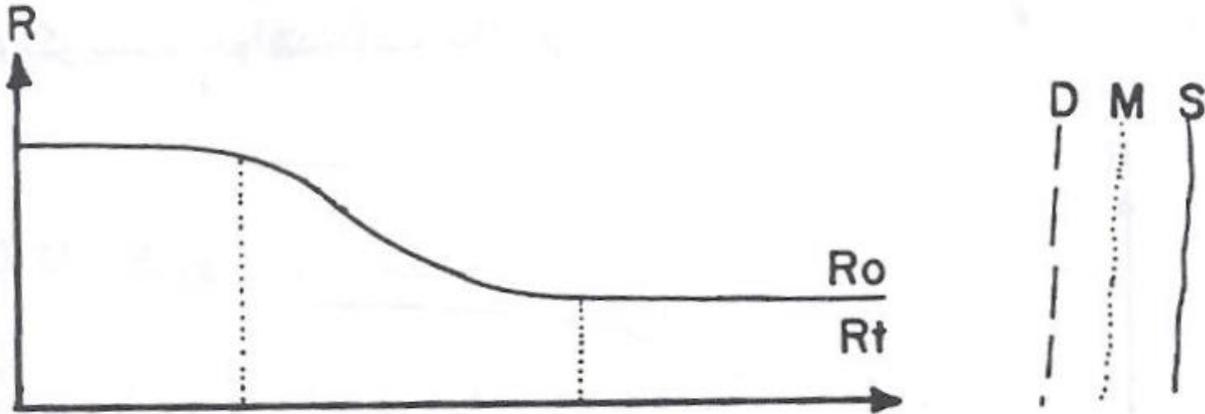


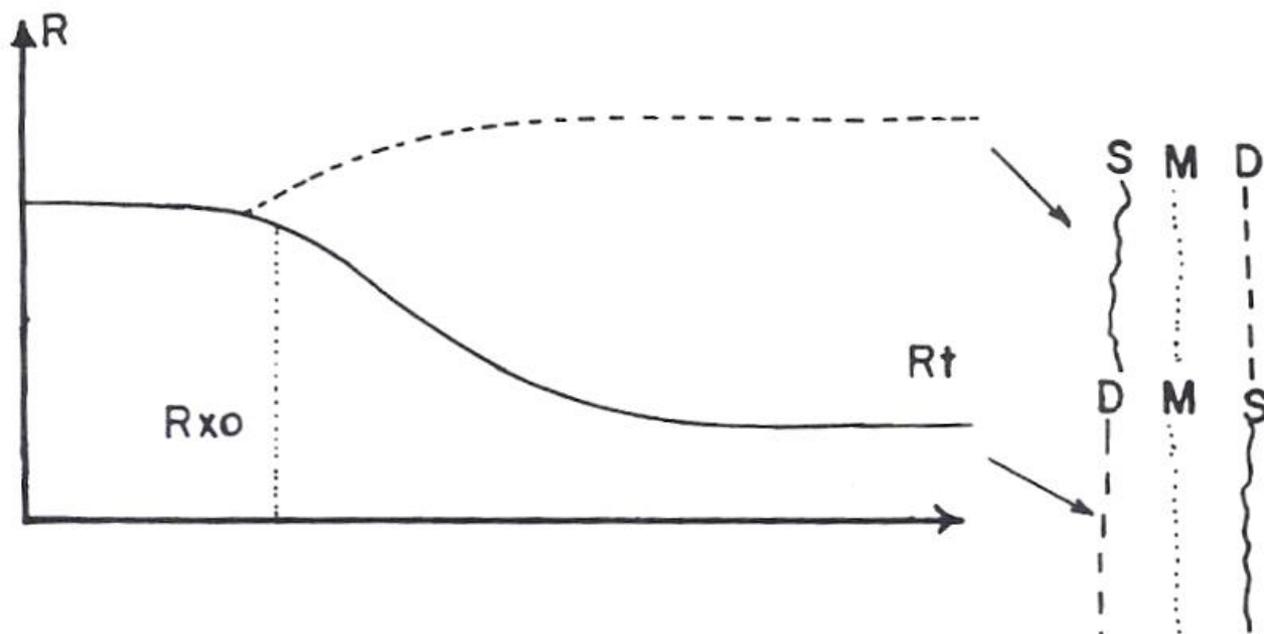
Figure 4-8 - The influence of bed-thickness and resistivities on the shapes of the lateral and normal responses.

## چند نکته در نمودار مقاومت

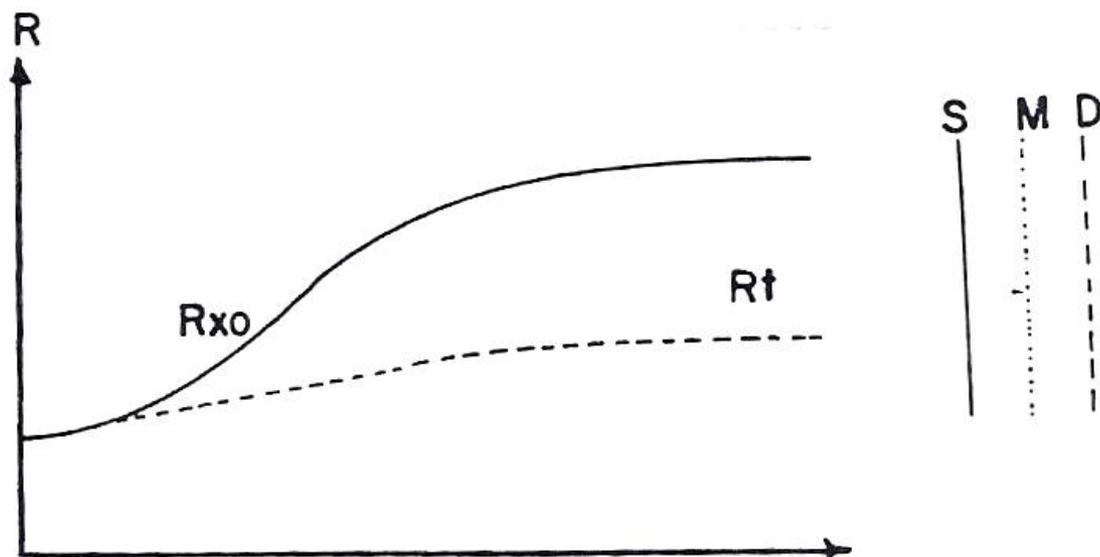
1. در گل حفاری آب شیرین، مقاومت مخصوص گل حفاری بیشتر از آب سازند است. در زون آبدار مقاومت مخصوص ناحیه شسته شده نیز بیشتر از آب سازند است. با نزدیک شدن به ناحیه بکر مقاومت کاهش می یابد.



2. در زون هیدروکربور دار که با گل شیرین حفاری شده است، مقاومت مخصوص پشت زون شسته شده (ناحیه عبوری و بکر) ممکن است بیشتر یا کمتر باشد که بستگی به اشباع آب و مقاومت مخصوص آب سازند دارد.

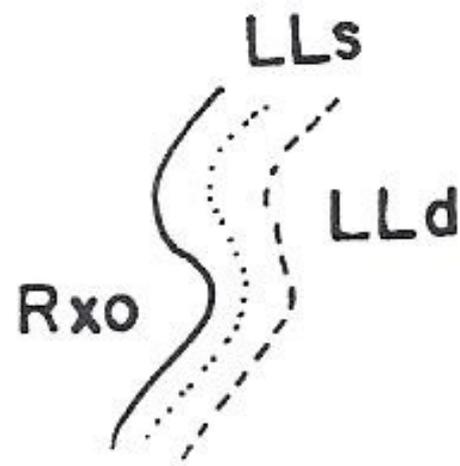


3. اگر با گل حفاری شور حفاری شده باشد. ناحیه شسته شده دارای مقاومت مخصوص کمتری از سایر قسمت ها می باشد. اگر سازند دارای آب باشد و مقاومت مخصوص آن نیز بیشتر از گل باشد در این صورت مقاومت مخصوص ناحیه بکر یا مساوی یا بیشتر از ناحیه شسته شده خواهد بود. در حالت دیگر اگر سازند دارای هیدروکربور باشد مقاومت ناحیه بکر بیشتر خواهد بود.



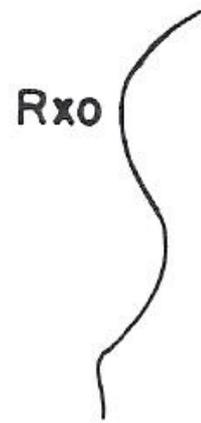
- تفسیر منحنی ها در حالتی سازند دارای هیدروکربور باشد (مقاومت مخصوص سیال سازند بیشتر از گل حفاری باشد) حالت های زیر قابل تفسیر است.
1. عدم نفوذ تراویده گل و یا نفوذ بسیار سطحی

قطر نفوذ > قطر چاه + ۲ اینچ



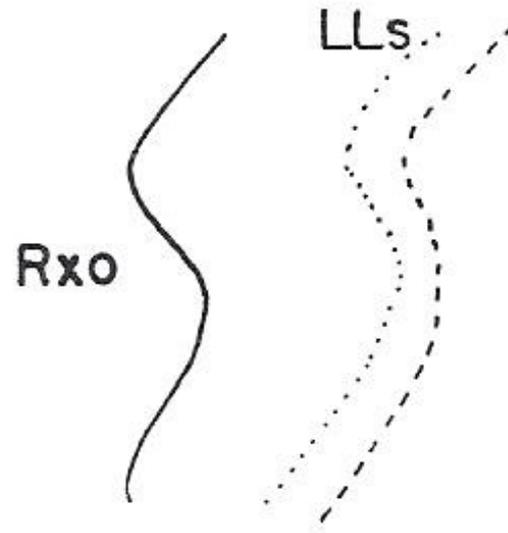
2. نفوذ متوسط تراویده گل به درون سازند

قطر چاه + ۲ اینچ > قطر نفوذ > ۴۰ اینچ



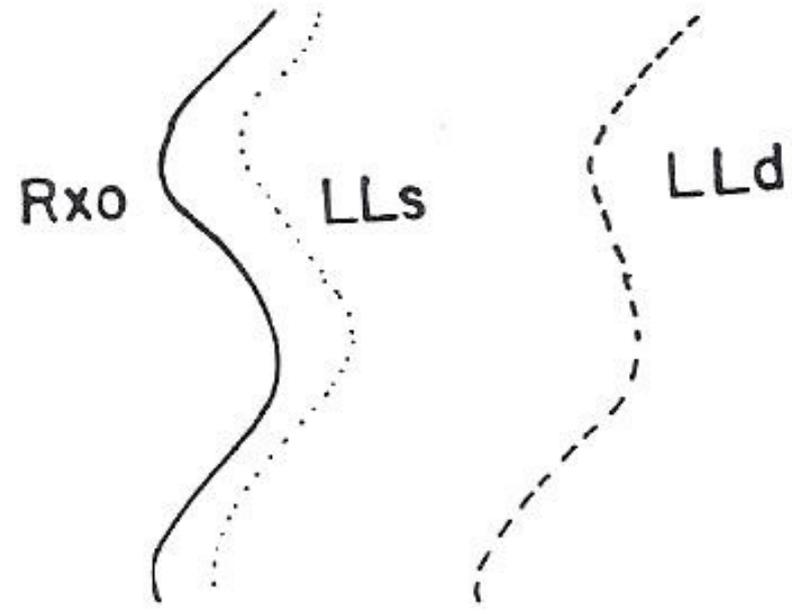
3. نفوذ عمیق تراویده گل به دورن سازند

۶۰ اینچ < قطر نفوذ < ۴۰ اینچ

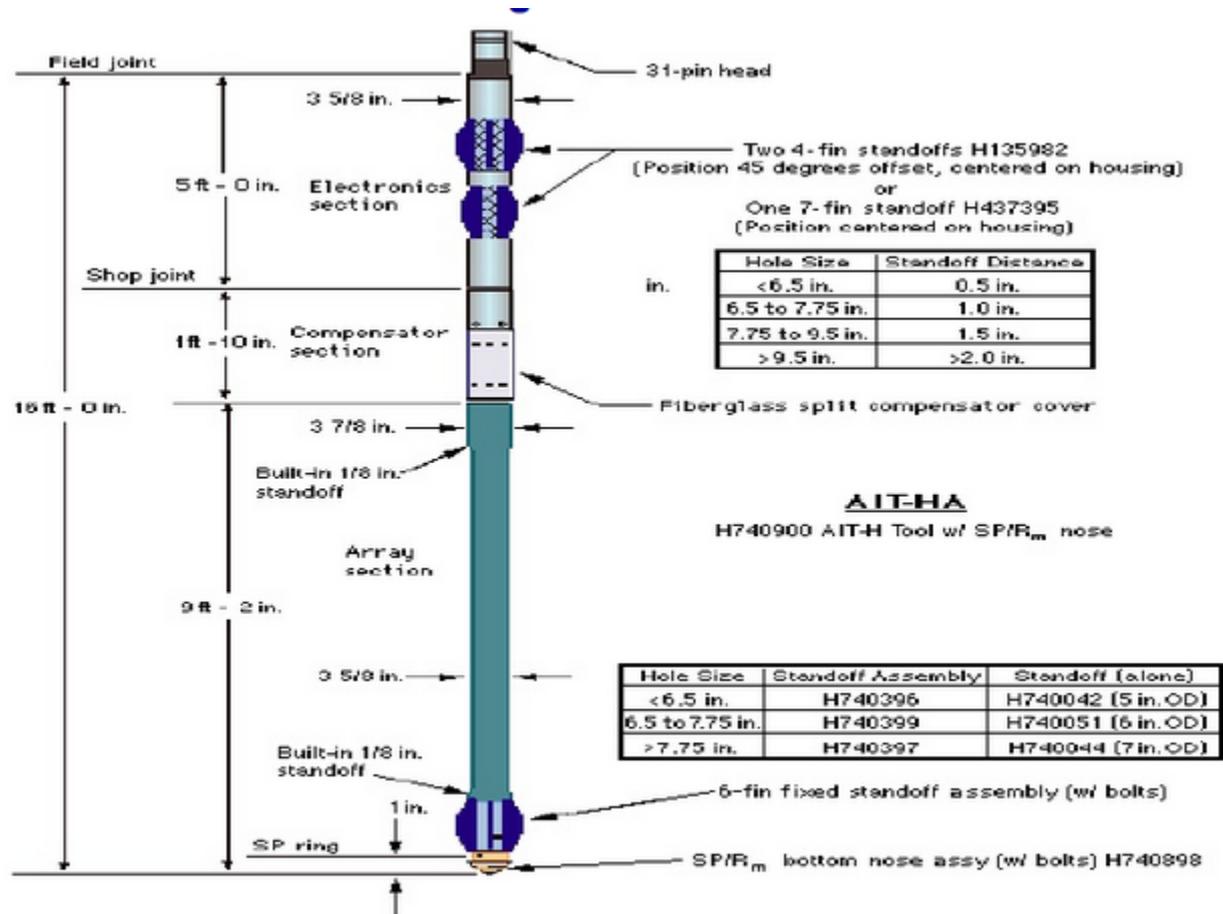


4. نفوذ بسیار عمق تراویده گل به دورن سازند

۶۰ اینچ > قطر نفوذ

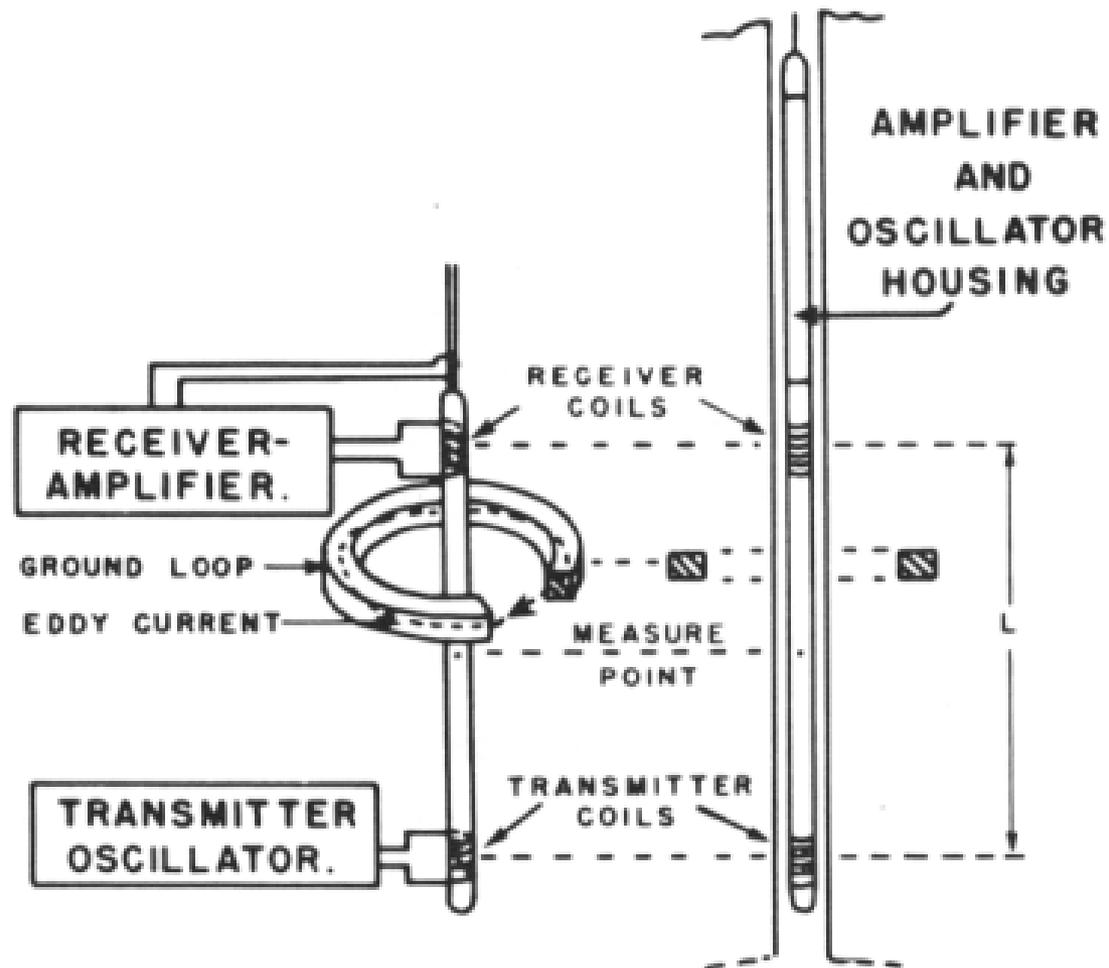


# Induction Log

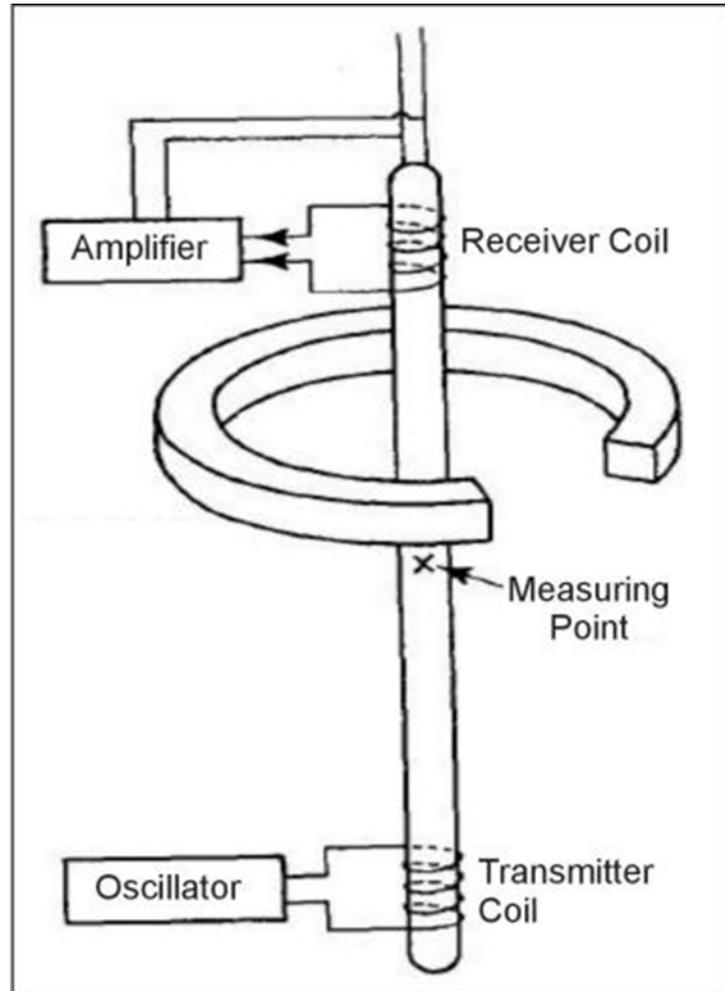


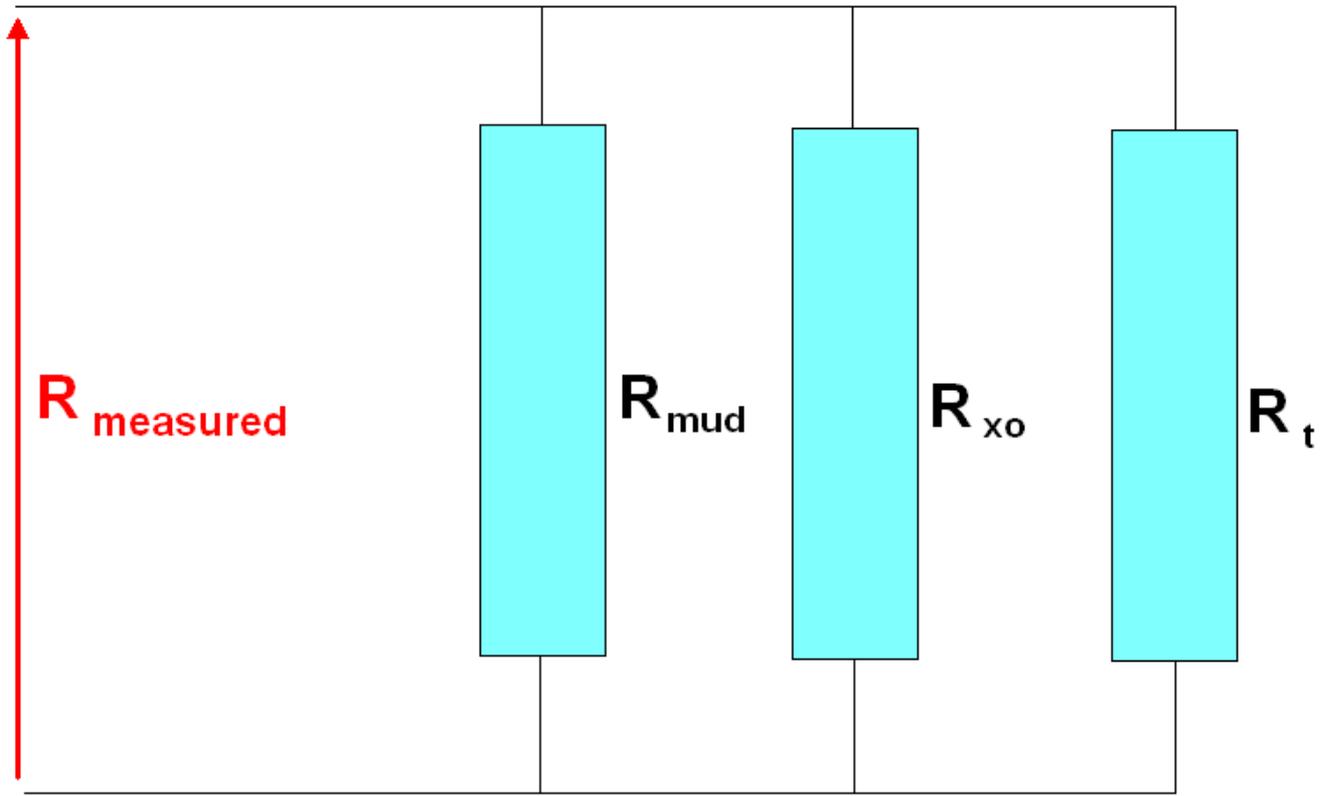
Induction tools are based on principles of electromagnetic induction. A magnetic field is generated by an AC electrical current flowing in a continuous loop/transmitter coil. The magnetic field from the transmitter coil induces ground loop currents in the formation. These ground current loops will in turn have an associated alternating magnetic field which will induce a voltage in the receiver coil, the magnitude of which is proportional to the formation conductivity.

- It works in oil based muds and air filled holes where latero tool fails.
- Tool accuracy is excellent for formations having low to moderate resistivity (up to ~100 Ohm.m).
- The Dual Induction Latero (DIL) tool records three resistivity curves having different depths of investigation (ILD,ILM & LL3)



**Induction Log Equipment**  
*(Courtesy of Schlumberger)*



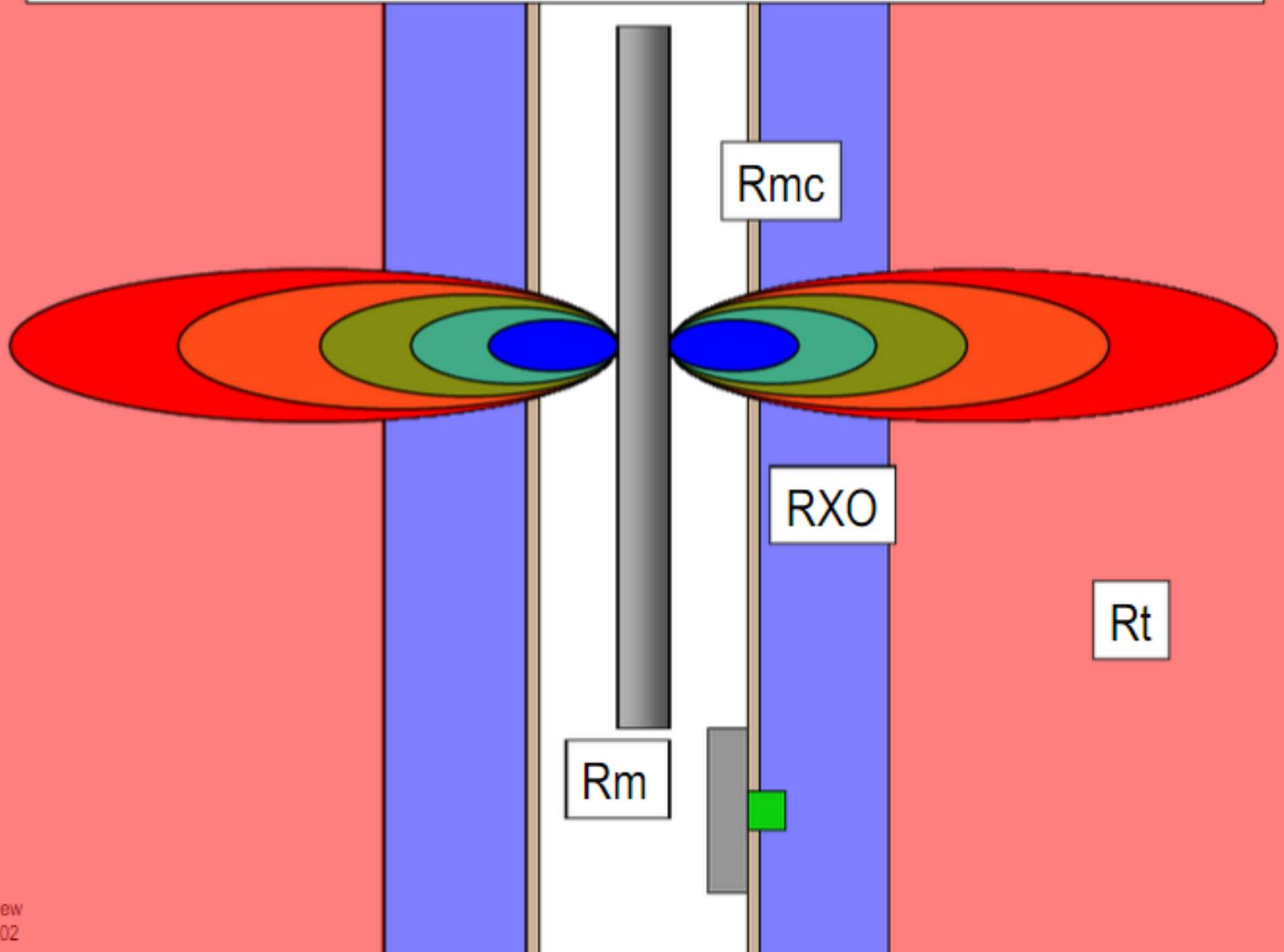


$$\frac{1}{R_{\text{measured}}} = \frac{1}{R_{\text{mud}}} + \frac{1}{R_{\text{xo}}} + \frac{1}{R_{\text{t}}}$$

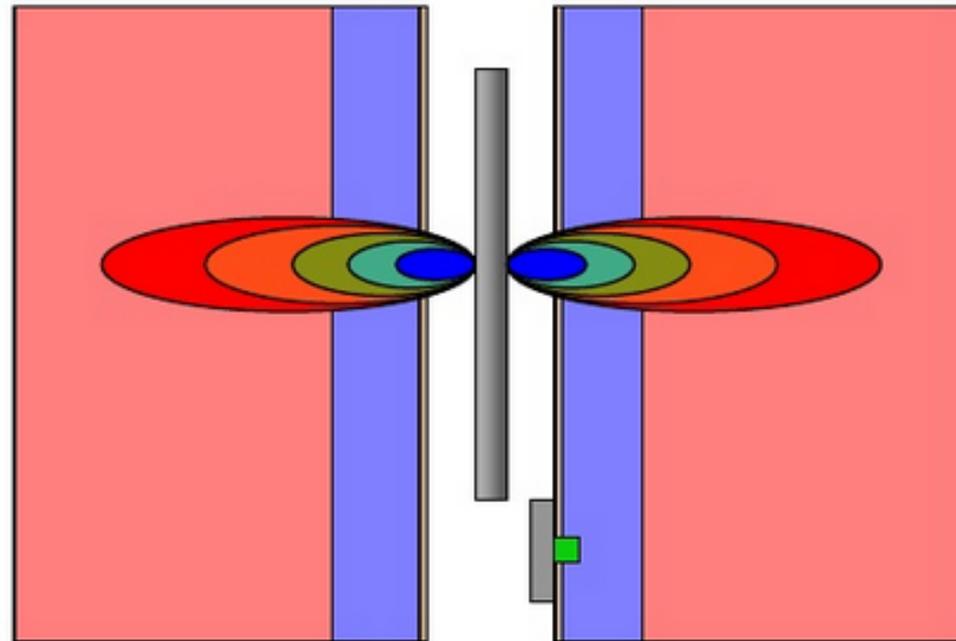
### Operating Range

- 0.1 to 2000 ohmm
- Moderate  $R_{xo} < R_t$
- $R_t/R_m < 100$  (with hole diameter considered)
- Large diameter holes with moderate  $R_t/R_m$  and moderate  $R_t$

$$1/Ra = 1/(V_{Rm}(Rm)) + 1/(V_{Rmc}(Rmc)) + 1/(V_{rxo}(Rxo)) + 1/(V_{Rt}(Rt))$$



## Resistivity : Induction

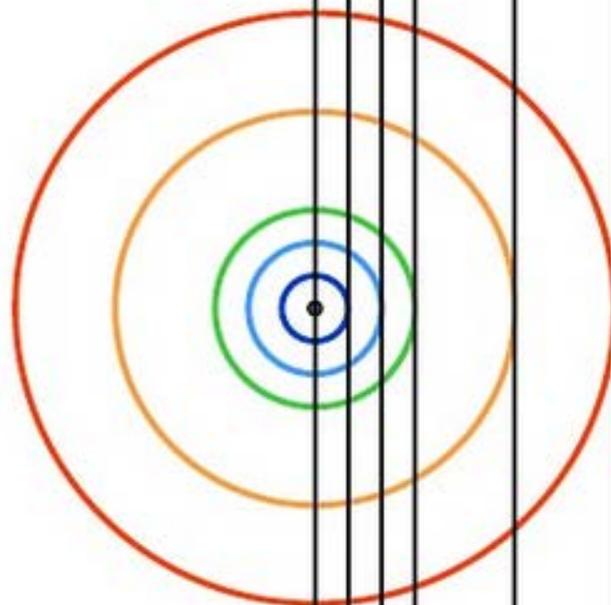
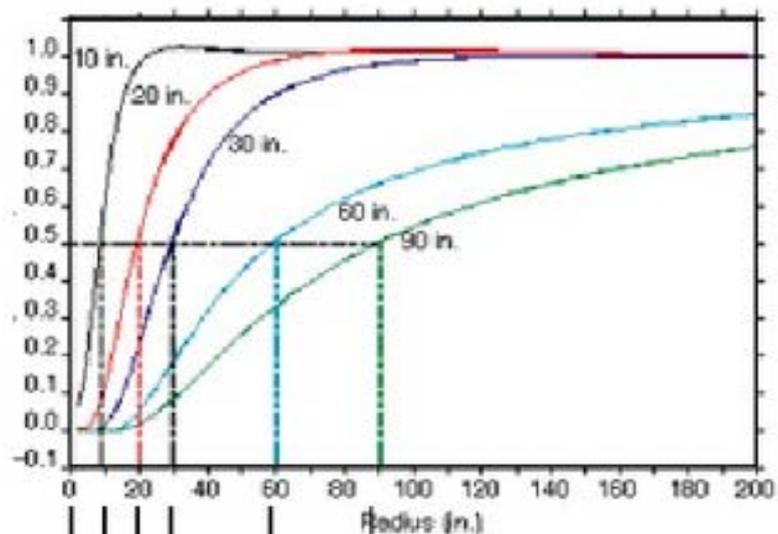


If  $R_{mf} < R_w$ ,  $AT_{10} < 20 < 30 < 60 < 90$

If  $R_{mf} > R_w$ ,  $AT_{10} > 20 > 30 > 60 > 90$

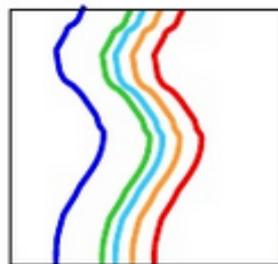
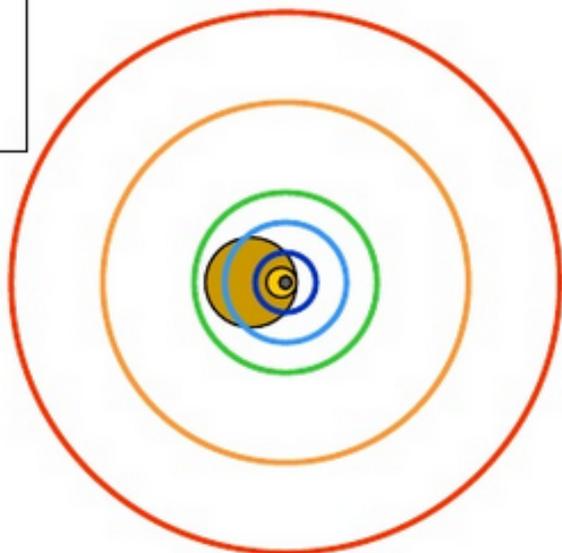
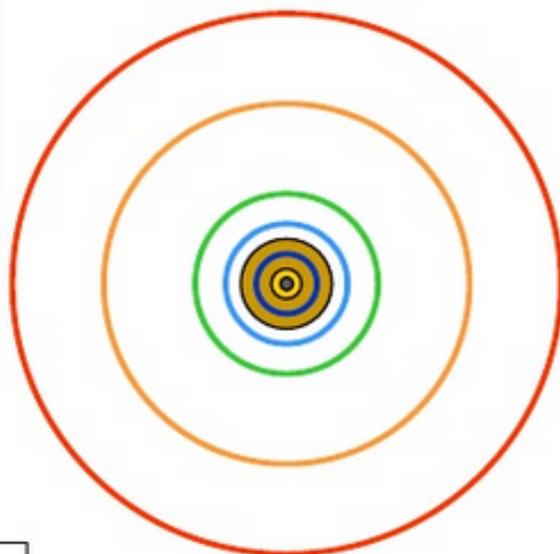
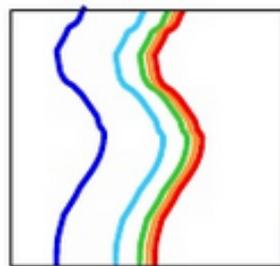
From the 5 curves  $R_t$  can be computed

# Resistivity : Induction Focusing

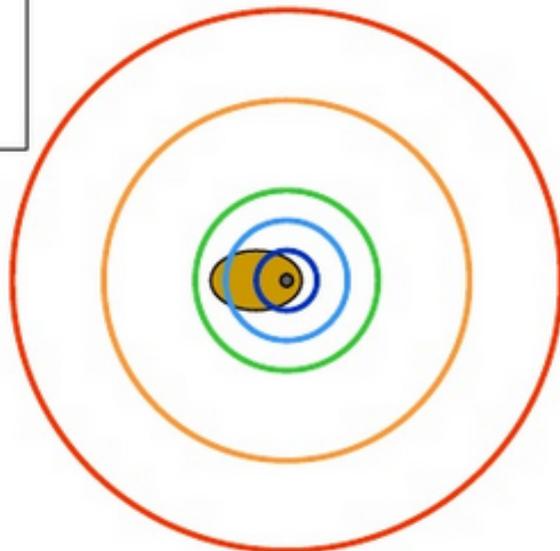


## Resistivity : Induction Hole size and shape

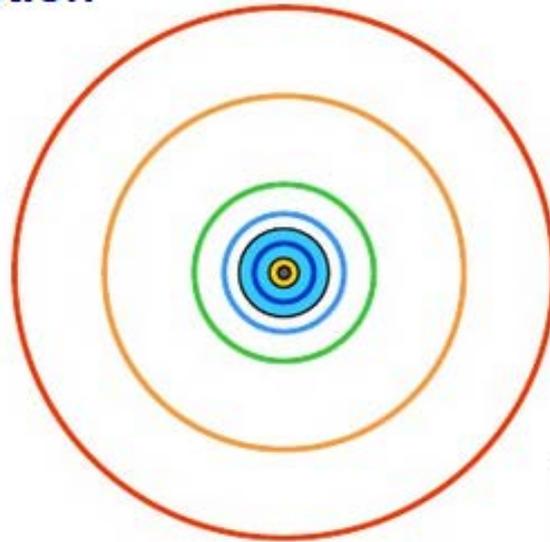
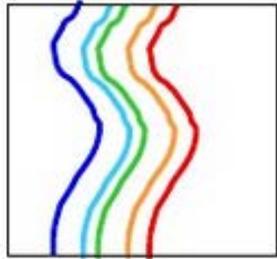
Uncertainty in hole size or mud resistivity can cause large errors on the shallow curves but much smaller errors on the deeper measurements



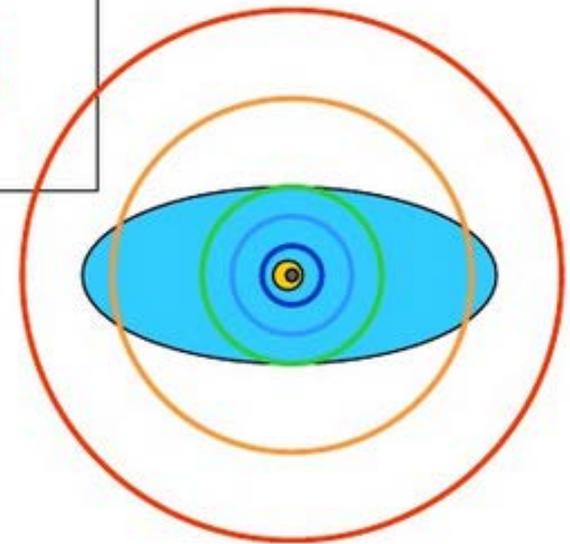
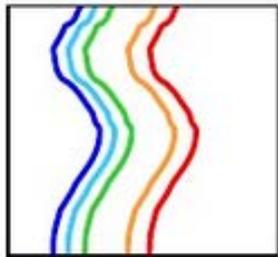
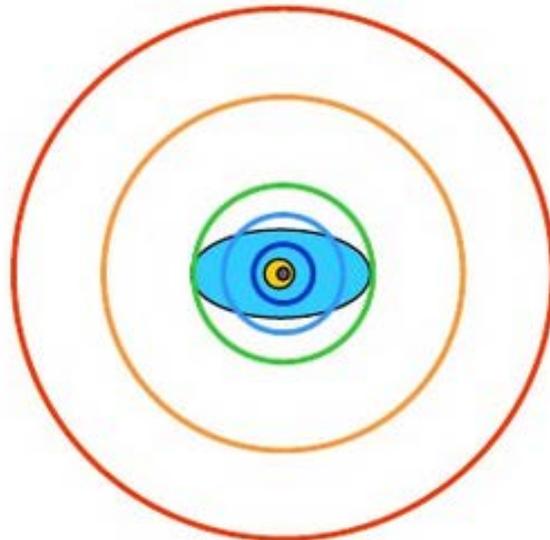
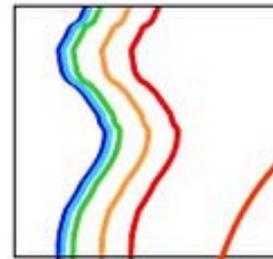
Out of  
sequence



## Resistivity : Induction Invasion

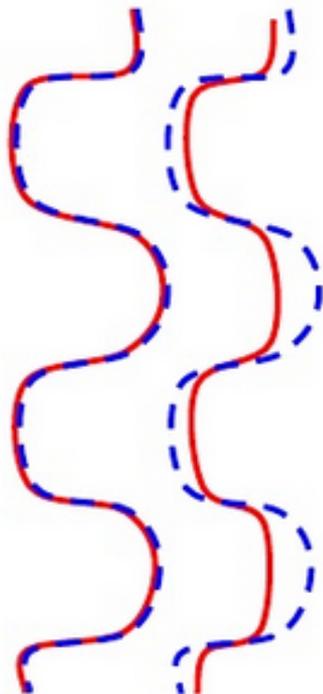


Very deep invasion can affect even the deepest measurements, non-cylindrical invasion may affect the  $R_t$  computation



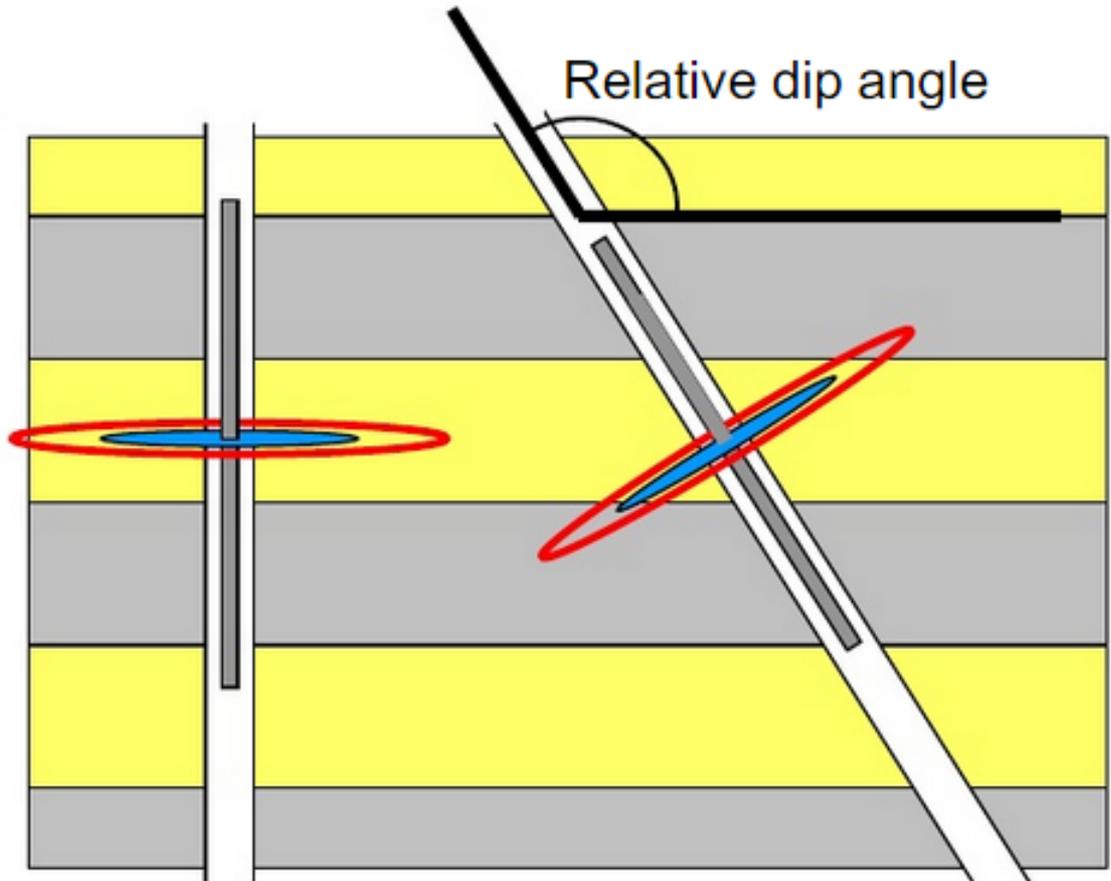
# Induction Resistivity in Deviated Wells

Shallow Resistivity  
Deep Resistivity



low relative  
dip angle

high relative  
dip angle



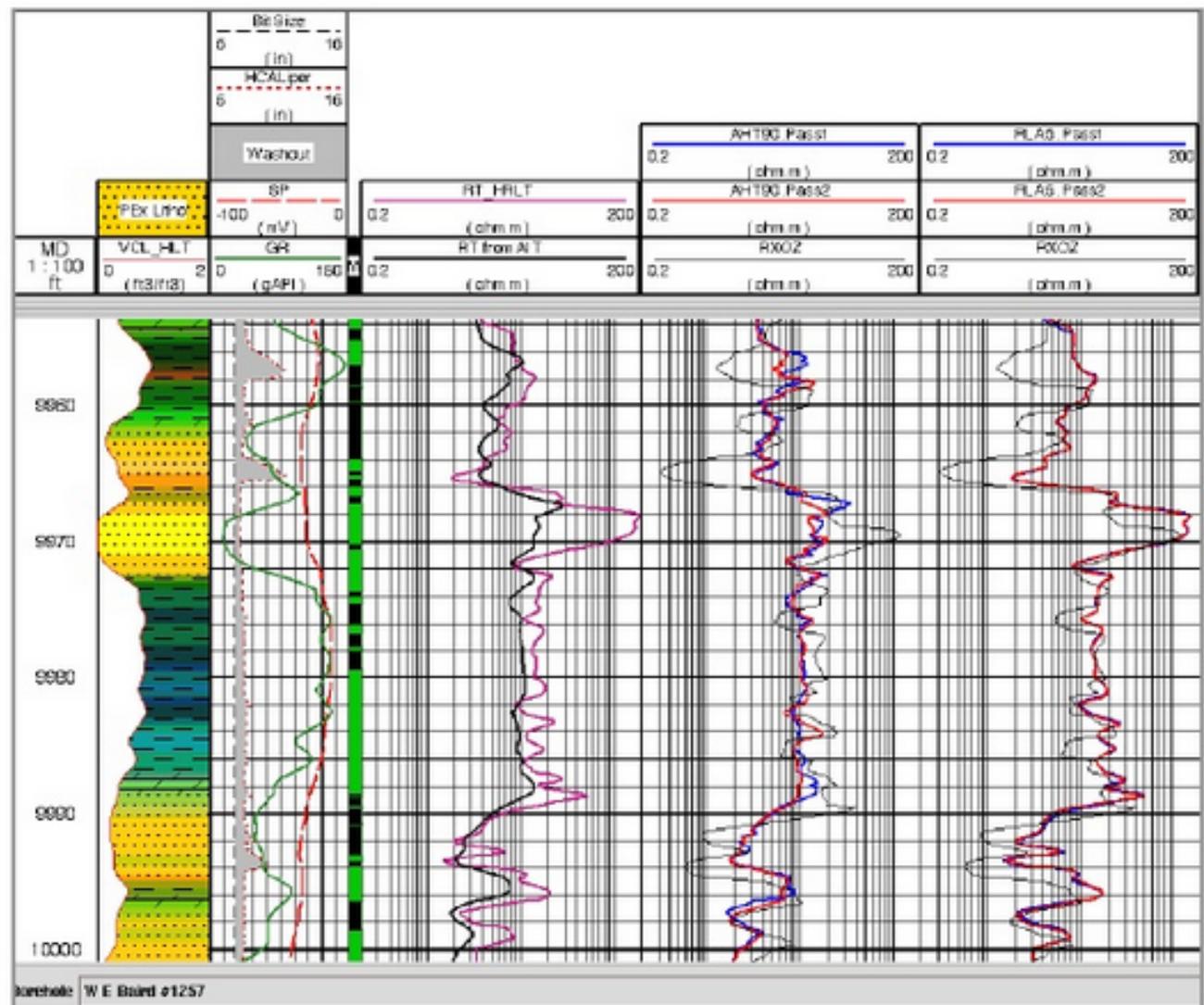
BS = 8"

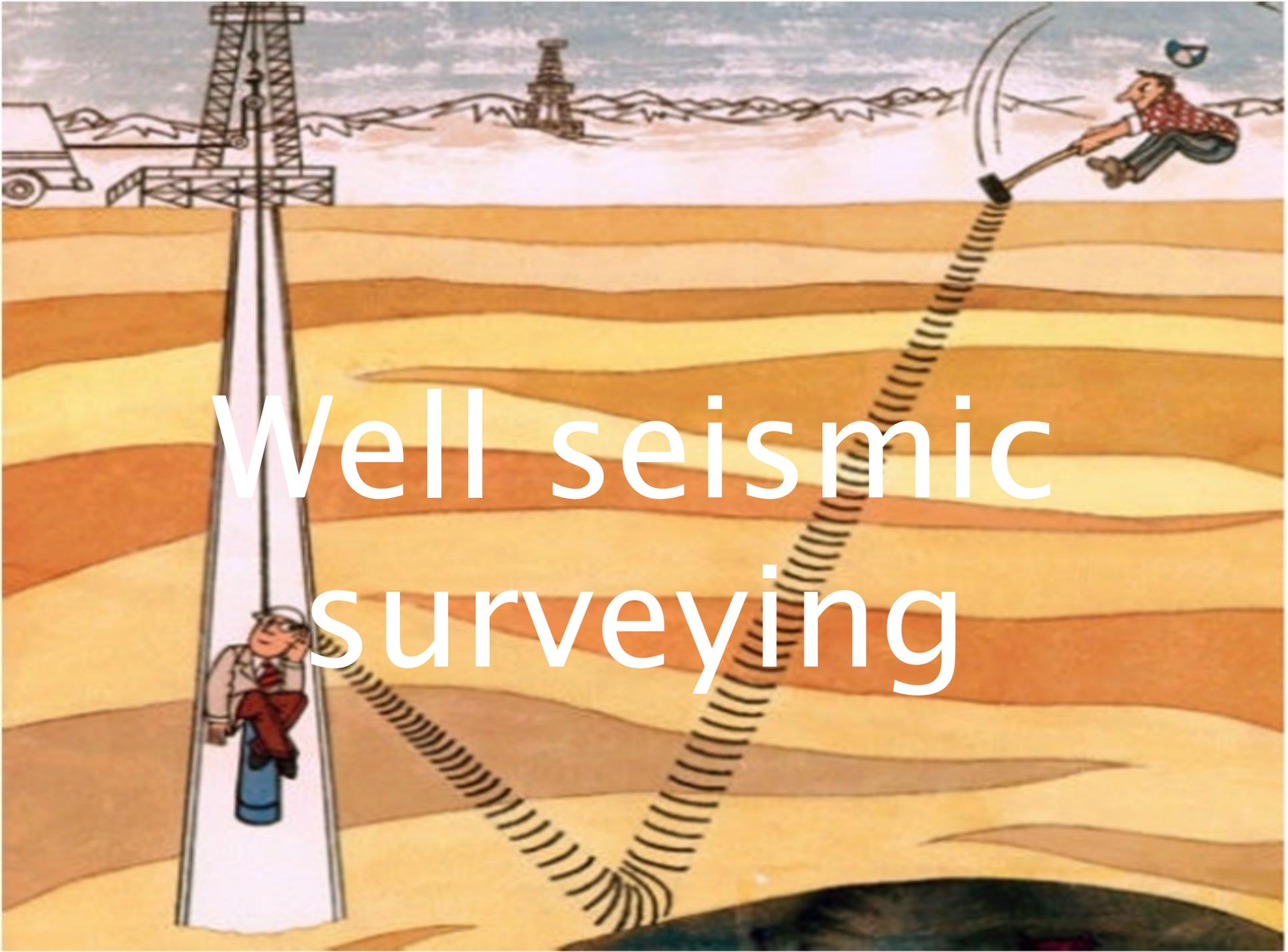
Rt = 200

Rxo = 30

Rm = 0.1

S/O = 1.5"

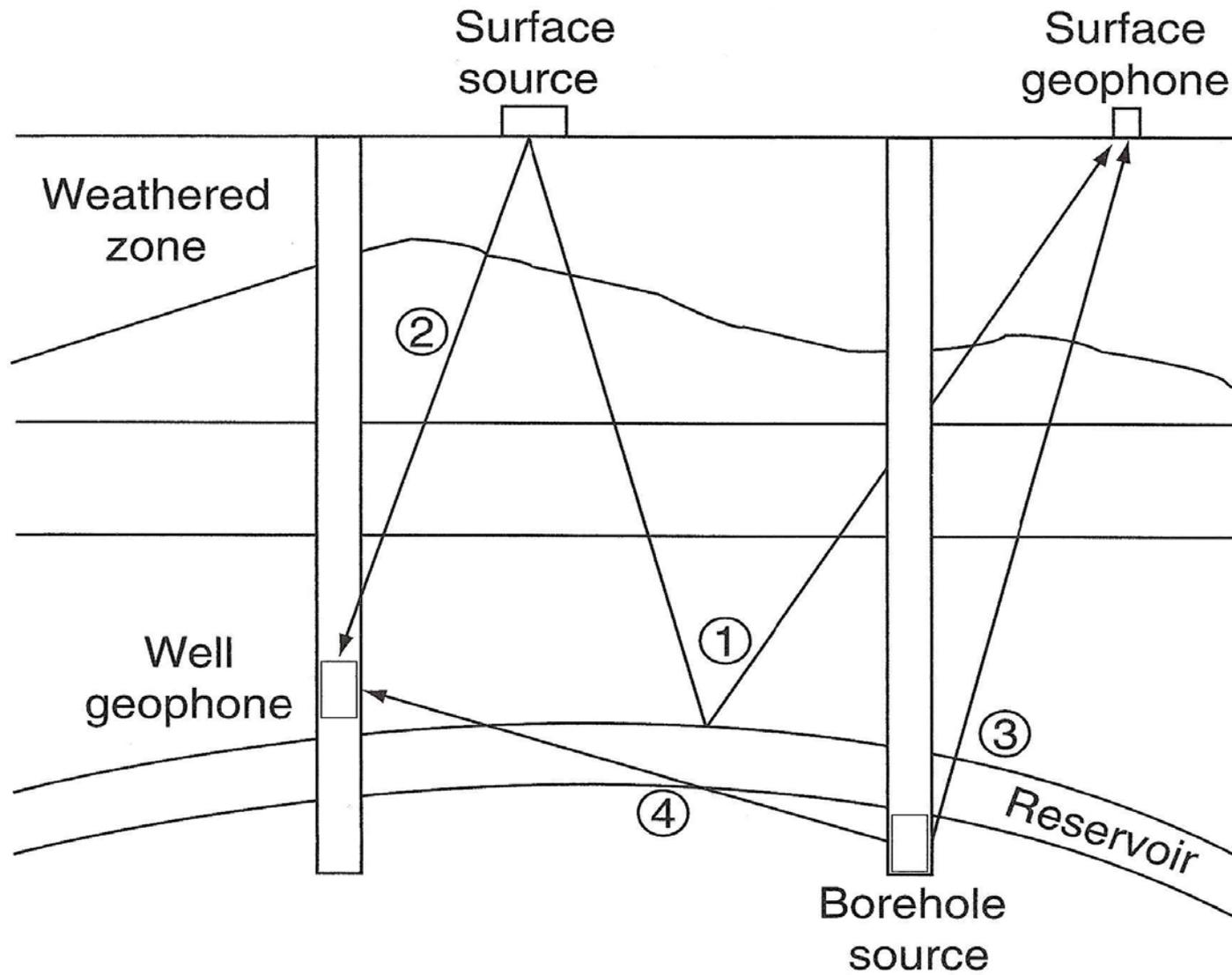




# Well seismic surveying

## مقدمه

- در لرزه نگاري معمولي ، فرستنده و گیرنده هردو در سطح زمین قرار دارند و اطلاعات مربوط به ساختار زمین را به این وسیله شناسایی می شود ، اما در لرزه نگاري درون چاهي منبع یا گیرنده و یا هردوي آنها در داخل چاه قرار می گیرند و داده ها به این روش بدست می آیند.
- استفاده از لرزه نگاري درون چاهي این امکان را به ما می دهد که يك فهم دقيق تري از مخزن در حين عملیات اکتشاف بدست آوریم.
- در زیر انواع لرزه نگاري درون چاهي را مشاهده می کنید.



▶ در شکل قبل سه نوع لرزه نگاري درون چاهي را مشاهده مي کنيد که عبارتند از:

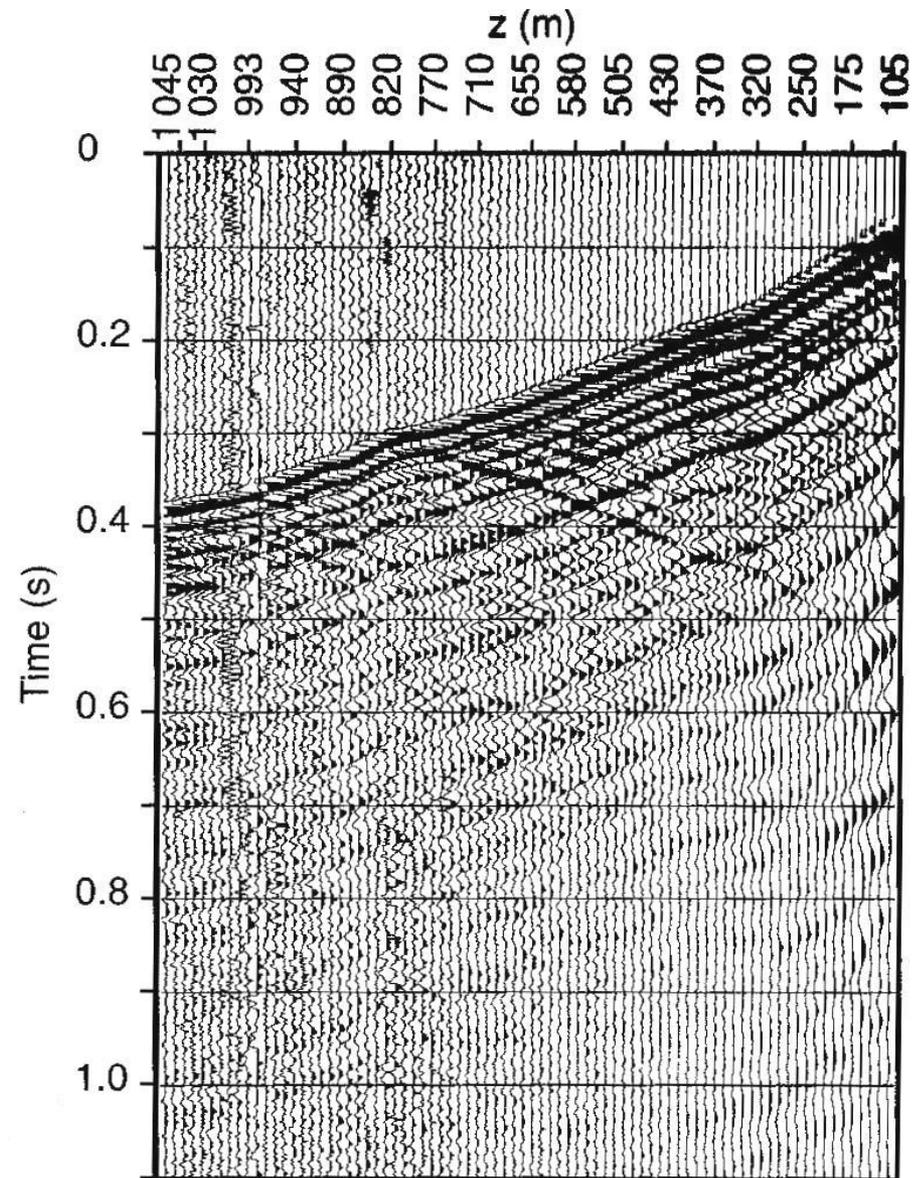
1. شات در سطح و برداشت در چاه

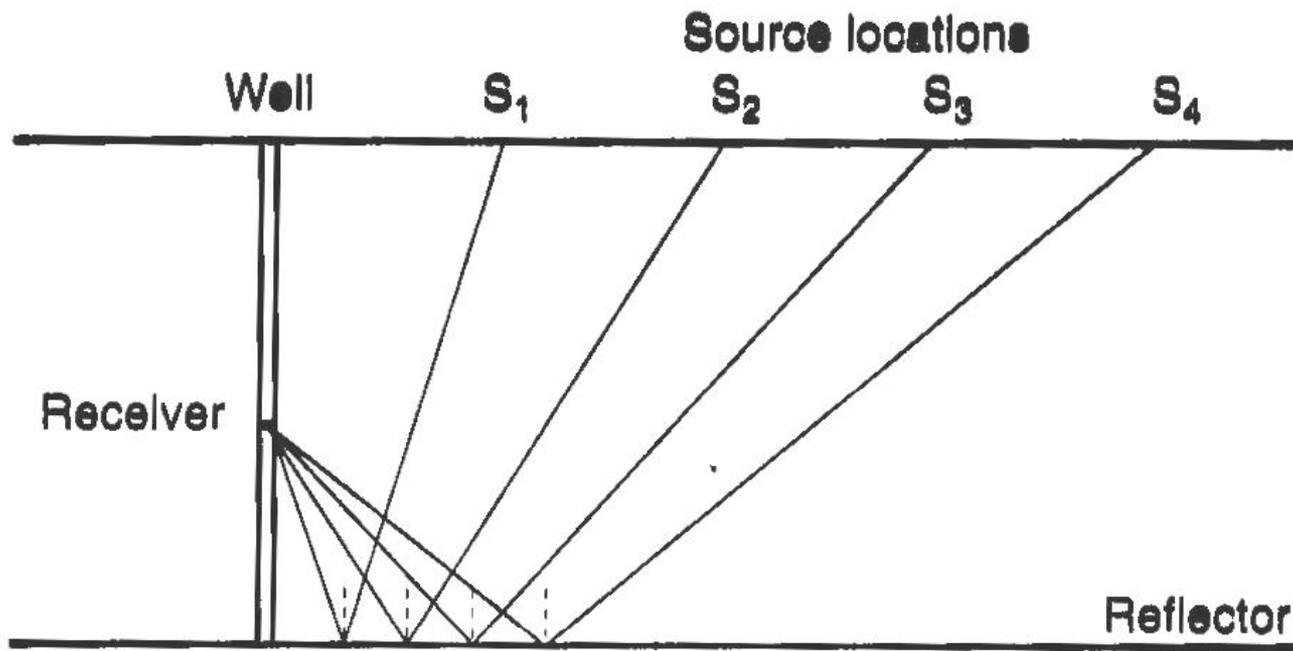
2. شات در چاه و برداشت در سطح

3. شات در چاه و برداشت در چاه ديگر

# Surface shot

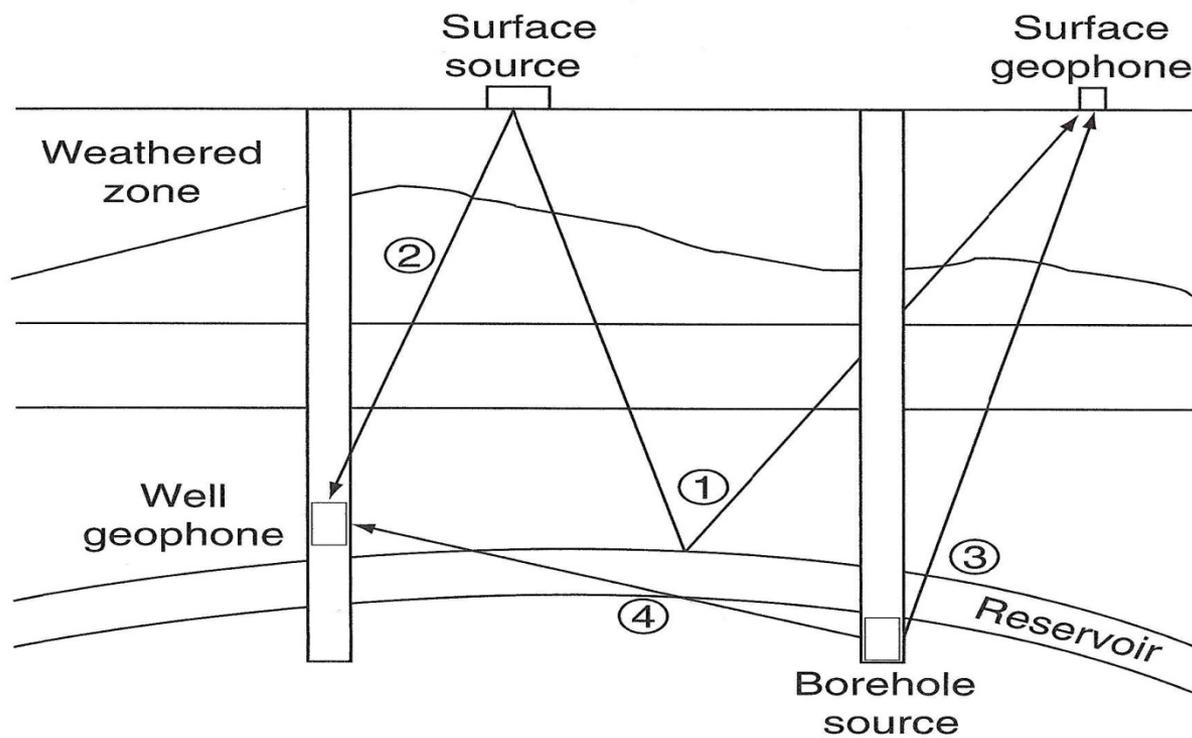
- ▶ يك نوع از این عملیات **vertical seismic profile (VSP)** می باشد.
- ▶ در شکل اسلاید بعد می توان یک نمونه از برداشت های **VSP** را مشاهده کرد ، در این برداشت ها محور افقی ژئوفون ها در اعماق مختلف بوده و محور قائم زمان است.
- ▶ در **VSP** فاصله ی دو ژئوفون در چاه معمولاً بین 3 تا 23 متر است.
- ▶ در **VSP** برای این که بتوان مساحت جانبی بیشتری را مورد بررسی قرار داد ، می توان تعدادی شات با **offset** های مختلف انجام داد و با افزایش **offset** میزان جستجوی جانبی نیز افزایش می یابد.





# Shot in the well

- مسیر شماره 3 در شکل زیر می باشد.

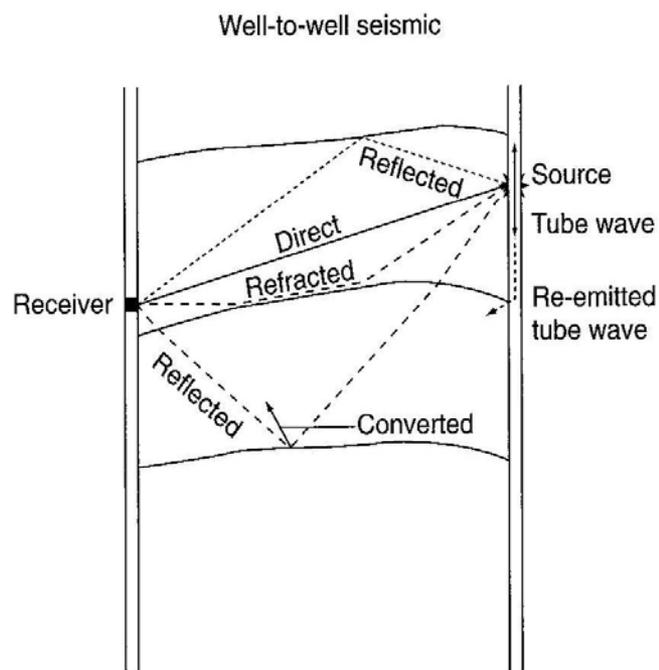


- در این روش به يك منبع در داخل چاه نیاز داریم و دریافت کننده ها بر اساس آرایشي که از قبل انتخاب شده است در سطح قرار مي گیرند.
- يك سري از **Seismic while drilling(SWD)**ها از این نوع مي باشد که از امواج توليدي از مته را به عنوان منبع استفاده مي کنند.

# Well – to – well seismic

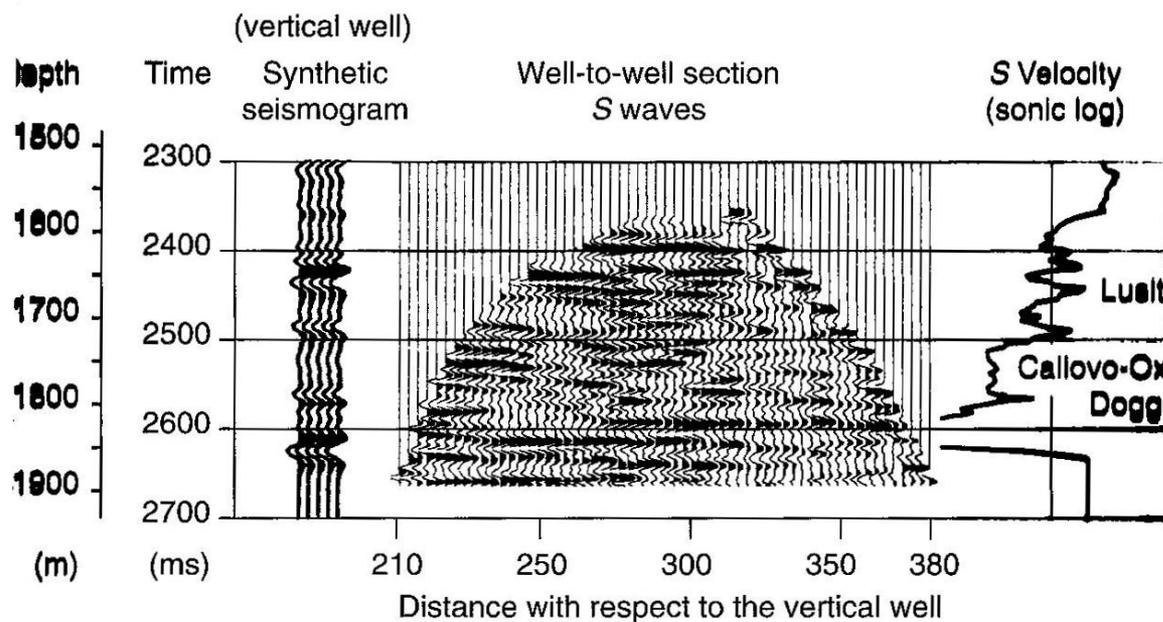
• استفاده از این روش به علت وجود امواج بازتابی زیاد نسبت به دو روش دیگر تفسیرش مشکل تر و پرهزینه تر

می باشد.

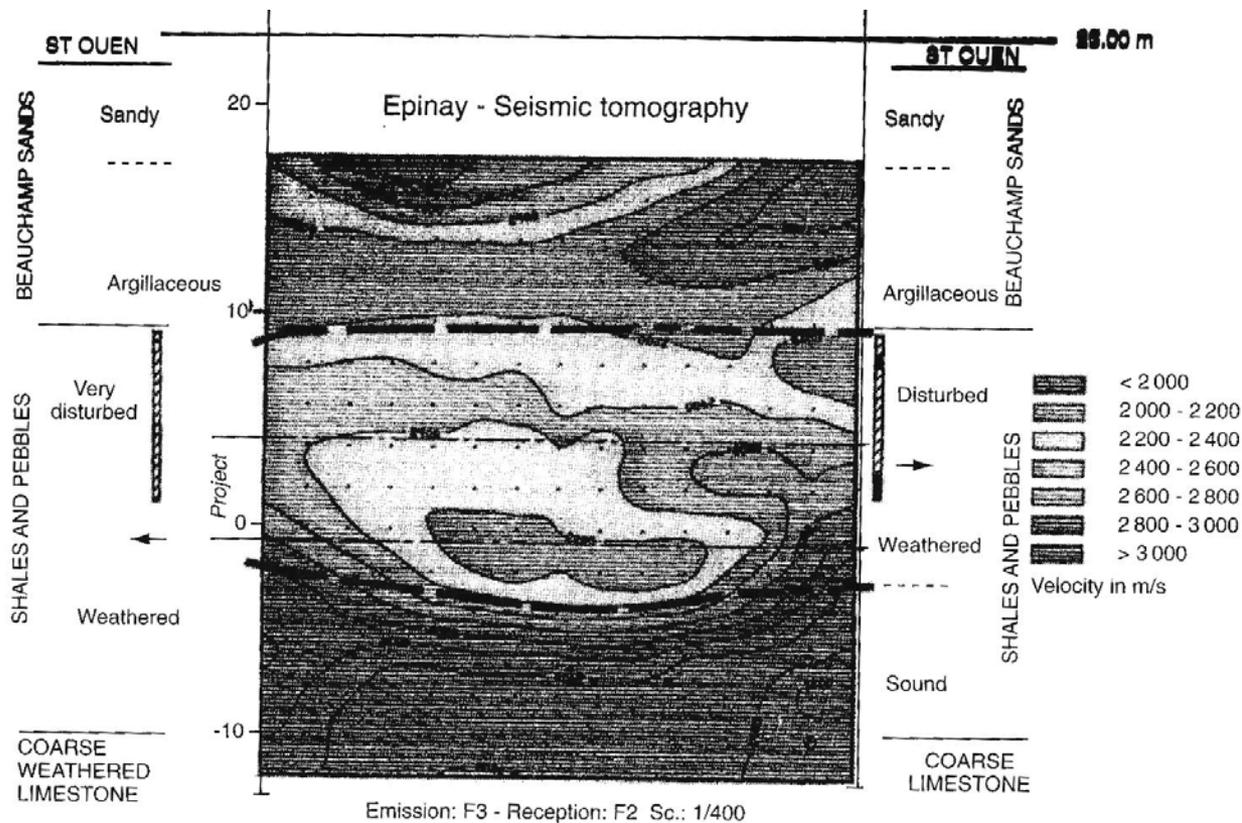


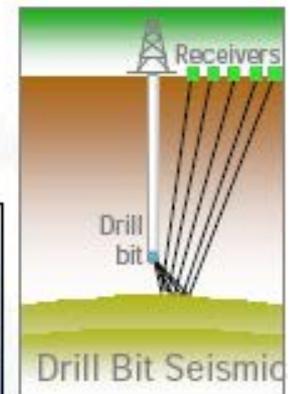
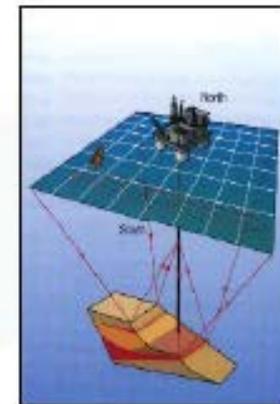
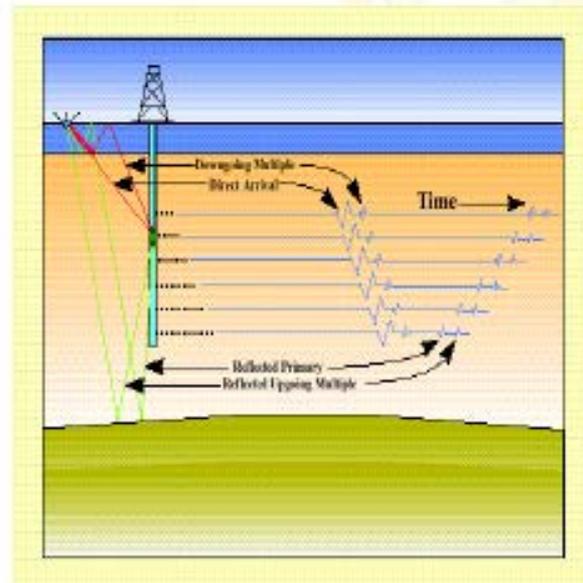
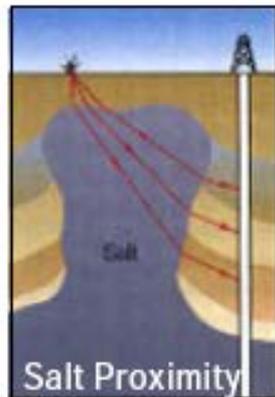
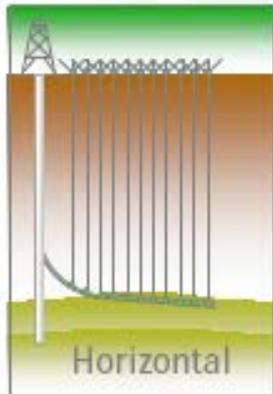
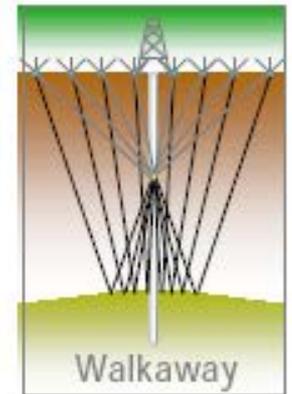
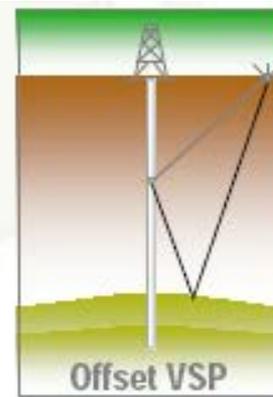
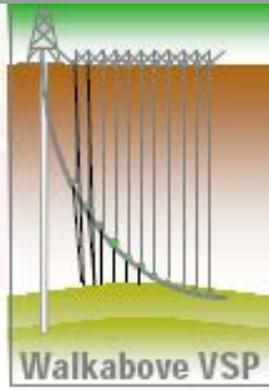
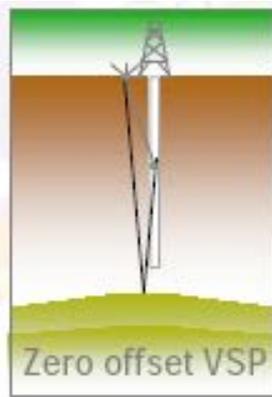
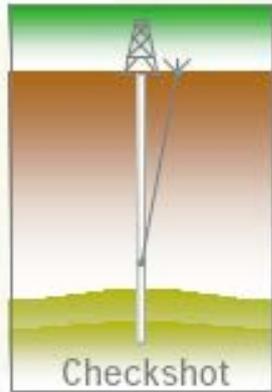
- این روش معمولاً در عملیات عمرانی و یا معدن استفاده می شود اما در بررسی مخازن با عمق کم هم قابل استفاده است.

- این روش منجر به بدست آوردن يك section از لایه های بین دو چاه می شود.



• در زیر مثالی از کاربرد این روش در مهندسی عمران را مشاهده می کنید.

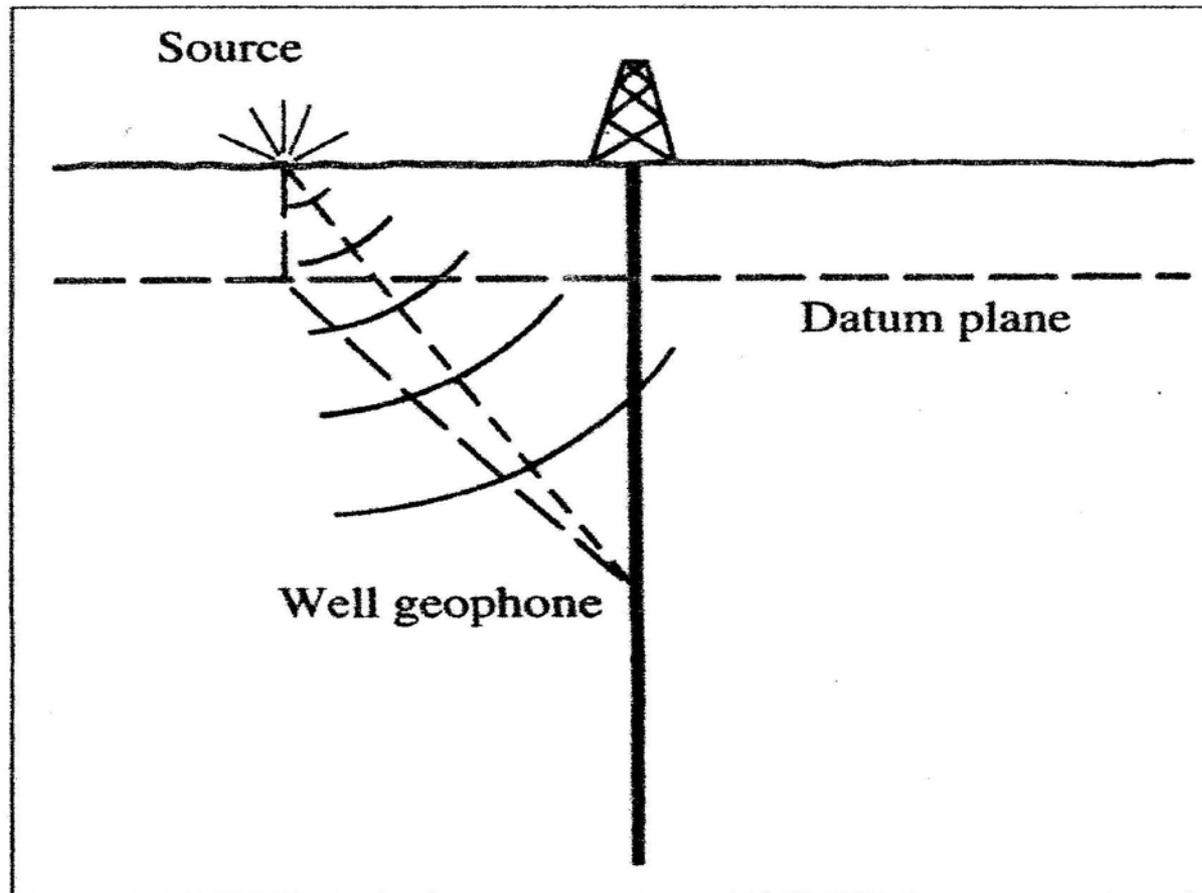




# VSP

- وقتي در عمليات VSP شات مي کنيم ، امواج از فرستنده در تمام جهات پراکنده مي شوند ، در نتيجه يکسري از امواج مستقيما به ژئوفون ها موجود در چاه مي رسد ، اما يکسري امواج بعد از چندين انعکاس به گيرنده مي رسند (Multiple).
- در تفاسير VSP سطح مبنا را انتهاي لايه ي هوازده در نظر مي گيريم.





Implementation of seismic well velocity survey.

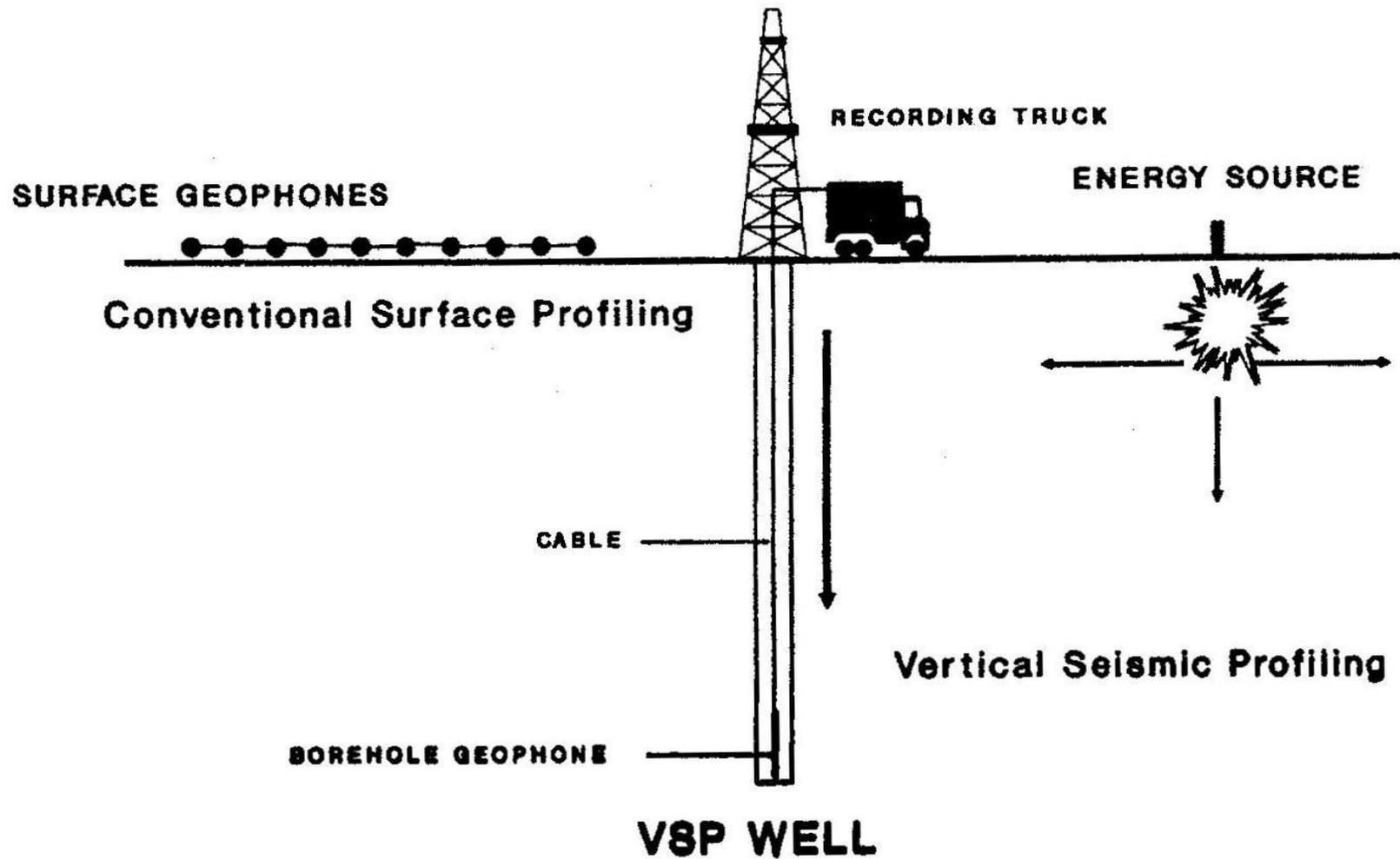
- در شکل بعد مي توان اختلاف بين VSP و horizontal Seismic profile را مي توان مشاهده کرد.

- VSP همانند velocity survey مي باشد اما دو تفاوت عمده دارد:

1. فاصله ي ژئوفون ها در VSP حداکثر 23 متر است ولي در velocity survey فاصله به چند صد متر هم مي رسد.

2. در velocity survey اولين موج رسیده براي ما اهميت دارد و ثبت مي شود اما در VSP از امواج بعدي هم استفاده مي شود.

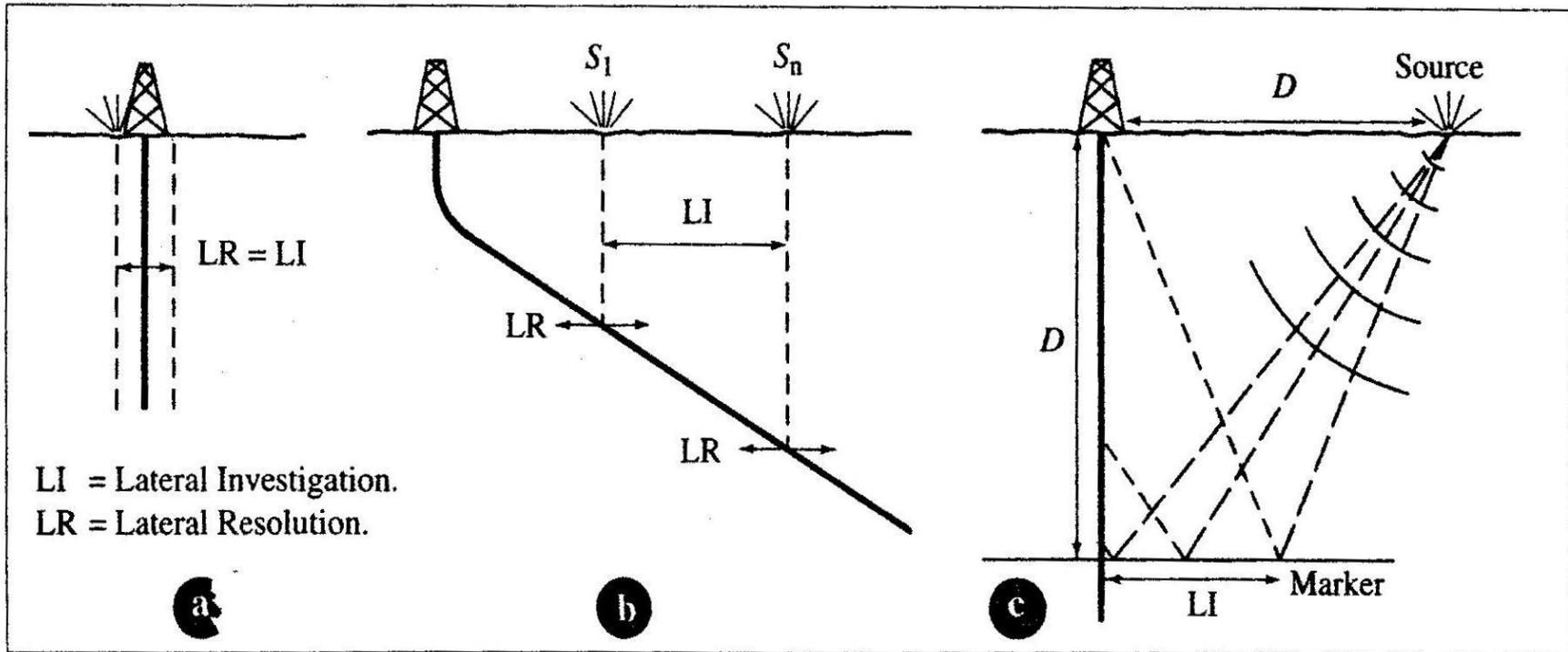
## VSP concept



▶ در عملیات VSP باید مراحل زیر را طی کنیم:

1. چك کردن عمق ابزارها در چاه.
  2. گیر دادن ابزارها به دیواره و شل کردن کابل
  3. ثبت امواج لرزه ای
  4. مشخص کردن اولین امواج رسیده
  5. محکم کردن کابل
  6. آزاد کردن ابزارها
- ▶ حاصل عملیات بالا يك نمودار زمان انتشار در مقابل عمق است ( $t=f(z)$ ).

- در عملیات VSP اگر چاه قائم باشد معمولاً در يك نقطه شات مي كنيم ، اما اگر چاه مایل باشد باید تعداد زيادي شات داشته باشيم.



Lateral range of investigation (LI) and lateral resolution (LR) in a vertical seismic profile.

- همانطور که در شکل بالا مشاهده شد، در چاه قائم مقدار **Lateral investigation** برابر **lateral resolution** است، اما در چاه مایل این دو مقدار با هم متفاوت است (بخش **b**).
- يك راه براي افزايش **LI** استفاده از **offset** بيشتري است (بخش **c**).
- در **VSP offset** مقدار **LI** حدودا نصف **offset** مي باشد.

- در  $VSP$  مقدار فاصله ی ماکزیمم ( $\Delta Z_{max}$ ) بستگی به حداقل سرعت لایه ها ( $V_{min}$ ) و ماکزیمم فرکانس لایه ها ( $F_{max}$ ) دارد و داریم:

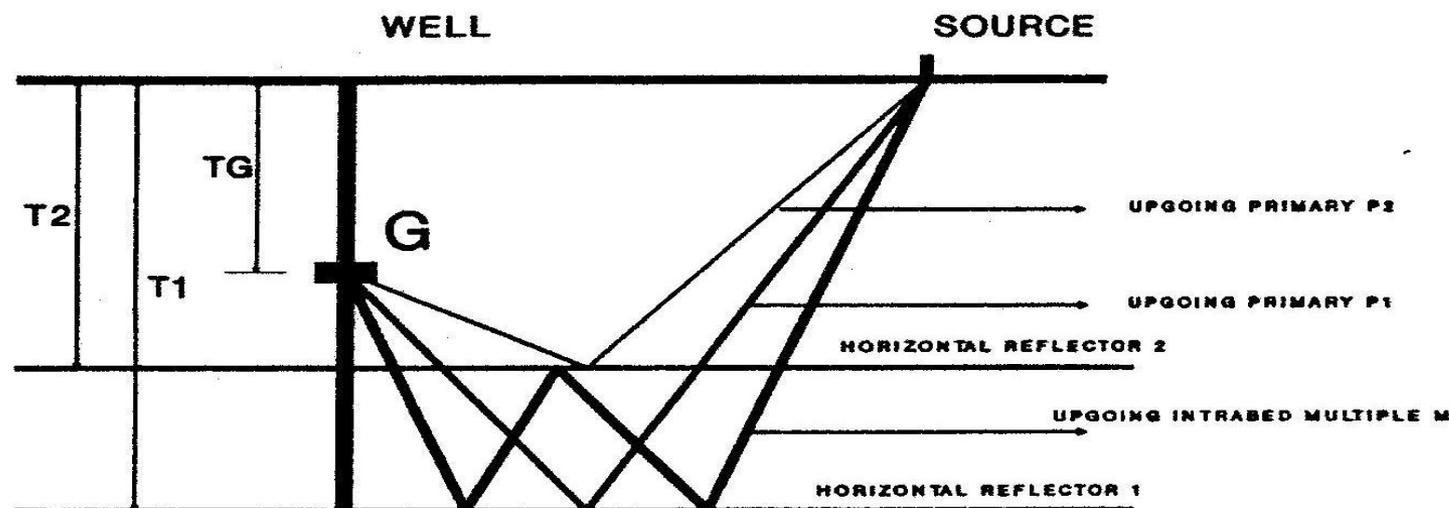
$$\Delta Z_{max} = V_{min} / 2F_{max}$$

- به عنوان مثال اگر سرعت حداقل برابر 150 متر بر ثانیه و فرکانس بیشینه برابر 150 هرتس باشد بیشترین فاصله مجاز ژئوفون ها برابر 5 متر است.

# Separation upgoing & downgoing wave

- در دو شکل زیر می توان ایده ی خوبی از امواج بالا رونده و پایین رونده بدست آوریم.

## Upgoing primaries and multiples



$T_1, T_2, T_G$  are one way vertical travel time to reflectors 1,2 and geophone G. Large offset is assumed for better visual clarity. Reflectors 1,2 are assumed to be horizontal.

$t_1$ : Upgoing travel time from reflector 1 to geophone.

$$t_1 = T_1 + (T_1 - T_G) = 2T_1 - T_G$$

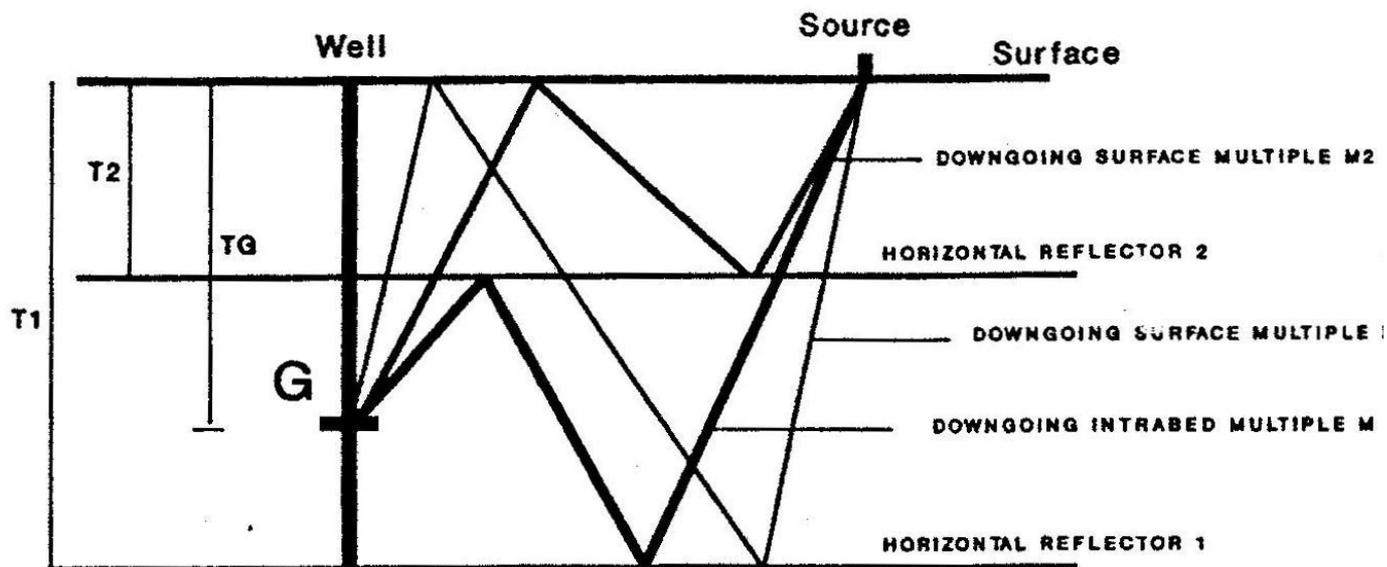
$t_2$ : Upgoing travel time from reflector 2 to geophone.

$$t_2 = T_2 + (T_2 - T_G) = 2T_2 - T_G$$

$t_M$ : Upgoing multiple travel time from reflector 1 to geophone

$$t_M = T_1 + 3(T_1 - T_2) + T_2 - T_G = 2T_1 + 2(T_1 - T_2) - T_G$$

## Downgoing surface and intrabed multiples



RAYPATHS DESCRIBING THE DOWNGOING SURFACE MULTIPLES AND  
INTRABED MULTIPLES THAT ARRIVE AT THE VSP GEOPHONE.

ASSUME THAT REFLECTORS 1, 2 ARE HORIZONTAL

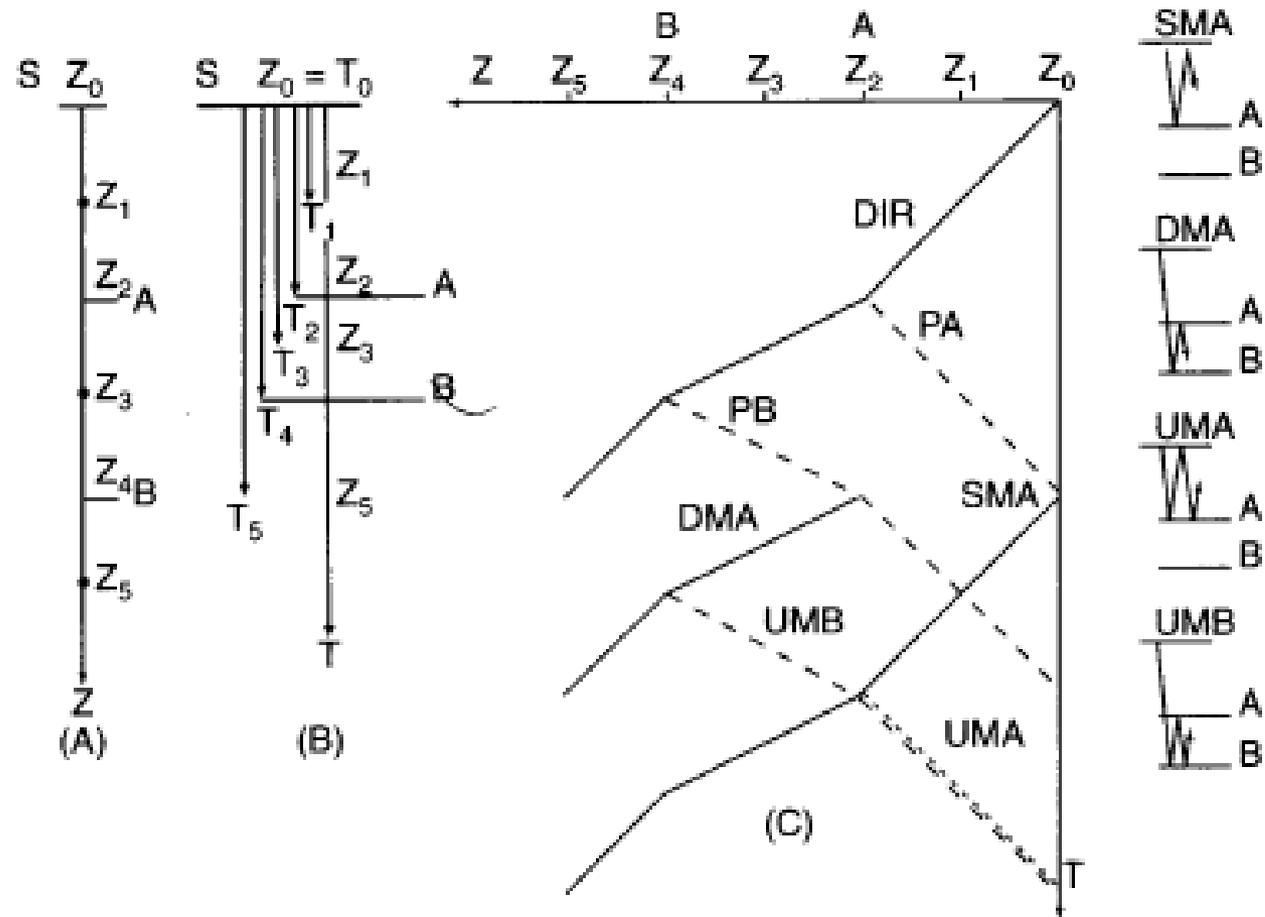
$$t_1 = 2T_1 + TG$$

$$t_2 = 2T_2 + TG$$

$$t_M = T_1 + (T_1 - T_2) + (TG - T_2) \\ = T_1 + T_1 - T_2 + TG - T_2$$

$$t_M = 2(T_1 - T_2) + TG$$

- در شکل بعد **trace** هاي كلي مربوط به يك عمليات **VSP** که داراي دو بازتاب کننده ي **A** و **B** و 5 گیرنده در اعماق مختلف مي باشد را مشاهده مي کنيد.
- در اين شکل 7 سري موج رسیده را مشخص کرده ايم.



▶ در ادامه می خواهیم به بررسی هفت سری موج مشخص شده در بالا پردازیم.

1. **Direct arrival(DIR)**: این ها امواجی هستند که به طور مستقیم به هر کدام از گیرنده ها می

رسد، در شکل مشاهده می شود که با افزایش عمق زمان رسیدن نیز افزایش می شود و هر بازتاب کننده

باعث ایجاد يك شکستگی در روی نمودار می شود. این سری از امواج را توسط هر 5 گیرنده دریافت می

کنیم.

2. Primary reflection on horizon A (PA): این امواج عبارتند از امواج بازتابی از

سطح A که به گیرنده های بالایی این سطح می رسد. زمان رسیدن این امواج را می توان از رابطه ی زیر بدست آورد.

$$T_A = T_4 + (T_2 - T_i)$$

- در رابطه ی بالا  $i$  بین 0 تا 2 است.

- زمان  $T_A$  با افزایش عمق کاهش می یابد ، به عنوان مثال این زمان برای گیرنده ای در سطح برابر  $2T_2$  می باشد.

3. Primary reflection on horizon B(PB): این امواج عبارتند از امواج بازتابی از

سطح B که توسط گیرنده های اول تا چهارم ثبت می شود (گیرنده های بالایی سطح B).

- زمان رسیدن این امواج را می توان از فرمول مقابل بدست آورد.

$$T_B = T_4 + (T_4 - T_i)$$

- در رابطه ی بالا  $i$  بین 0 تا 4 است.

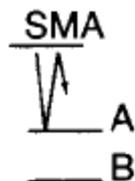
#### 4. (SMA) Surface multiple after reflection on horizon A

همانطور که می دانیم امواج بازتابی از سطح  $A$  به سمت بالا حرکت می کنند اما در سطح بین این لایه با هوا به علت اختلاف آمپیدانس زیاد این موج مجدد به سمت پایین بازتاب می کند و باعث ایجاد

**Multiple** هایی در تمام ژئوفون ها می شود. اثر این امواج بر روی نمودار  $x-t$  همانند امواج **DIR**

می باشد با این تفاوت که یک انتقال زمانی به اندازه  $i$  زمان سیر از سطح  $A$  تا سطح زمین نیز دارد.

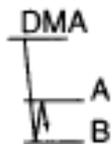
▶ زمان رسیدن این امواج تقریباً برابر با  $2T_2 + T_1$  می باشد که  $i$  بین 0 تا 5 می باشد.



## 5. Downgoing multiple creat by horizon A after reflection

on horizon B (DMA): این امواج عبارتند از امواج حاصله از بازتاب مجدد امواج بازتابیده از

سطح بالایی افق B توسط سطح پایینی A.



این امواج توسط گیرنده ی 2 به بعد ثبت می شود و با افزایش عمق زمان آن نیز زیاد می شود.

زمان رسیدن این امواج برابر است با:

$$T = T_4 + (T_4 - T_2) + (T_i - T_2)$$

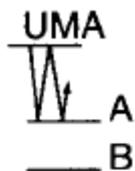
اثر این امواج مشابه امواج DIR می باشد با این تفاوت که از گیرنده ی دوم به بعد ثبت شده و دارای

انتقال زمانی برابر  $2(T_4 - T_2)$  می باشد.

6. Upgoing multiple created by horizon A after reflection at

the surface (UMA): این امواج را می توان بازتابی از امواج SMA توسط سطح A

دانست و یا به عبارت دیگر امواج دوبار بازتاب شده بین سطح و افق A هستند.



این امواج در گیرنده های بالای سطح A اثر دارد همانند امواج PA.

زمان رسیدن این امواج برابر است با:

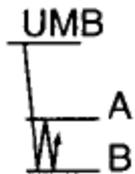
$$T = 3T_2 + (T_2 - T_i)$$

در این رابطه A بین 0 تا 2 می باشد.

## 7. Upgoing multiple created by horizon B after reflection

on horizon A (UMB): این امواج عبارتند از امواجی که از بازتاب امواج DMA توسط

سطح B و یا به عبارت دیگر امواج دوبار بازتاب شده بین سطح A و B می باشند.



▶ زمان رسیدن این امواج با کاهش عمق افزایش می یابد و تنها توسط گیرنده های بالای سطح B ثبت می شوند.

▶ زمان رسیدن این امواج برابر است با:

$$T = T_4 + 2(T_4 - T_2) + (T_4 - T_i)$$

▶ در این رابطه A بین 0 تا 4 می باشد.

## چند نکته

- با داشتن زمان رسیدن اولیه (first arrival time) برای هر دو گیرنده ی متوالی (i و i+1) می توان سرعت متوسط را بین این دو گیرنده از رابطه ی زیر بدست آورد.

$$V_{i,i+1} = (Z_{i+1} - Z_i) / (T_{i+1} - T_i)$$

- در صورتی که بدانیم دو گیرنده در يك لایه قرار دارند می توان تخمینی از سرعت در آن لایه را با فرمول بالا بدست آورد.

• امواج رسیده به گیرنده هارا مي توان دو دسته تقسیم بندی کرد:

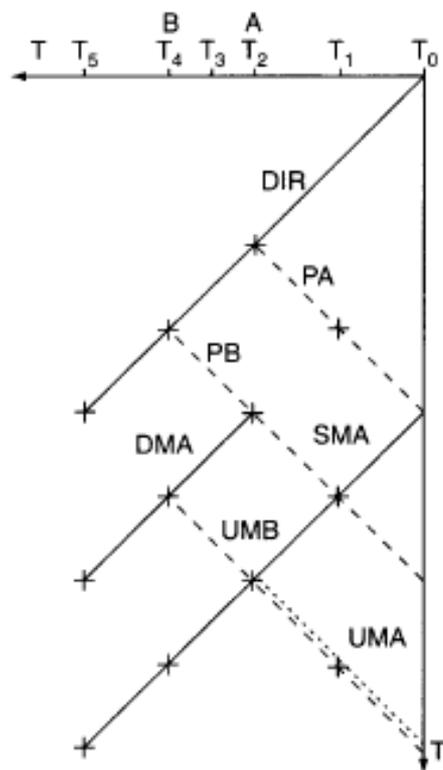
1. امواج پایین رونده (downgoing): عبارتند از ، DMA,SMA,DIR که بوسیله ي خطوط پر رنگ در شکل مشخص شده و با افزایش عمق زمان هم زیاد مي شود.
2. امواج بالا رونده (upgoing): عبارتند از: PA,PB,UMA,UMB که توسط خطوط نقطه چین در شکل مشخص شده اند و با کاهش عمق زمان آنها زیاد مي شود.

در عملیات VSP اگر امواج **upgoing** را مورد بررسی قرار دهیم می توان با استفاده از یک انتقال زمانی برای هر کدام از ژئوفون ها در عمقهای مختلف پروفیل لرزه نگاری درون چاهی را به پروفیل لرزه ای سطحی تبدیل کرد ، مقدار انتقال زمانی برابر است با:

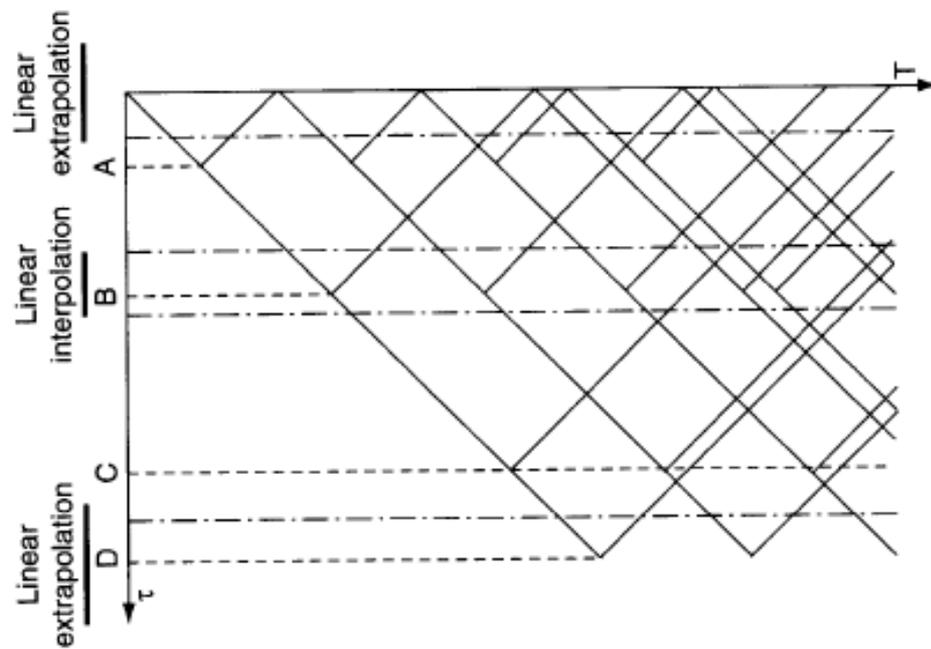
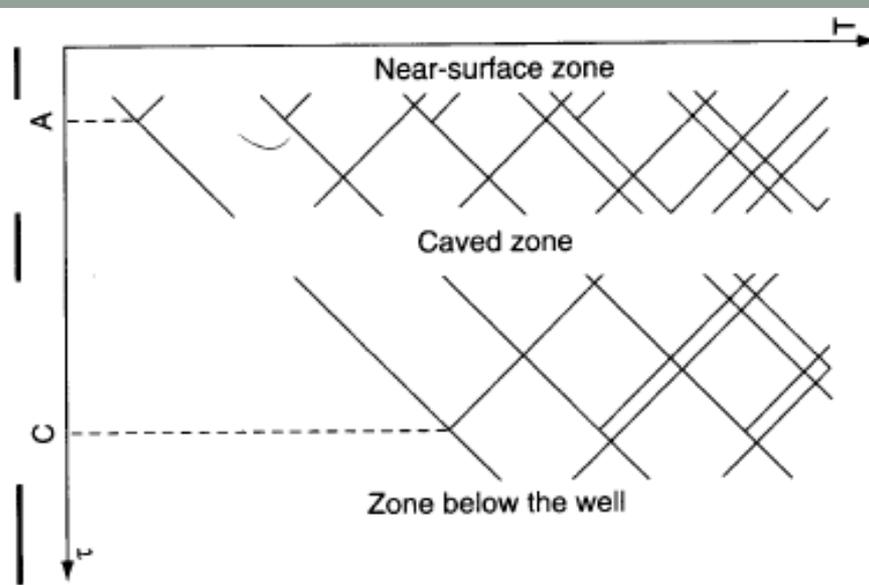
$$T = T_s - T_i$$

- ▶ در این رابطه  $T$  برابر است با زمانی که ژئوفون ها موج را دریافت کرده و  $T_s$  برابر است با زمانی که اگر ژئوفون در امتداد مسیر امواج به سطح انتقال داده شود لازم است که این زمان به آن اضافه شود.
- ▶  $T_i$  هم برابر است با زمان رسیدن اولین موج مستقیم به ژئوفون ها ( زمان مربوط به **DIR**).
- ▶ با این روش می توان پروفیل های لرزه ای درون چاهی را با پروفیل های لرزه ای سطحی مقایسه کرد و هر دو را با هم مورد بررسی قرار داد.

- اگر در نمودار  $x-t$  به جاي مکان ژئوفون ها از زمان رسیدن موج به آنها استفاده کنیم ، تمام سرعت ها در مسیر یکسان می شود با این تفاوت که شیب امواج بالا رونده برابر 1- و شیب امواج پایین رونده برابر با 1 می شود.

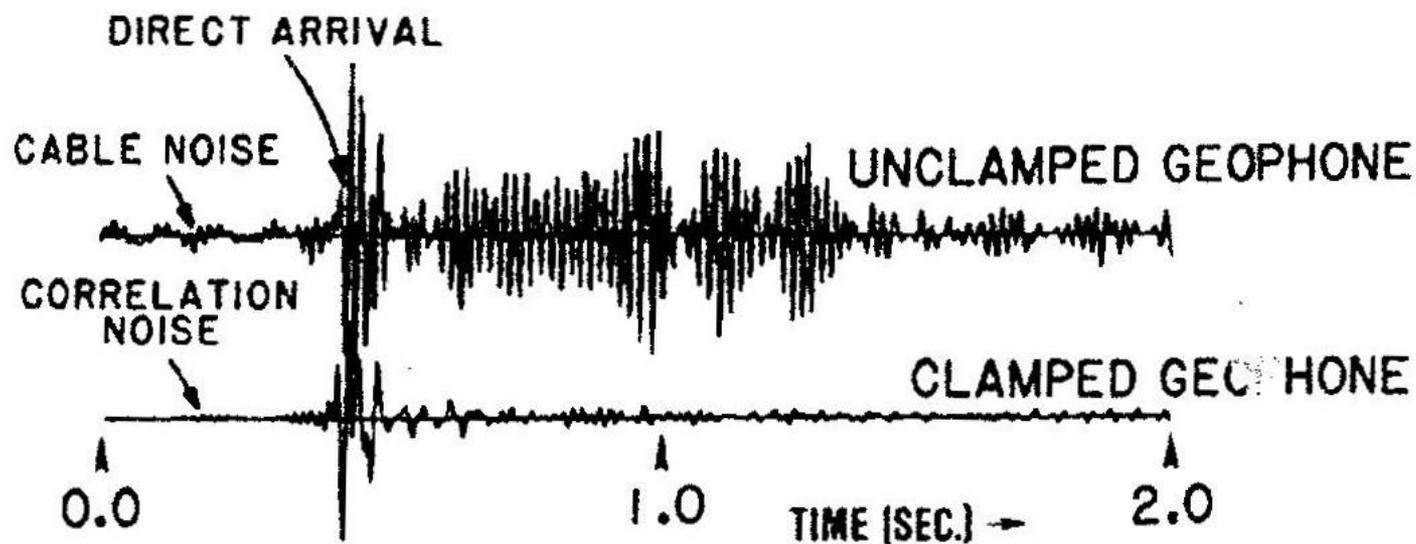


- ▶ از محاسن این روش این می باشد که می توان امتداد اثرهای بدست آمده را امتداد داد (بدون داشتن خطا زیرا خط راست را امتداد می دهیم) و در جاهایی که اطلاعات بدست نیامده اطلاعات بدست آوریم.
- ▶ با این روش می توان به راحتی افق ها را مشخص کرد ، به عنوان نمونه محل برخورد PA با DIR نشان دهنده ی افق A می باشد و یا محل برخورد PB با DIR هم نشان دهنده ی افق B می باشد.
- ▶ اگر ما يك ناحیه ی ریزش کرده در دیواره چاه داشته باشیم ، نمی توان از آنجا اطلاعاتی بدست آورد ولی با این روش می توان امتداد امواج گذرنده از این ناحیه را رسم کرد و سطح لایه را بدست آورد.
- ▶ در شکل بعد نمونه ای از این امتداد دادن را مشاهده می کنید.



# Noise

- **Random noise**: ممکن است حرکت سیال در پشت لوله جداری که خوب سیمان نشده و یا حرکت سیال داخل چاه يك سري نويز در برداشت ها ایجاد می کند.
- **Geophone coupling**: در لرزه نگاري سطحي يك سري نويز هاي ناشي از بد قرار گرفتن ژئوفون ها در سطح زمین ایجاد می شود ، اما در ژئوفون هاي درون چاهي بد وصل شدن آنها به یکدیگر و نامناسب بودن اتصال آنها به دیواره باعث ایجاد يك سري نويز بعد از رسیدن جبهه ي اصلي به ژئوفون می شود ، این امواج باعث حرکت ژئوفون شده و این نویزها تولید می شود.



GEOPHONE DEPTH - 1295 METERS  
SOURCE OFFSET - 209 METERS

EFFECT OF GEOPHONE CLAMPING ON SIGNAL RESPONSE.

► **Cable wave**: انتشار موج در امتداد کابل نیز امکان دارد ، سرعت انتشار این امواج بستگی به

دانشیته ی کابل دارد.

► سرعت انتشار امواج در امتداد کابل بین 2500 تا 3500 متر بر ثانیه است.

► در چاه های کم عمق یا لایه های زمین شناسی کم سرعت ، امواج رسیده از کابل می تواند اولین موج رسیده

باشد(همانند شکل قبل).

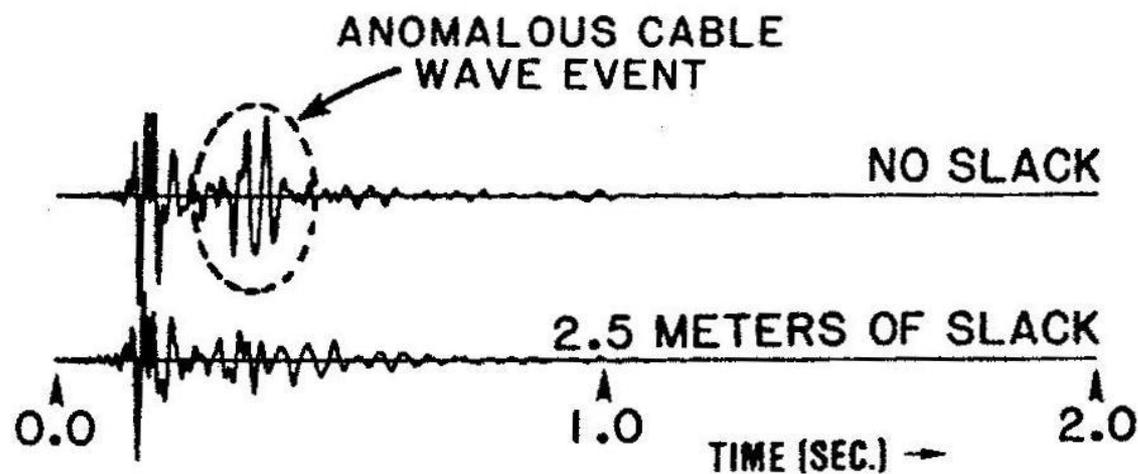
► برای رفع این مشکل باید طناب را از حالت کشش خارج کرد و آن را شل کرد(**slacking**) ، به این گونه

که بعد از اینکه از این ژئوفون ها به عمق مناسب رسیدند و به طور محکم در دیوار مستقر شدند طناب را

مقداری آزاد می کنیم ، اثر **slacking** را در اساید بعد مشاهده می کنید.

**Effect of cable slack on geophone signal** (courtesy Geophysical Press, from Hardage, B.A.: "Vertical Seismic Profiling, Part A: Principles," 1983)

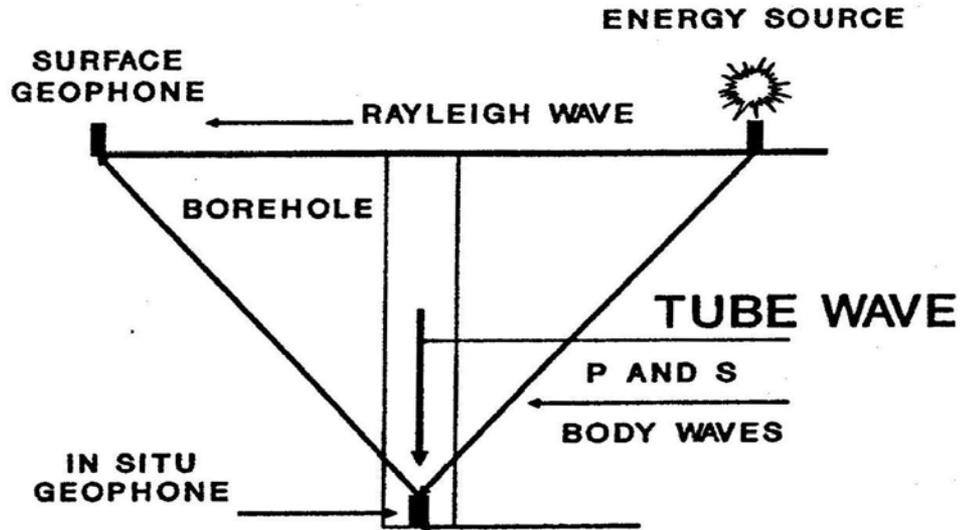
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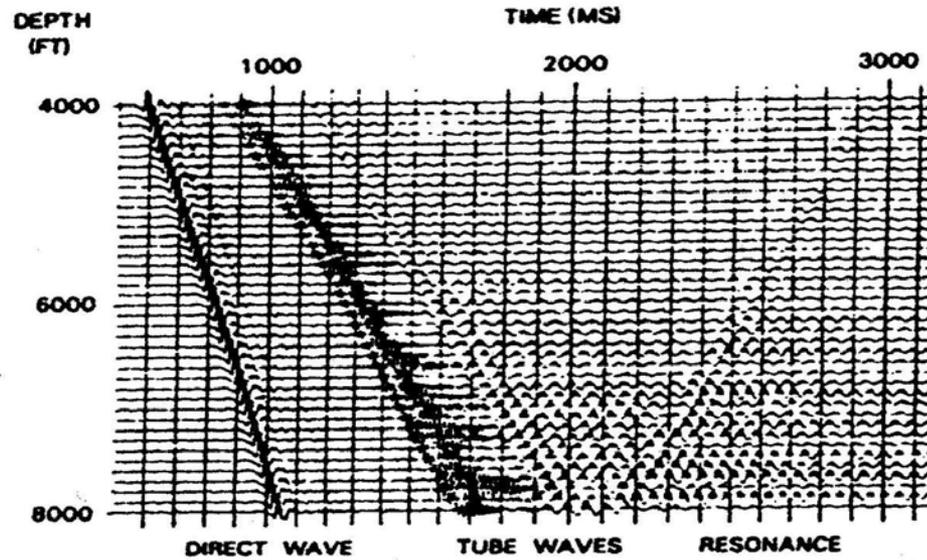
GEPHONE DEPTH - 305 METERS  
SOURCE OFFSET - 209 METERS

- **Surface wave**: در اکتشاف لرزه ای سطحی امواج ریلی و لاورا در نزدیکی سطح داریم و این امواج در ژئوفون های سطحی ثبت می شود ، با افزایش عمق اثر این امواج از بین می رود.
- اما در **VSP** چون عمق ژئوفون ها زیاد است امواج سطحی توانایی رسیدن به آن نقطه را ندارند.
- **Unbounded casing**: لوله ی جداری سیمان نشده باعث کاهش شدید انرژی و دامنه ی امواج می شود و کیفیت داده ها را از بین می برد.

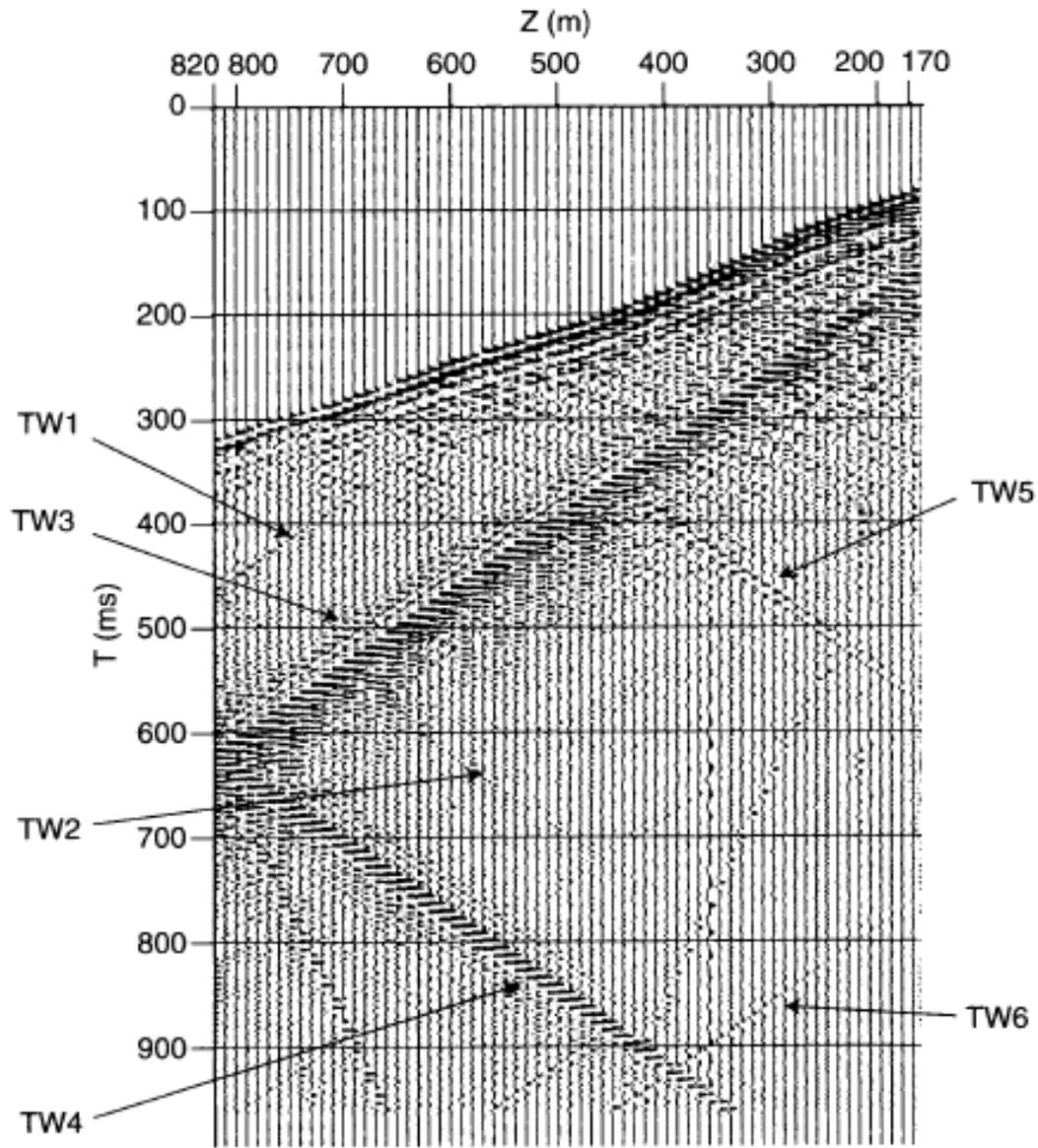
- **Tube wave**: يك چاه پر شده از مایع باعث ایجاد يك محیط برای انتشار موج های ناخواسته اي به نام امواج لوله اي مي شود.
- شكل شماتيك زیر گسترش این امواج را مشاهده مي کنید.
- این امواج يکي از مخربترین الگوهاي نويز مي باشد، زیرا این امواج همدوس بوده و با عمل **stacking** نه تنها نمی توان اثر آنها را کاهش داد بلکه اثر آنها تقویت مي کند.
- این امواج برای شناسایی بعضي از ساختارها مانند لایه های تراوا یا شکستگی ها می تواند کمک کند.



ELASTIC WAVE MODES INVOLVED IN SUBSURFACE SEISMIC RECORDING.



- امواج لوله اي وقتي حاصل مي شوند که ذرات موجود در ستون گل که حفره ي چاه را پر کرده اند به حرکت در آیند.
- امواج سطحي (امواج rayleigh) که به حفره چاه مي رسند تبدیل به امواج لوله اي شده و در امتداد چاه حرکت مي کنند.
- امواج لوله اي به سمت بالا و پايين چاه حرکت کرده و با تغيير آمپیدانس در بالاي ستون گل و يا ته چاه و يا هر تغيير در قطر چاه امواج لوله اي ثانويه را توليد مي کنند.



- يك راه براي کاهش امواج لوله اي اين است كه چون اين امواج از امواج سطحي توليد مي شوند مي توان با کاهش سطح گل در چاه مانع از نفوذ نويژه‌هاي سطحي به داخل سيال چاه شده و مقدار امواج لوله اي را کاهش داد.

- اين راه حل به شرطي قابل اجرا است كه عواملی مانند فشار چاه اجازه ي خارج كردن مقدار از گل حفاري را بدهد.

• **Surface cultural noise**: علت ایجاد این امواج حرکت افراد و ماشین آلات در نزدیکی سایت

VSP می باشد.

• نحوه ی کاهش و حذف این نویزها ایجاد محیط ساکت و آرام در حین عملیات می باشد.

# VSP applications

کاربردهای VSP را می توان در دو گروه کلی زیر جای داد: ►

- a. Exploration application
- b. Reservoir engineering & drilling application

a. Exploration application:

- Determining reflection
- Identification of seismic coefficients
- Comparison of VSP with synthetic seismogram
- Fresnel zone and VSP horizontal resolution
- Seismic amplitude studies
- Determining physical properties of the rocks
- Seismic wave attenuation
- Thin bed stratigraphy

b. Reservoir engineering & drilling application:

- Predicting depth of seismic reflectors
- Predicting rock condition ahead of the bit
- Defining reservoir boundaries
- Locating faults
- Monitoring secondary recovery processes
- Seismic tomography & reservoir description
- Predicting high – pressure zone ahead of the bit
- Detection of man – made fractures

# Reflection coefficient

- ▶ امواج صوتي از سطحي که آمپیدانس صوتي تغيير کند بازتاب مي شوند.
- ▶ پلاریته، دامنه و خاصیت فازی ( phase characteristics ) موجك ها توسط reflection coefficient در مرزها تعیین مي شود.
- ▶ امواج بالارونده نسبت به امواج پایین رونده اطلاعات بیشتری از اعماق مي دهند چون از بازتاب کننده ي عمیق تر بازتابیده شده اند.
- ▶ دانستن این ضریب وقتی اهمیت پیدا مي کند که بخواهیم داده هاي VSP را تفسیر کنیم ، چون این داده ها شامل داده هاي بالارونده و پایین رونده مي باشند که هم از سطح بالایی و هم از سطح پایینی بازتابیده شده اند.

- مقدار reflection coefficient برابر است با:

$$R = (\rho_2 v_2 - \rho_1 v_1) / (\rho_1 v_1 + \rho_2 v_2)$$

- این پارامتر وقتی که اطلاعات lithological و stratigraphic را در تفاسیر VSP وارد کنیم بسیار اهمیت پیدا می کند.

# Identification of a seismic reflector

- يك تفسير خوب تلاشي است که براي ارتباط داده هاي بدست آمده با ساختار چينه شناسي طبقات و رخساره هاي رسوبي.
- در صورت داشتن اطلاعات خوب **VSP** قادر هستيم که عمق هر لايه (رخساره) را در نزديکي چاه توسط امواج بالارونده اوليه مشخص کنيم.
- در نتيجه با استفاده از **VSP** مي توان نقشه هاي ساختاري بدست آمده از لرزه نگاري سطحي را اصلاح کرد.

▶ با استفاده از يك برداشت VSP با مقدار S/N (signal to noise ratio) پايين مي توان به

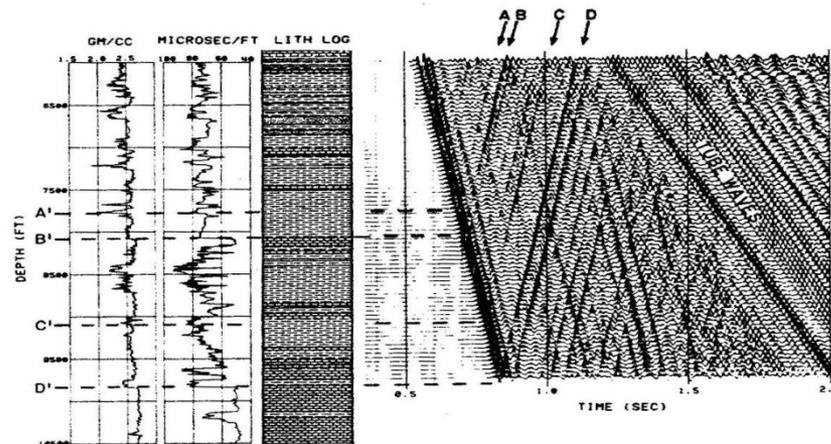
سوالات زير پاسخ داد.

1. بازتاب کننده ي ثبت شده توسط روش هاي ديگر آيا مرز لايه است يا يك ناپيوستگي مي باشد؟

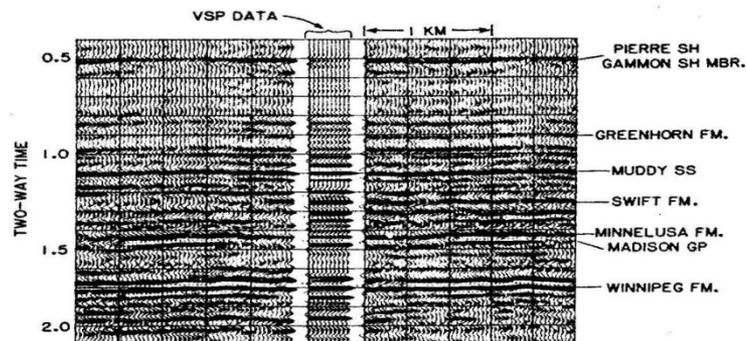
2. کدام مرز سنگ ها را مي توان توسط داده هاي لرزه نگاري سطحي تشخيص داد و کدام را نه!

▶ در شكل زير مي توان يك نمونه از تعيين بازتاب کننده ها را مشاهده كرد.

**Identification of a seismic reflector (courtesy Geophysical Press, from Hardage, B.A.: "Vertical Seismic Profiling, Part A: Principles," 1983, adapted from Balch et al., 1981)**



AN EXAMPLE OF THE RELIABILITY WITH WHICH VSP DATA CAN OFTEN IDENTIFY PRIMARY SEISMIC REFLECTORS. FOUR UPGOING PRIMARY REFLECTIONS ARE SHOWN BY THE LINEUP OF BLACK PEAKS LABELED A, B, C, D. THE SUBSURFACE DEPTH OF THE INTERFACE(S) THAT GENERATED EACH REFLECTION CAN BE DEFINED BY EXTRAPOLATING THE APICES OF THE BLACK PEAKS DOWNWARD UNTIL THEY INTERSECT THE FIRST BREAK LOCI OF THE DOWNGOING COMPRESSIONAL EVENT. THESE DEPTHS ARE LABELED A', B', C', D'. THESE ARE RAW FIELD DATA. NO PROCESSING HAS BEEN DONE OTHER THAN A NUMERICAL AGC FUNCTION HAS BEEN APPLIED TO EQUALIZE ALL AMPLITUDES.

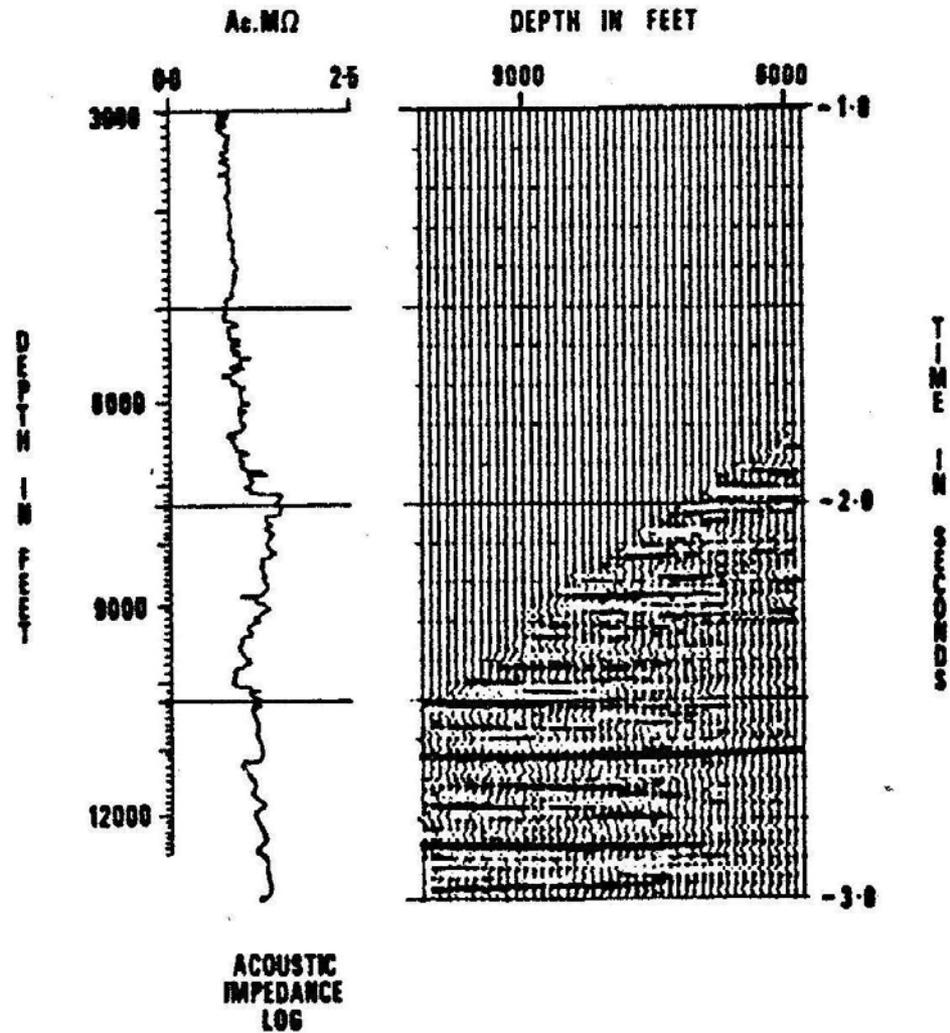


COMPARISON BETWEEN SURFACE-RECORDED REFLECTION DATA AND PROCESSED VSP DATA AT THE USGS MADISON LIMESTONE TEST WELL NO. 2. (ALTERED FROM BALCH ET AL., 1981B).

# Predicting interval velocity

- یکی دیگر از داده های بدست آمده از آنالیز داده های VSP نمودار آمپیدانس صوتی در مقابل عمق است.
- مقدار تغییرات دانسیته نسبت به تغییرات سرعت در رسوبات تقریباً ناچیز است بنابراین می توان از تغییرات دانسیته نسبت به سرعت صرف نظر کرد
- شکل زیر یک نمونه از این نمودار است.

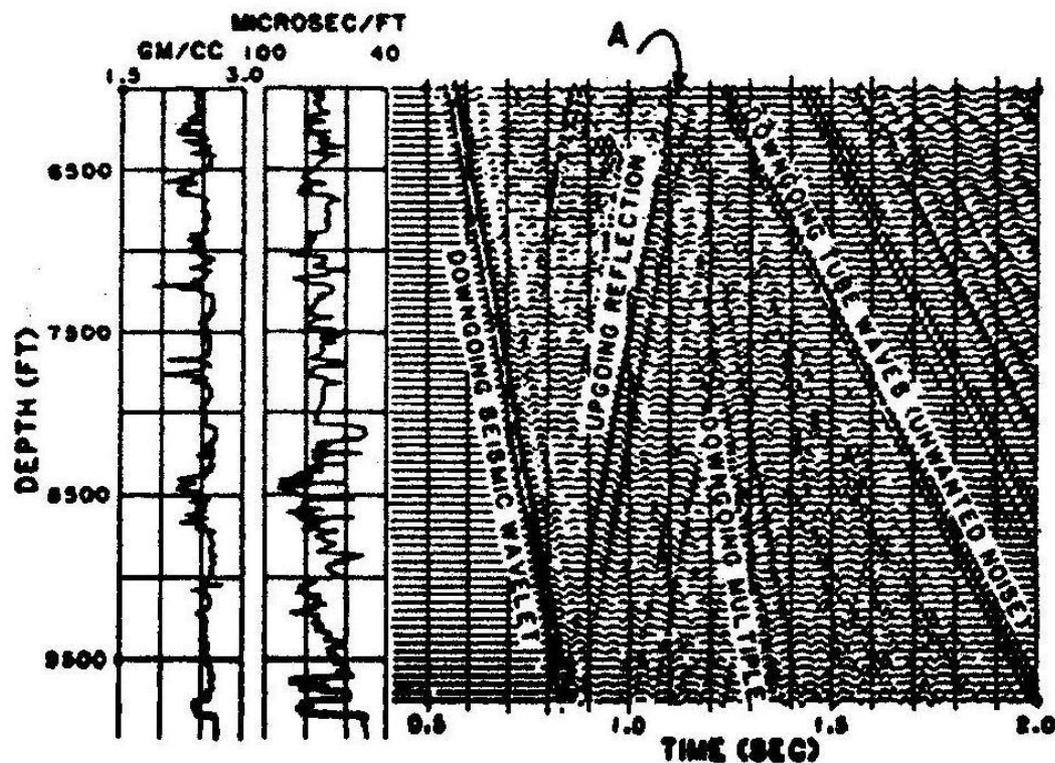
Predicting velocity ahead of the bit (courtesy of Seismograph Service Corporation)



# Predicting depth of seismic reflector

- دانستن عمق سر سازندها در حین حفاری و عملیات بعد از آن بسیار با اهمیت است ، مشخص کردن سرسازندها را می توان با استفاده از لرزه نگاری سطحی هم بدست آورد ولی در مناطقی که چاه اکتشافی می خواهیم حفر کنیم ، استفاده از اطلاعات سطحی با عدم قطعیت بالایی همراه است. بنابراین از اطلاعات **VSP** استفاده می کنیم.
- از مزایای استفاده از **VSP** به جای لرزه نگاری سطحی در تعیین سر سازندها این می باشد که چون ژئوفون ها در عمق است کمتر تحت تاثیر نویزهای سطحی قرار می گیرند و تحلیل آنها راحت تر است.
- شکل بعد یک مثال از یافتن سرسازندها است ، در اینجا برای مشخص کردن سرسازندها محل برخورد امواج بالارونده با پایین رونده را مشخص کرده ، این محل برخورد سطح بازتاب کننده می باشد که در این شکل در عمق 9850 فوتی قرار دارد.

Predicting depth of a seismic reflector (courtesy Geophysical Press, from Hardage, B.A.: "Vertical Seismic Profiling, Part A: Principles," 1983)

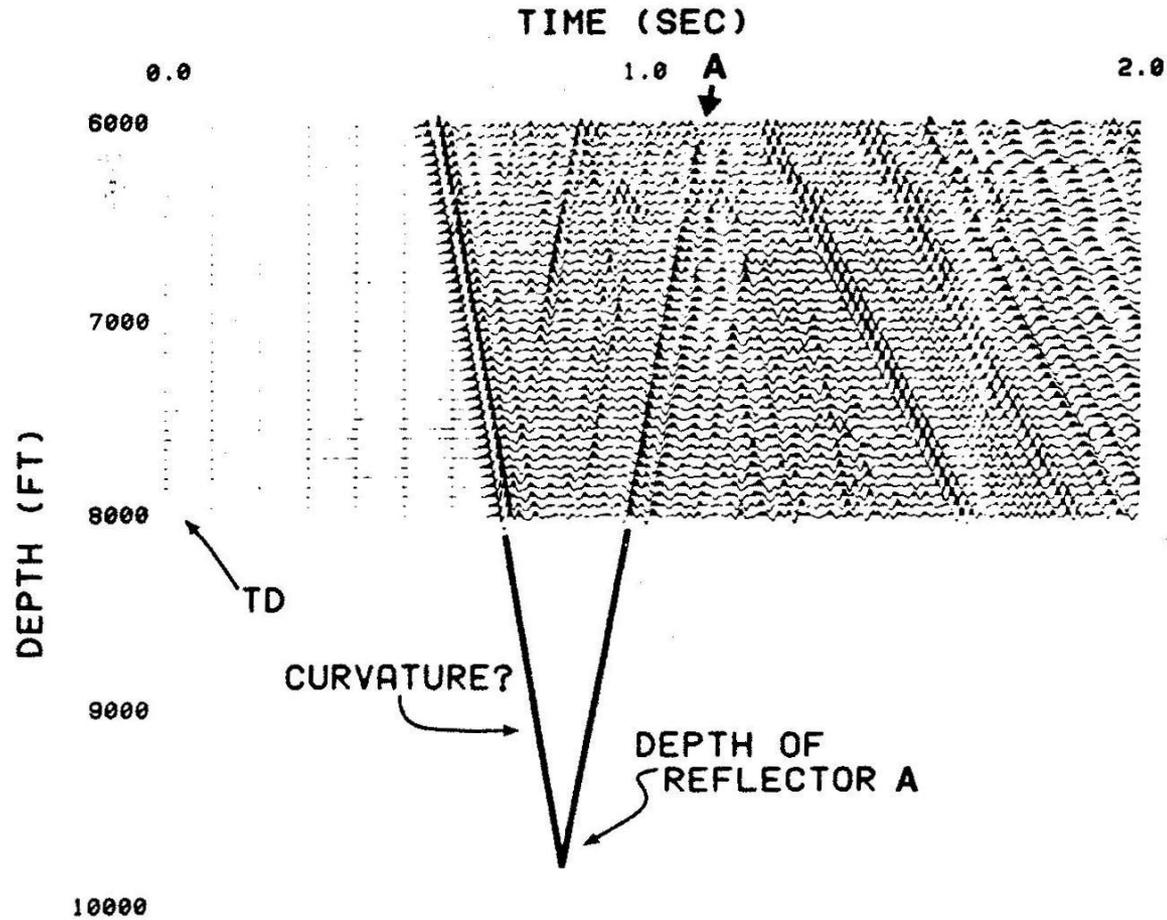


VSP DATA SHOWING A STRONG REFLECTOR, "A", ORIGINATING AT A DEPTH OF 9,850 FEET

# Looking ahead of the bit

- ▶ از دیگر استفاده های VSP پیش بینی فاصله ای است که مانده و باید حفاری شود تا به سرسازند مورد نظر برسیم.
- ▶ بر این اساس می توان آمادگی لازم برای وارد شدن به آن لایه را از قبل داشت و در نتیجه عواملی مثل وزن گل را به مقدار لازم برسانیم.
- ▶ در اسلاید بعد تا عمق 8000 فوتی حفاری شده است و سپس داده های VSP برداشت شده ، سپس برای مشخص کردن محل سرسازند موجك های حاصل از امواج بالارونده و پایین رونده را امتداد داده و محل برخوردشان محل سرسازند را مشخص می کند.

Looking ahead of the bit (courtesy Geophysical Press,  
from Hardage, B.A.: "Vertical Seismic Profiling, Part A: Principles,"  
1983)

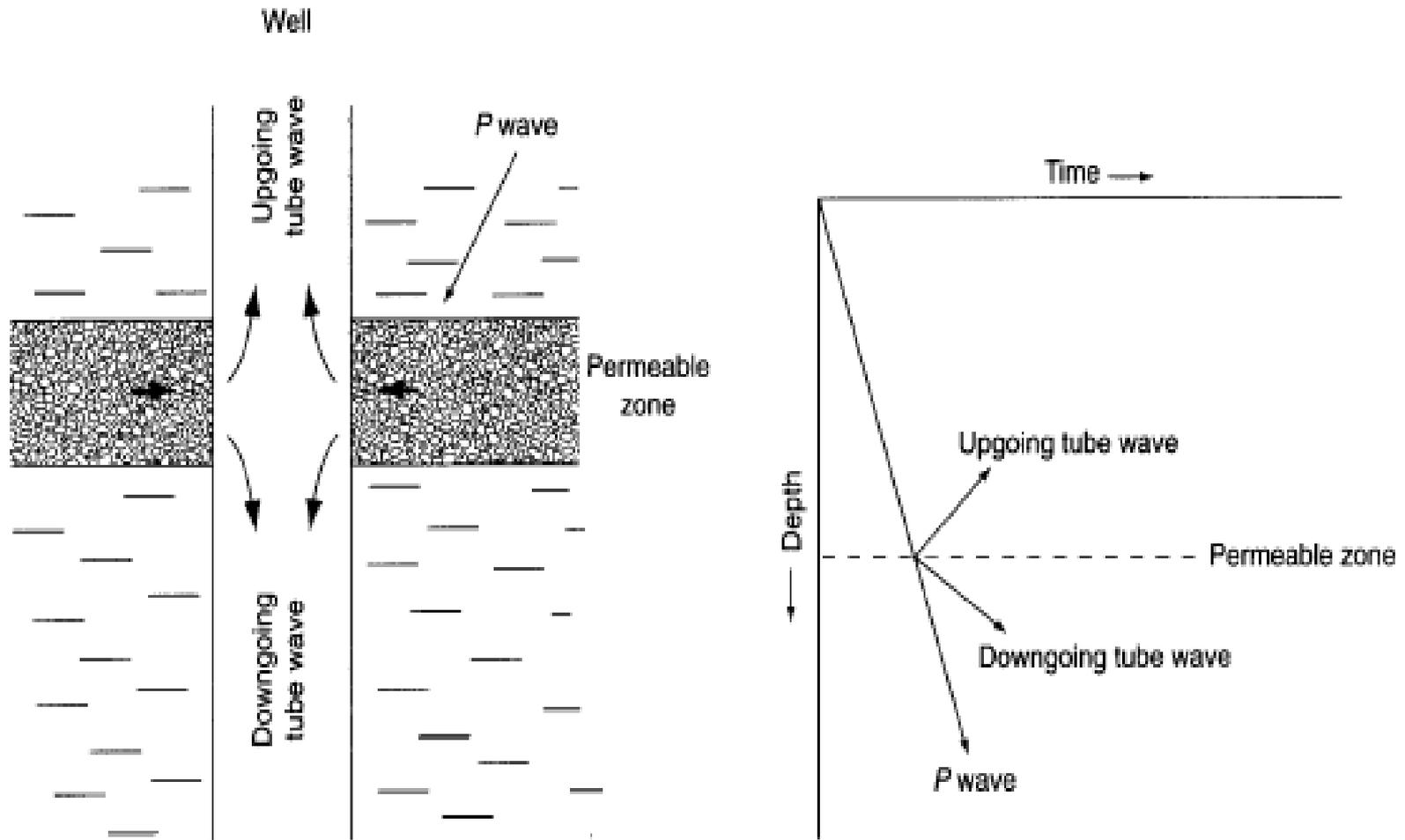


# Predicting pore pressure & porosity ahead of the bit

- یکی دیگر از کاربردهای جالب VSP این می باشد که شرایط زیر مته را می توان توسط آن پیش بینی کرد.
- Stone و همکاران از VSP برای محاسبه ی سرعت نفوذ و عمق مته استفاده کردند و با تلفیق آن با اطلاعات پتروفیزیکی توانستند pore pressure و تخلخل را به طور دقیقی مشخص کنند.

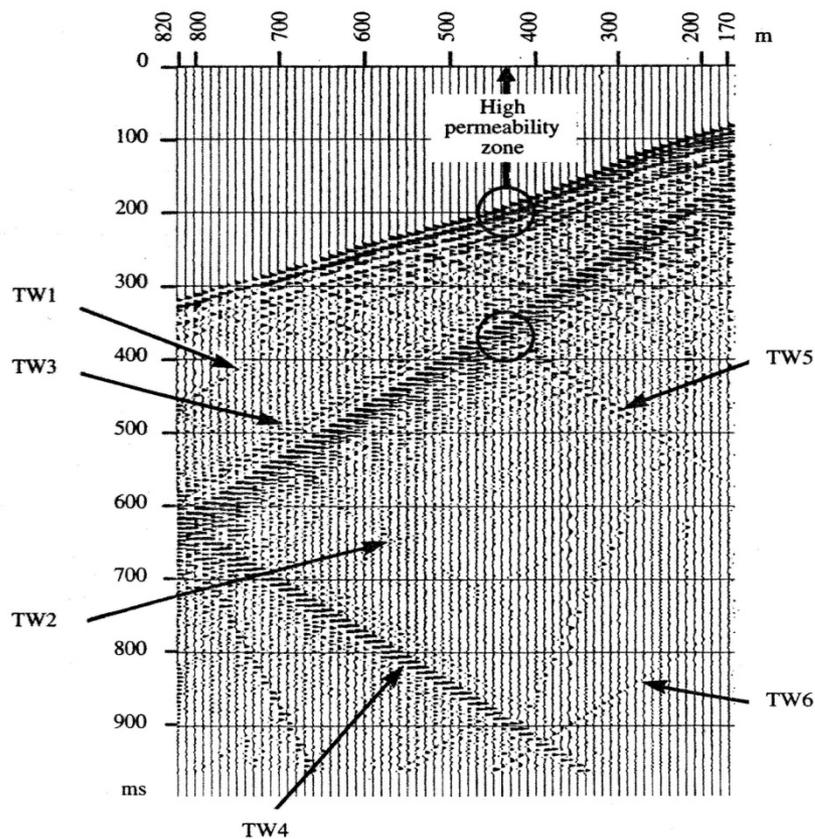
## مشخص کردن لایه با تراوایی بالا و ناحیه شکافدار

- امواج لوله ای علاوه بر تولید توسط موارد گفته شده می توانند توسط امواج فشاری گذرنده از یک لایه با تراوایی بالا نیز تولید شده (شکستگی ها هم یک بخش با تراوایی بالا محسوب می شوند) و به سمت بالا و پایین چاه حرکت کنند.



- همانطور که گفته شد امواج لوله ای در امتداد چاه حرکت کرده و در برخورد با نقطه ای که آمپیدانس صوتی تغییر کند امواج لوله ای ثانویه را ایجاد می کنند.

- شکل زیر یک نمونه ی خوبی از امواج لوله ای می باشد.



Tube waves (TW1 to TW6).  
(Courtesy of Gaz de France-IFP)

▶ در این شکل احتمال می رود که در عمقی حدود 440 متری يك لایه با تراوایی بالا وجود داشته باشد.

▶ در توجیه گفته ی بالا می توان گفت که:

1. امواج فشاری در عمقی حدود 440 متر يك سری امواج لوله ای تولید کرده که به سمت پایین در حرکت است به نام  $TW_1$ .

2. امواج  $TW_3$  امواج لوله ای حاصل از امواج سطحی می باشند زیرا از اعماق کم شروع شده و به سمت اعماق زیاد میروند،

اما این امواج در عمق در حدود 440 متری امواج لوله ای ثانویه به نام  $TW_5$  را به علت تغییر آمپیدانس بازتابانده به سمت

بالا.

▶ امواج  $TW_4$  نیز امواج بازتابانده است و  $TW_2$  و  $TW_6$  نیز امواج لوله ای پایین رونده هستند.

• در ادامه به بررسی يك Case stuy در مورد تعیین شیب لایه ها با استفاده از VSP در منطقه ي

AUZANCE مي پردازيم.

• در این مطالعه بعد از برداشت داده ها ، پردازش هاي اوليه زیر را روی آنها انجام داده ایم.

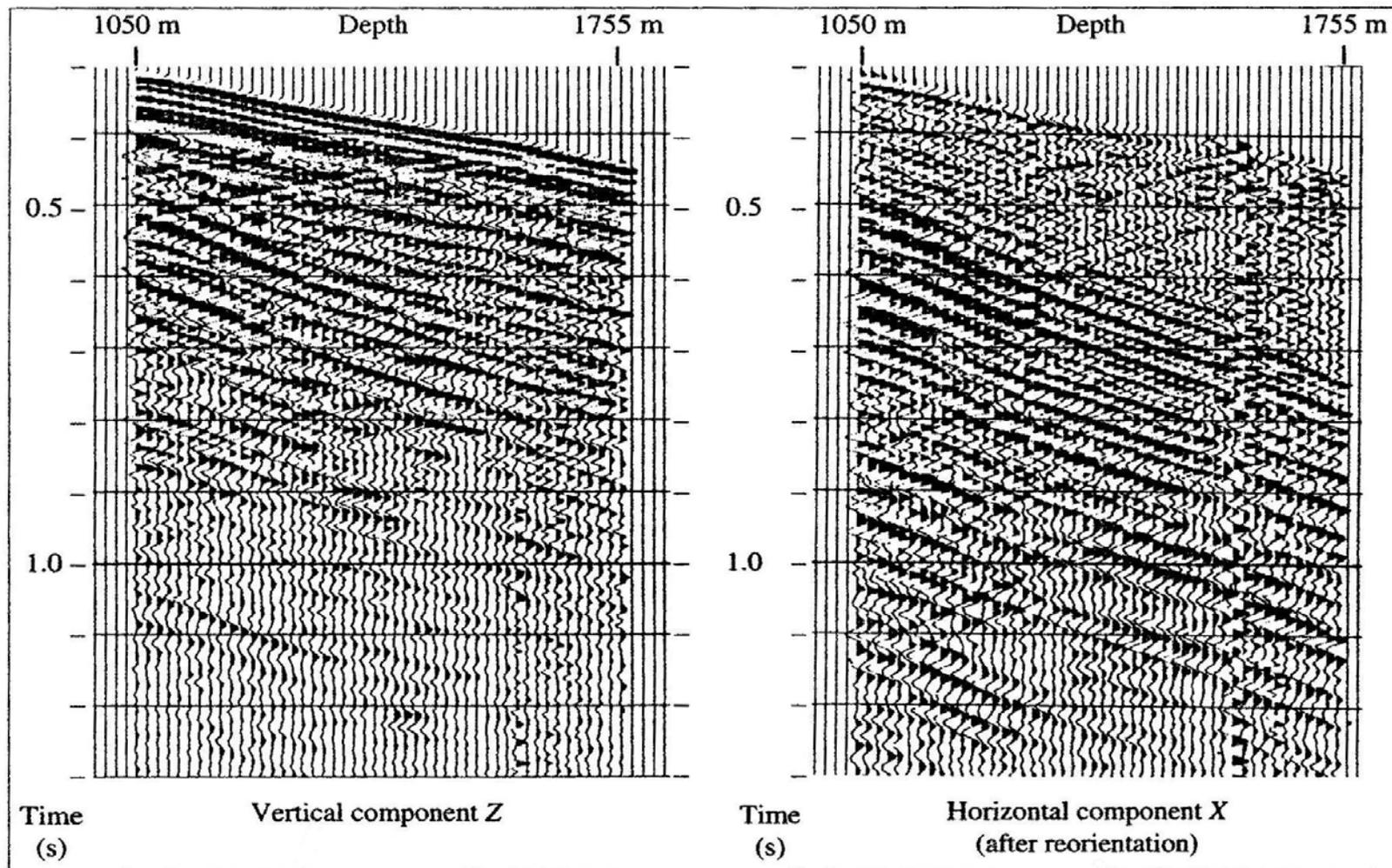
1. اصلاحات مربوط به استفاده از يك vertical vibrator با sampling rate برابر 2 ميلي ثانيه.

2. Stack کردن سیگنال هاي خوانده شده.

3. اصلاحات مربوط به جهت هاي هر ژئوفون.

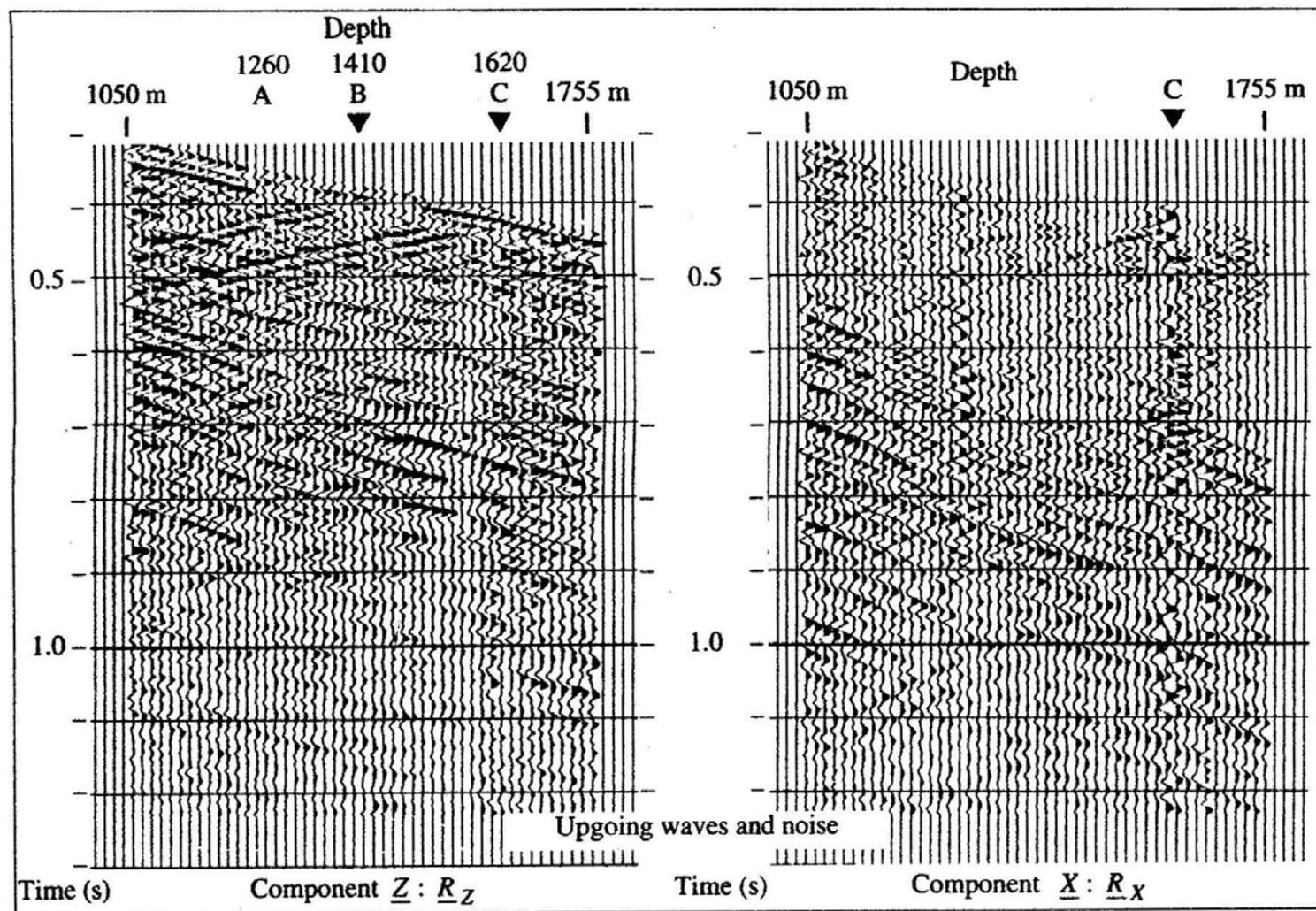
4. Despike کردن داده هاي بدست آمده.

• در شکل زیر می توان لرزه نگاشت مربوط به امواج برشی و فشاری را مشاهده کرد.



Horizontal and vertical components of VSP (well AZ 08).

- در این مطالعه الگوریتمی که برای جداسازی امواج به کار رفته ، الگوریتمی ابتکاری است که توسط **Mari & Gavin** در سال 1990 پیشنهاد شده و ترکیبی از فیلتر سرعت و فیلتر پلاریزان می باشد.
- نهایتاً با استفاده از داده های **first arrival downgoing** مقدار سرعت ها بدست آمده و بر اساس الگوهای متقاطع مشخص شد که 3 بازتاب کننده داریم که در اسلاید بعد آن را مشاهده می کنید.



Residual VSP sections.

▶ شکل بالا سه بازتاب کننده A,B,C که به ترتیب در اعماق 1753 ، 1410 و 1260 است مشخص شده است.

▶ حال برای بدست آوردن شیب لایه ها از **cross plot** داده های عمق بر حسب **transmit time** استفاده می کنیم ( **cross plot** مورد استفاده ابتکاری است که در سال 1991 توسط **Mari Gavin** , پیشنهاد شده است).

▶ به عنوان نمونه در اسلاید بعد این **cross plot** را برای بازتاب کننده ی **C** مشاهده می کنید.

▶ بر اساس این **cross plot** شیب بازتاب کننده بین 20 تا 25 درجه بدست می آید.

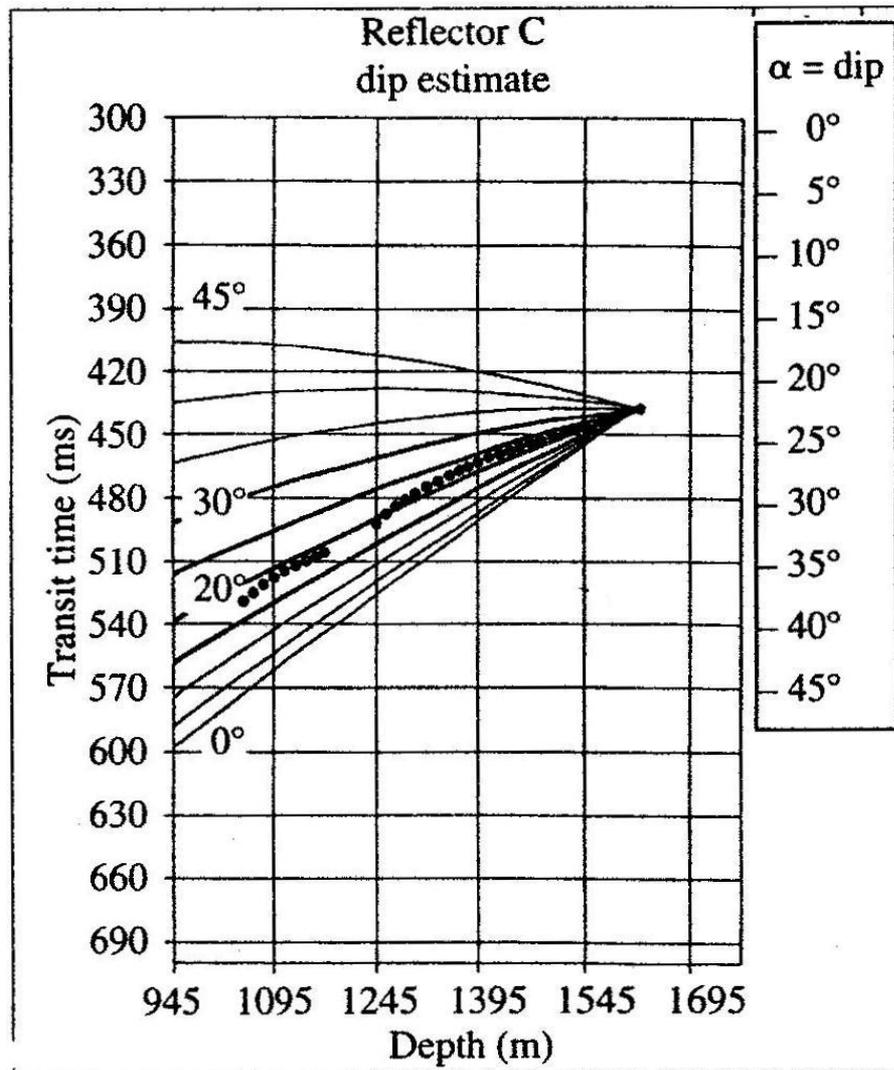


Chart used to estimate dip of reflector C.

- در جدول زیر می توان داده های بدست آمده برای هر سه سطح بازتاب کننده را مشاهده می کنید.

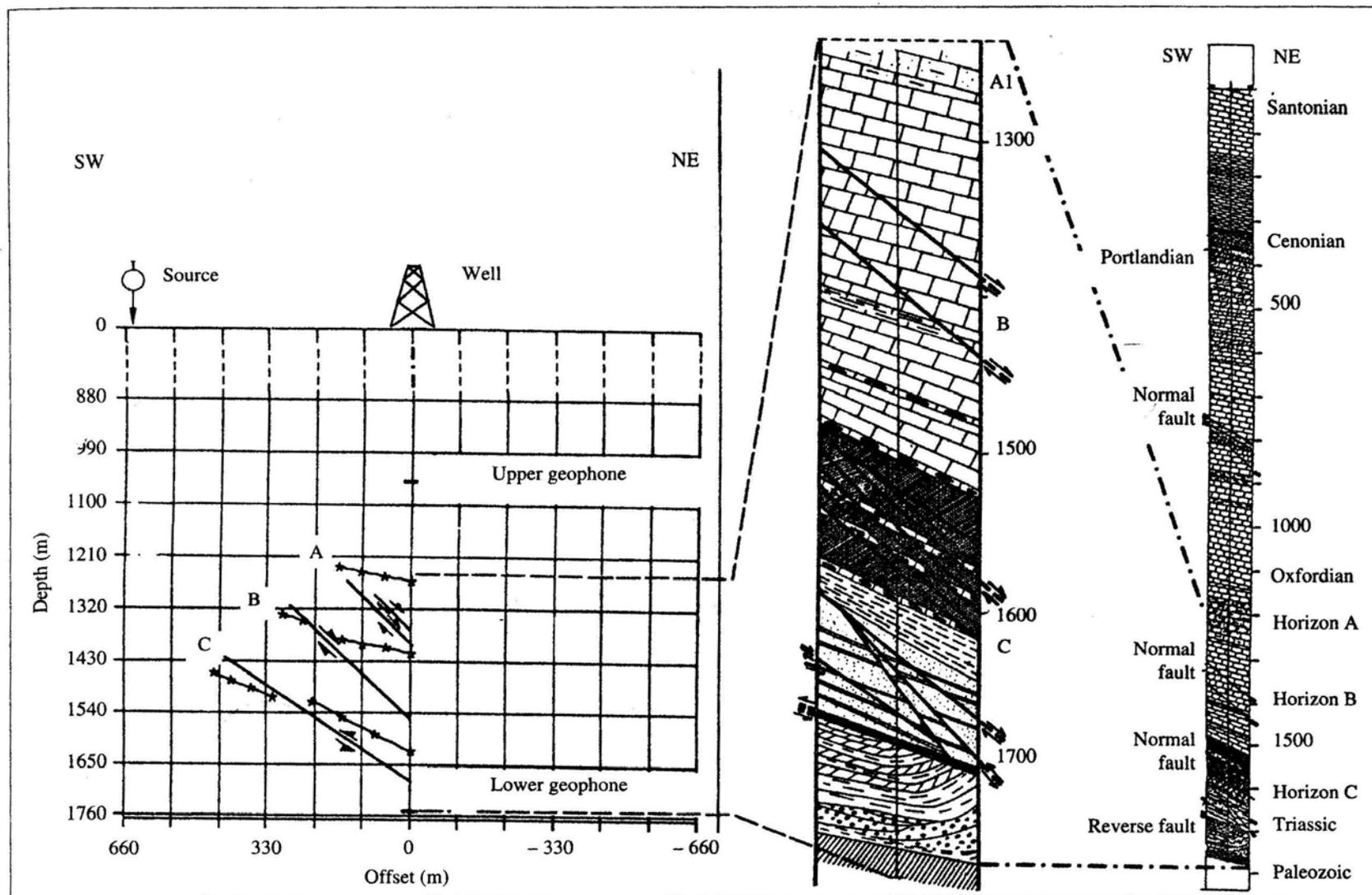
| Marker | Depth(m) | Velocity(m/s) | Seismic dip(degrees) |
|--------|----------|---------------|----------------------|
| A      | 1260     | 3750          | 10                   |
| B      | 1410     | 3800          | 10 To 15             |
| C      | 1620     | 4000          | 20 To 25             |

- براي نشان دادن صحت اين روش نتايج را با نتايج حاصل از نمودار **dipmeter** مقايسه مي كنيم و به اين نتيجه مي رسيم كه دقت كار **VSP** در حدود 5 درجه اختلاف با نتايج نمودار شيب سنج دارد.
- داده هاي شيب سنج برابر است با:

A  $\longrightarrow$  10 – 20

B  $\longrightarrow$  14 – 18

C  $\longrightarrow$  20 - 30



Geological model of the Auzance structure based on VSP survey and dipmeter logging. (Courtesy of Gaz de France)

▶ ابزار مورد نیاز در VSP عبارتند از:

1. حفره چاه
2. منبع انرژی
3. ژئوفون درون چاهی
4. سیستم جمع آوری اطلاعات

# Borehole

▶ فاکتورهاي اثر گذار در مورد چاه عبارتند از:

(a) Hole deviation

▶ برداشت در چاه قائم اقتصادي تر و تفسير آن راحت تر مي باشد.

▶ در چاه کج ، داراي يك عدم قطعيت در مورد محل ژئوفون ها مي باشيم.

▶ چاه کج داراي اين حسن مي باشد که در صورتي که از يك سکوي دريائي چندين چاه کج حفر کرده باشيم

مي توان با داده هاي بدست آمده يك مدل بسيار عالي از لايه ها و مخزن بسازيم.



(b) لوله ي جداري و سيمان کاري:

- انجام عمليات VSP در يك چاه داراي لوله جداري ترجيح داده مي شود ، چون مشكلاتي نظير گير کردن ابزار ، وجود انحنای ناخواسته در ديواره و ... وجود ندارد.
- در جايي که لوله جداري وجود دارد بايد پشت آن حتما سيمان شده باشد تا اينکه يك محيط که توانايي انتقال انرژی صوتي را دارد ايجاد شود.

• در کل ژئوفون ها ممکن است در 4 محیط مختلف قرار گیرند که عبارت است از:

1. يك لوله جداري که به تنهائي سيمان شده است

2. بدون لوله جداري (open hole)

3. يك لوله جداري بدون سيمان شدگي ولي قديمي به گونه اي که گل و مواد همراه گل در پشت لوله جداري به شکل جامد درآیند.

4. يك لوله جداري جديد که هنوز سيمان نشده است.

(c) شعاع چاه:

- در يك چاه **uncased**، ناهمواري هاي ديواره چاه مي تواند روي چسبانده شدن ژئوفون به ديواره مشكل ايجاد كند به خصوص در مناطقي كه **washout** شده باشد، بر همين اساس بايد قبل از انتخاب محل قرار گيري ژئوفون ها نمودار **caliper** گرفته شود و بر اين اساس محل ژئوفون ها مشخص شود.

- **Blair** در سال 1982 نشان داد که به شرطی که طول موج امواج بیش از 10 برابر قطر چاه باشد می توان ژئوفون ها را در هر سمت از دیواره چاه قرار داد و در صورتی که طول موج کوچکتر از 10 برابر قطر چاه باشد باید از دو ژئوفون در دو سمت مقابل استفاده کرد ، به این آرایش **waveshadow** می گویند.

d. موانع موجود در چاه:

▶ در چاه هاي casing شده ممکن است موانعي مانند packer و يا هر وسيله اي ديگري در در چاه وجود داشته باشد که در مسیر ژئوفون ها ايجاد ممانعت کند براي همين ما قبل از انجام عمليات VSP بايد به وسيله ي يك tools ارزان که از نظر قطر با قطر ژئوفون ها یکسان باشد را در چاه راند و مشخص کرد که مانعي در سر راه ژئوفون ها وجود ندارد و سپس شروع به عمليات VSP کنیم.

▶ ترجیح بر این است که ما ژئوفون ها را در عمق هايي قرار دهيم که بيشتريين اطلاعات پتروفيزيکي را از آن نقطه داريم ، به خصوص نمودار CBL که مشخص مي کند پشت لوله جداري سيما ن است يا نه!

# VSP energy source

- منبع باید يك جبهه موج استوار و قابل تکرار ایجاد کند.
- مقدار انرژی منبع باید با دقت مشخص شده و يك مقدار optimum انتخاب شود ، زیرا ”بیشترین انرژی منبع ، بهترین نتایج را نمی دهد“.
- ابزاری که از آنها به عنوان منبع ایجاد می شود عبارتند از:
- 1- دینامیت 2- mechanical impulse source 3- vibrator 4- air guns

# Seismic source

می توان منبع انرژی را به دو گروه خشکی و دریایی تقسیم کرد. ▶

منبع انرژی دریایی اصلی عبارتند از: ▶

1. Air gun
2. Water gun

منبع انرژی خشکی اصلی عبارتند از: ▶

1. Vertical vibrator or horizontal vibrator
2. Weight – droppers

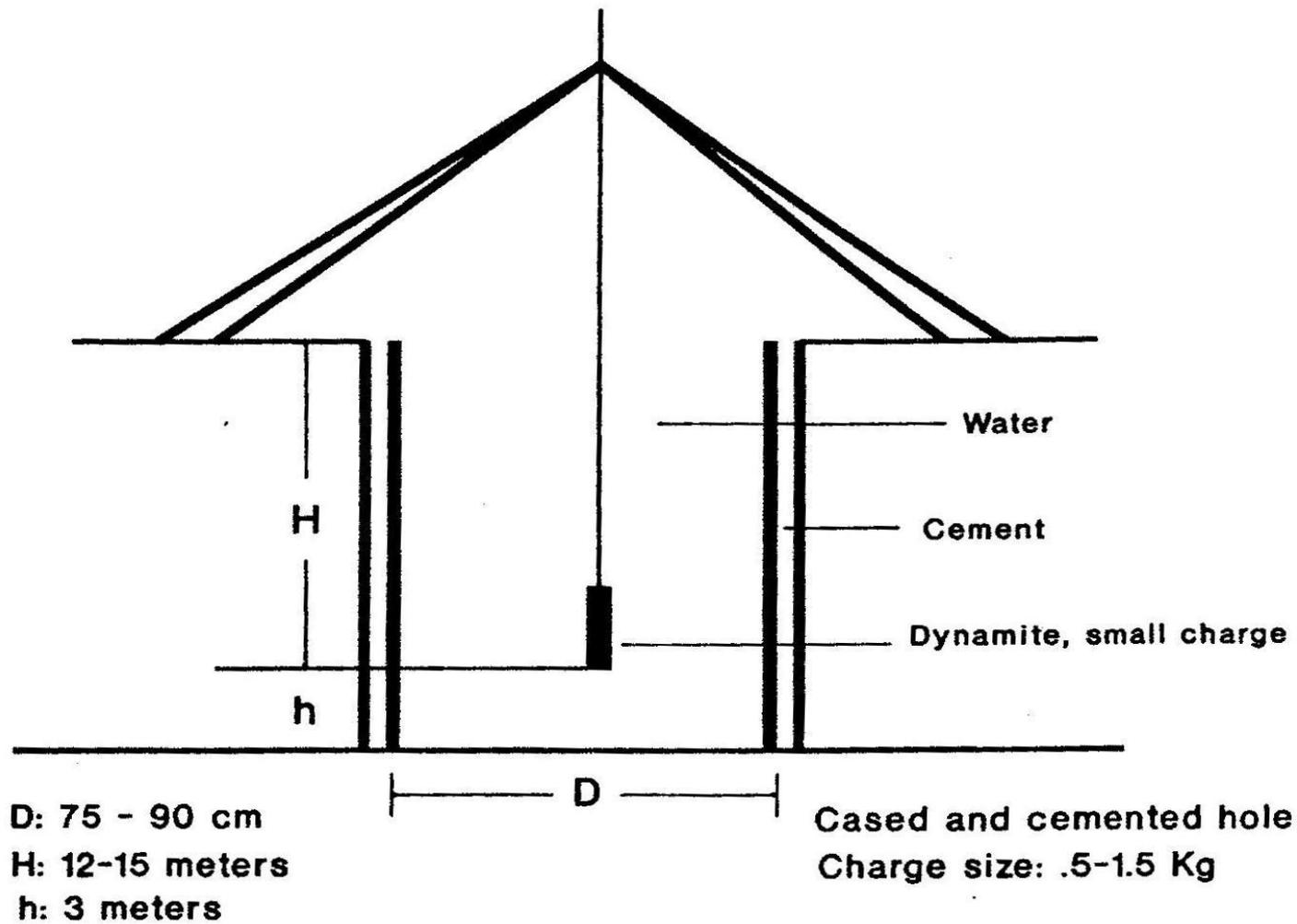
3. با حفريك گودال آب از **air gun** استفاده كنيم.

## دینامیت

- ▶ دینامیت دفن شده مقدار ضریب کاهش دامنه ای برابر 2 دارد اما دینامیت معلق در هوا ضریب کاهشی برابر 30 دارد.
- ▶ استفاده از دینامیت برای این که بخواهیم چند شات داشته باشیم که جبهه ی یکسانی داشته باشد مشکل است.
- ▶ در استفاده از دینامیت قطر و عمق گمانه انفجار باید به دقت مشخص شود و این عمق باید زیر لایه هوازده باشد ، و نیز دیواره گمانه باید casing گذاری شده باشد تا سازند به داخل نریزد.
- ▶ می توان داخل گمانه محل انفجار را پر از آب کرد تا ضریب کاهش دامنه را کم کنیم.

**Shot hole design for repeatable wavelet (modified from Hardage, 1983)**

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# Mechanical impulse source

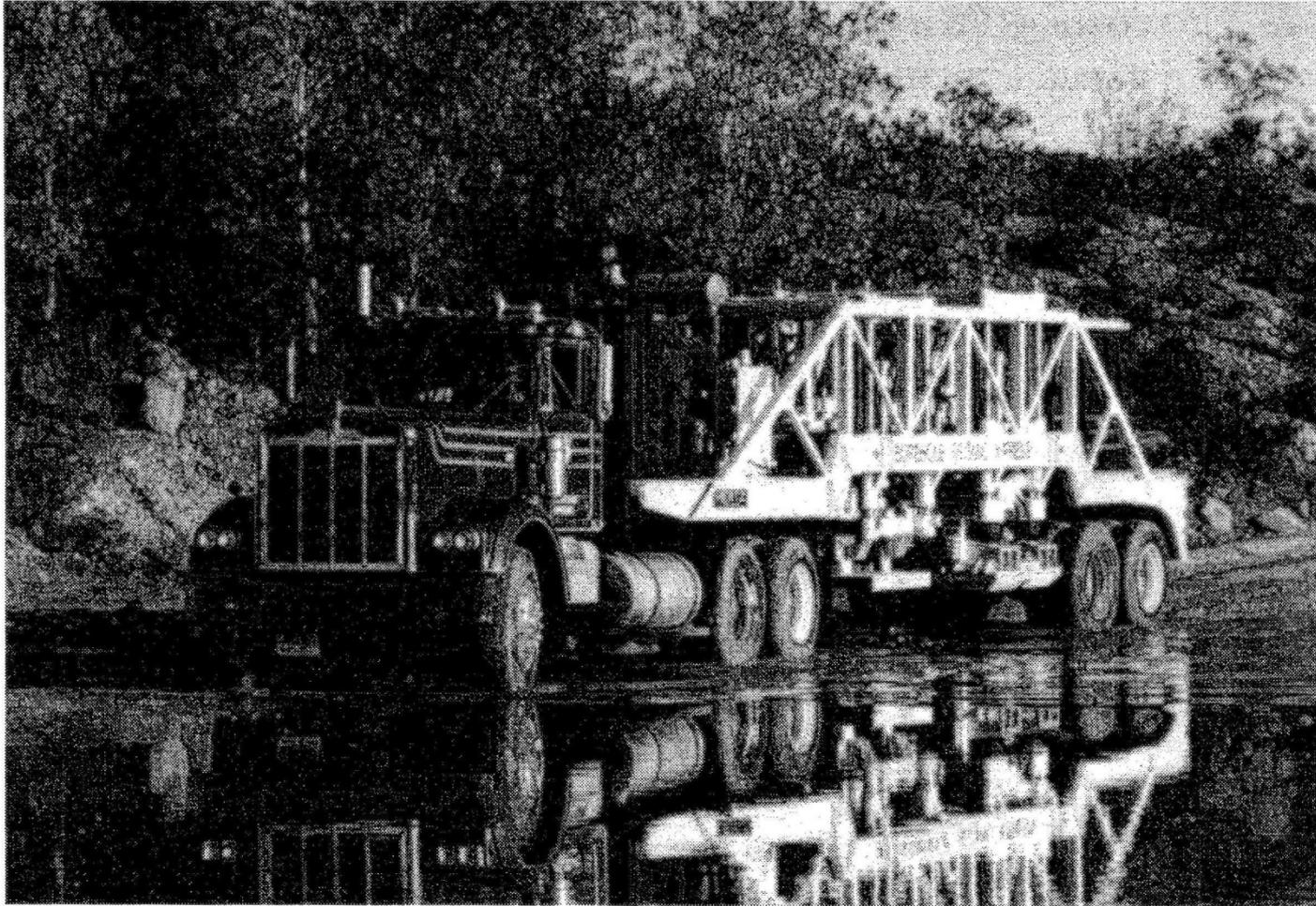
- استفاده از این منبع برای عملیات VSP بسیار مناسب است ، اما باید قبل از انجام کار محل عملیات برای امکان استفاده از این روش تست شود.



Mixed *P*- and *S*-wave impulse source: Soursile (IFP).

# Vibrators

- این وسیله چون قابل حمل است این امکان را می دهد که در نقاط مختلف شات داشته باشیم.
- **Vibrator** بهترین انتخاب برای عملیات **VSP** می باشد چون می تواند يك جبهه موج مناسب و تکرار پذیر را ایجاد کند.



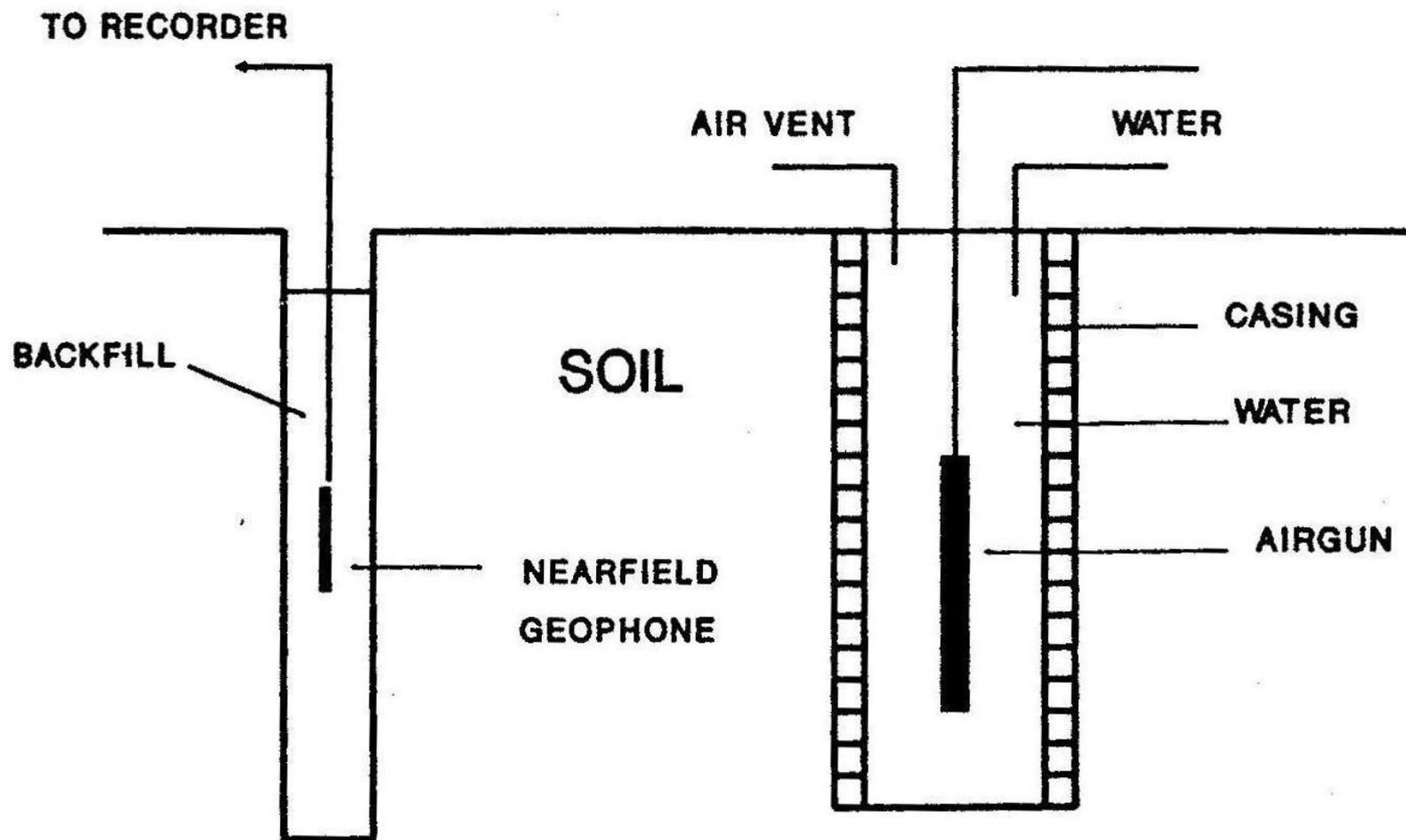
Mixed *P*- and *S*-wave vibrator source specially designed for well seismic acquisition (Mertz).

# Air gun

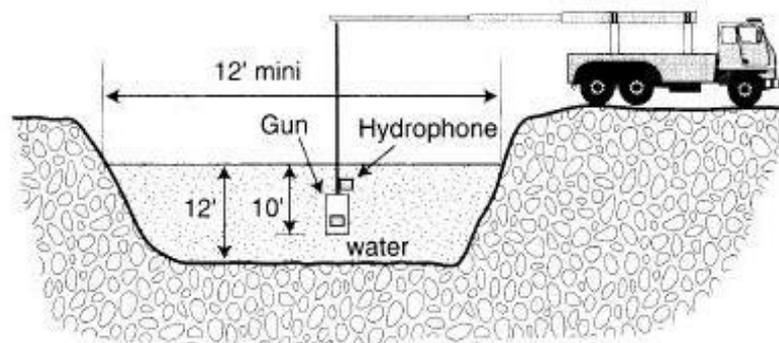
- عملیات با air gun خیلی راحت است.
- Air gun وسیله ای ایمن است.
- Air gun را می توان مطابق شکل زیر در خشکی هم استفاده کرد

Using a marine air gun as an onshore VSP energy source  
(modified from Hardage, 1983)

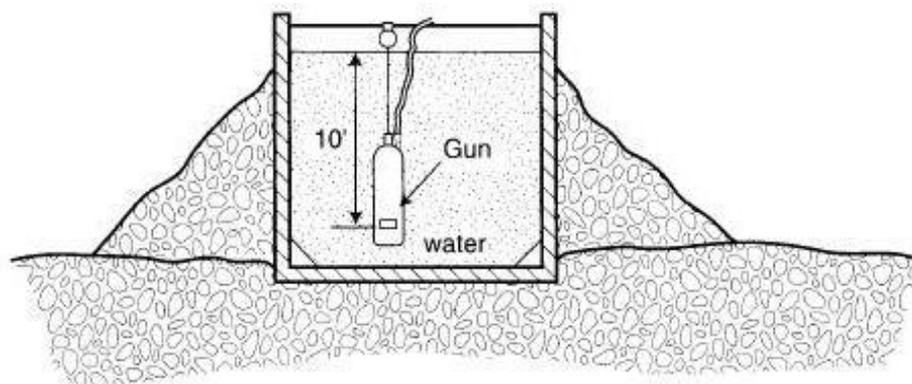
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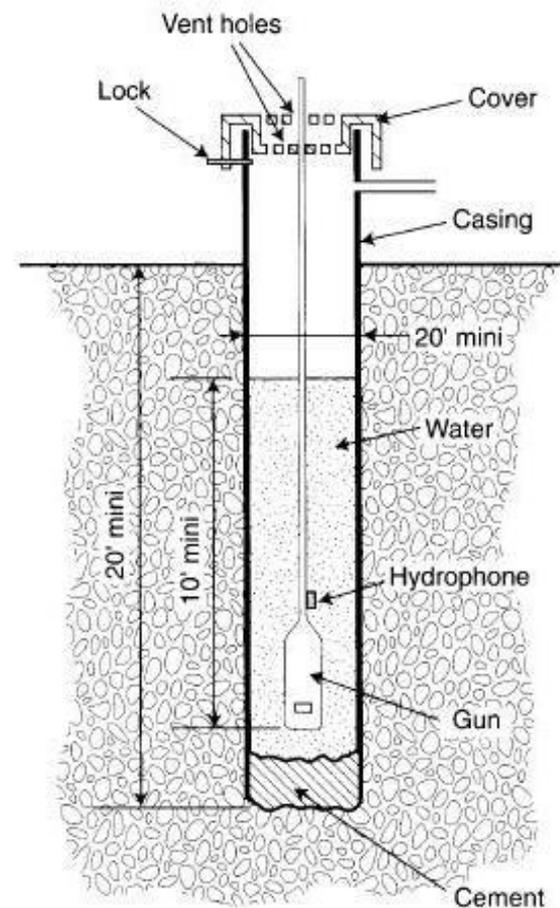
Typical setup for a land pit



Typical setup with a portable steel tank



Typical setup for a wet soft ground



Possible implementations of marine sources in onshore well seismic acquisition (Schlumberger).



# Energy in put

- ▶ مقدار انرژی velocity survey و VSP survey کاملاً با هم متفاوت است حتی می توان گفت که مقابل هم می باشند.
- ▶ در velocity survey فقط می خواهیم اولین موج رسیده را مورد بررسی قرار دهیم ولی در VSP علاوه بر اولین موج رسیده به امواج بالارونده و پایین رونده را هم نیاز داریم.
- ▶ بنابراین در عملیات VSP نیاز به انرژی بیشتری داریم زیرا موج باید بعد از بازتاب در بازتاب کننده ای در عمق ، در ژئوفونی در فاصله ی بسیار بالاتر از آن ثبت شود برای همین انرژی بیشتری نیاز داریم.

# cable

- در عملیات VSP کابل کلاس 7 به کار می رود که توسط Well – logger ها به کار می رود.

# The downhole geophone

- در شکل زیر می توان تفاوت ظاهری ژئوفون های سطحی را با درون چاهی مشاهده کرد.
- ژئوفون های درون چاهی قابلیت تحمل دما و فشار بالا را دارند و توسط يك **arm** به دیواره می چسبند.

**A typical land geophone and a VSP geophone (modified from Hardage, 1983)**

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**Spike-planted land geophone**



**Downhole VSP geophone**

---

### **Parameters**

**Length: 10 cm ( 4 Inches )**  
**Diameter: 3 cm ( one Inch )**  
**Weight: 200 gm (.45 Pound )**

**Length: 3 m ( 9.8 Feet )**  
**Diameter: 10 cm ( 4 Inches )**  
**Weight: 100 Kg ( 225 pounds )**

▶ گیرنده باید دارای دو خاصیت باشد:

1. حداقل اثر را از امواج لوله ای بگیرد.

2. به بهترین وجه به سازند بچسبد.

▶ برای رسیدن به هدف اول باید ابزار حداقل سایز و قطر را داشته باشد.

▶ برای رسیدن به هدف دوم باید حداقل وزن و بیشترین سطح تماس را با چاه داشته باشد.

• ژئوفون ها درون چاهي امروزه داراي سه بخش هستند.

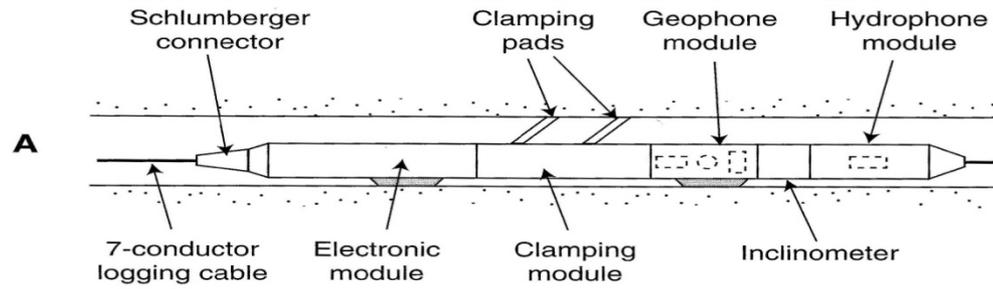
1. ژئوفون

2. هیدروفون

3. Inclinator

• ژئوفون ها نسل جديد داراي يك گيرنده گاماري نيز مي باشند كه نتايج بدست آمده از آن را با نمودار گاماي

بدست آمده از عمليات logging مقايسه کرده و براي تصحيح عمق VSP به کار برده مي شود.



**B**



CGG-IFP ARTEP SPH well-logging tool (IFP). Length: 2.36 m; diameter: 10 cm; weight: 94 kg; temperature and pressure limits: 180°C and 1200 bars; seismic equipment: 3-component geophone, hydrophone, inclinometer. **A.** Schematic. **B.** Picture.

## THE CSI<sup>®</sup> TOOL: A new design architecture

### A New Architecture

The CSI tool is a new-generation three-axis borehole seismic tool. It is designed for superior performance and combinability with itself, an array of sensors, and with other tools such as:

- Gamma Ray for accurate depth control
- Incliner tool for accurate spatial orientation
- Auxiliary measurement sonde for safety

### Features

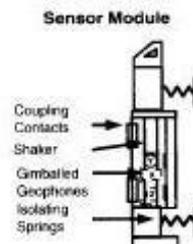
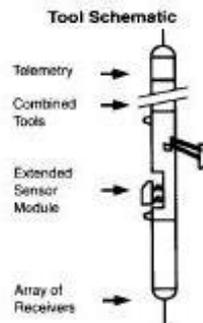
- Sensor module decoupled from sonde body
- Combinability
- Coupling quantified through shaker responses
- Powerful downhole electronics
- Gimbal-mounted geophones with locking system
- In-situ geophones and electronic calibration

### Design Objectives

- **Acoustic quality of the system**  
Cartridge, sonde, module, gimbal and sensors have been designed and tested to ensure a system response identical to that of a single geophone.
- **Acoustic quality optimized in the borehole**  
Sensor module decoupling, points of contact design and explicit measurement of the coupling quality through shaker activation, all contribute to enhance signal quality.
- **Signal processing quality**  
All electronic and mechanical parameters affecting signal reproduction are measured by in-situ tests.
- **Efficiency through combination**  
The new receiver architecture has brought combination capability without compromising signal quality.

Combinable Seismic Imager

\* Mark of Schlumberger



### General

|                   |          |           |
|-------------------|----------|-----------|
| Length (1 tool)   | 5340 mm  | 214 in.   |
| Weight (1 tool)   | 123 kg   | 271 lbs   |
| Diameter*         | 117 mm   | 4-5/8 in. |
| Maximum opening** | 483 mm   | 19 in.    |
| Anchoring force:  |          |           |
| 5 in.             | 280 da N | 630 lbs   |
| 10 in.            | 320 da N | 719 lbs   |
| 19 in.            | 500 da N | 1124 lbs  |

Gimbal tilt range  
\* 4 in. without stand-off  
\*\* 22 in. with pad extension  
0 to 90°

### Environmental ratings

|                    |           |            |
|--------------------|-----------|------------|
| Pressure rating    | 1400 bars | 20,000 psi |
| Temperature rating | 175°C     | 350°F      |

### Measurements

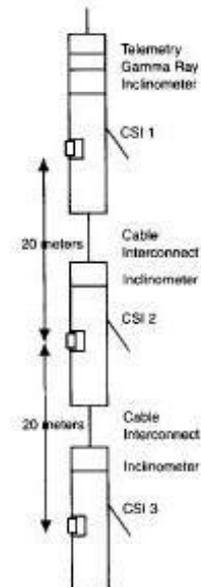
|   |  |
|---|--|
| Sampling rate   | 2 KHz  |
| Selectable output sampling rates:                             | 0.5, 1, 2 and 4 ms                               |
| Analog-to-digital conversion with autorange:                  | 16 bits  |
| Preamplifier gain:  | 30 dB  |
| Amplifier gain:   | 6-72 dB in 6 dB steps;<br>selectable per channel |
| Analog filter:  |  |
| Low-cut frequency (-3 dB)                                     | 2.5 Hz   |
| Low-cut slope   | +12 dB/octave                                    |
| High-cut frequency (-3 dB)                                    | 300 Hz   |
| High-cut slope  | -36 dB/octave                                    |
| Digital filter rejection at Nyquist                           | >70 dB   |
| Synchronization   | * 45 μs after calibration                        |
| Tool transfer function flat below geophone spurious frequency |  |
| Gimbal deviation  | ±1° after calibration                            |
| Gimbal relative bearing                                       | ±1° after calibration                            |
| Caliper   | ±0.1° after calibration                          |
| In-situ calibration tests                                     |  |
| Multiplexer for logging, seismic and auxiliary channels       |  |
| Sonde control and safety in absence of telemetry              |  |

Combinable Seismic imager

\* Mark of Schlumberger

## Combinations

### Example of open hole combination



Maximum recommended combinations:  
3 tools in open hole  
4 tools in cased hole

Characteristics of the CSI tool (Schlumberger).

# Downhole Geophone Array Specifications

## TOOL CONFIGURATION

- (a.) Master Unit comprising:  
 Tension Compression Unit      **TCU**  
 Seismic Telemetry Unit        **STU**  
 Hydraulic Power Unit            **HPU**  
 Hydraulic Clamping Unit        **HCU**
- (b.) Up to 12 individual receivers or  
 Hydraulic Seismic Unit         **HSU**
- (c.) Weight Unit                    **WU**  
 (incorporates motion sensor)

### TENSION COMPRESSION UNIT (TCU)

|                 |                         |
|-----------------|-------------------------|
| Accuracy        | +/- 10 daN              |
|                 | +/- 22 lbf              |
| Tension max     | +/- 5000 daN            |
|                 | +/- 11,250 lbf          |
| Temperature max | 180°C    358°F          |
| Pressure max    | 1,200 bar    17,600 psi |

### SEISMIC TELEMETRY UNIT (STU)

|                       |                         |
|-----------------------|-------------------------|
| Temperature max       | 150°C    300°F          |
| Pressure max          | 1,200 bar    17,600 psi |
| Uplink telemetry rate | 512 kbaud               |

### HYDRAULIC POWER/CLAMPING UNIT (HPU/HCU)

|                            |  |
|----------------------------|--|
| Temperature max            | 180°C    358°F                           |
| Pressure max               | 1,200 bar    17,600 psi                  |
| Pump motor voltage         | 220 V    (270V at surface on wireline)   |
| Pump motor current (max)   | 700 mA    (torque limiter acts at 800mA) |
| Over pressure relief valve | 155 bar    2,280 psi                     |
|                            | +/- 5 bar    +/- 70 psi                  |
| Tension safety valve       | 850 daN    1,900 lbf                     |
| Hydraulic oil capacity     | c. 10 litres    c.2.2 gals               |
| Hydraulic oil type         | Univis J13                               |

### HYDRAULIC SEISMIC UNIT (HSU)

|                 |   |
|-----------------|---|
| Temperature max | 150°C    300°F                                    |
| Pressure max    | 1,200 bar    17,600 psi                           |
| Locking force   | 140 daN max.<br>300 lbf max                       |
| Weak links      | Graduated decreasing values with depth down sting |

|                            |   |
|----------------------------|---|
| Hydraulic oil capacity     | 1 litre    0.22 gals                        |
| Digitisers                 | 24 bit delta-sigma                          |
| Sample rate & alias filter | 2.1, 0.5, 0.25 ms,<br>187.5,375,750,1500 Hz |
| Dynamic range              | > 110 dB                                    |
| Distortion                 | < 0.1 %                                     |
| DC offset                  | < 0.1 µV<br>(self calibrating)              |

|                       |   |
|-----------------------|---|
| Geophone pre-amp gain | 54 dB   |
| Receivers             | - 3 orthogonal SMC1850 10 Hz gimbaled geophones.<br>or 3 orthogonal SMC1850 10 Hz fixed geophones<br>or 3 orthogonal SMC1850 30 Hz fixed geophones<br>- 1 down-hole hydrophone, sensitivity -88 dB re 1V / µbar |



### SURFACE CONTROL PANEL (SCP)

|                           |  |
|---------------------------|--|
| Operating temperature max | 40 deg C   |
| Mains voltage             | 230 V AC   |
| Current max               | 5 A  |
| Size                      | 18" 6U chassis   |
| Features                  | Telemetry receiver with dedicated FFT processor card and cable equalisation<br>Graphical display of motor current vs. time.<br>Software control of Parameters and settings |

### ACQUISITION SURFACE PANEL (ASP)

|                           |   |
|---------------------------|---|
| Operating temperature max | 40 deg °C   |
| Mains Voltage             | 90-260V AC  |
| Current max               | 5 A   |
| Size                      | 19" 6U chassis  |
| Features                  | 48 seismic + 4 auxiliary digital channels via data link from SCP<br>8 analogue channels (24 bit delta-sigma as in SST500 HSUs)<br>Source controller interlaces Control and data link to PC recording system |

### WEIGHT AND DIMENSIONS

|                                   | 12 level<br>10m int. | 6 level<br>10m int. | 6 level<br>20m int. | 8 level<br>15m int. |
|-----------------------------------|----------------------|---------------------|---------------------|---------------------|
| Complete Tool String              |                      |                     |                     |                     |
| Tool string length overall        | 132.7m (435.4ft)     | 72.7m (238.4ft)     | 132.7m (435.4ft)    | 132.7m (435.4ft)    |
| Length below HCU depth zero point | 128.2m (420.6ft)     | 68.2m (223.7ft)     | 128.2m (420.6ft)    | 128.2m (420.6ft)    |
| Tool string weight in air         | 630kg (1390lbs)      | 450kg (993lbs)      | 542kg (1196lbs)     | 588kg (1298lbs)     |

### LOCKING RANGES

|                | Maximum tool o/d | Minimum Locking dia | Max Locking dia |
|----------------|------------------|---------------------|-----------------|
| 7" arm kit     | 92mm (3 5/8")    | 102mm (4")          | 183mm (7.2")    |
| 9 5/8" arm kit | 103mm (4")       | 108.6mm (4.27")     | 231 mm (9.1")   |
| 13" arm kit    | 155mm (6.1")     | 165mm (6.5")        | 330mm (13.0")   |
| 16" arm kit    | 165mm (6.1")     | T.B.A               | 408mm (16.1")   |

### INTER-RECEIVER INTERVALS

|                |          |          |          |
|----------------|----------|----------|----------|
| Selectable at: | 10 metre | 15 metre | 20 metre |
|----------------|----------|----------|----------|

All specifications subject to change without notice

1998 CGG

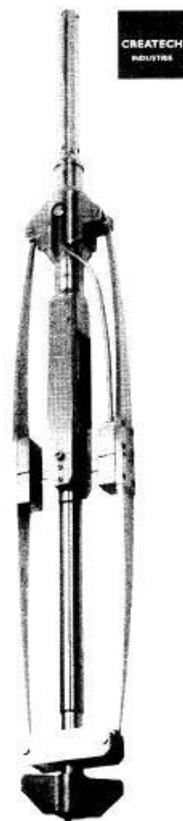
All specifications subject to change without notice

1998 CGG

Characteristics of the SST-500 tool (CGG).

• در زیر ابزار جدید schlumberger می باشد که نام آن MAST است و ویژگی های

آن را در اسلاید بعد مشاهده می کنید.



CREATECH  
INDUSTRIES

**TRIAxIAL GEOPHONE  
SONDE FOR SEISMIC  
MONITORING**

SAS 2000 series for wells from 4" ID and above

**SPECIFICATIONS**

|                                |                              |
|--------------------------------|------------------------------|
| Pressure rating                | 1000 bar                     |
| Operating temperature          | -55 to +150°C                |
| Shocks                         | 100 g, 11 ms                 |
| Length of sonde                | 1000 mm                      |
| Closed diameter                | from 4" to above             |
| Opened diameter                | 2" larger                    |
| Nominal anchoring force        | 800 N                        |
| Weight                         | 12 kg                        |
| Geophone type                  | GEOSPACE 28 Hz               |
| Geophone sensitivity           | 23 V/m/s                     |
| Frequency response             | 20 Hz to 800 Hz              |
| <b>Digital version</b>         |                              |
| Dynamic range                  | 19 bits                      |
| Calibration circuit            |                              |
| Digital transmission           |                              |
| Input noise level              | 0.3 $\mu$ V (10 Hz to 5 kHz) |
| Runs on mono cable             |                              |
| <b>Analog version</b>          |                              |
| Amplifier with a variable gain | 40 dB to 100 dB              |
| Calibration circuit            |                              |
| Differential transmission      |                              |
| Input noise level              | 0.5 $\mu$ V (10 Hz to 5 kHz) |
| Runs on hepta cable            |                              |

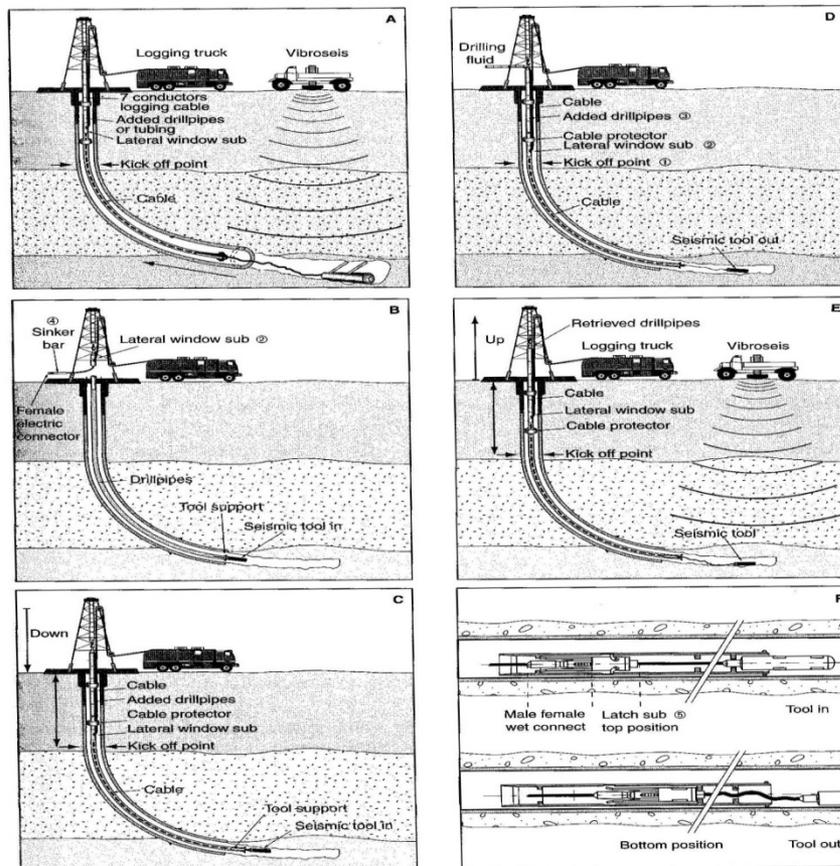
Example of monitoring tool (Createch).

|                               |                             |
|-------------------------------|-----------------------------|
| <b>Clamping type</b>          | mechanical arm              |
| <b>Clamping force</b>         | 165 lbs                     |
| <b>Tool Weight</b>            | 10 kg/22 lbs (shuttle)      |
| <b>Tool Length</b>            | 5 ft (shuttle)              |
| <b>Tool Type</b>              | array                       |
| <b>Simultaneous levels</b>    | up to 8                     |
| <b>Spacing</b>                | variable                    |
| <b>Combinability</b>          | GR                          |
| <b>Sensor Type</b>            | GAC* (3-200 Hz)             |
| <b>Diameter</b>               | 48 mm / 1 7/8"              |
| <b>Min Operating Diameter</b> | 59 mm / 2 5/16"             |
| <b>Max Operating Diameter</b> | 270 mm / 10.6"              |
| <b>(using different arm)</b>  | 450 mm / 17.7"              |
| <b>Max Deviation</b>          | no limit                    |
| <b>Downhole AD conversion</b> | 16 bits                     |
| <b>Downhole Dynamic Range</b> | 152 dB                      |
| <b>Sample rate</b>            | 0.5, 1, 2, 4 ms             |
| <b>Time between shots</b>     | 15 s (4 s/1 ms/24 channels) |
| <b>Max Temperature</b>        | 140°C/285°F                 |
| <b>Max Pressure</b>           | 10000 psi                   |
| <b>Recording System</b>       | Standalone (PC)             |
| <b>Logging Cable</b>          | Mono/Heptacable             |

Technical characteristics of the MSAT system  
(*Modular Seismic Array Tool*) (Schlumberger).

# VSP در چاه کج

• در شکل زیر انواع برداشت VSP در چاه کج را مشاهده می کنید.



Description of the Horseis method (IFP patented) used to lower a sensor in a deviated or horizontal well. **A.** Setup during seismic recording. **B.** Lowering of the tool via the drillpipe. **C.** Connection of the tool with the cable. **D.** Expulsion of the tool out of its protecting sleeve. **E.** Clamping of the tool to the formation. **F.** Schematic of the connector and of the tool protecting sleeve [after Mari, Wittrisch et al., 1990].

# VSP field procedures

- قبل از انجام عملیات و بعد از آن باید کل سیستم را تست کنیم و مطمئن شویم که سیستم ثبت داده ها یکسری از سیگنال ها را به طور ناخواسته حذف نکند.

# SEISMIC WHILE DRILLING (SWD)

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- استفاده از **VSP** معمولی اطلاعات بسیاری را به ما می دهد اما برای انجام آن نیاز است حفاری متوقف شود ، رشته ی حفاری از چاه خارج شود ، ژئوفون های درون چاهی به داخل چاه رانده شود تا عملیات شروع شود و نهایتاً دوباره رشته حفاری به داخل چاه رانده شود تا عملیات حفاری شروع شود و این باعث افزایش زمان و صرف هزینه ی زیادی می شود.
- علاوه بر افزایش زمانی ، خطراتی هم مانند **Sticking** و یا **fish** شدن ابزار **VSP** هم وجود دارد که ممکن است بر مشکل بیفزاید.
- همچنین چون **VSP** در هر لحظه انجام نمی شود نمی توان محل دقیق مته را در هر زمان مشخص کرد.

# Seismic while drilling

- SWD را مي توان به دو گروه تقسيم کرد:
- Reverse ray path همانند drill bit seismic
- Normal ray path همانند VSP – WD

# SWD

▶ **Drill bit - SWD** عبارت است از استفاده از انرژی مته های **CONE – 3** به عنوان منبع

انرژی در حین حفاری برای یافتن **time – to – depth** و **look – ahead** information.

▶ در سال 2000 توسط شرکت schlumberger ابزار **vertical seismic profile**

**while drilling (VSP-WD)** ارائه شد که در این روش امواج در سطح توسط یک منبع تولید

می شود و توسط ژئوفون مخصوصی در بالای مته برداشت می شود، در این روش اطلاعات یا ذخیره شده یا

توسط ابزار **MWD** به سطح منتقل می شود (این عمل در هنگامی که پمپ ها خاموش است انجام می شود

تا **S/N** افزایش یابد).

- ▶ SWD باعث مي شود کارآيي و ايمني حفاري به مقدار زياد افزايش يابد.
- ▶ با SWD مي توان محل دقيق قرار گيري لوله ي جداري و يا محل **core** گيري را با دقت مشخص کرد.
- ▶ مي توان با SWD وضعیت سازندهاي پيش رو را مشخص کرد و وزن گل مناسب را تعيين کرد.
- ▶ با SWD مي توان محل دقيق مته را مشخص کرد.
- ▶ با SWD مي توان مشخص کرد که در ادامه و در مقابل مته چه سازندي را خواهيم داشت.
- ▶ با استفاده از SWD مي توان به درستي به سمت محلي که مي خواهيم به آن برسيم حرکت کنيم.

## تاریخچه SWD

- ▶ ایده SWD به سال 1930 برمی گردد ، زمانی که حفاری ضربه ای رایج بود.
- ▶ اولین تلاش برای استفاده از سیگنال های تولید توسط مته در سال 1968 توسط یکی از ژئوفیزستهای IFP بر می گردد.
- ▶ در گذشته نمی توانست از مته های PDC به عنوان منبع استفاده کرد ، زیرا میزان امواج صوتی آنها کم بود.
- ▶ استفاده از مته های roller – cone هم محدودیت هایی دارد مانند این که سازند باید hard to medium hard باشد ، دندانهای مته باید به اندازه ی کافی بلند باشد و ....

- در دهه ي 90 تلاش هاي بسياري براي پيشرفت اين روش انجام شد و نهايتا در سال 2000 شركت schlumberger ابزار خود را معرفي كرد كه مي تواند بالاي مته بسته شود و توسط يك منبع در سطح امواج را ايجاد كرد و توسط ابزار جديد ثبت كنيم و نهايتا توسط MWD اطلاعات ثبت شده به سطح منتقل مي شود.

- اخيرا ابزاري با نام swept impulse hydraulic به بازار آمده كه استفاده از مته هاي PDC را نيز ممكن کرده و محدوديت هاي استفاده از roller cone را هم رفع کرده است.

• عملیات SWD دارای دو مرحله است:

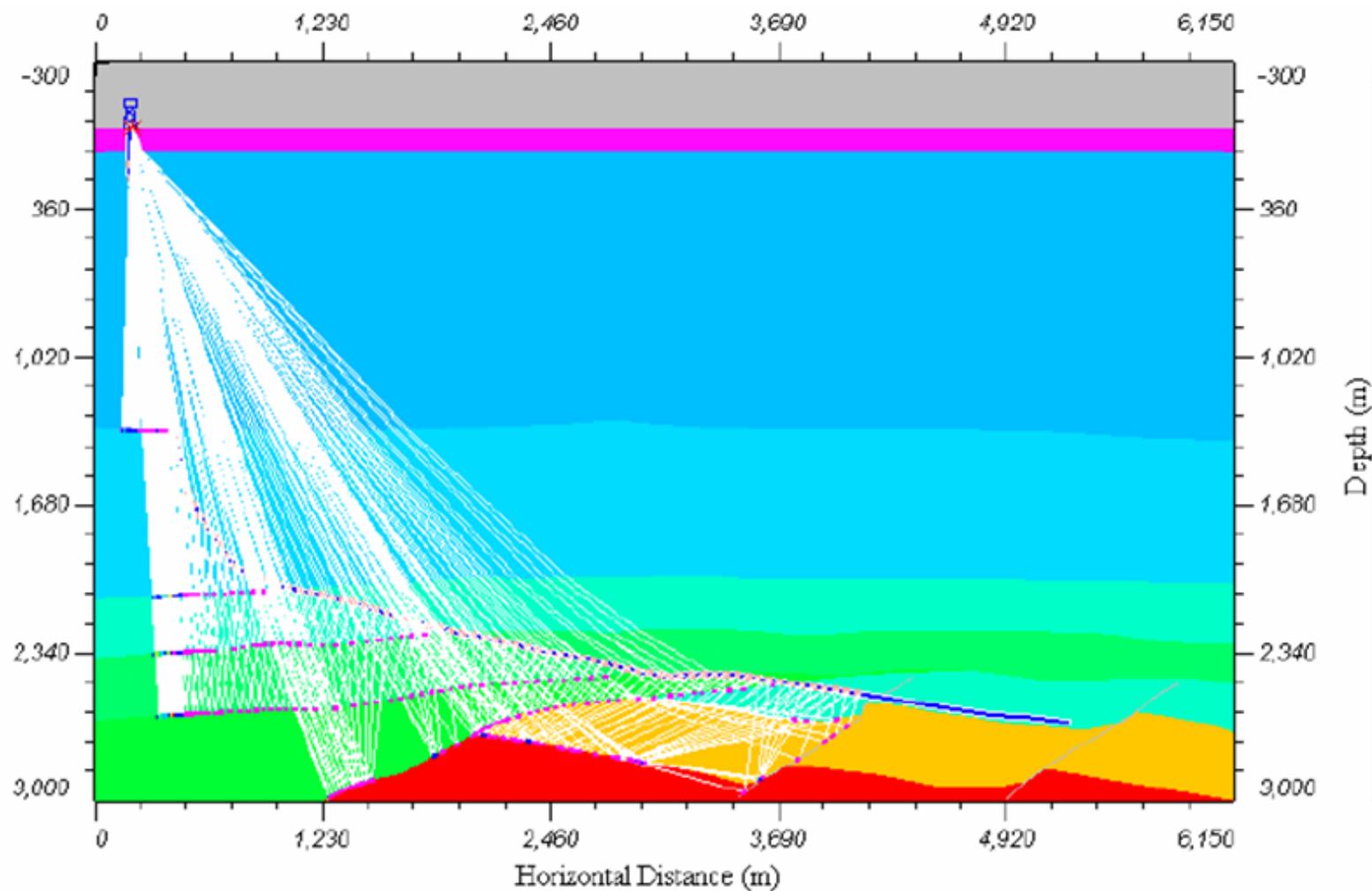
- Planning
- Operation

• مراحل **planning** شامل موارد زیر می باشد:

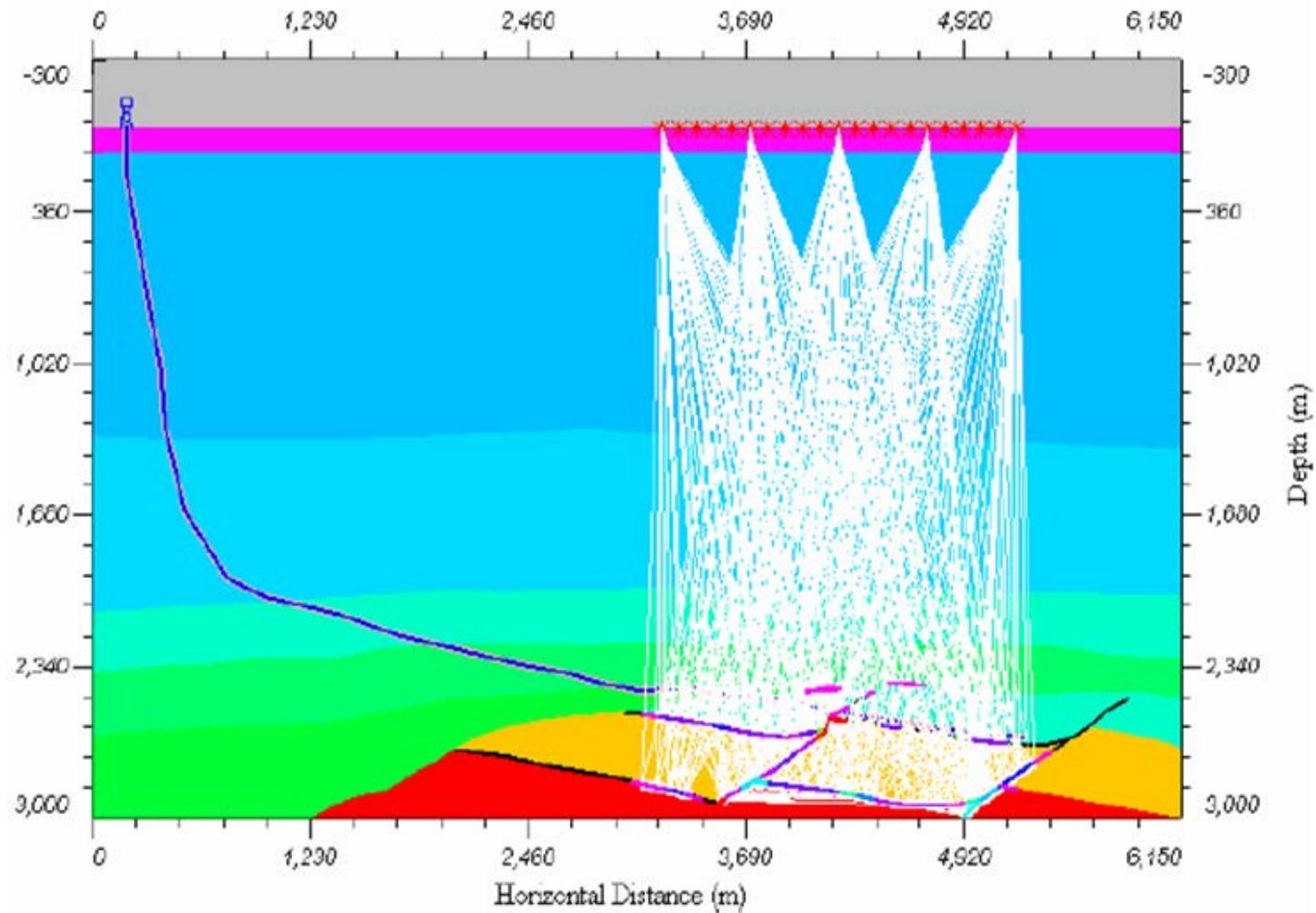
- Ray trace modeling
- Real time processing
- Acquisition density
- Site survey
- Rig setup
- Drilling personnel training

• مراحل Operation شامل موارد زیر می باشد:

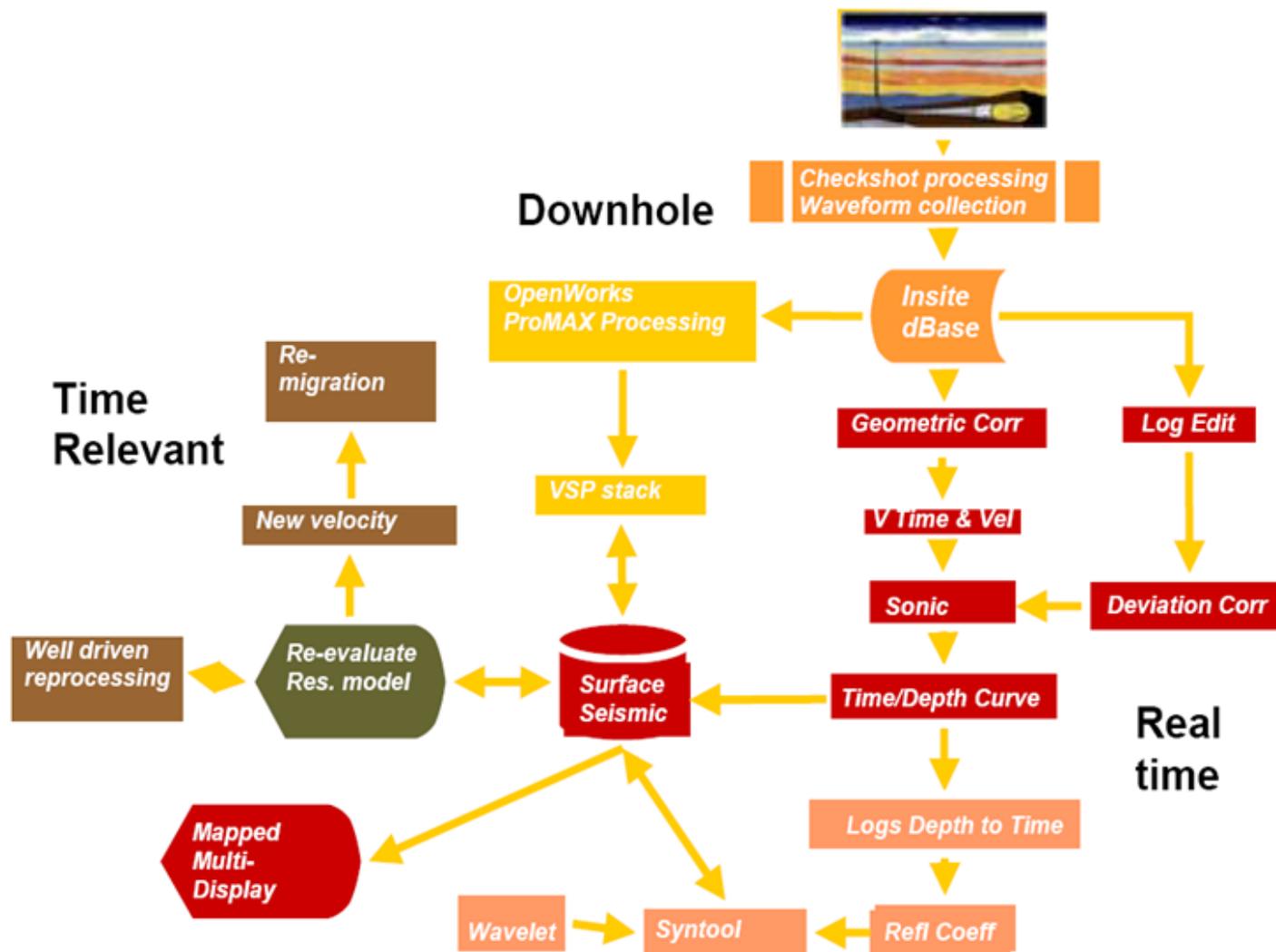
- Source handling
- Network/application performance
- Decision making process/resources



Rig-source raypath analysis



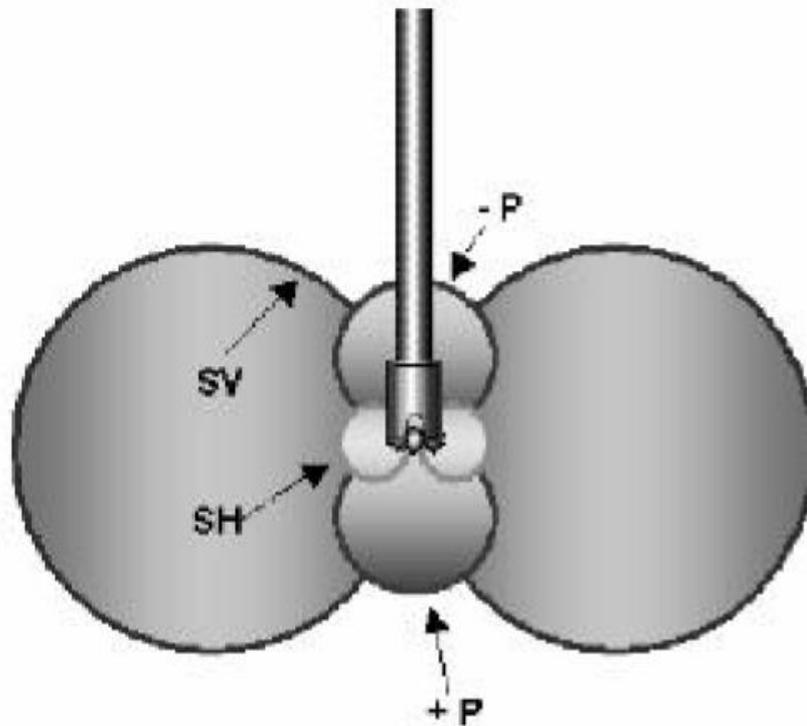
Vertical incidence ray path analysis



SWD processing flow

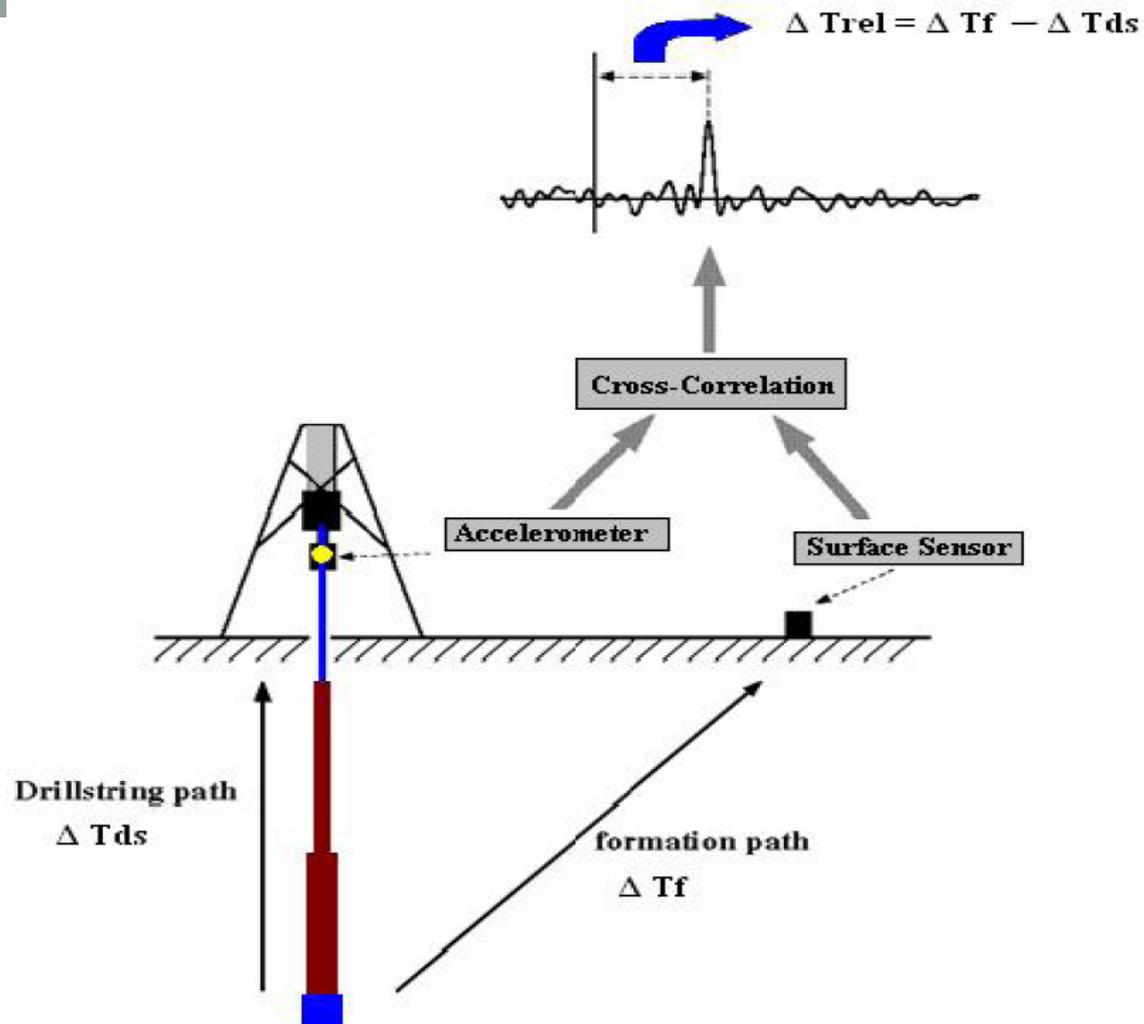
# Drill bit seismic

- Drill bit seismic را با نام seismic guided drilling هم می شناسند.
- در این روش منبع مته ای است که در حال ویران کردن سازند ته چاه می باشد.



Accoustic Radiation Pattern of a Tri-Cone Bit.

- وقتي دندان‌هاي مته در سازند نفوذ مي‌کنند باعث ايجاد يك ارتعاش محوري در رشته ي حفاري مي‌شود.
- علاوه بر اين امواج ، امواج فشاري هم در جهت مخالف در سازند ايجاد مي‌شود که اين امواج نهايتاً توسط ژئوفون در سطح برداشت مي‌شود.
- امواج لرزه اي محوري هم که در امتداد رشته حفاري گسترش يافته اند نيز مي‌توان توسط **accelerometer** که در روي **top drive** و يا **swivel** قرار مي‌گيرد مشخص مي‌شود.



Cross correlating the accelerometer signal and the surface sensor signal gives a relative time difference ( $\Delta T_{rel}$ ). Once the relative time difference is determined ( $\Delta T_{rel}$ ), the time taken along the axial string ( $\Delta T_{ds}$ ) could be determined and from both these information the travel time along the formation path ( $\Delta T_f$ ) can be calculated.

▶ در شکل بالا همانطور که مشاهده شد و زمان ثبت می شود یکی  $\Delta t_{ds}$  که مربوط به **accelerometer** بوده و ناشی از انتشار امواج در امتداد رشته ی حفاری است ، دوم  $\Delta t_f$  که حاصل انتشار امواج در سازند می باشد.

▶ برای این که بتوان مقایسه ای بین  $\Delta t_f$  و  $\Delta t_{ds}$  کرد باید داده های  $\Delta t_{ds}$  را یک انتقال زمانی بدهیم.

▶ برای محاسبه ی این انتقال زمانی ، مته را مقداری از سطح بالا کشیده و رها می کنیم و یک پیک شاخص را در **accelerometer** بدست می آوریم و مطابق شکل  $\Delta t_{rel}$  را یکبار حساب می کنیم.

- حال با توجه به اینکه در حین حفاری داده های مربوط به **acclerometer** دارای صحت بیشتری نسبت به داده های ژئوفون می باشد، می آیم تمام داده های حاصل از **accelerometer** را به اندازه  $\Delta t_{rel}$  انتقال می دهیم. سپس  $\Delta t_f$  را بدست آورده و مورد آنالیز قرار می دهیم.
- حال اگر متهم وارد ناحیه ی جدیدی شد مراحل بالا را مجدد تکرار کرده و  $\Delta t_{rel}$  را حساب کرده و مانند مراحل بالا دوباره تکرار می کنیم.

▶ در این روش دو سري گیرنده داریم:

1. اندازه گیری لرزش محوري توسط يك Accelerometer که روي top drive ويا swivel قرار دارد.
2. يك آرایه از ژئوفون ها در نزدیکی چاه ، روي زمین ، که شامل 12 تا 36 عدد ژئوفون مي باشد( در این روش فاصله ي ژئوفون ها حدود 20 تا 30 متر از well head مي باشد).

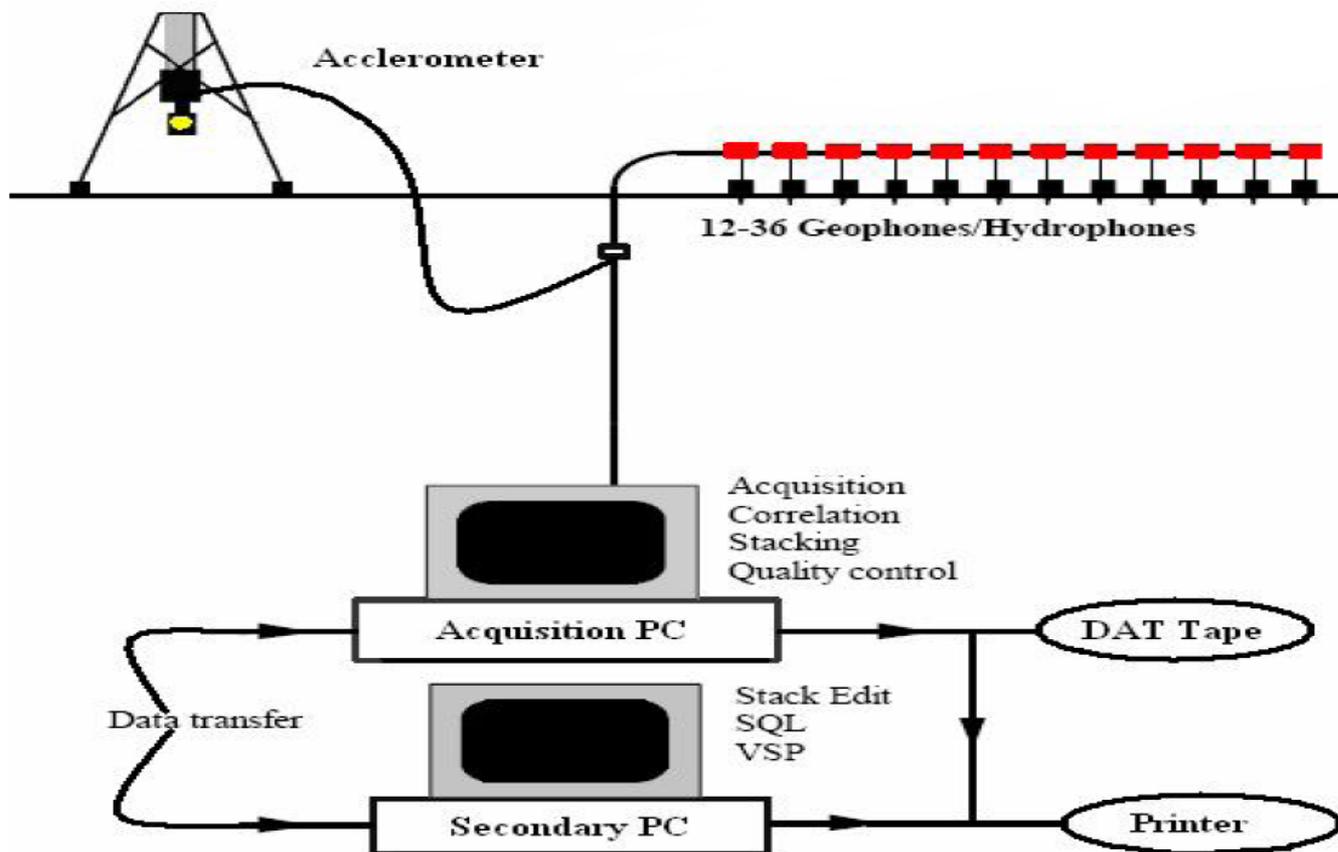
▶ در سري دوم گیرنده ها توصیه مي شود که ژئوفون ها در يك چاله دفن شوند تا اثر امواج سطحي کمتر شود.

▶ لایه هوازده در دو جا مشکل ایجاد مي کند.

1. اگر سازند مورد حفاري سخت باشد امواج قوي تولید مي شود و در نتیجه امواج سطحي قوي توسط این لایه تولید مي شود و کیفیت برداشت از بین مي رود.
2. اگر سازند مورد حفاري نرم باشد امواج توليدي ضعيف است و در لایه هوازده جذب مي شود.

# Acquisition system

- در شکل زیر يك شمائي كلي از سيستم جمع آوري اطلاعات را مشاهده مي كنيد.



Schematic of Data Acquisition Process.

- ▶ شکل بالا دارای دو **PC** بوده که یکی برای جمع آوری داده ها و دیگری برای پردازش داده ها می باشد.
- ▶ در برداشت های عادی برای جمع آوری داده های ژئوفون ها از **single chanel** استفاده می کنند که تمامی خروجی های ژئوفون ها به آن وصل است و به این طریق نویزها کاهش می یابد.
- ▶ اما در **SWD** مقدار نویزهای حاصل از محیط و امواج سطحی خیلی بیش از این می باشد که با این روش بتوان اثر آنها را کم کرد. برای همین هر ژئوفون را به صورت جداگانه برداشت می کنیم و با استفاده از یک **PC** تمام داده ها را جمع کرده و سپس برای پردازش از کامپیوتر دیگری استفاده می کنیم.
- ▶ در جایی که داده ها به طور جداگانه برداشت شود می توان تصحیحات آماری و **NMO** را راحت تر از حالتی که تمام داده ها با هم جمع می شود انجام داد.

# Overview of signal processing

- ▶ نمودار **time – depth** را با داشتن زمان سیر موج در امتداد رشته ی حفاری می توان بدست آورد.
- ▶ زمان عبور موج را می توان با استفاده از دانستن سرعت موج در هر قطعه از رشته ی حفاری و دانستن طول آن قطعه مشخص کرد.
- ▶ برای محاسبه ی این زمان می توان سرعت امواج در لوله های حفاری را با استفاده از فرمول زیر محاسبه کرد.

$$V = \sqrt{(E/D)}$$

E: young's modulus

D: density

- سرعت در رشته ي حفاري تقريبا برابر 5150 متر بر ثانيه مي باشد.
- در صورتي كه در داخل لوله ها و بين لوله ها و ديواره گل باشد سرعت عبور موج تا 10% مي تواند کاهش يابد.
- راه ديگر مشخص كردن **traveling time** در رشته ي حفاري ، ايجاد ضربه توسط مته به تنهائي و محاسبه ي زمان رسيدن اين ضربه به سطح و مشخص كردن آن توسط **accelerometer** مي باشد.

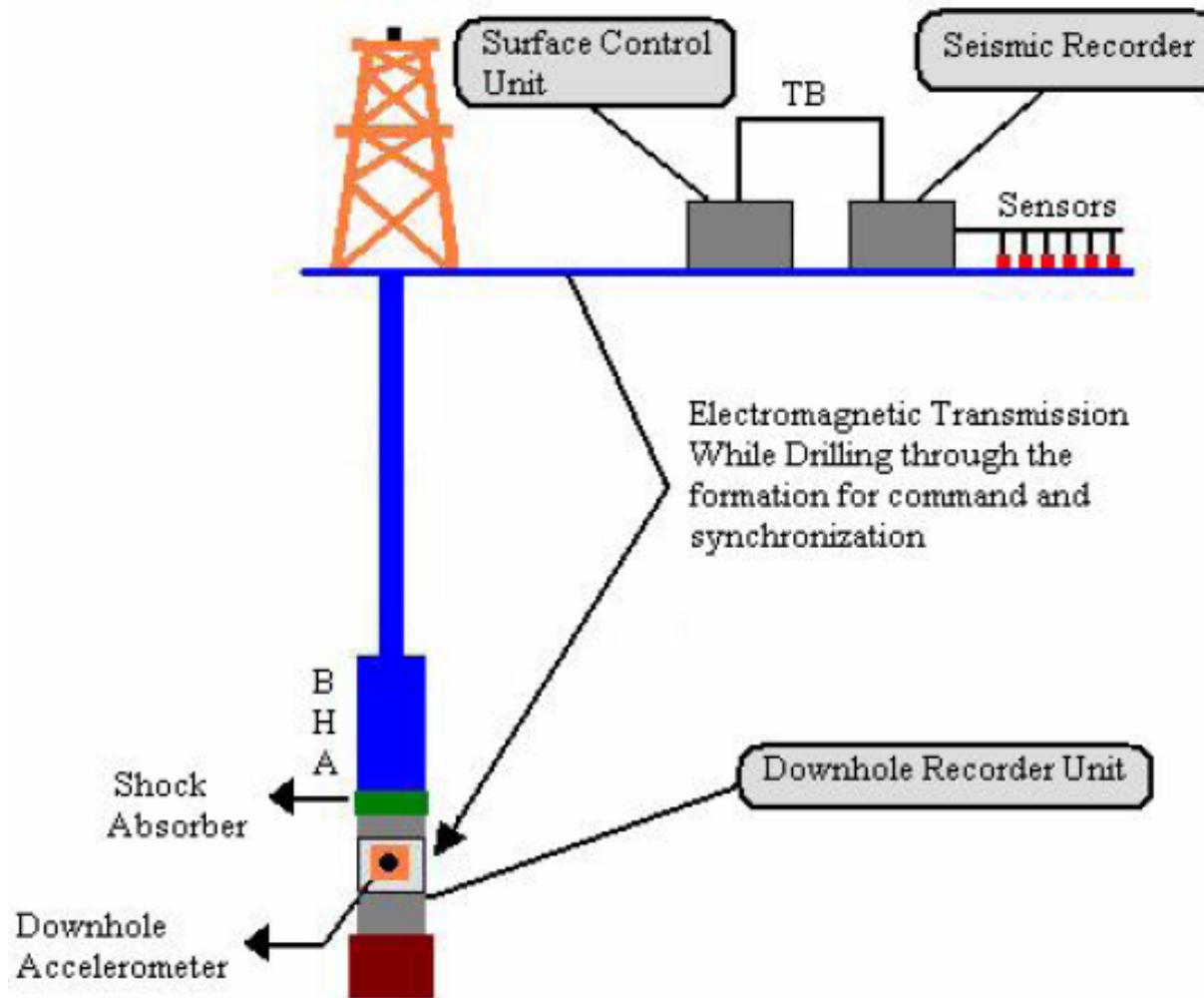
# Noise removal

- ▶ ابزاري مانند پمپ ها و موتورهاي ديزل باعث ايجاد نويز شديد مي شوند.
- ▶ گاهي اوقات امواج ضعيف حاصل از مته در بين اين نويزها كاملا محو مي شود.
- ▶ معمولا حذف نويزها در حفاري خشكي سخت تر از حذف نويزهاي حفاري دريايي است.
- ▶ يكسري از نويزها هم توسط حركت سيال در ديواره چاه ايجاد مي شود.
- ▶ با **stack** كردن مي توان مقدار زيادي از اين نويزها را حذف كرد.
- ▶ نويزها ايجاد شده توسط دكل حفاري معمولا با استفاده از **digital filter** حذف مي شود.
- ▶ وقتي امواج در امتداد رشته ي حفاري حركت مي كنند ممكن است به علت تغيير آمپيدانس در طول رشته ي حفاري (مانند تغيير قطر لوله ها) يك سري **multiple** ها ايجاد شده كه توسط **accelerometer** مشخص مي شوند و براي حذف اين ها از **drill string image processing** استفاده مي كنيم.

- در دریا وقتی امواج تولید شده توسط مته به بستر دریا می‌رسد و وارد آب می‌شود، اما در سطح دریا چون مقدار ضریب بازتاب بسیار بالا است و دوباره به سمت بستر بازتاب می‌کند و باعث ایجاد **multiple** هایی می‌شود.
- برای غلبه بر این مشکل در برداشت دریایی هم از هیدروفون استفاده می‌شود و هم از ژئوفون و امواج هم در سطح دریا و هم در بستر دریا ثبت می‌شود و با انطباق مناسب نتایج این دو می‌توان این **multiple** ها را حذف کرد.

# Drill bit seismic with shock absorber & EMWD

- IFP به جاي accelerometer که بیرون چاه روی top drive قرار می گرفت از down hole accelerometer استفاده کرد و برای انتقال داده های آن به سطح از MWD بهره جست.
- سپس مشاهده کرد که down hole accelerometer هم مانند قبل مقدار زیادی multiple در یافت می کند اما مقدار فرکانس آن بالاتر می باشد.
- سپس ژئوفیزیکست های IFP متوجه شدند که اگر بالای مته يك vibro seismic قرار دهند مقدار multiple ها به شدت کاهش می یابد که این ابزار را به نام shock absorber نامیدند.
- امروزه استفاده از shock absorber به شدت رایج شده و با این روش توانسته اند S/N را به مقدار زیادی بهبود بخشند.



A sketch of Drill-Bit EM-SWD recoding chain

- استفاده از MWD دارای یکسری مشکل است، از جمله نیاز به نگهداری فراوان دارد، اما شرکت Geoservices ابزاری با نام electromagnetic measurement while drilling(EMWD) را پیشنهاد کرد که مشکلات MWD را از میان بر می داشت.

## کاربردهای Drill bit – SWD عبارت است از: ►

1. Salt proximity survey.
2. Predicting Pore pressure ahead of the Bit.
3. Creating a Look Ahead Image.
4. Locating the Drill-Bit.
5. Optimizing casing/coring point.
6. Drilling hazard risk reductions.

# Salt proximity survey

- ▶ Drill-Bit seismic salt proximity survey, where drill bit act as a source at different depths with geophone array at the surface above the salt domes .Seismic travel time are recorded and are combined with other information such as exact location of both source and receiver and the velocity of signal in salt and surrounding rock and distance of the top of the salt domes helps in construction of salt dome profile. Vertical and lateral variation observed on both the drill-bit seismic and wireline VSP can be used to update the geological model. This survey reduced the cost of an additional sidetrack and saved more than \$ 100000 in case of a well like Qarn Nihayda-1 of North Oman.

# Predicting Pore pressure ahead of the Bit

- Pore pressure can be predicted from the amalgamation of seismic while- Drilling velocities and other drilling parameters in association with various modeling techniques. Accuracy in predicted pore pressure helps to predict the optimum mud weight to be used.

# Creating a Look Ahead Image

- ▶ Seismic Image of the formation ahead of the Bit can be generated on a real time basis which can be correlated with the surface seismic section to make up any time difference. This helps in correcting the position of horizons as seen on the surface seismic sections.

# Locating the Drill-Bit

- ▶ The time to depth information obtained on a real time basis help to locate the position of the bit on the surface seismic section with the progress in drilling activities. This information could be successfully used to guide the well trajectories and assigning accurate target.

# Optimizing casing/coring point

- ▶ With the help of Look- Ahead image and position of the drill bit the position of casing and coring points could be determined with precision .Thus, by elimination of planned casing in some cases7 save enormous money.

# Drilling hazard risk reductions

- ▶ An abrupt increase in formation pressure could lead to significant drilling hazard, particularly if the depth of hazard is not known to a high degree of accuracy prior to drilling. When combined with intermediate VSP's the while drilling technique can provide a look ahead to potential deviations from a normal pressure regime. Deviations from the trend often indicate onset of overpressure, and they can be seen in seismic while drilling results hundreds of meters ahead of the bit, in time to take action to drill ahead safely.

## مزایای استفاده از Drill bit SWD

1. کاهش ریسک حفاری
2. کاهش هزینه های حفاری
3. افزایش کارایی حفاری به مقدار زیاد
4. کنترل چاه را به مقدار زیادی بهبود می بخشد
5. باعث افزایش تولید می شود ، با هدایت کردن دقیق چاه به محل مخزن

## محدودیت های Drill bit SWD

1. این تکنولوژی در سازند های نرم و یا خیلی عمیق نمی توان استفاده کرد.
  2. در چاه های که زاویه انحراف آنها زیاد باشد نیز نمی توان از این تکنولوژی استفاده کرد ، چون مقدار جذب و ضعیف شدن امواج بسیار زیاد می شود.
  3. از این روش زمانی که مته **roller cone** باشد می توان استفاده کرد ، به این دلیل نمی توان از مته های **PDC** استفاده کرد زیرا لرزش محوری آنها کم است.
- ▶ توجه: محدودیت های 1 و 2 با ابزار **MWD** که اندازه گیری را در نزدیکی مته انجام می دهد رفع می شود.
- و مشکل 3 با ابزار جدیدی که به تازگی به بازار عرضه شده برطرف می شود.

# Vertical seismic profiling while drilling(VSP – WD)

▶ **VSP** معمولی دارای کیفیت بالای داده می باشد ولی محدودیت های بسیاری باعث می شود که استفاده از

آن را محدود می کند ، از جمله محدودیت ها می توان به موارد زیر اشاره کرد.

◦ اتلاف بیش از حد زمان

◦ افزایش خطرات حفاری

◦ در چاه های **high – deviated** به روش معمول قابل استفاده نیست ، در صورت اجبار هم نیاز به ابزار **tough**

**logging equipment** دارد که هزینه و پیچیدگی کار را افزایش می دهد.

▶ برای غلبه بر محدودیت های یاد شده ابزار **VSP – WD** ابداع شد که در ادامه به بررسی آن می

پردازیم.



▶ **VSP** و **VSP – WD** از نظر **source** و **sensor** فرقي ندارد، فقط در **VSP –**

**WD** به جاي کابل از فرستنده ي ویژه اي استفاده مي کنند که در شکل زير آن را مشاهده مي کنيد.

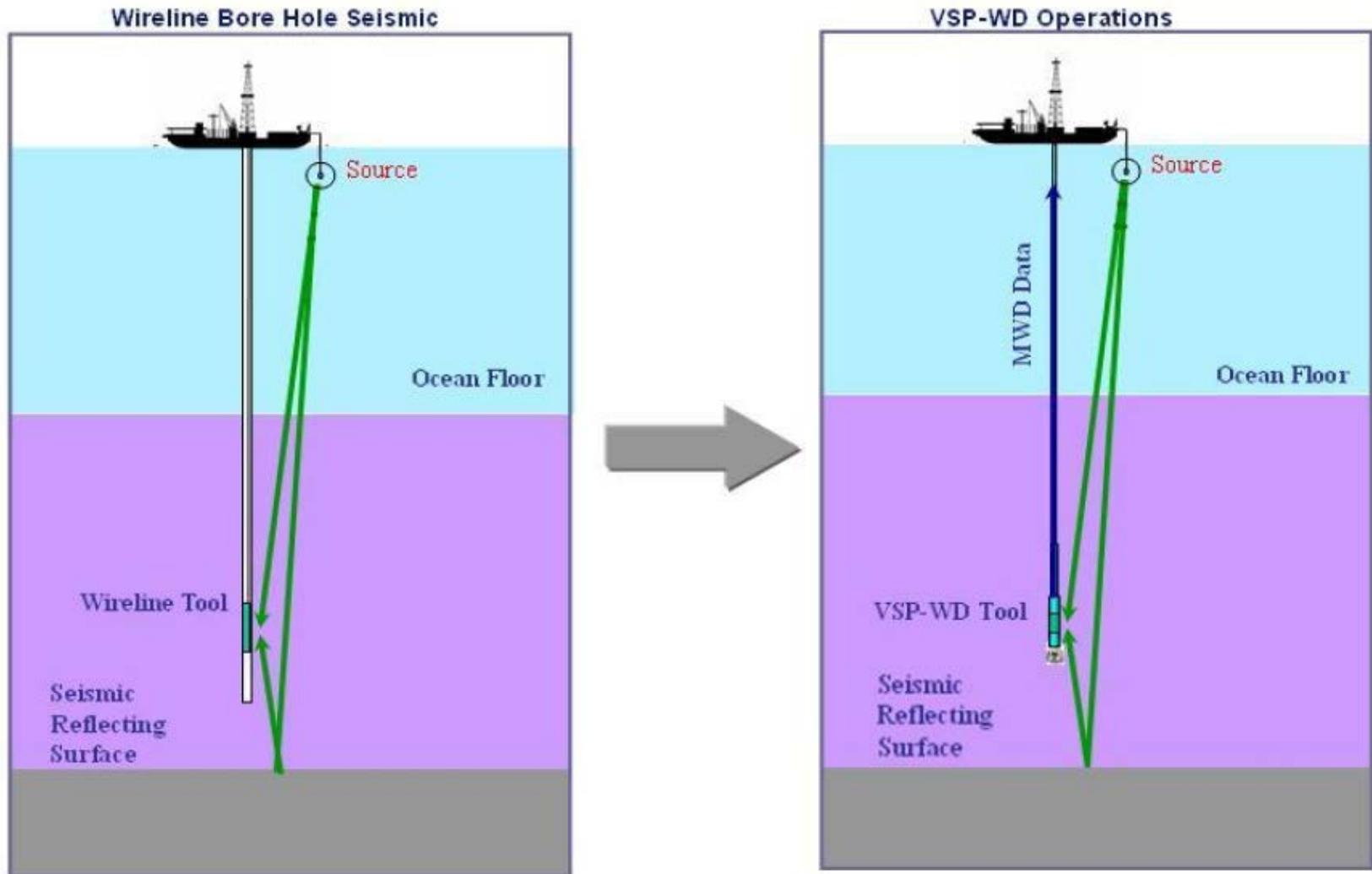
▶ **VSP – WD** در زماني که حفاري به عللي متوقف شده باشد انجام مي شود تا مقدار نويژها به حداقل

برسد.

▶ در **VSP – WD**، **first break time** توسط **mud pulstelemetry** به سطح

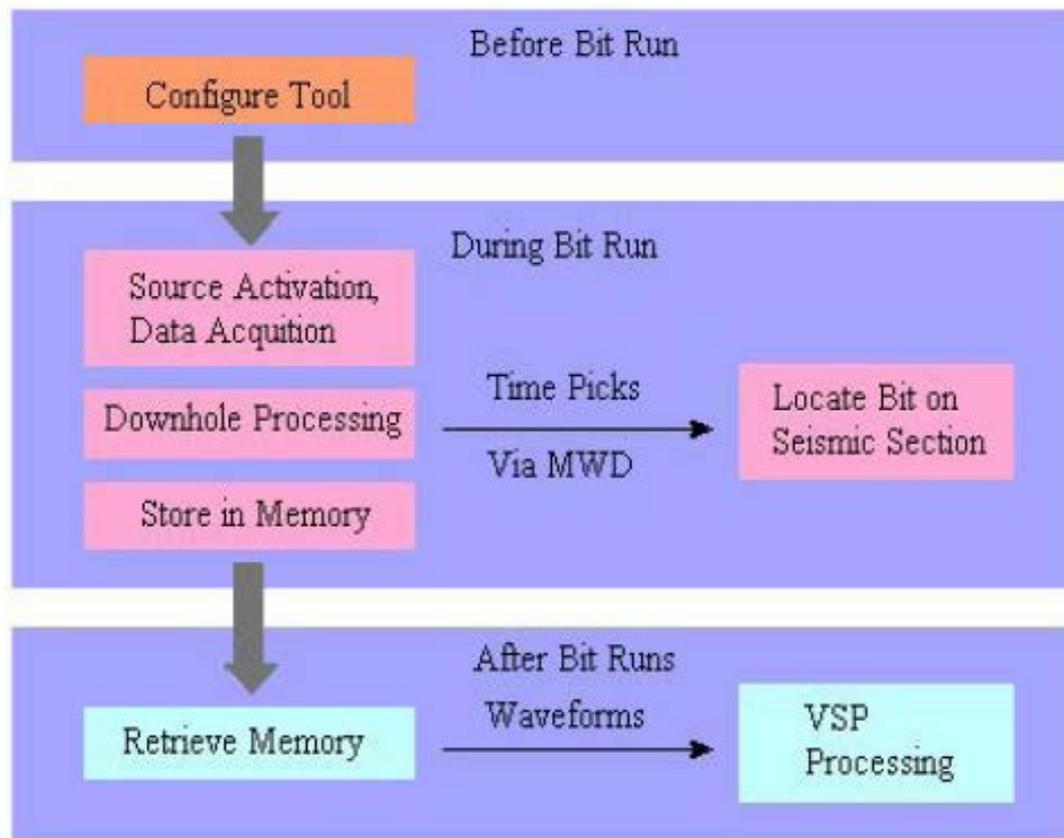
فرستاده مي شود و اطلاعات **full – wave form** در حافظه ي دستگاہ مي ماند و در حين

**trip** مي توان آن را بدست آورد.



- Transfer of Wireline seismic Technology to Drilling Operations

- مراحل کار VSP – WD را در شکل زیر مشاهده می کنید.

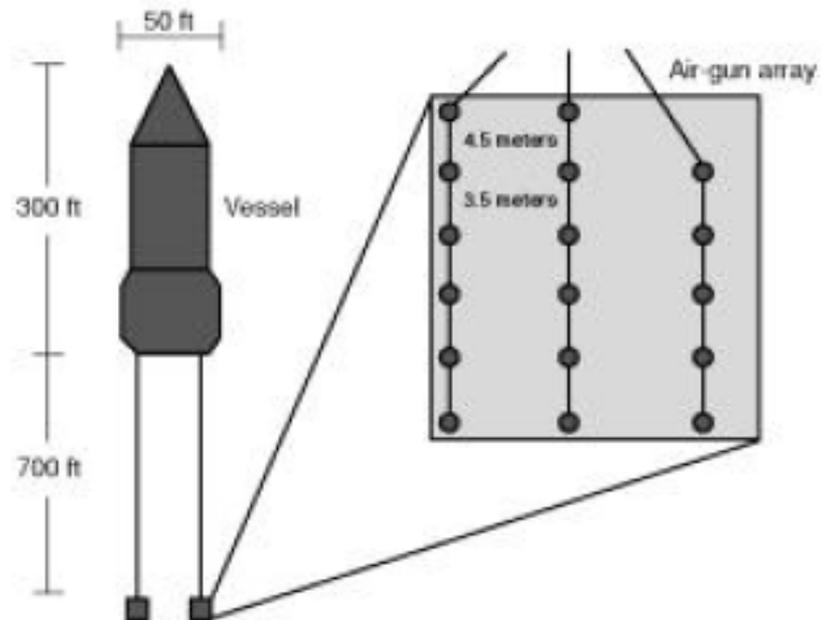


General operating procedures for VSP-WD surveys

- در هنگام بالا کشیدن رشته ي حفاري اين امکان وجود دارد که منبع مرتب فعال باشد و ما در هر عمقي که گیرنده قرار مي گيرد يك برداشت داشته باشيم همانند **VSP** معمولي.
- **VSP – WD** شديدا به ژئومتری چاه و محل منبع وابسته است.
- استفاده از اين ابزار در چاه هاي قائم با **zero offset source** بهترين نتيجه را مي دهد.

- وسایل لازم برای این عملیات عبارتند از:
  - Air gun system
  - کامپیوتر برای تهیه process data و timing information
  - يك منبع هوا با فشار بالا (حدود 3000 psi)
  - سیستم GPS برای مشخص کردن محل دقیق منبع به خصوص در offset source
  - Processing software برای QC اولیه و آنالیز اولیه
  - Tap tester برای تست کردن ساعت های ابزارها

### Typical Air-gun Geometry



The schematic diagram shows an air-gun array towed several hundred meters behind a seismic vessel to provide an energy source for the acquisition of marine seismic data.



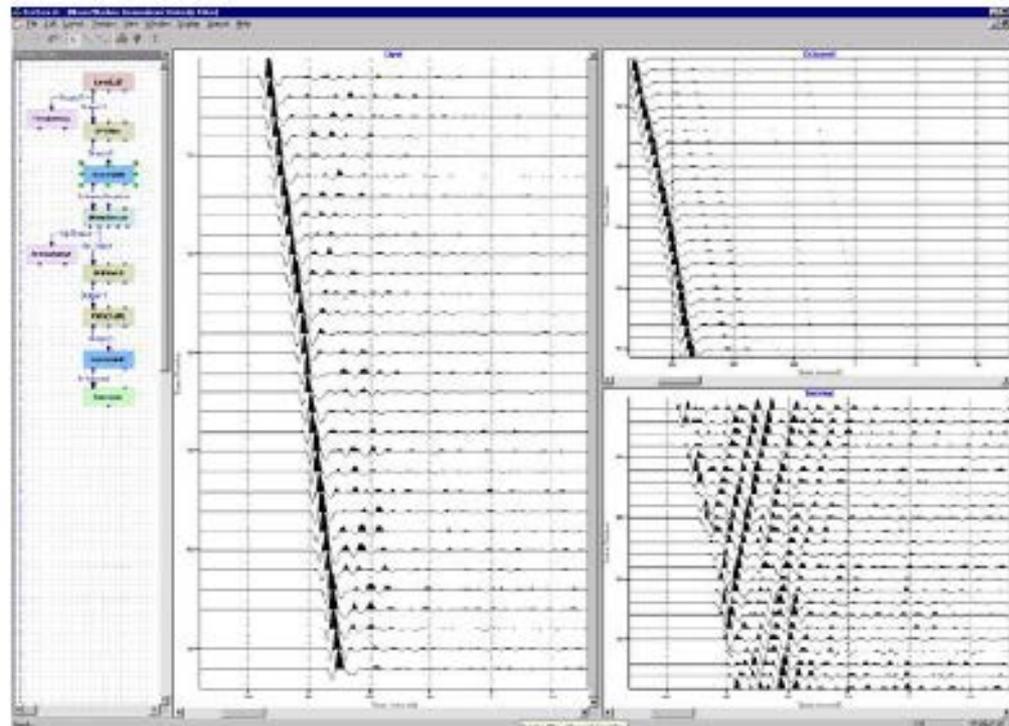
**The surface system**



**The Source Equipment**



**Seismic Navigation and Processing system.**



**Seismic Processing Software with highly configurable interface.**



Synchronization check of the clock and the entire system during a shallow hole test prior to running in the hole.

- در **VSP – WD** براي اينكه بتوان داده ها را با هم مقايسه كرد بايد از ابزار درون چاهي و ابزار سرچاهي كه هر 15 ثانيه يكبار با هم همزمان شود استفاده كرد (براي اين هر 15 ثانيه چون منبع هر 15 ثانيه يكبار مي تواند شات كند)
- دستگاه به طور خودكار هر سه شات كه در يك مكان انجام مي شود (زمان اضافه كردن هر **stand** حدود 45 ثانيه است كه مي توان سه شات در اين زمان كرد) را با هم **stack** کرده و نتايج را توسط **mud telemetry** به سطح مي فرستد.

# Real time processing

- يك بخش هر نرم افزار به تهيه real time visualization اختصاص دارد. در زير يك نمونه را مشاهده مي كنيد.

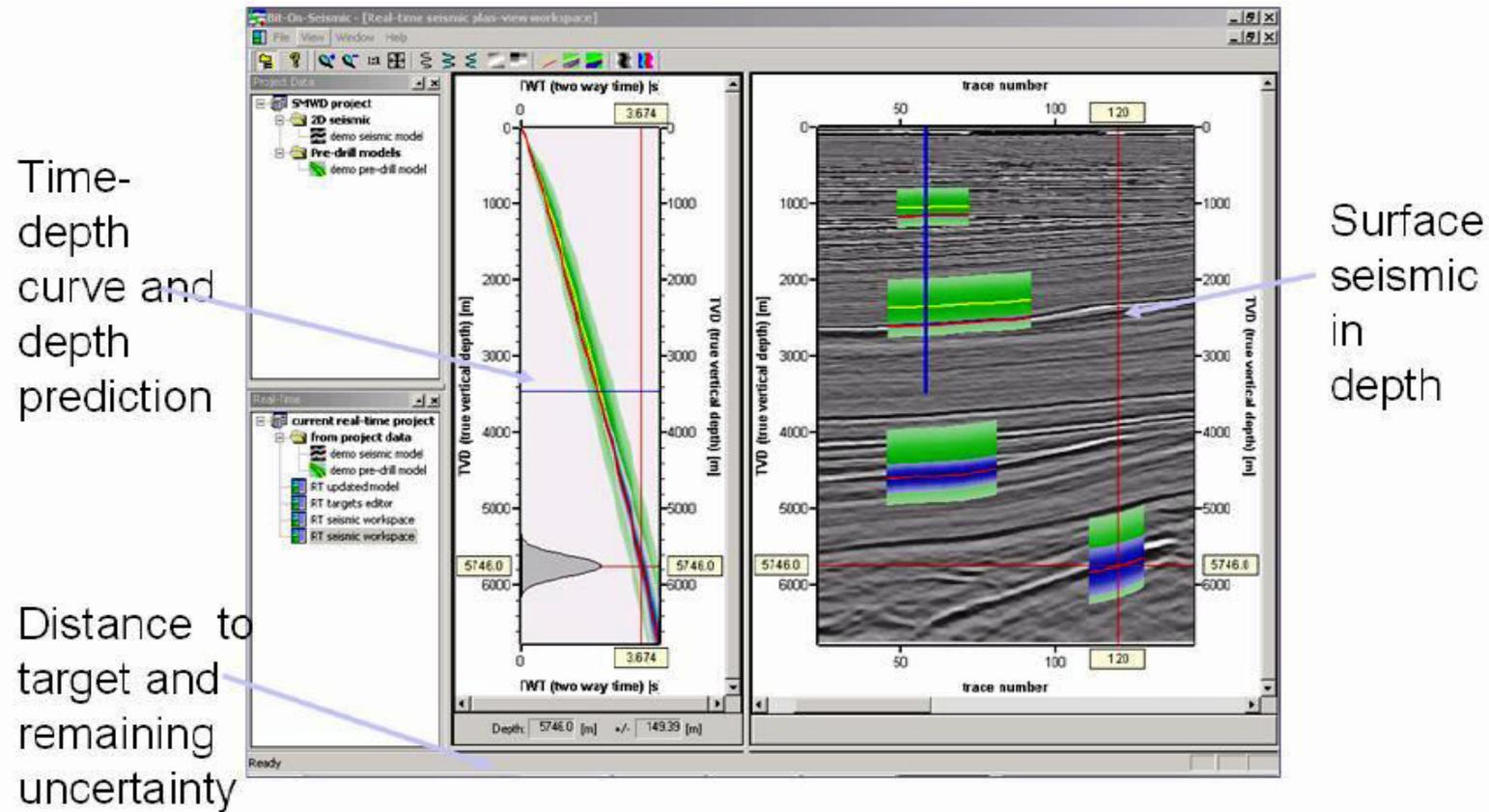


Figure shows a snapshot of Realtime Processing software. VSP-WD tool's time-depth/ velocity information is used to continuously update the bit position on the surface seismic. This real-time information minimizes uncertainty when drilling towards target horizons.

- **Real – time** باعث ایجاد ارتباط مستقیم بین حفارها و ژئوفیزیکست ها می شود و می توان مسیر حفاری

را به دقت مشخص کرد.

- نرم افزار دو **seismic section** را تهیه می کند.

- یکی برحسب زمان برای ژئوفیزیکست ها

- دیگری برحسب عمق برای حفاران که محل دقیق مته را مشخص کنند.

## مزایای VSP - WD

1. تنها روشی است که می توان در چاه های افقی هم اطلاعات VSP را بدست آورد.
2. حفارها می توانند محل دقیق مته را مشاهده کرده و لایه های پیش رو را مشخص کنند.
3. توسط این روش چون لایه ها به طور کامل مشخص می شود می توان محلی که می خواهیم **core** بگیریم را به راحتی مشخص کرد و نیازی به کم کردن سرعت حفاری برای مشخص کردن لایه حفر شده از روی **cutting** ها نداریم.
4. با مشخص شدن محل دقیق **core** گیری از **core** گیری بیش از حد ممانعت می کند.

5. در این روش نیاز به نگه داری عمل حفاری نیست و به طور متوسط \$ 420000 صرفه جویی می شود.
6. ناپیوستگی ها به راحتی مشخص می شود.
7. محل قرار گیری لوله ی جداری به راحتی و با سرعت و دقت مشخص می شود.
8. می توان pore pressure را پیش بینی کرد و وزن گل لازم را مشخص کرد.

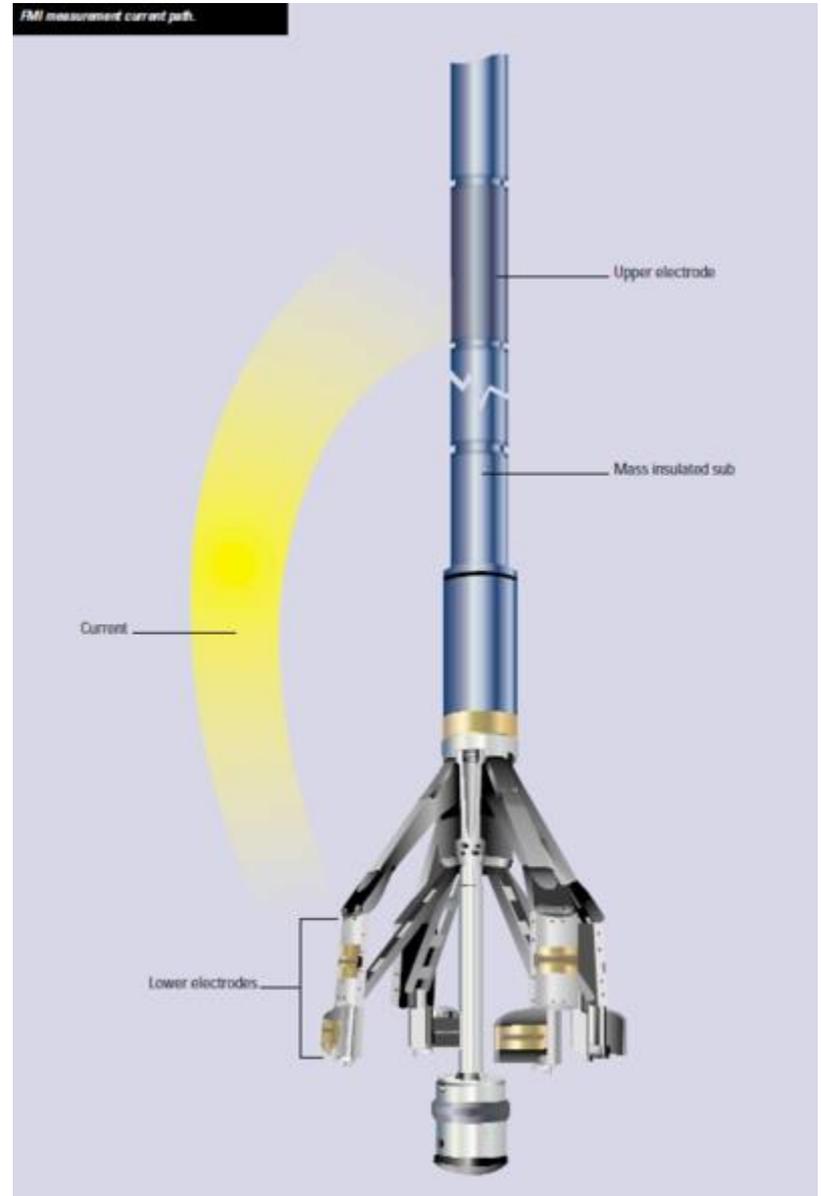
## VSP - WD محدودیت های

1. It is claimed that it provides look-ahead imaging, however the range and accuracy of this capability is still not accurately known.
2. Mud Pulse telemetry of processed velocity is planned but not presently commercial.
3. The biggest limitation of VSP-WD services is to ensure a good mechanical coupling of the VSP seismic sensor with the borehole and high precision required on downhole clock.

# Image Log



FMI measurement current path.



# Reservoir scale deformation

- Small scale faults and fractures plus the internal structure of faults revealed by core and image logs

# Core orientation

Core marked to show 'way-up'

Up



L R



# Recognition of natural fractures

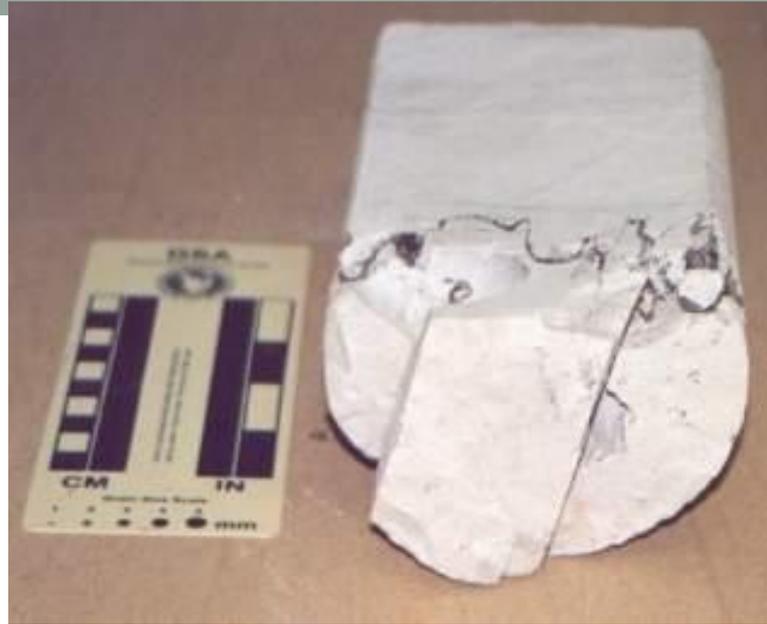
- Cementation
- No geometric relationship with core
- Shear offset
- Planar
- Propagation along bedding not down core
- Multiple sets

# Faults in core



# Natural fractures

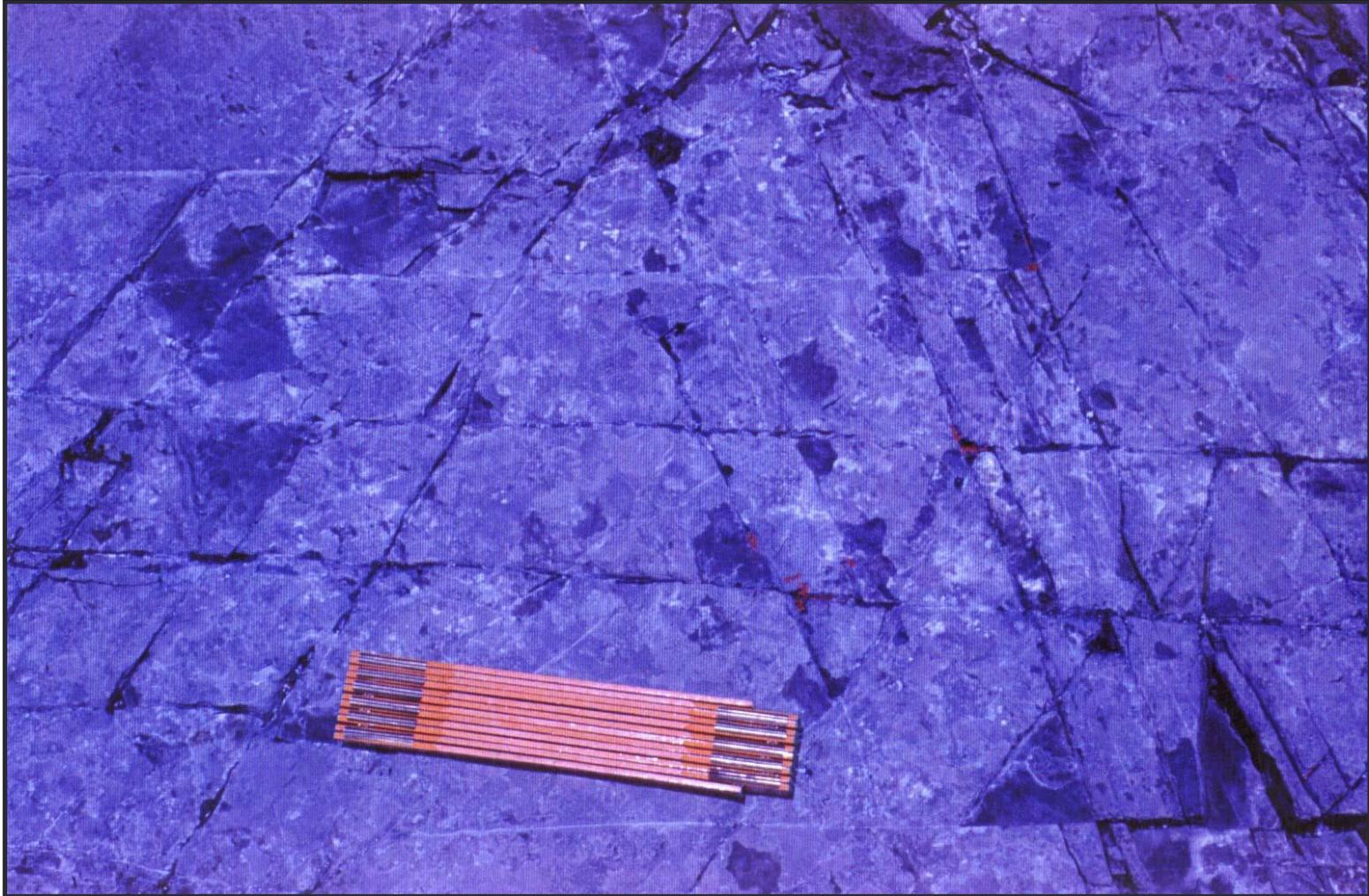
Fracture spacing and layer boundaries in Chalk core



# Fracture spacing

$$\text{Spacing} = \frac{\text{Core slab surface area}}{\text{Total fracture height in core}}$$

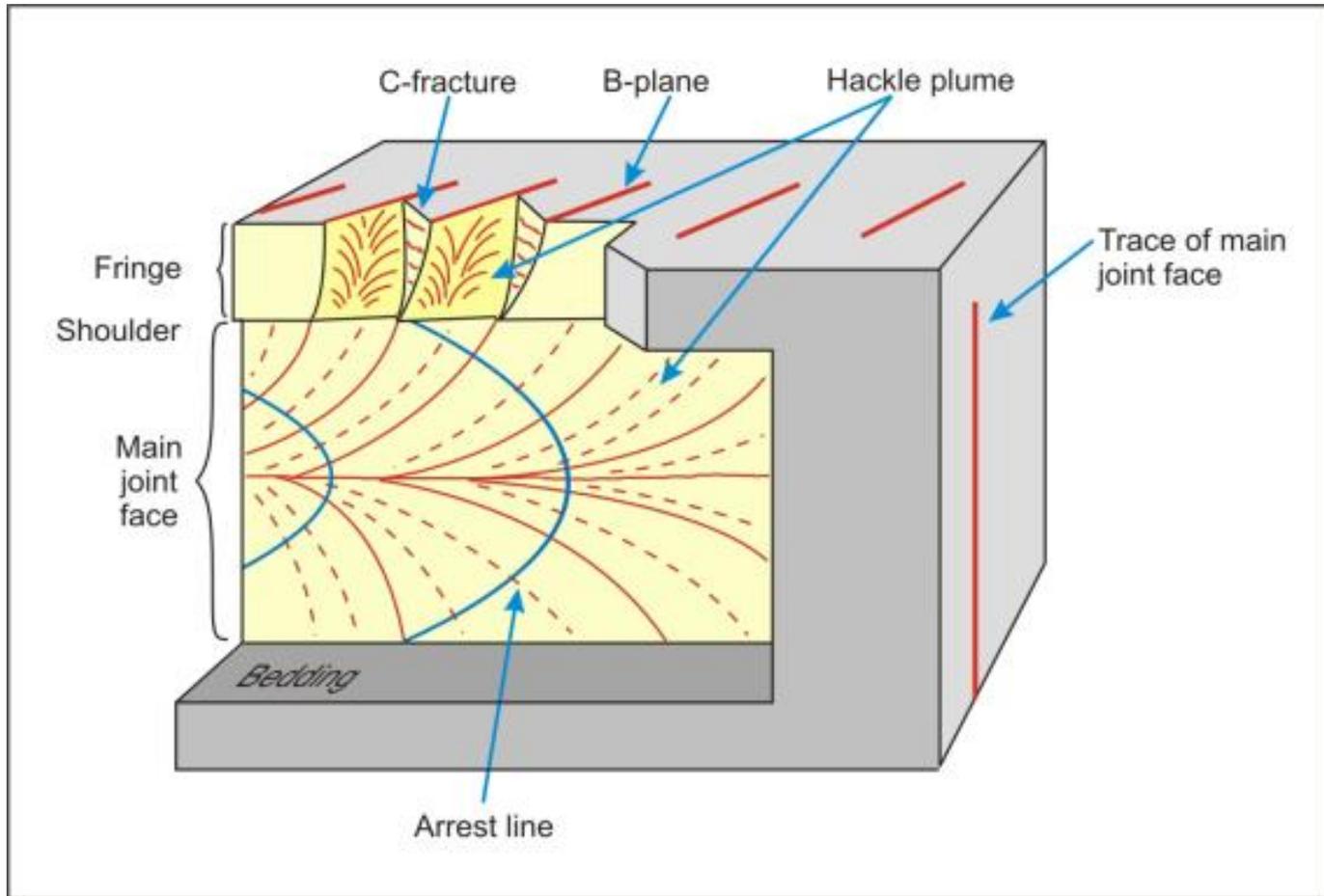
# Fracture Spacing in Miss. Madison Ls



# Coring induced fractures

- Can be mistaken for natural uncemented fractures and so influence identification of productive zones
- Types recognized using characteristic fracture surface morphology or fracture geometry:
  - Centreline fractures
  - Petal fractures
  - Torsional fractures
  - Scribe-knife related
  - Core-plug related
  - Unloading

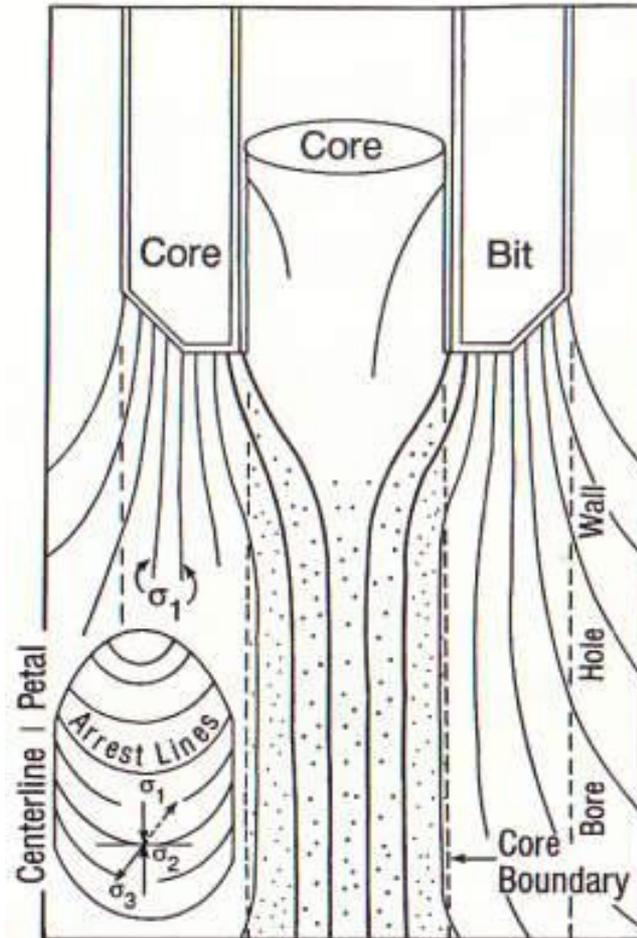
# Fracture surface morphology



# Arrest lines indicating Propagation down core



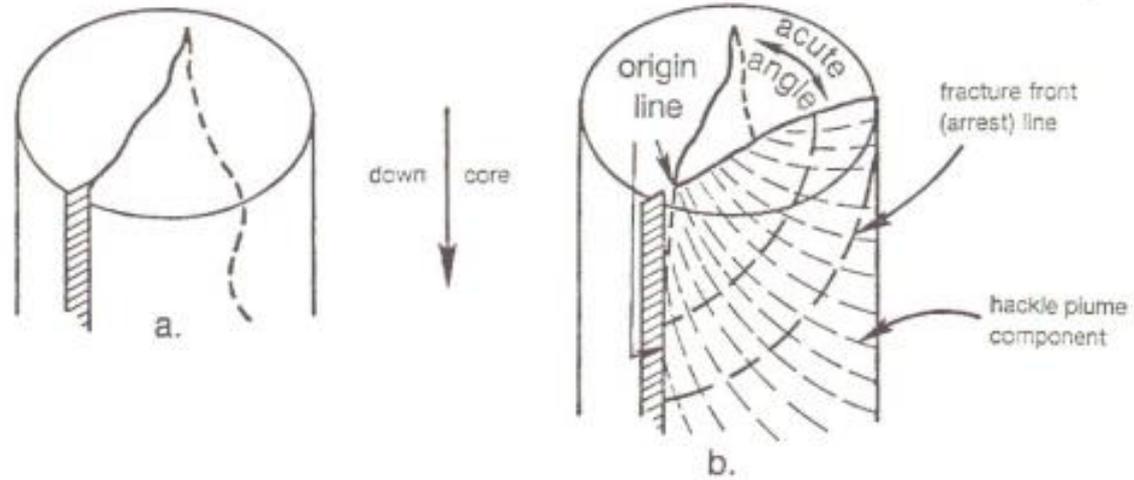
# Petal-centreline fractures



# Petal-centreline fractures



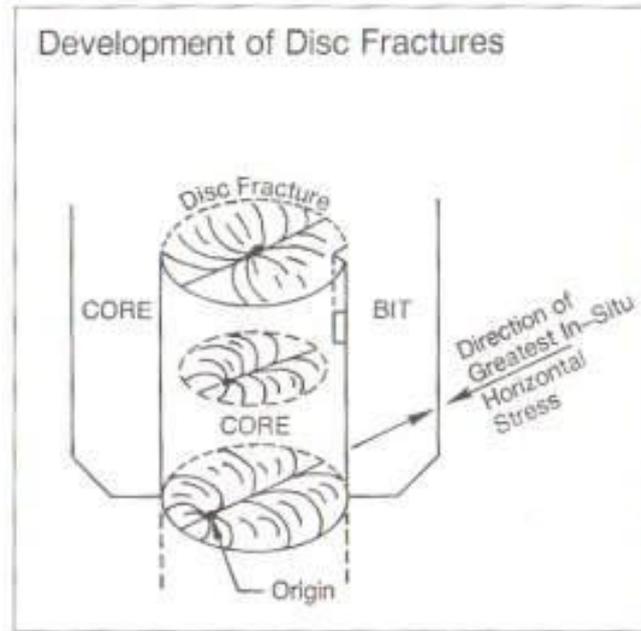
# Scribe knife damage



# Scribe knife damage



# Core discs



# Core discs



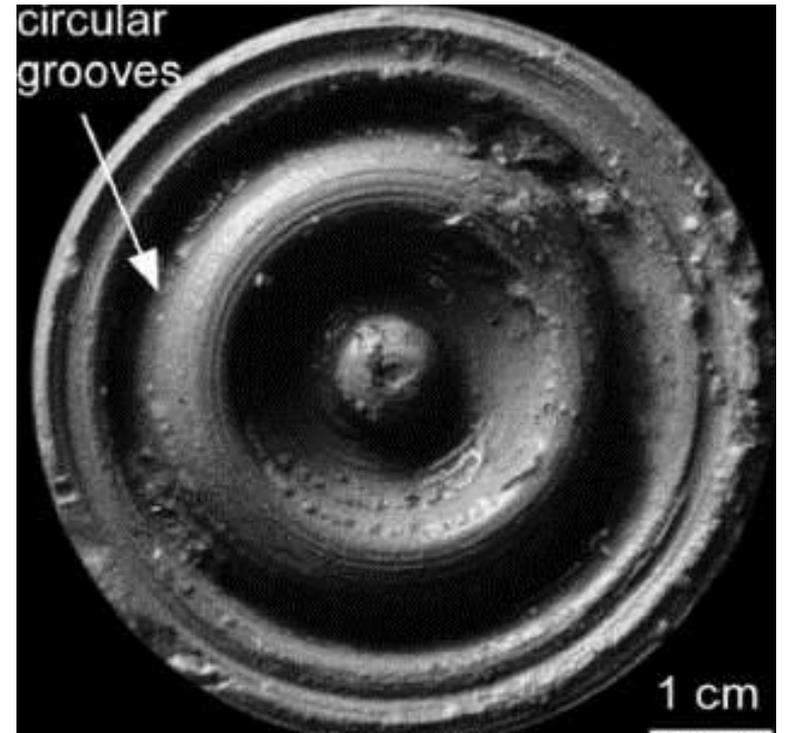
# Core disc



# Torsional fractures



# Core spin



From Paulsen *et al.* (2002)

# Rubble zones in core

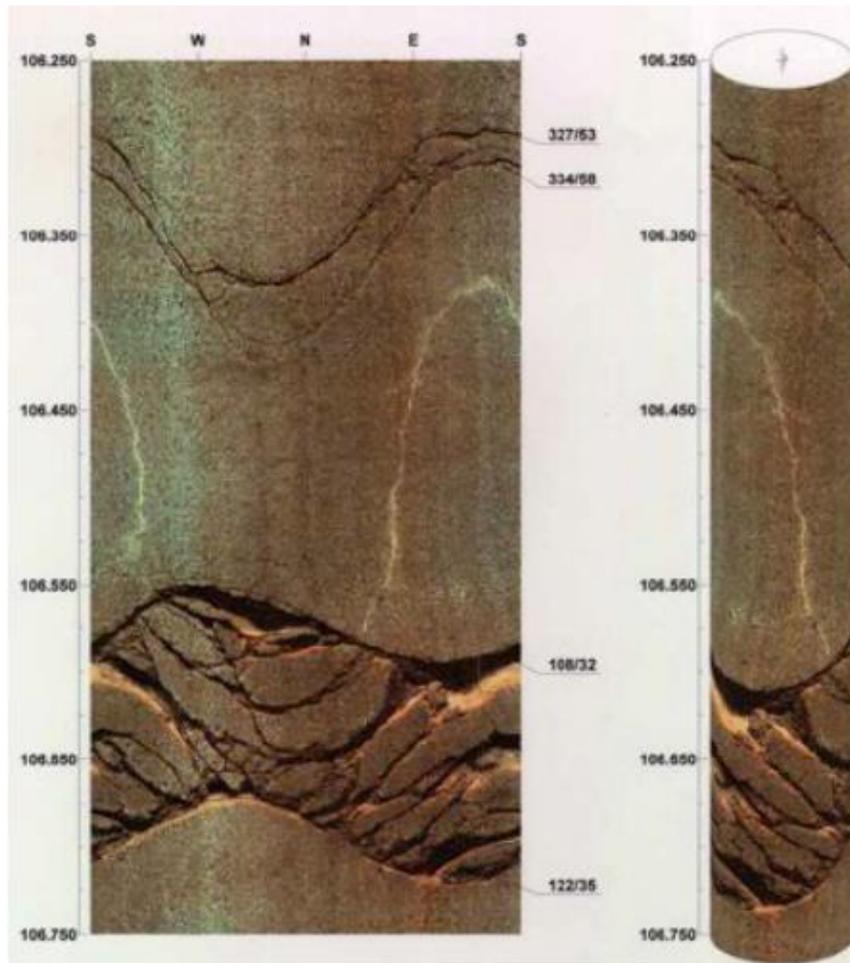
- Induced
- Often at base of a core
- Can develop where lithologies change

## Types of downhole image tools

- Electrical Resistivity: FMS (Formation MicroScanner), FMI (Formation MicroImager), RAB (Resistivity-At-Bit), etc
- Ultrasonic: UBI (Ultrasonic Borehole Imager), BHTV (BoreHole TeleViewer), etc
- Video.

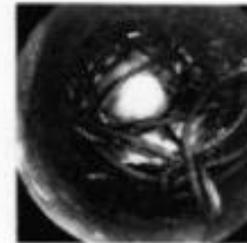
## Downhole video

Clear drilling fluid is required for downhole video - not often the case.



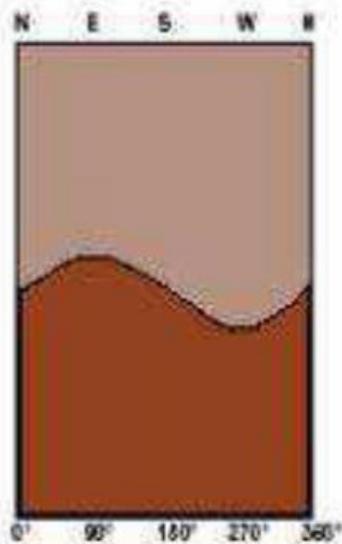
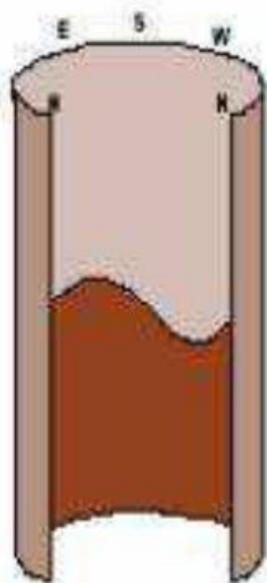
J. Nelson, COLOG

# The first downhole images?

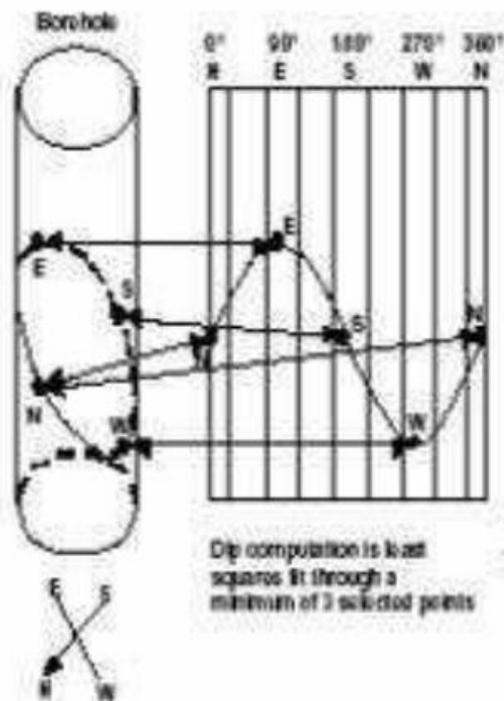


Thompson / Loran 1904,

Fig. 39. —Photographs of Lost Articles in Baku Oil Wells.



Images Viewed Inside Out



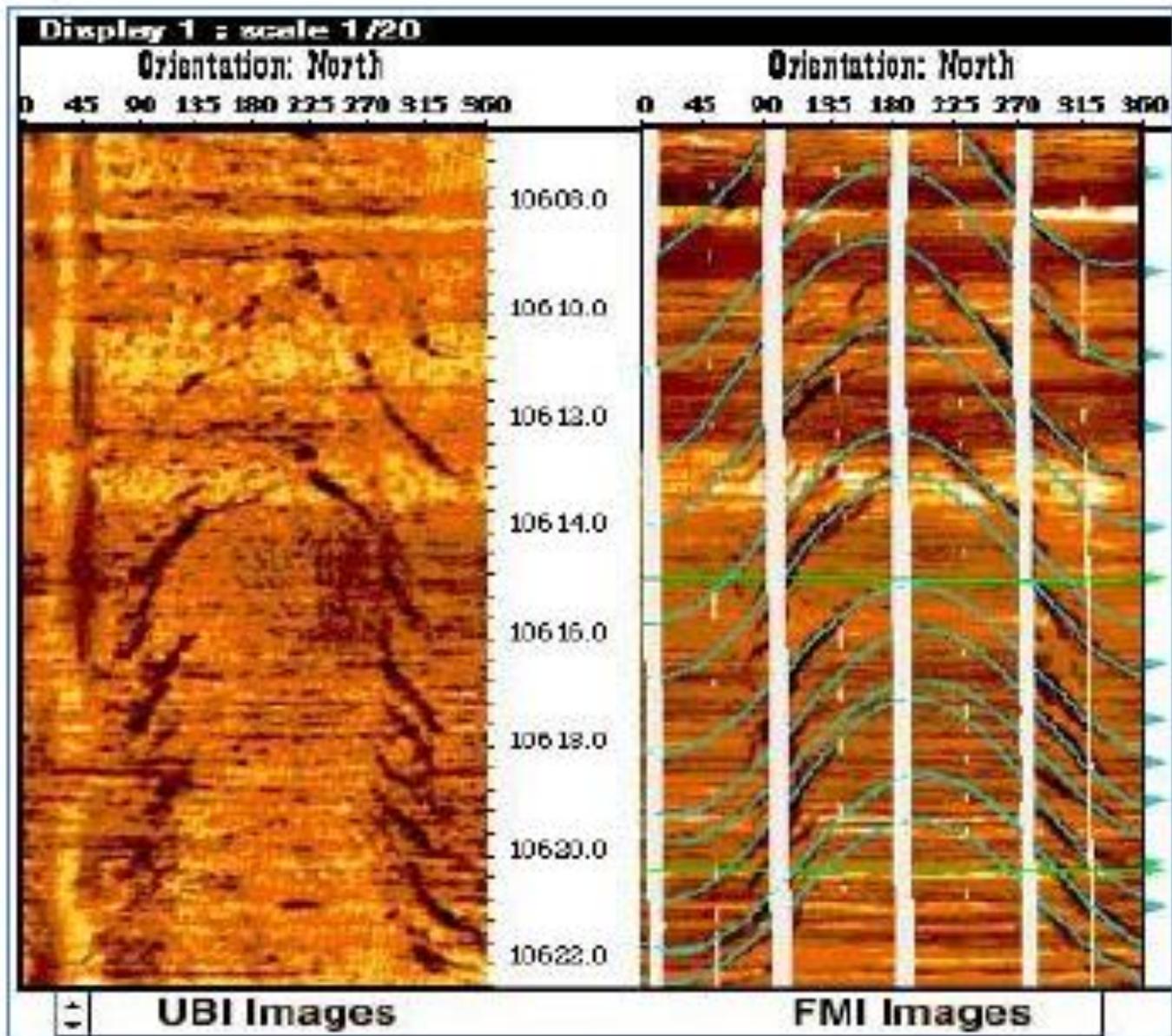


Table 1. Baker Hughes imaging tools summaries

| Service Company     | Tools  | Mud in Borehole               | Tools characteristics and capabilities   |
|---------------------|--|-------------------------------|--|
| <b>Baker Hughes</b> | <b>STAR Imager Service</b>                         | conductive /water based mud   | Pads with 24 sensors mounted on each of the six articulated arms, giving a total of 144 microresistivity measurements with a vertical and azimuthal resolution of 0.2 in (~5 mm). Operates alone or in combination with the Baker Hughes CBIL imaging. Able to log images in vertical, horizontal, highly deviated, and rugose wells.  |
|                     | <b>Earth Imager Service</b>                        | Non-conductive /oil based mud | Allows simultaneous acquisition of high-resolution microresistivity and acoustic borehole image data. Has an articulated six-arm carrier. Ability to log images in vertical, horizontal, highly deviated, and rugose wells.  |
|                     | <b>Circumferential Borehole Imaging Log (CBIL)</b> | All type of muds              | High-resolution borehole acoustic images in difficult conditions, including high-porosity, unconsolidated formations. Suitable for fracture and fault analysis. Can be used for interpretation of the near-wellbore stress field from borehole breakouts and drilling-induced fractures. 250-kHz operating frequency enables good performance in larger holes and heavier muds. Full 360-deg. borehole imaging tool operating in the pulse-echo mode. Generates sharp images and boundary delineation. Its small size of 3.625 in. (92 mm) allows for operation in slim holes as well as large-diameter holes.   |
|                     | <b>Ultrasonic Xplorer Imaging Service</b>          | All type of muds              | High-resolution borehole acoustic images in difficult wellbore conditions, including OBM and large boreholes. Attains full 360° image coverage providing sharp images and boundary delineation. The lower operating frequency (250 kHz), along with downhole digital signal processing (DSP), allows for better performance in larger boreholes and in highly attenuating muds. Quite effective in horizontal wells. Its small size 3.625 in. (92 mm) allows for operation in slim holes, as well as large-diameter holes up to 16 in. (406 mm). Provides an acoustic amplitude image and a travel-time image. By calibrating the travel-time image, it is possible to provide a high-resolution borehole shape. |

**Baker  
Hughes**

**GeoXplorer  
Imaging Service**

Non-  
conductive  
/oil based  
mud

Provides high-resolution formation microresistivity imaging in low-resistivity formations drilled with nonconductive mud systems. The high-resolution images allow for near-wellbore geological and petrophysical reservoir evaluation. 10 sensors mounted on six articulated arms to provide 60 microresistivity measurements, with a vertical resolution of 0.8 in (20 mm), and 79% borehole coverage in an 8.0" borehole. Operates in highly deviated boreholes. Determines an accurate net-pay even in thinly bedded intervals. Allows accurate positioning of fluid sampling or sidewall coring tools. The simultaneous acquisition of GeoXplorer and UltrasonicXplorer provides a more complete picture for accurate fracture evaluation, particularly in shale gas or fractured basement evaluation.

Table 2. Schlumberger imaging tools summaries

| Service Company     | Tools                                     | Mud in Borehole             | Tools characteristics and capabilities   |
|---------------------|---|-----------------------------|--|
| <b>Schlumberger</b> | <b>FMI Fullbore Formation MicroImager</b> | conductive /water based mud | <p>Provides real-time microresistivity formation images and dip with 80% borehole coverage in 8-in boreholes and 0.2-in image resolution in the vertical and azimuthal directions. Used for determining net pay in laminated sediments of fluvial and turbidite depositional environments, visualize sedimentary features to understand structure specially in not cored intervals, provide high quality of bedding dip data in highly deviated wells which improves the structural interpretation of seismic sections and computation of the true stratigraphic thickness. Improve modeling outputs, by supporting stochastic modeling of the sand-shale distribution. Define channel heights in amalgamated units, and others such as the channel width and channel sinuosity, can be estimated using geological analogs, based on detailed sedimentological analysis of FMI image data. Improve mechanical earth models for optimizing well planning. Better understanding of borehole stability.</p> |

**Schlumberger**

**Ultrasonic  
Borehole  
Imager (UBI)**

All type of  
muds

Analyze fractures, drilling-induced fractures and the stress regime and conduct borehole stability studies, with 100% borehole coverage, and structural interpretations. Two operating frequencies (measure both amplitude and transit time) modes of image resolution are available; standard and the higher resolution which deliver an accurate borehole cross section for deriving borehole stability and breakout information. The UBI processing technique avoids cycle skips and reduces echo losses. Image resolution is selected to correspond to the logging environment, such as mud type and density. The higher frequency yields higher image resolution. The lower standard frequency gives a robust measurement in highly dispersive muds. UBI tool measures attributes of ultrasonic waves reflected at the borehole wall and the rugosity of the borehole wall can dominate the reflection amplitude. UBI images are strongly sensitive to surface variations in the borehole wall but not to variations in lithology. Formation changes are normally seen on UBI images only if corresponding borehole surface effects, such as changes in rugosity or hole diameter, are present.

**Oil-Base  
MicroImager  
(OBMI)**

Non-  
conductive  
/oil based  
mud

OBMI microresistivity imaging tool with four pads acquires five potential difference measurements that are used to quantitatively determine the resistivity of the invaded zone., see structural, stratigraphic, and anisotropic features as small as 0.4 in [1 cm], giving high-resolution azimuthal information. The sensitivity of the OBMI measurement delivers computed dips that are highly accurate even in formations with little resistivity contrast.

Table 3. Halliburton imaging tools summaries

| Service Company    | Tools   | Mud in Borehole                   | Tools characteristics and capabilities  |
|--------------------|---|-----------------------------------|---|
| <b>Halliburton</b> | <b>Electrical Micro Imaging Service (EMI<sup>SM</sup>)</b>  | Conductive/<br>water based<br>mud | Six independent, articulating arms, each outfitted with 25 small electrodes on pad. Maintains optimum pad contact with a minimum of pad pressure, even in rugose, washed-out, or non-circular bore holes. An electrical current flows from the pads into the rock then upward in the wellbore to return at the top of the tool. Microresistivity contrast in the rock layers sampled 120 times per foot. Images are used to examine bed thicknesses ranging from a fraction of an inch to several feet; and accurately calculate sand thickness counts. Image enhancement techniques help further identify the precise characteristics of the formation reservoir. Identifies individual fault event and orientation. Detailed images of sedimentary features allow descriptions of bed boundaries, internal bed characteristics, textural changes, and laminated sand/shale sequences. Images can be presented in 2D and 3D formats. |
|                    | <b>Oil-Based Micro-Imager Tool (OMRI<sup>SM</sup>)</b>      | Non-conductive/oil based mud      | Six resistivity measurements per pad, each with a vertical resolution of 1 in. depth of investigation of about 3 in. data of 120 samples per foot with a proprietary signal acquisition scheme optimized for rugose hole conditions. The pads are mounted on six independent caliper arms. The sensor pads are mounted on the caliper arms with unique two-axis of articulation to improve pad contact in less ideal hole conditions which shows widest possible range of logging conditions. Used to analyze thin bed pay, structural and stratigraphic dips, sedimentary geometry and texture, borehole stresses, lithologic unit thickness, permeability barriers, sand attributes, clasts, vugs.  |
|                    | <b>X-Tended Range Micro Imager Tool (XRMI<sup>TM</sup>)</b> | Conductive/<br>water based<br>mud | Coverage is 67% in 8.5 in. hole with 120 samples/ft. Good quality images even in high Rt:Rm environments. Has 32 bit digital signal acquisition architecture. S/N ratio by a factor of up to five, and the dynamic range expanded by a factor of up to three. The resulting images offer good reliability even in highly resistive formations (Rt > 2000 ohmm) or relatively salty borehole fluids (Rm < 0.1 ohmm). Pads mounted on six independently articulated arms help to maintain pad contact in rugose, washed-out, elliptical, or highly deviated boreholes.  |

**Halliburton**

**Circumferential  
Acoustic  
Scanning Tool-  
Visualization  
(CAST-V™)**

All type of  
muds

A high-frequency acoustic transducer to provide a full hole image. A second acoustic transducer is mounted in the scanner housing to measure characteristics of the borehole fluid. A directional sub is provided to orient images. Run primarily in open hole, 200 points horizontally by 40 samples/ft vertically. It is designed to operate in conjunction with other sonic tools but must be run centralized in fluid filled boreholes. Provides structural, stratigraphic, and sedimentological analyses for optimized offset well placement, completion design, and hydrocarbon depletion efficiency, thin bed delineation and improved net pay estimations, 2D and 3D borehole geometry and breakout presentations.

# FMI

---

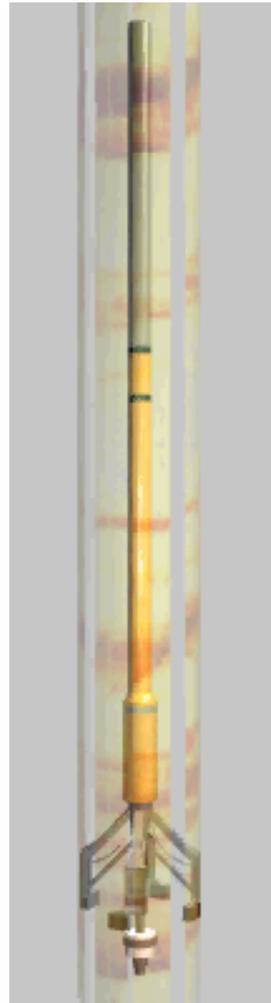
Fullbore Formation MicroImager Log.

# Topics

- Applications
- Tool History
- Current Tool Theory
- Factors Affecting Log Results
- Log Quality
- Tool Setup & Operations
- Tool Maintenance

# Applications

- Azimuthal Micro-Resistivities for dip, bed and fracture analysis
- Dip calculation data is a major input in reservoir modeling and interpretation
- Inclinometry for directional surveys.
- Borehole geometry from calipers.
- Hole volume



# Tool History

- SHDT (Stratagraphic High-Resolution Dipmeter Tool)
- FMS/MEST (Fullbore Micro-Scanner)
- FMI/FBST (Fullbore Scanning Tool)
- OBDT (Oil Based Dipmeter Tool)

# Slim - FMS (MEST-B)



- MEST-B (Above) is the slimhole version of the FMS. Two rows of 8 buttons on 4 pads.
- MEST-B 3 3/8" closing diameter.
- MEST-C 5" closing diameter.
- CTS telemetry.
- Bottom only

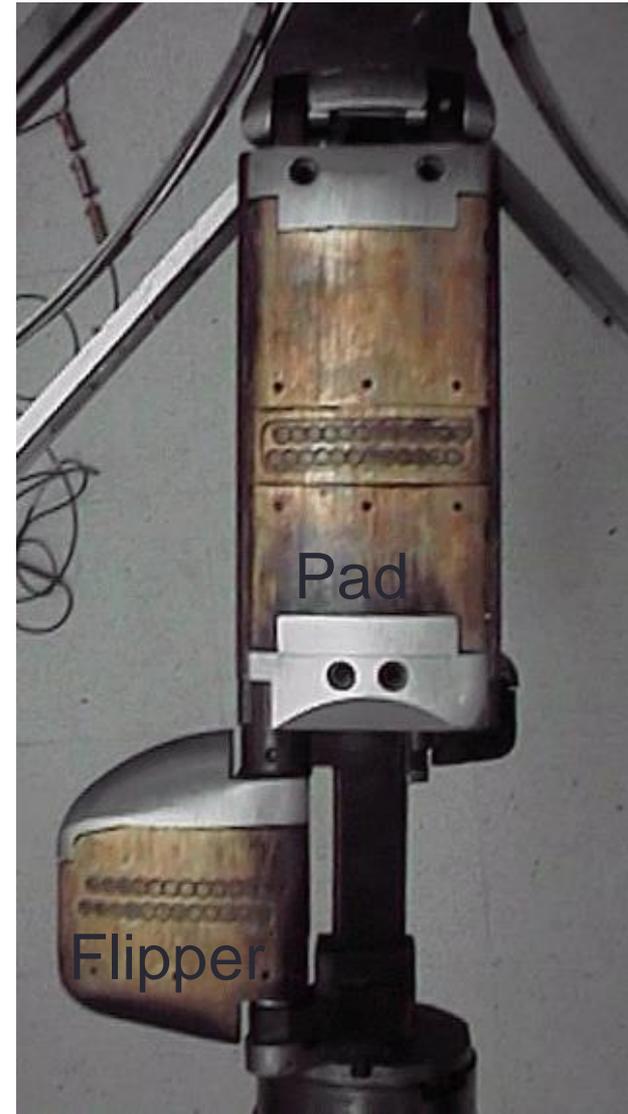
# FMI

- 4 pads, 4 flippers
- DTS telemetry
- 5" closing diameter



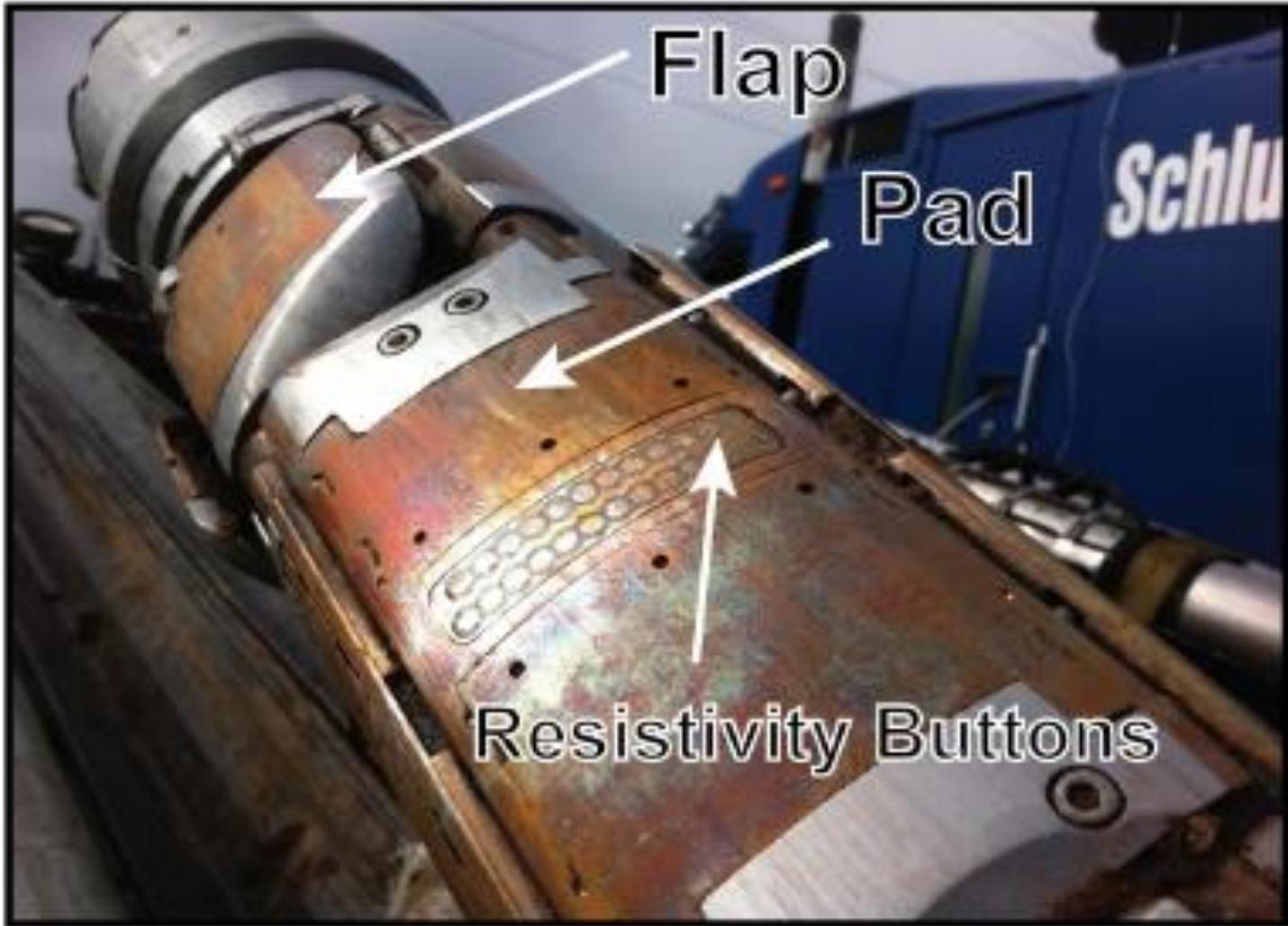
# PADS & FLIPPERS?

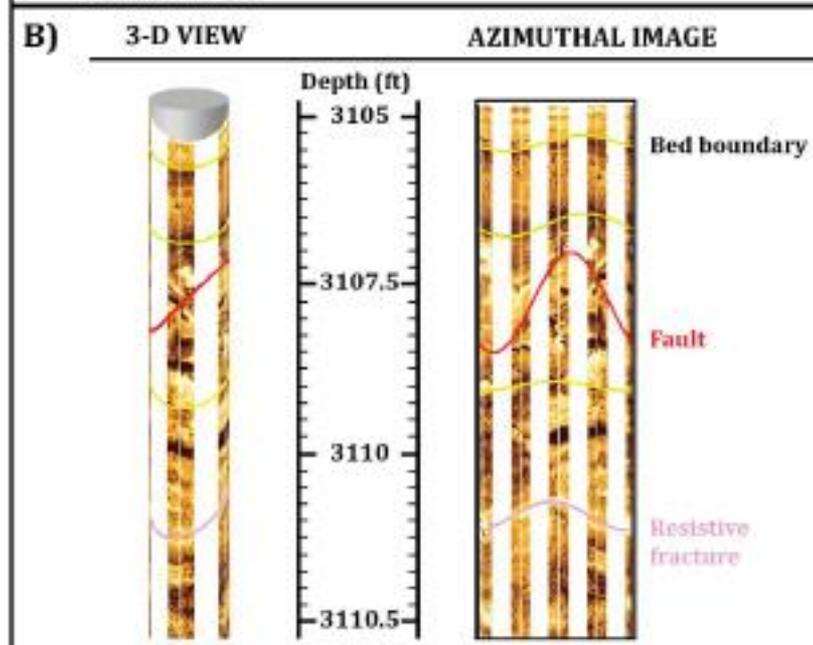
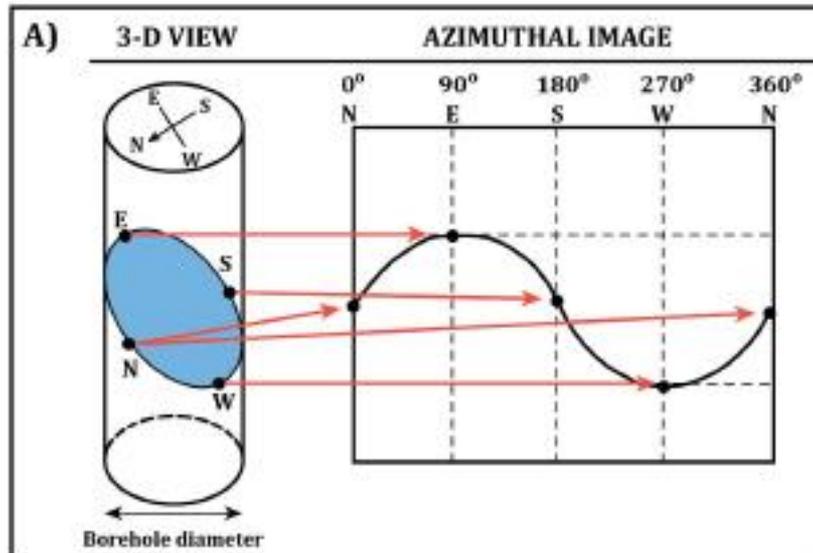
- Pads are connected to the calipers.
- Flippers are hinged to the pads, and are not hydraulically controlled
- Pad pressure can be hydraulically increased.

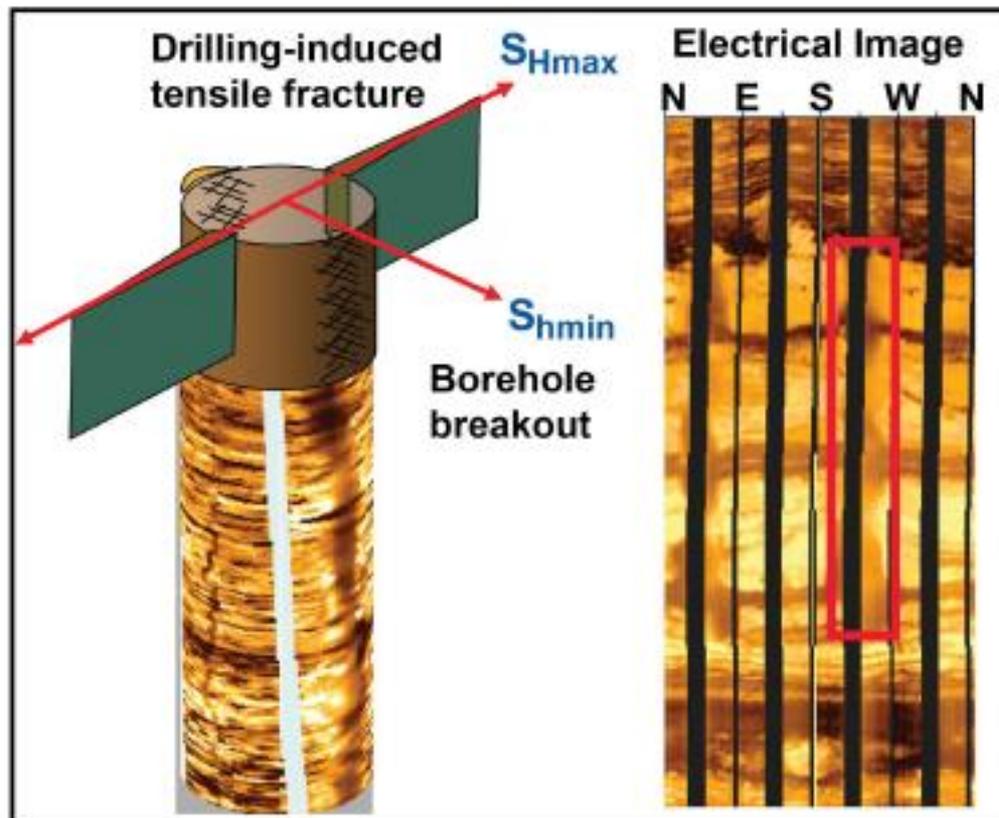


Pad

Flipper.

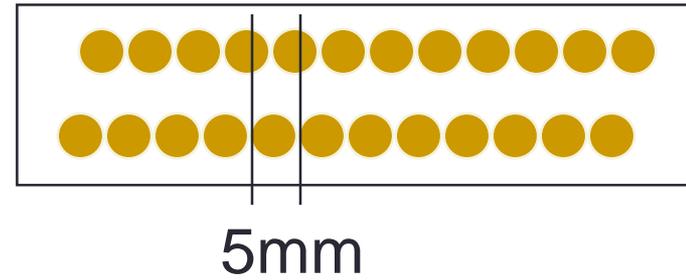






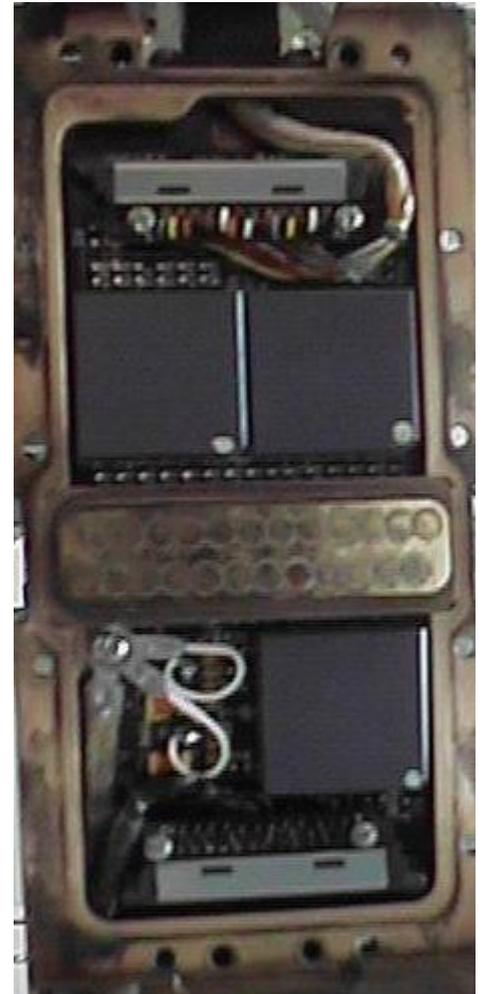
# Resolution

- Samples: 62.5 Hz
- 5mm resolution (Button Size)
- Logging Speed must be less than 1800 fph



# FMI PADs Have Guts Too!

- Button signals are multiplexed at the pads to reduce noise.
- Don't hit them with hammers!

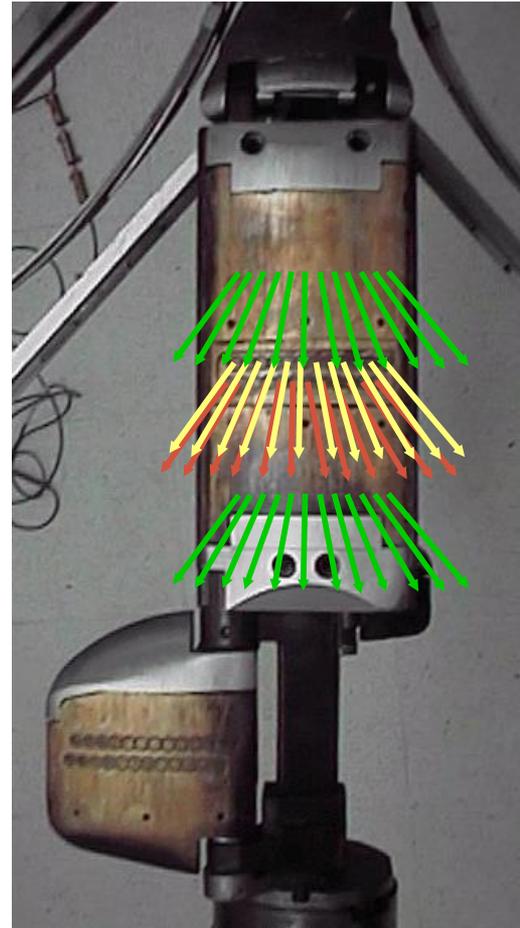
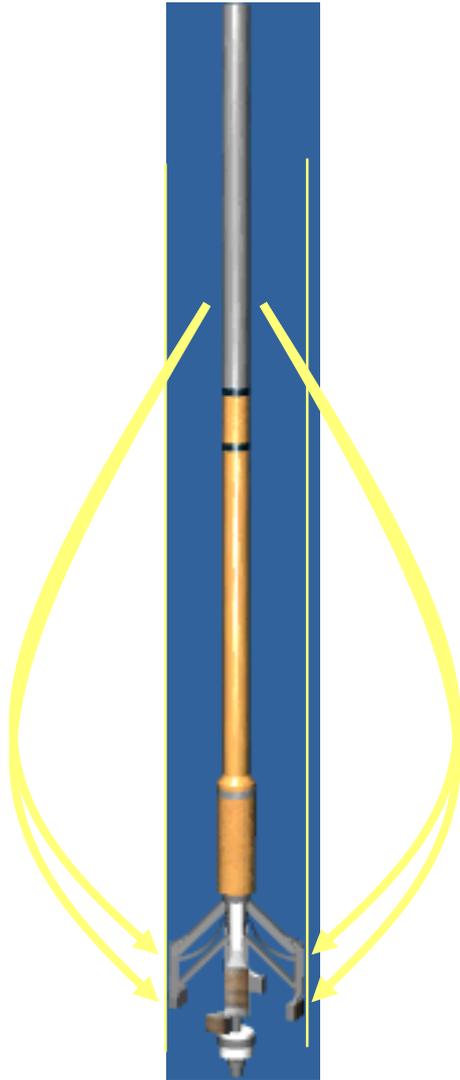


- Uphole power supply
- Phantommed on lines 1 and 4 to tool.
- Magnitude and Gain controlled either automatically (changes with formation) or manually.

# Passive Focusing

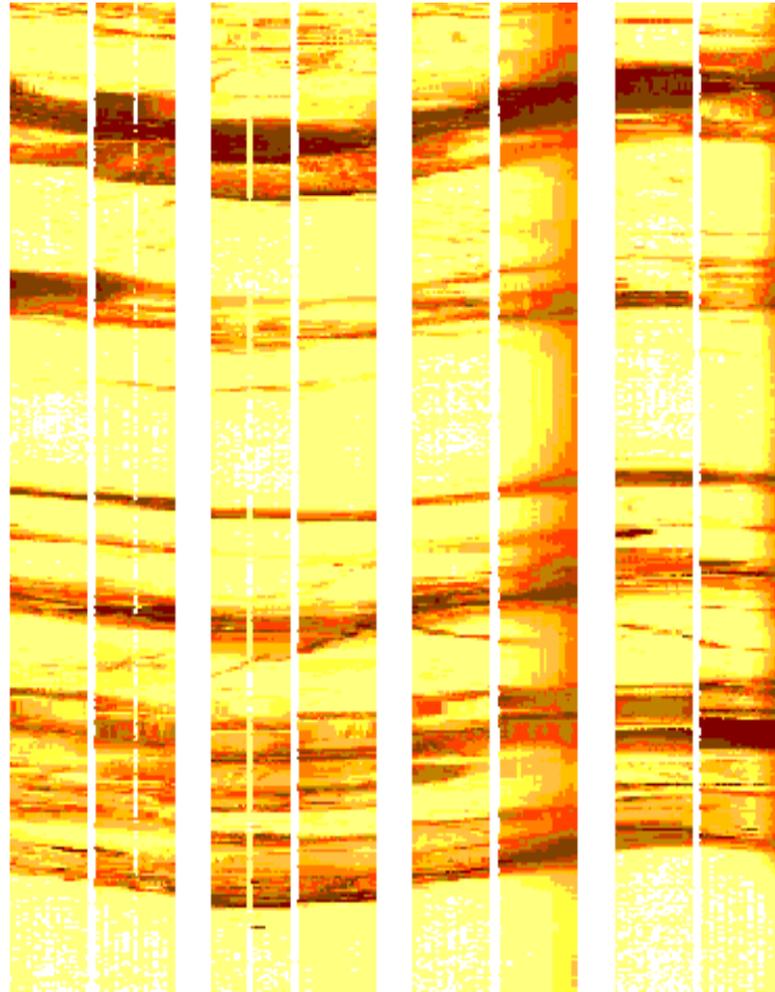
- As opposed to Active Focusing (Dual-Laterolog).
- Simple but has limited functionality.
- Current is emitted from buttons and pads, creating an equipotential surface parallel to the borehole wall. The current returns to the cartridge.

# Passive Focusing

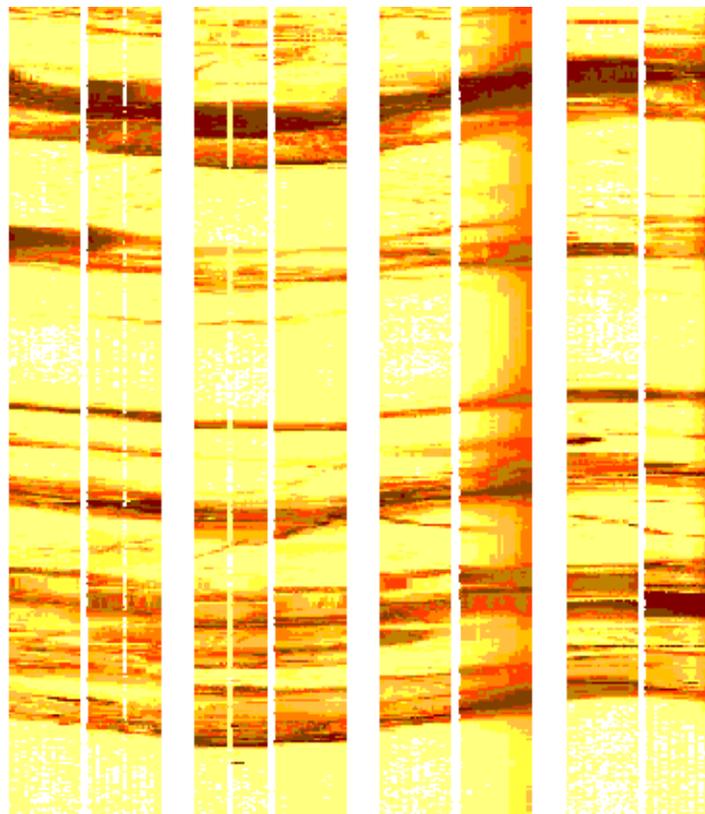


# Dips

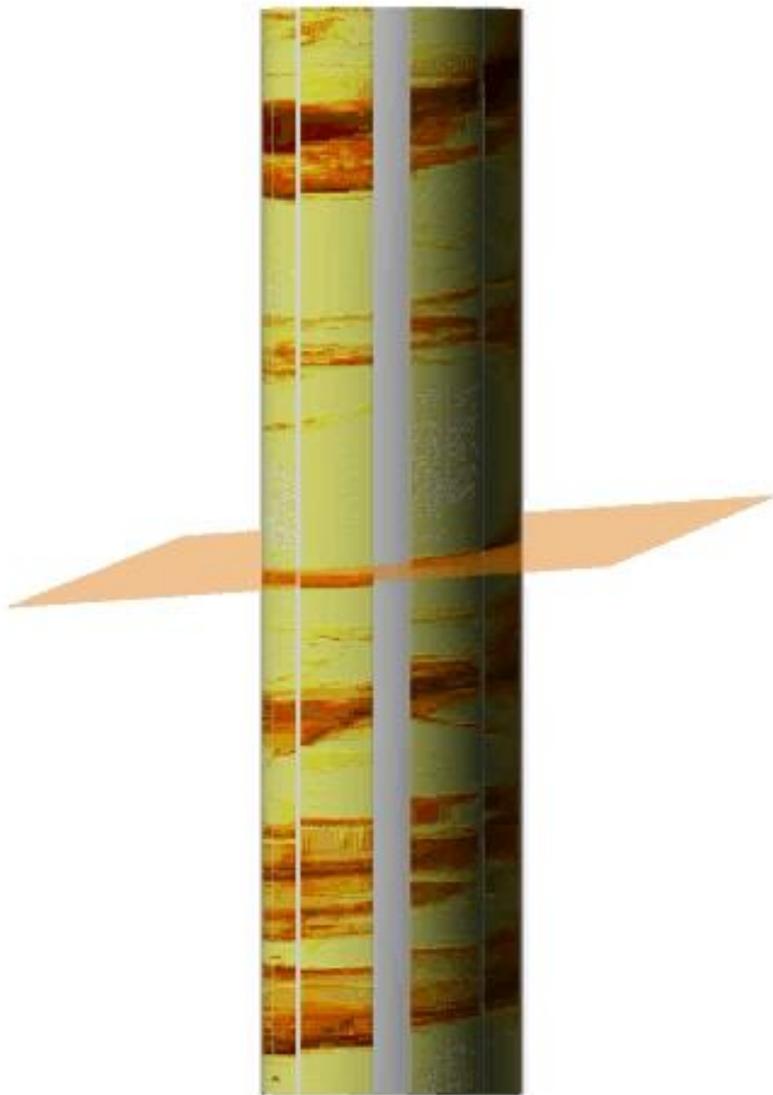
- Dips show up as sinusoidal features on an FMI Image
- Colors represent different micro-resistivities



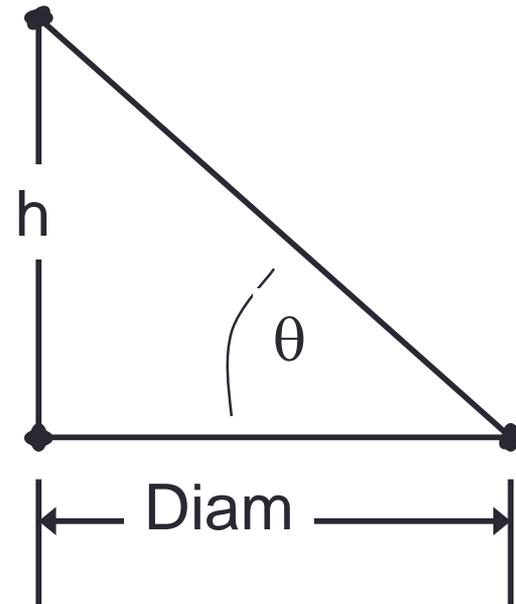
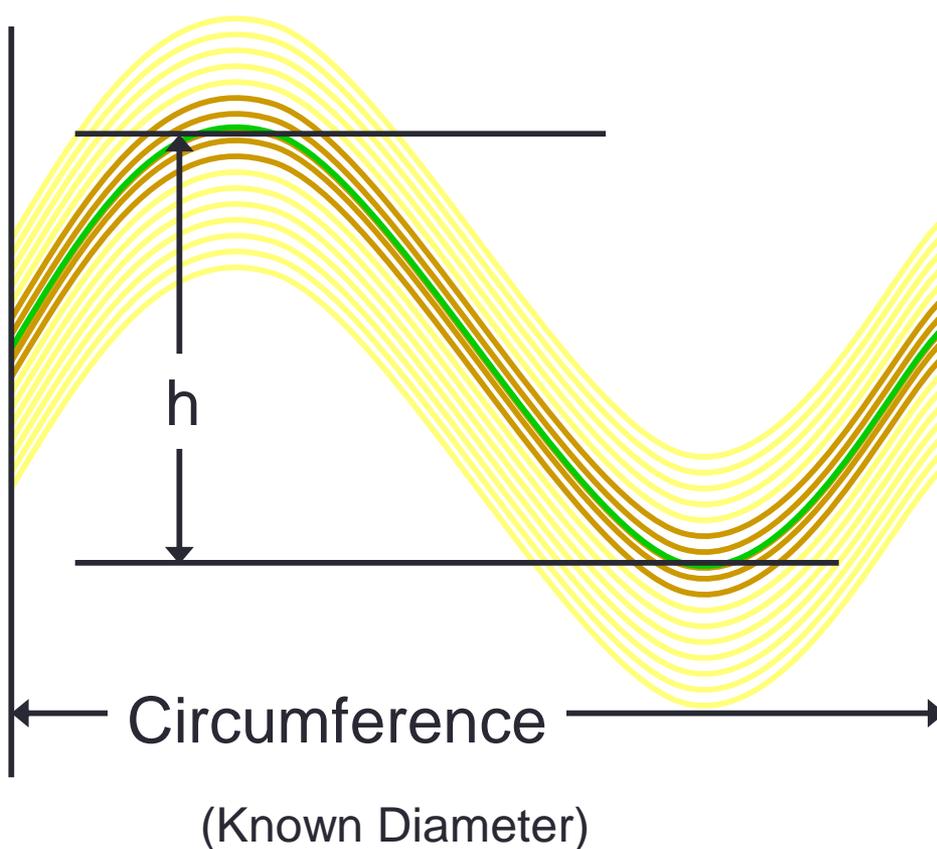
# Dips



# Dips



# Dip Calculation



$$\theta = \text{ATan} ( h / \text{Diam} ) \\ = \text{Dip Angle}$$

- به طور کلی، در نمودارهای تصویری، صفحات لایه بندی و شکستگی هایی که با دیواره چاه برخورد کرده است، به صورت منحنی های سینوسی با رابطه کلی زیر استنباط می شوند

$$y=A \sin(x+B)+C$$

$$A=R \tan \varphi$$

$$B = \frac{\pi}{2} - \beta$$

- $R$  شعاع چاه،  $\varphi$  شیب،  $\beta$  آزیموت و  $C$  موقعیت منحنی سینوسی در تصویر است. صفحات لایه بندی، اغلب دارای شیب و امتداد کم و بیش ثابت بوده و شیب آنها کمتر از ۴۵ درجه می باشد.

# Geographic Features



# Tool Rotation

- Since the tool will rotate during the log, we must know “HOW” it is rotating.
- If we don't know the rotational position of the dipmeter tool, then we will not know which direction the dip is.

# With Orientation

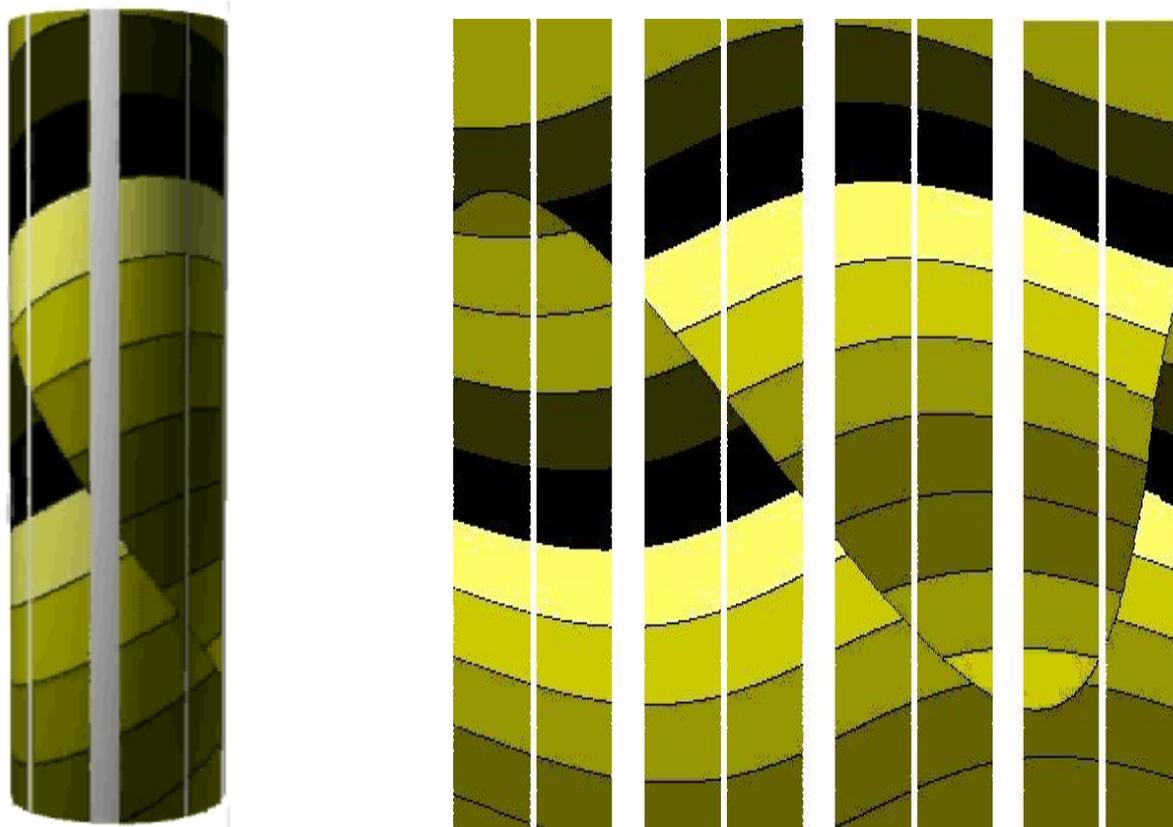


N

S

N

# No Orientation

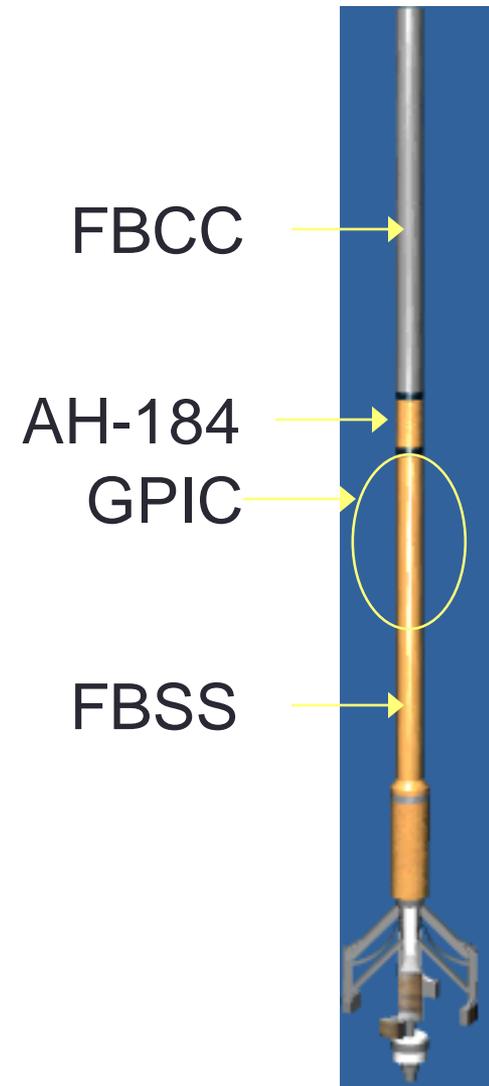


# Inclinometry

- “Where” the data came from is as important as the data itself.
  - Images can be oriented with respect to North or to the top of the borehole.
- Compare it to taking a core or sample but not knowing what depth it came from.
- For this reason, an inclinometry tool is required: GPIT

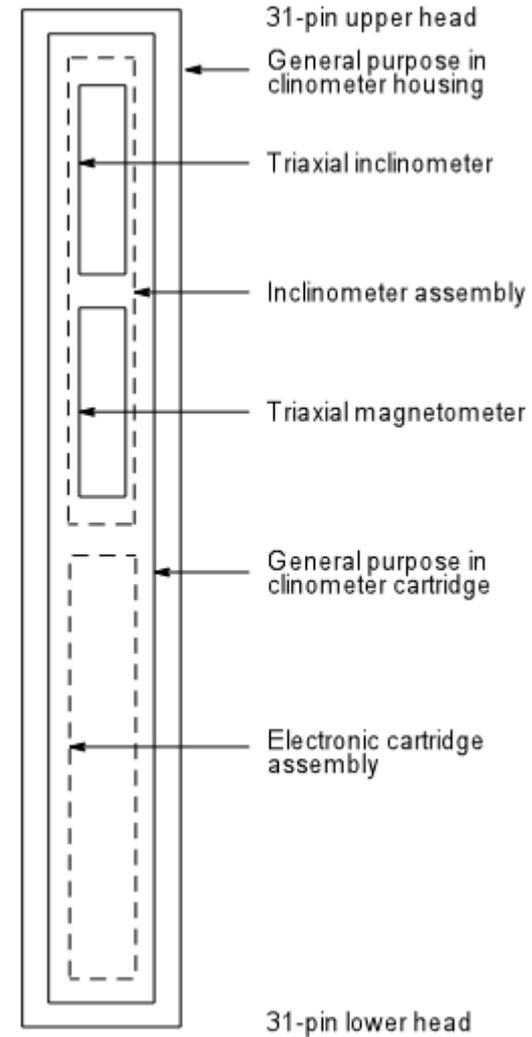
# Inclinometry, GPIT

- The GPIT is located inside the FMI sonde (FBSS).
- It can be removed and placed into its own housing.



# GPIT Block Diagram

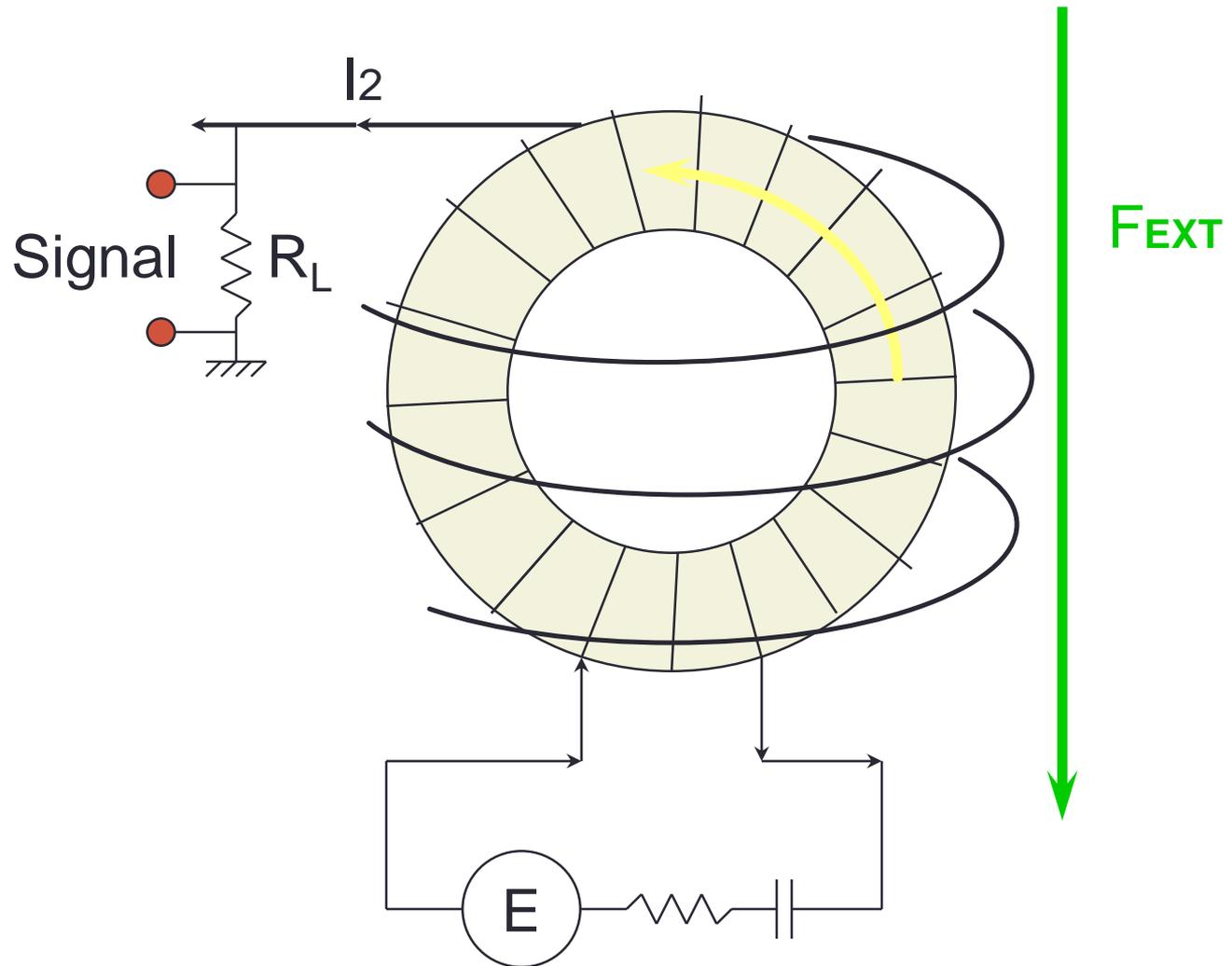
- GPIC-AC : DTB
- GPIC-C : FTB



# Magnetic Field Strength

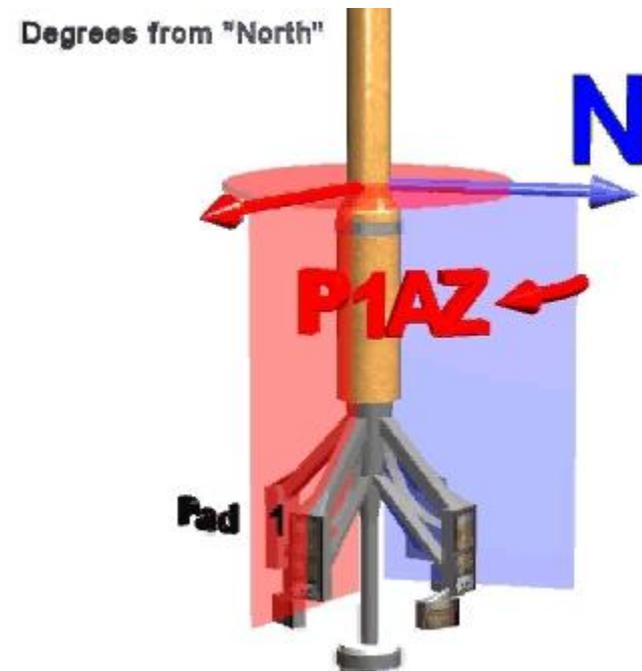
- A Triaxial magnetometer (three single axis magnetometers) are used to determine the rotational position of the tool, relative to the Earth's magnetic field. (Magnetic North)
- $F_{\text{NOR}} = \sqrt{F_X^2 + F_Y^2 + F_Z^2}$
- $F_{\text{NOR}} =$  Depends on where you are.

# Flux Gate Magnetometer



# Inclinometry, P1AZ

- Pad 1 Azimuth
- Degrees from Magnetic north on a horizontal plane.
- I.e.: P1AZ = 180 means Pad 1 is south.

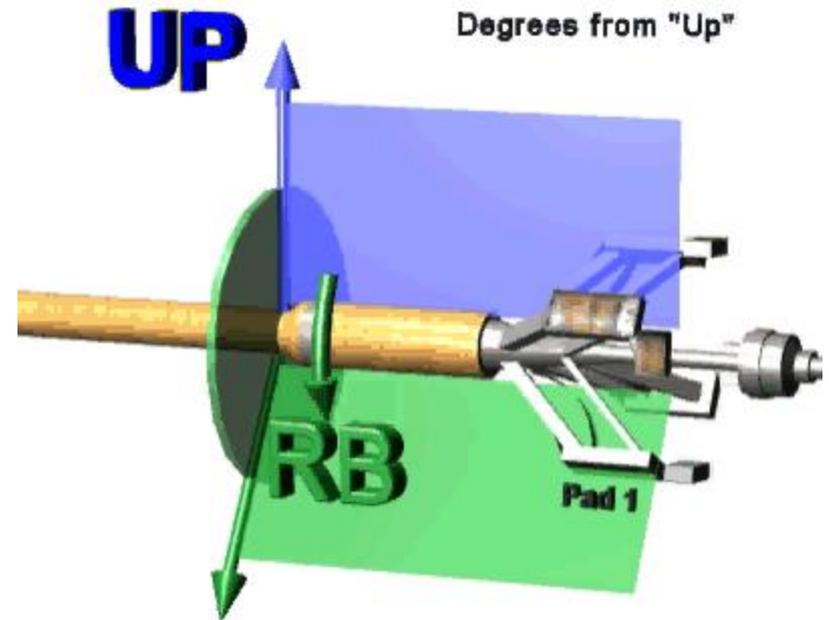


# Longitude / Latitude

- LATD: Latitude (in degrees)
- LOND: Longitude (in degrees)

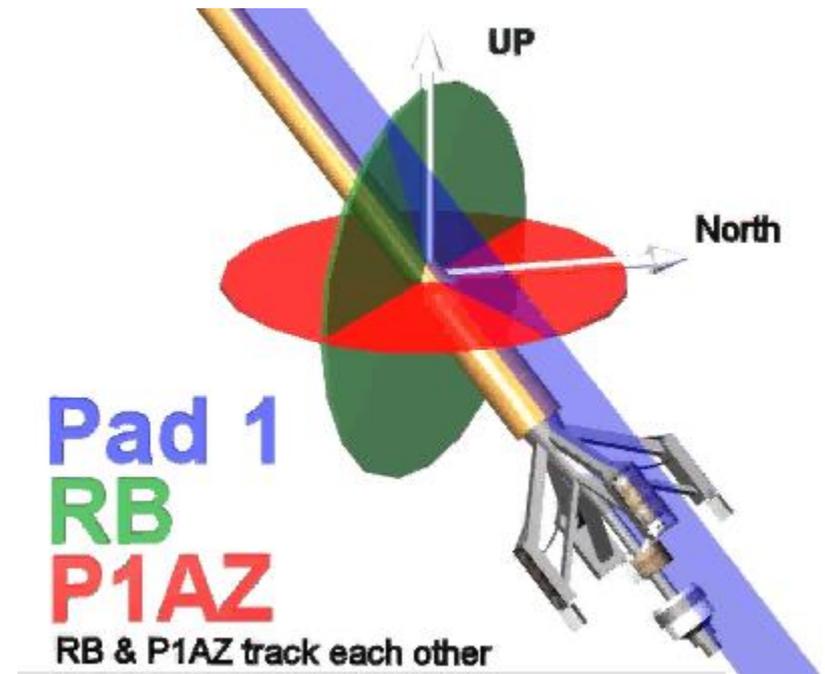
# Inclinometry, RB

- Relative Bearing
- Degrees from "UP" on a vertical plane
- i.e. RB = 180 means Pad 1 is down.



# Inclinometry, Deviated Well

- Relative Bearing & P1AZ Track each other
- In deviated wells, both can be used to orient images



# Inclinometry

- HAZI
  - Direction the hole is travelling (N,S,E,W)
- DEVI
  - Deviation of the hole (From Vertical)
  - i.e.:
    - Vertical well = 0 deg deviated
    - Horizontal well = 90 deg deviated

# Worst Case

- In the event of the failure of one (**and only one**) of the GPIT accelerometer in the Ax or Ay or magnetometer channels, the job can still be rescued in a computing center. If the accelerometer along the z-axis fails, speed correction can no longer be performed.

# Repeatability

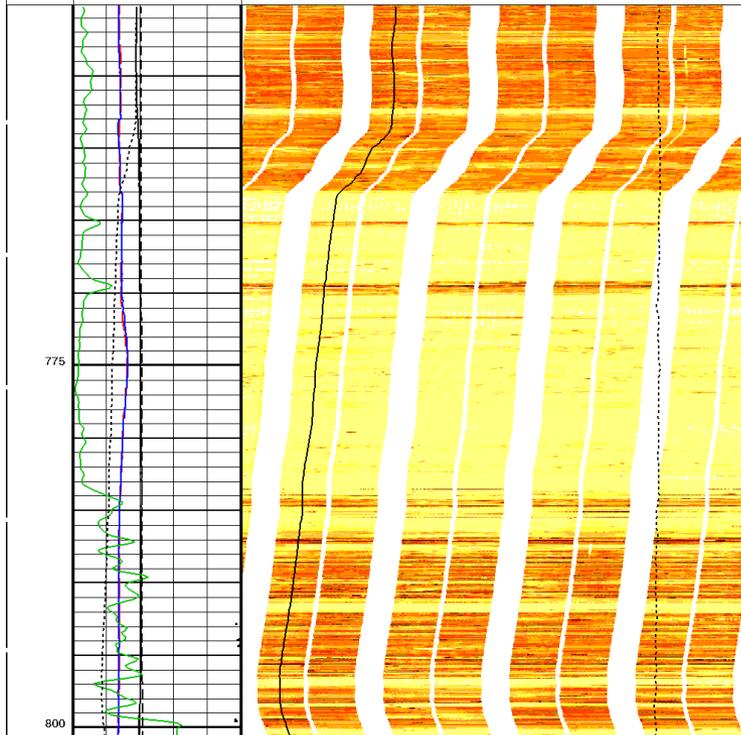
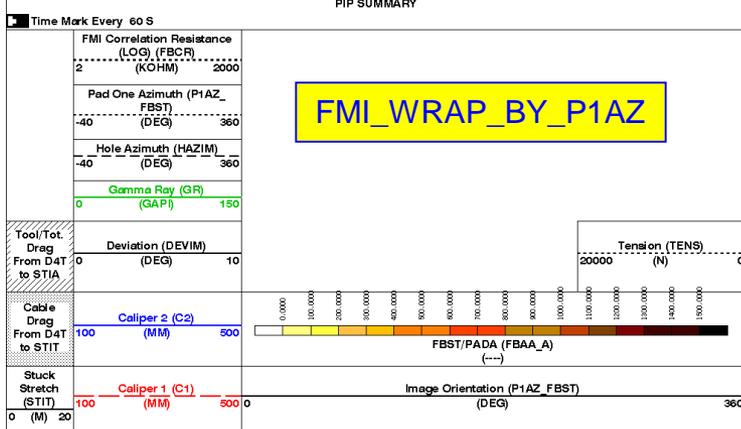
- AZIM  $\pm 2^\circ$
- DEVI  $\pm 0.2^\circ$
- CALI  $\pm 0.25$  in.

| Input DLIS Files  |            |       |          |                   |                 |
|-------------------|------------|-------|----------|-------------------|-----------------|
| DEFAULT           | FBSTA .033 | FN:50 | PRODUCER | 19-Oct-2000 19:26 | 809.5 M 497.5 M |
| Output DLIS Files |            |       |          |                   |                 |
| DEFAULT           | FBSTA .015 | FN:14 | PRODUCER | 24-Oct-2000 18:58 | 809.5 M 750.1 M |

**OP System Version: 9C1-303**  
MCM

|        |           |       |           |
|--------|-----------|-------|-----------|
| FBST-A | OP91-kp2  | DTA-A | OP91-KP1a |
| SGT-N  | OP91-KP1a | DTC-H | OP91-KP1a |

PIP SUMMARY

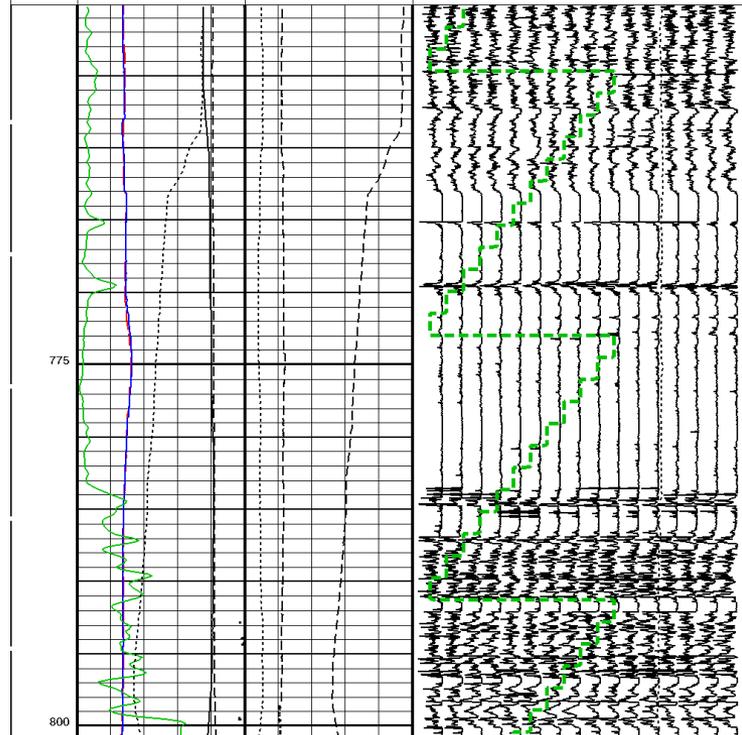
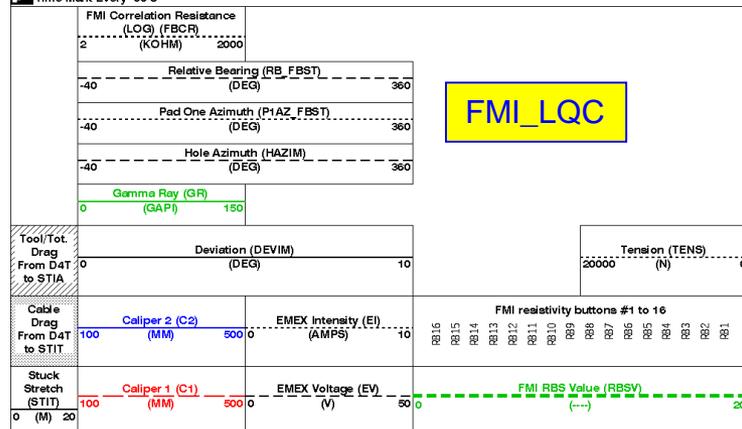


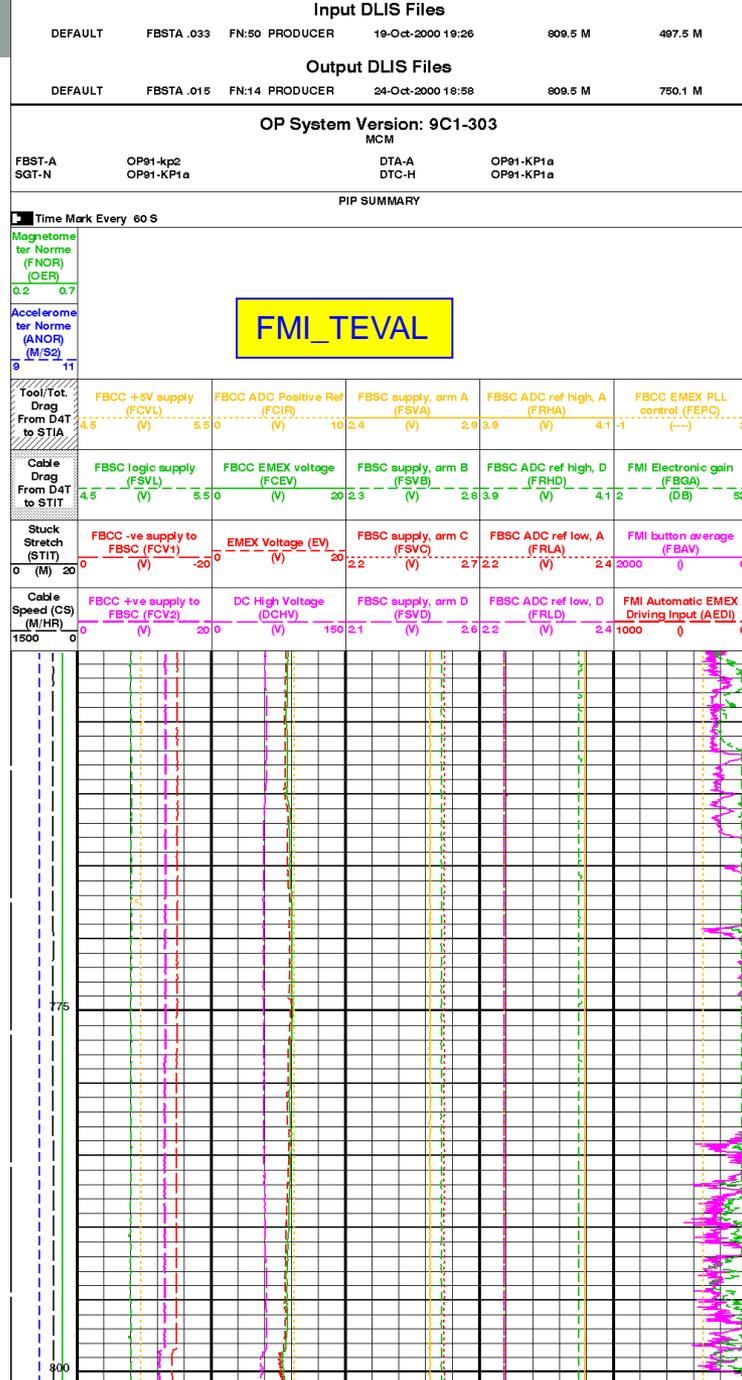
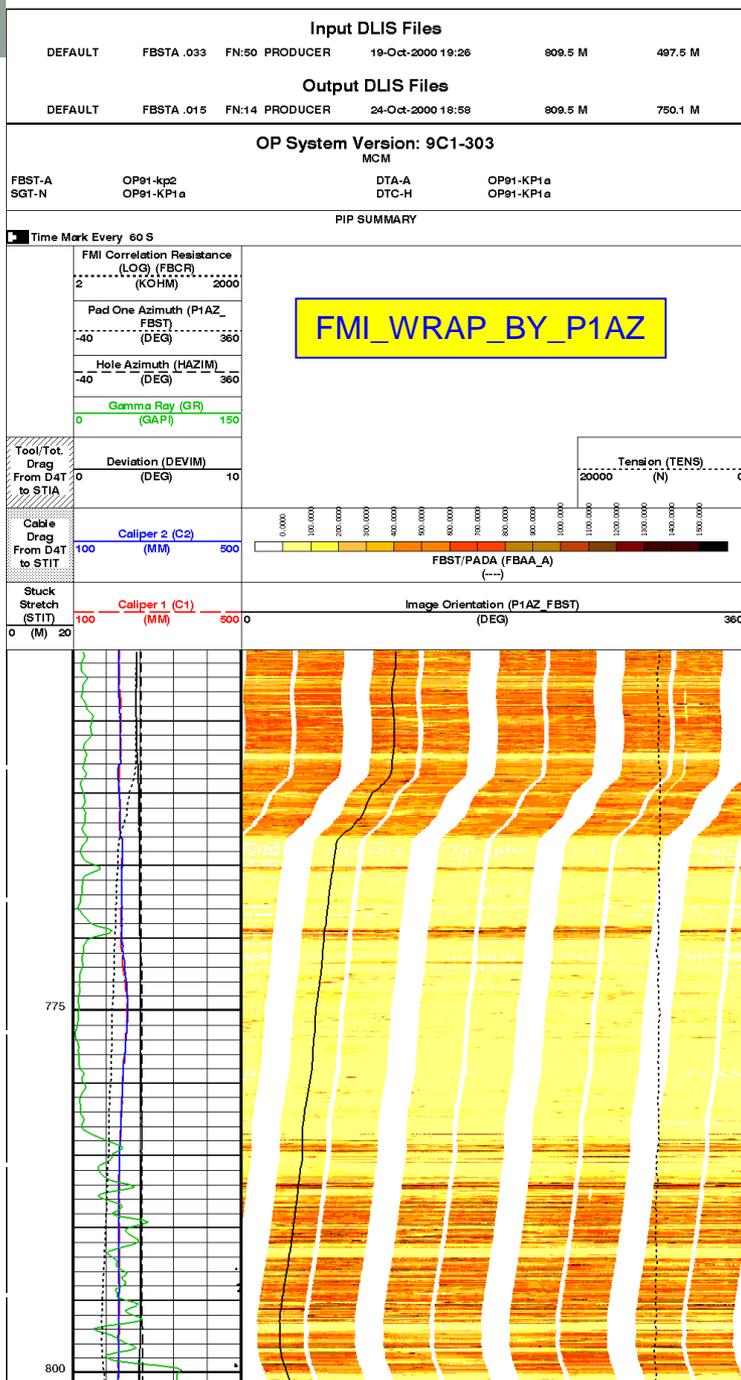
| Input DLIS Files  |            |       |          |                   |                 |
|-------------------|------------|-------|----------|-------------------|-----------------|
| DEFAULT           | FBSTA .033 | FN:50 | PRODUCER | 19-Oct-2000 19:26 | 809.5 M 497.5 M |
| Output DLIS Files |            |       |          |                   |                 |
| DEFAULT           | FBSTA .015 | FN:14 | PRODUCER | 24-Oct-2000 18:58 | 809.5 M 750.1 M |

**OP System Version: 9C1-303**  
MCM

|        |           |       |           |
|--------|-----------|-------|-----------|
| FBST-A | OP91-kp2  | DTA-A | OP91-KP1a |
| SGT-N  | OP91-KP1a | DTC-H | OP91-KP1a |

PIP SUMMARY





**Input DLIS Files**

DEFAULT FBSTA .033 FN:50 PRODUCER 19-Oct-2000 19:26 809.5 M 487.5 M

**Output DLIS Files**

DEFAULT FBSTA .015 FN:14 PRODUCER 24-Oct-2000 18:58 809.5 M 750.1 M

**OP System Version: 9C1-303**

MCM

FBST-A OP91-kp2 DTA-A OP91-KP1a  
 SGT-N OP91-KP1a DTC-H OP91-KP1a

**PIP SUMMARY**

Time Mark Every 60 S

FMI Correlation Resistance  
 (LOC) (FBCR)  
 (KOHM) 2000

Pad One Azimuth (P1AZ\_  
 FBST)  
 (DEG) 360

Hole Azimuth (HAZIM)  
 (DEG) 360

Gamma Ray (GR)  
 (GAP) 150

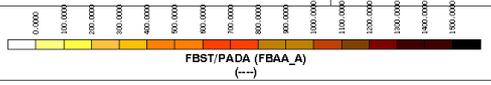
Tool/Tot.  
 Drag  
 From DAT  
 to STIA 0

Deviation (DEVIM)  
 (DEG) 10

Tension (TENS)  
 (N) 20000 0

Cable  
 Drag  
 From DAT  
 to STIT 100

Caliper 2 (C2)  
 (MM) 500

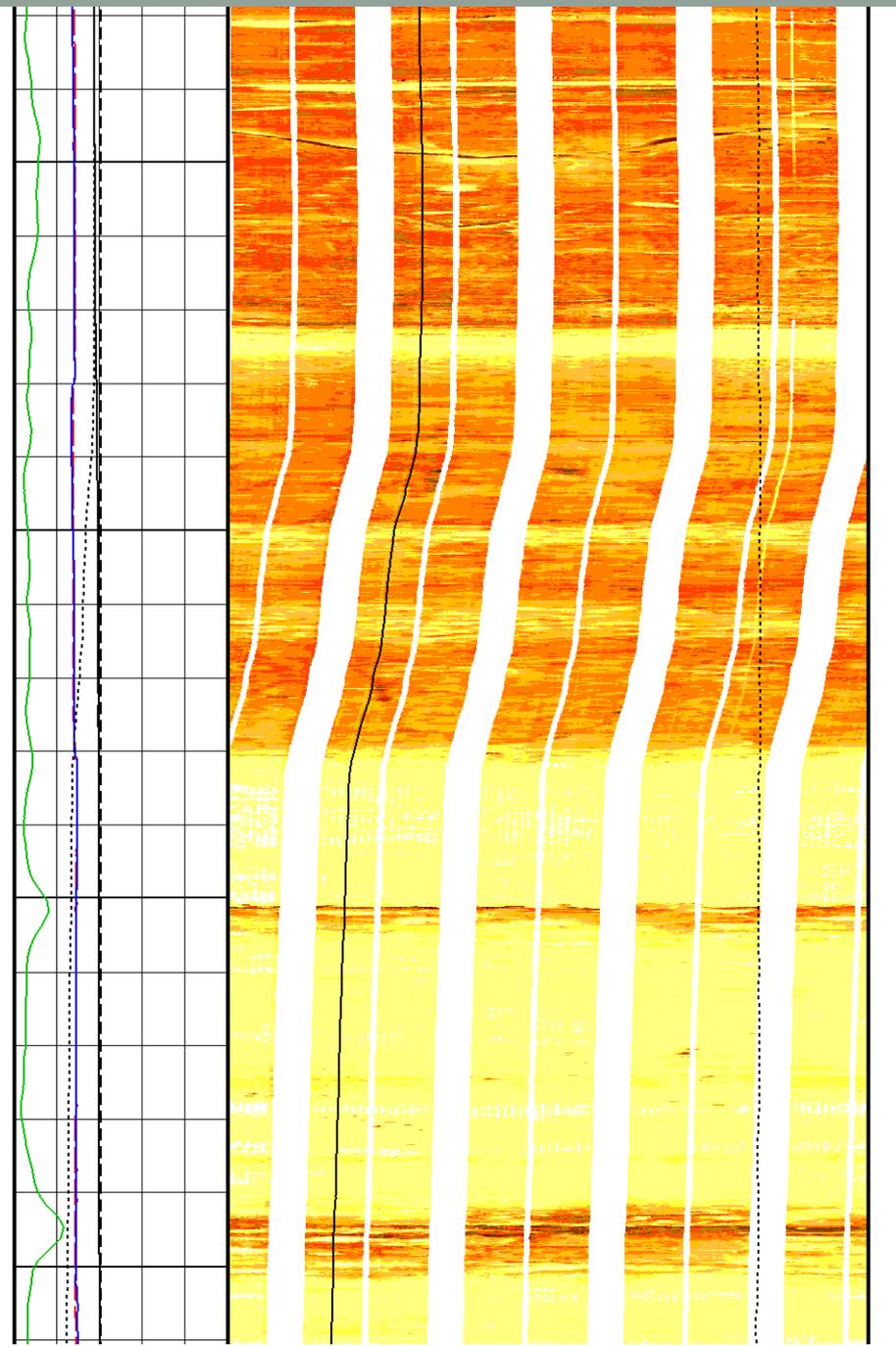
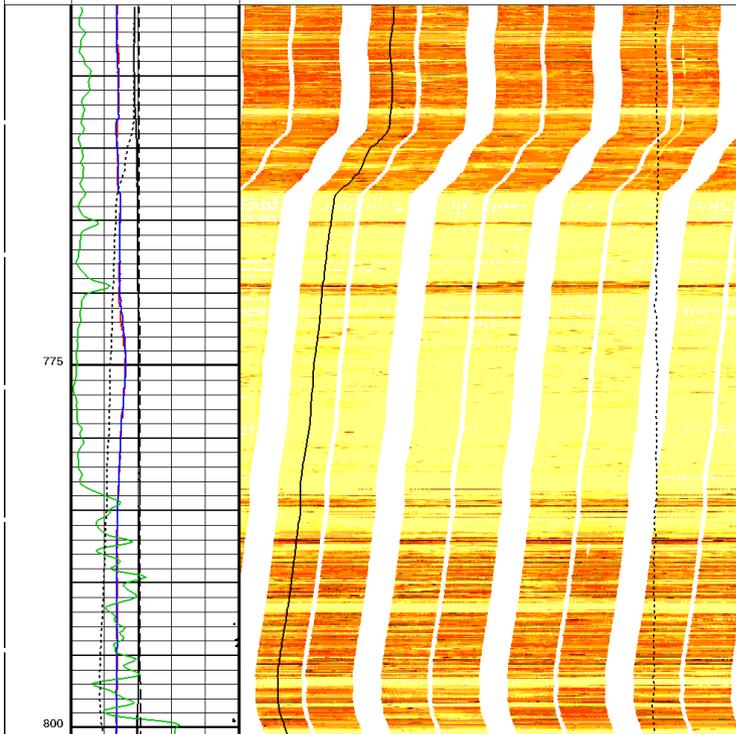


Stuck  
 Stretch  
 (STIT) 0

Caliper 1 (C1)  
 (MM) 500

Image Orientation (P1AZ\_FBST)  
 (DEG) 360

FMI\_WRAP\_BY\_P1AZ



- To visualize the image logs, two different types of color normalization are done on the data; Static and Dynamic normalization
- Static normalized images have the same color scaling over the entire logged interval and thus show large-scale resistivity variations related to lithology changes and structural events (faults, fractures unconformities, etc...). Dynamic normalized images are color scaled on a 2- ft-sliding window, thus maximizing rock fabric detail (texture) and bedding information.n.

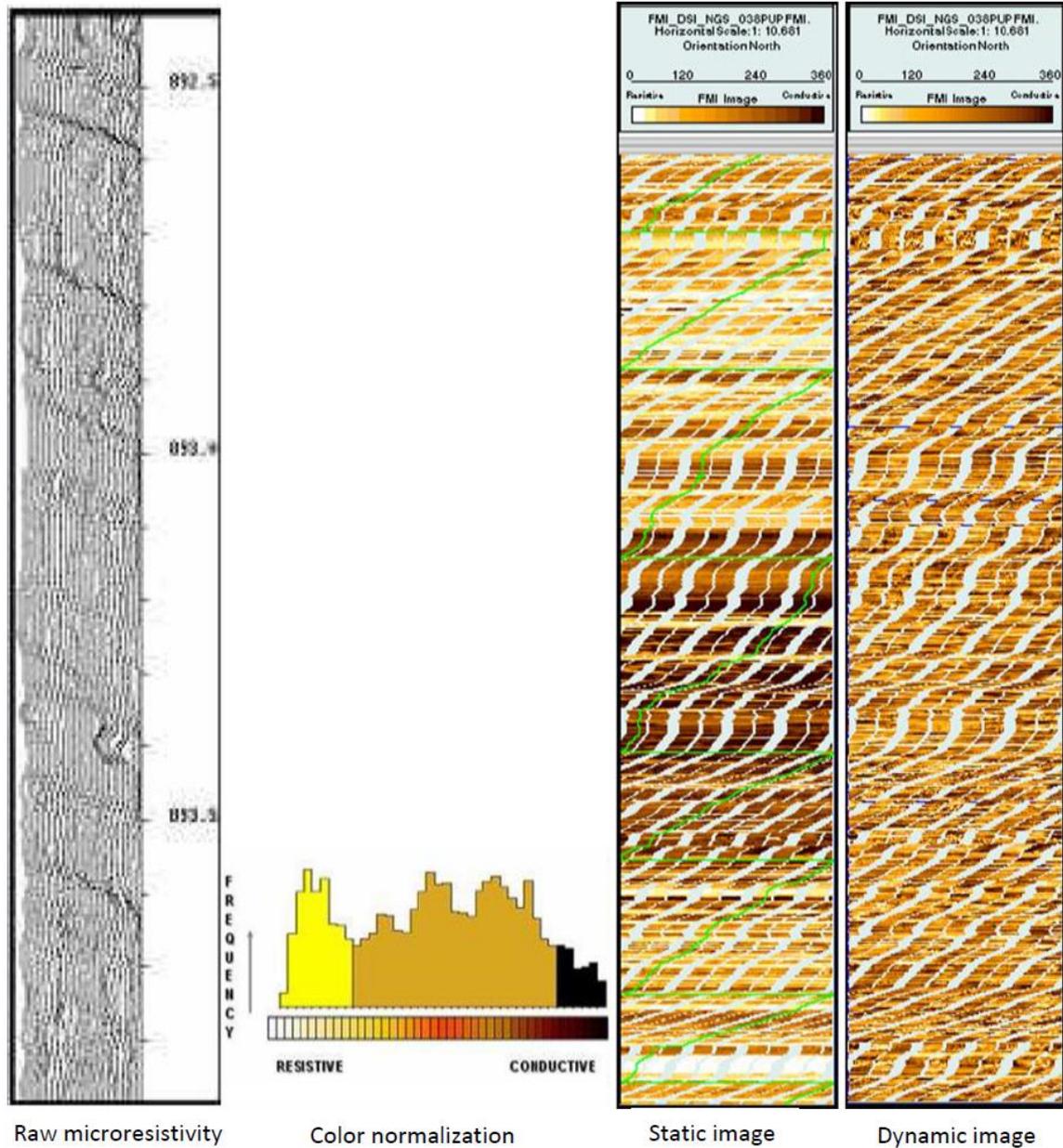


Figure 9. FMI log data from raw to static and dynamic normalized images, (Schlumberger)

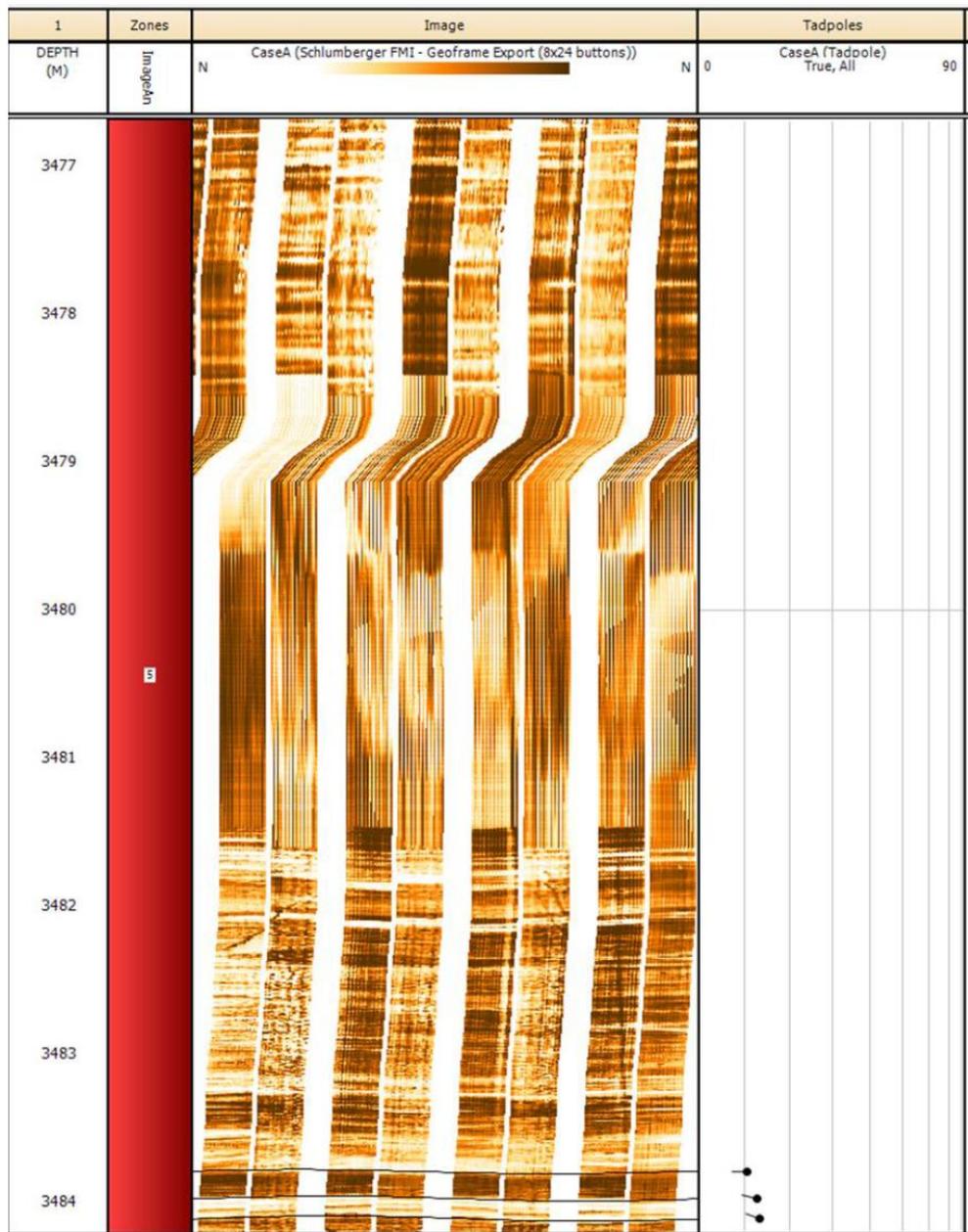
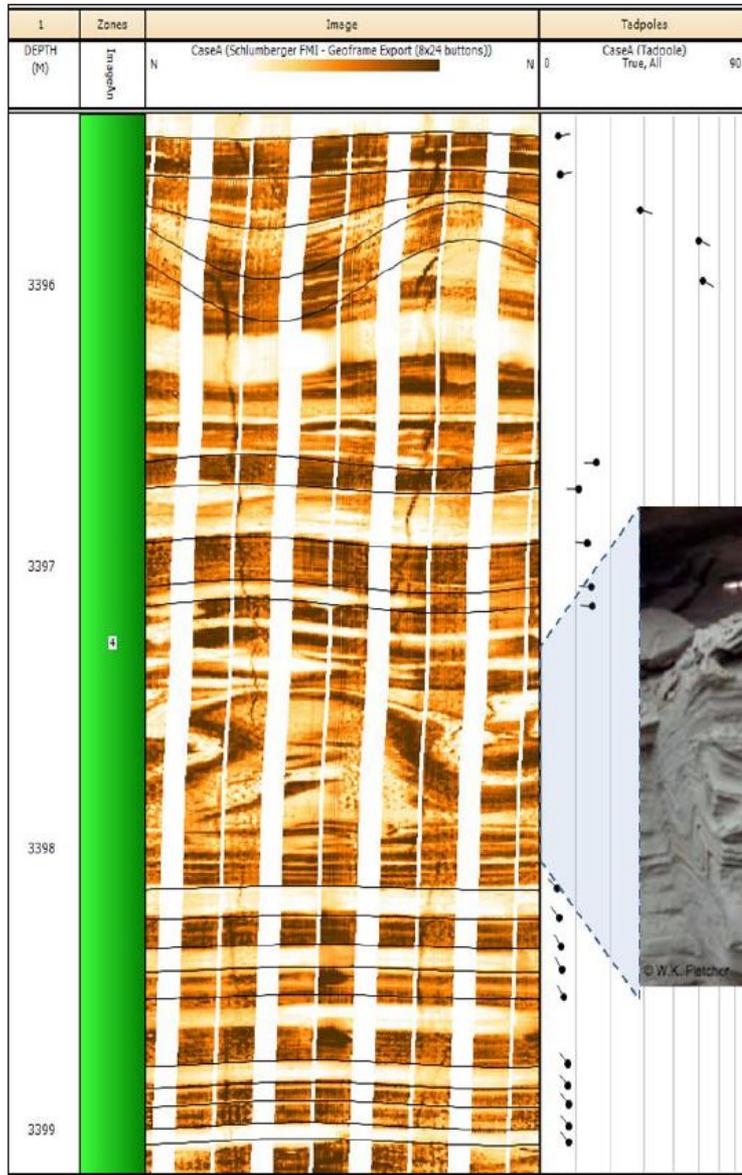
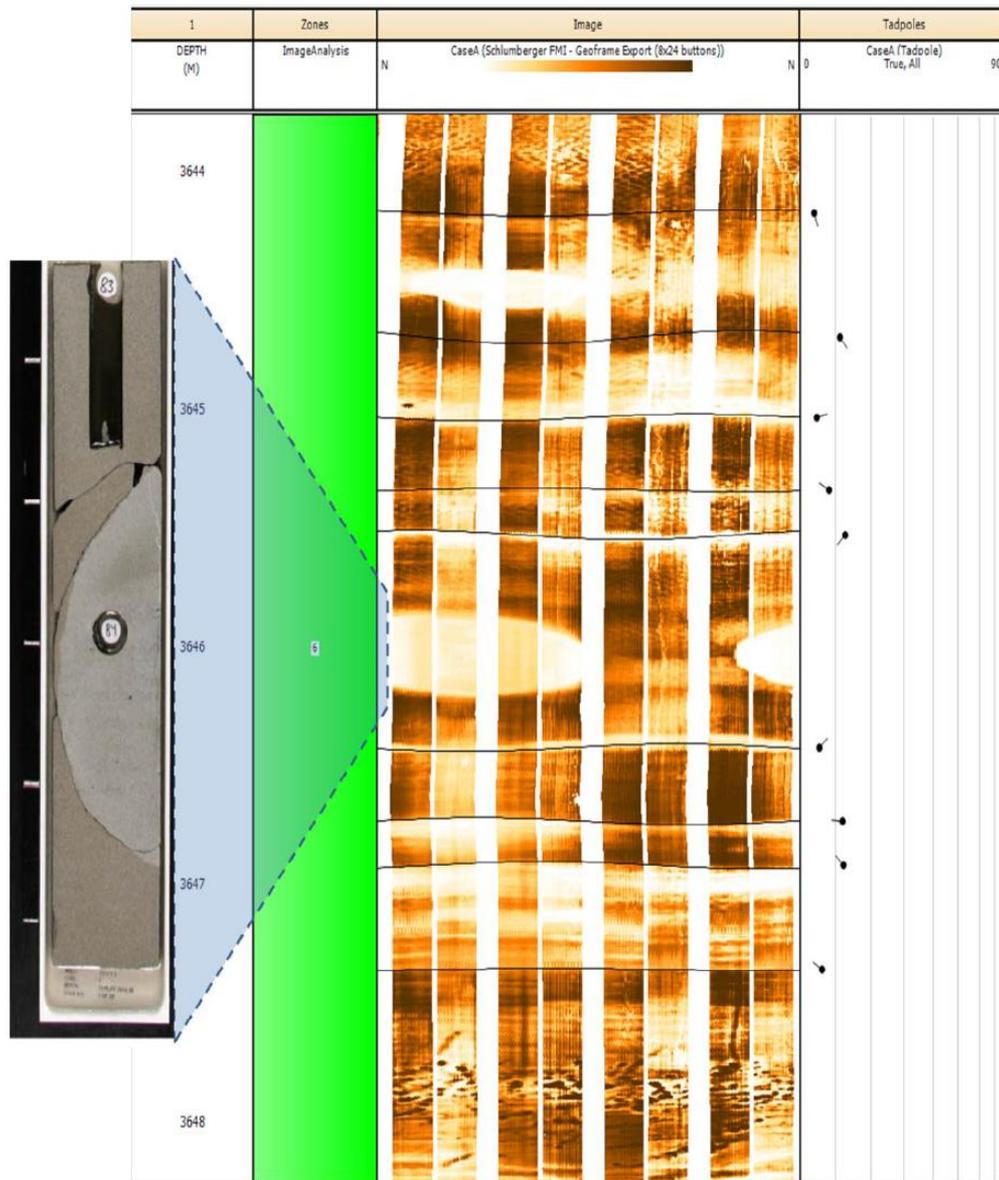


Figure 14. Bad hole image data due to tool stuck and release over the 3 meter interval. (Scale 1/20)



**Figure 15. Deformation of soft sediment leading to convolute bedding (slump), suggesting intense structural deformation of the turbidity flow deposits. (Slump photo from GEOL342: Sedimentation and Stratigraphy Spring 2013). (Image log scale 1/20)**



**Figure 19. FMI image log with calcite cemented nodule. Image log shows that the nodule has not been detected by all image tool pads as can also be seen in the core photo. Note the possible bioturbation pattern in the bottom of the image log. (Core photo unit is 10cm and image log scale 1/20)**

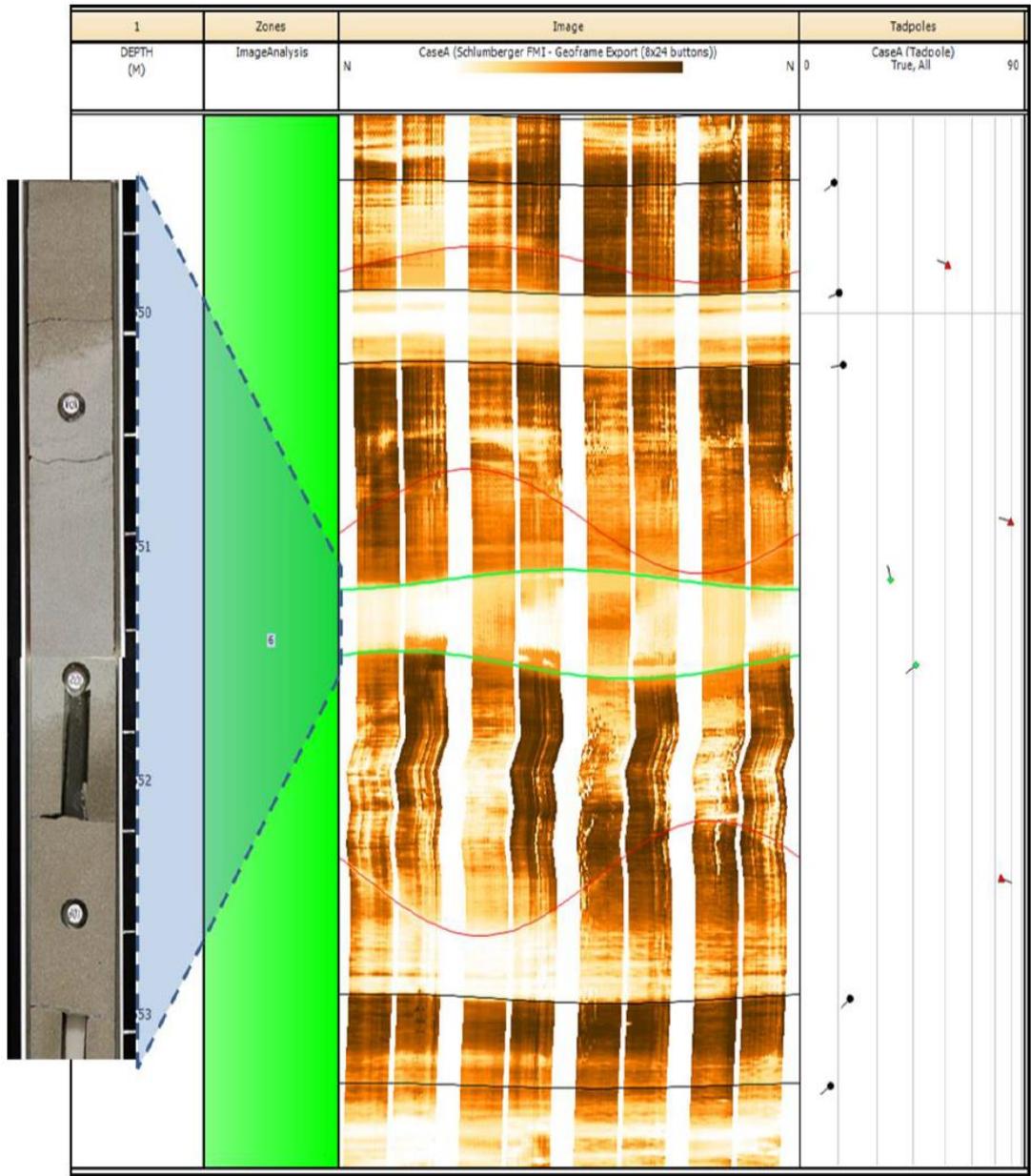


Figure 20. FMI image log with three conductive fractures and one diffusive calcite cemented zone. (Core photo unit is 10cm and image log scale 1/20)

3637.5m

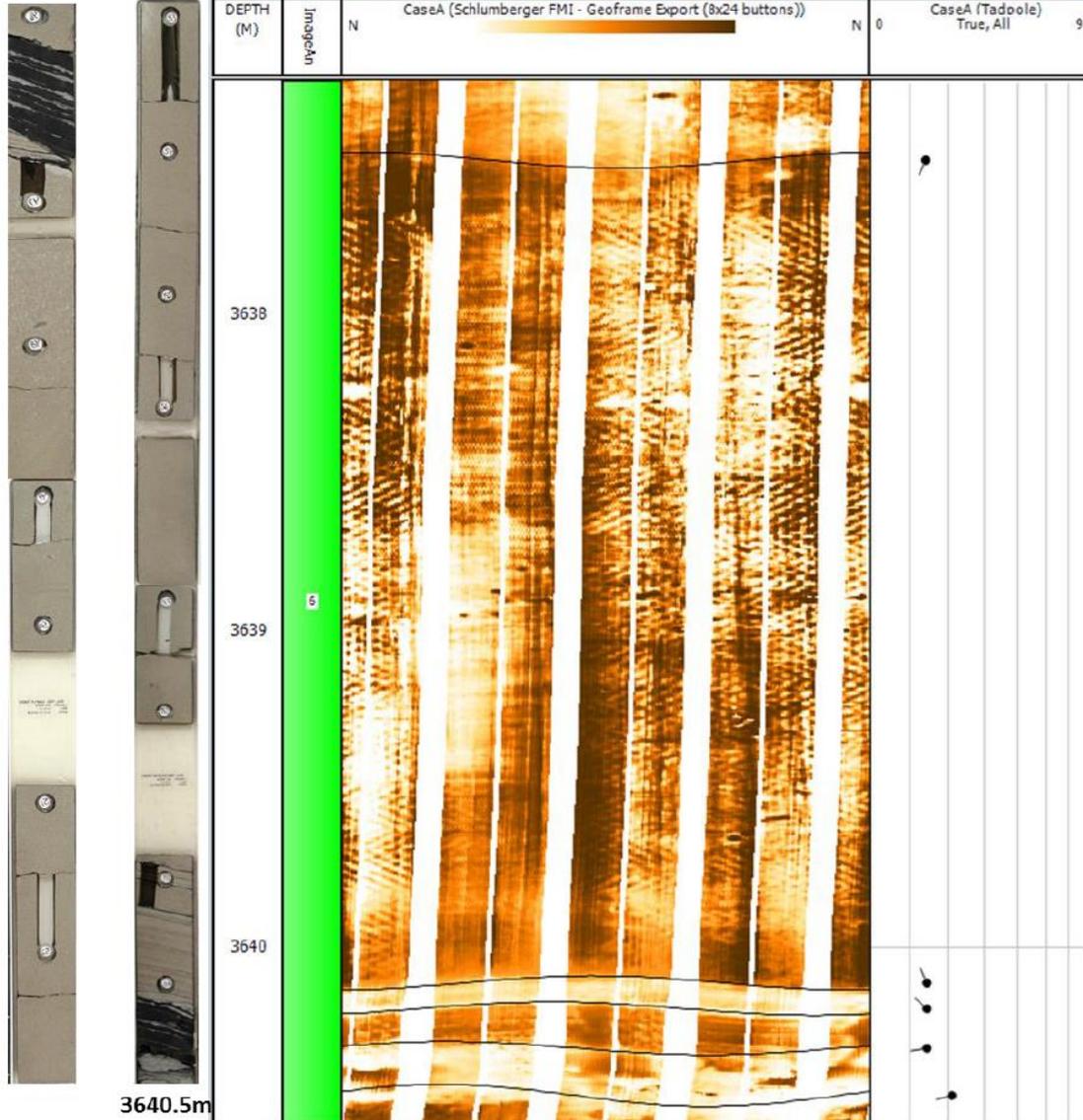


Figure 21. FMI image of 2.5m thick homogeneous sandstone layer without identifiable dip angle/azimuth in the sand. Few resistive mixtures of tight shales and calcite cement are identified at the top and bottom of the interval. (Every core column is 1.5m and image log scale is 1/20)

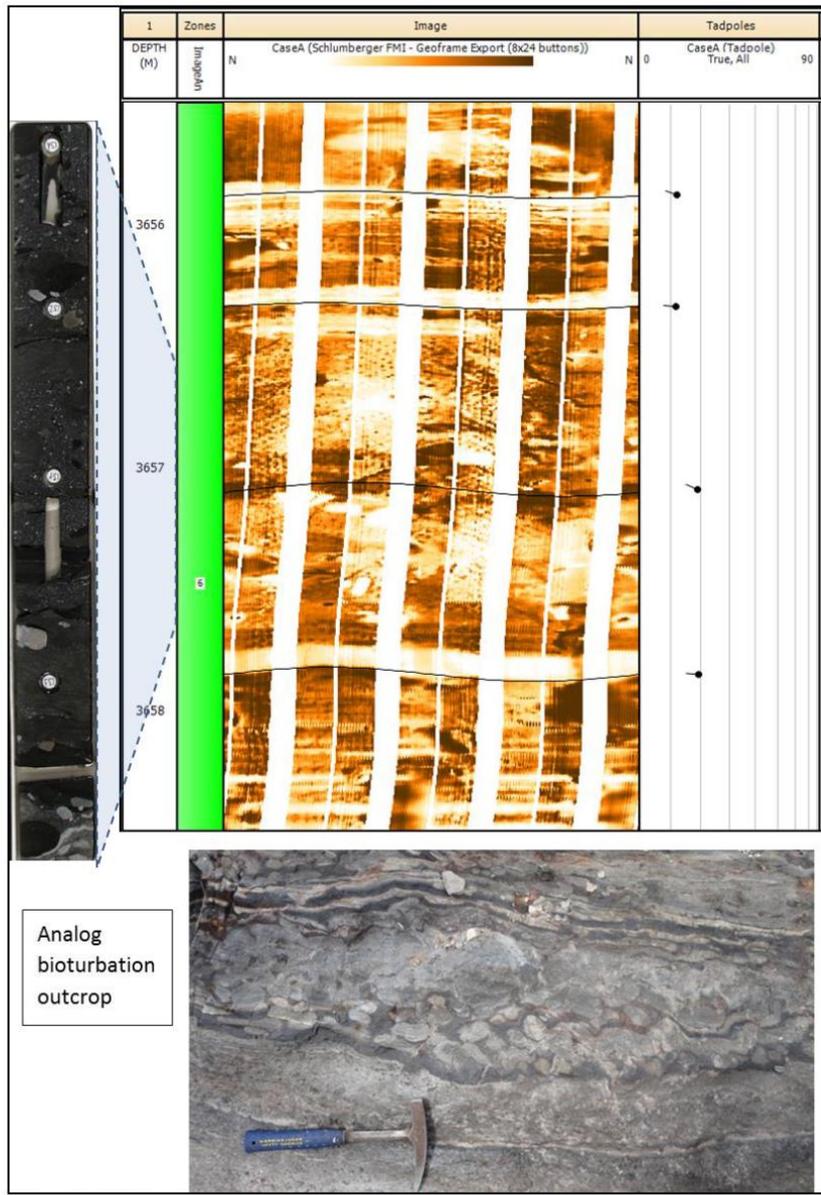


Figure 22. FMI image log of bioturbated zone with core photo of the zone. An analog outcrop of bioturbation is shown below the figure. (Core scale is 1m and image log scale is 1/20)

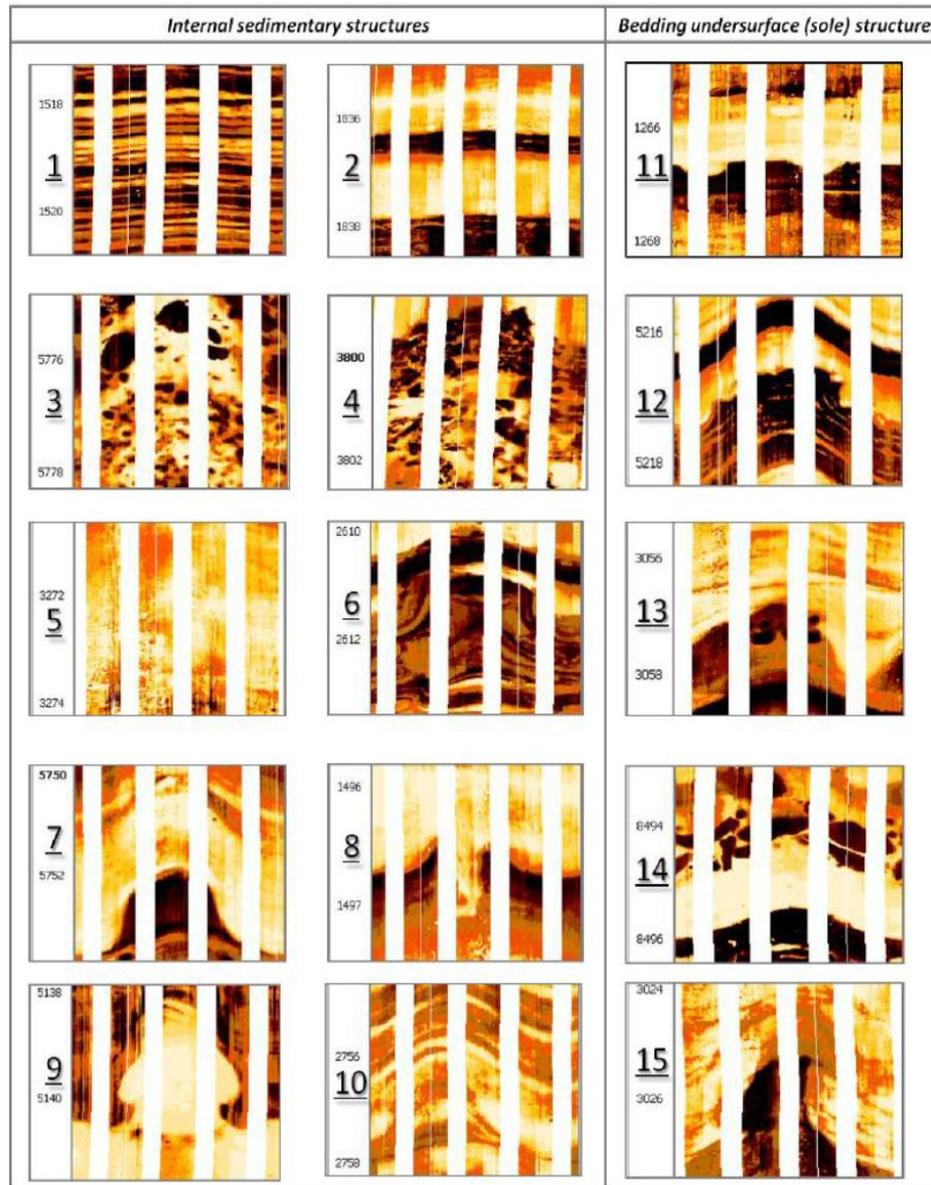


Figure 3. Sedimentary structures observed on the high-resolution borehole image logs. (depth in feet): 1,lamination ; 2,bedding; 3, inverse/reverse grading; 4, conglomerates; 5,massive bed; 6, convolute bedding (slump); 7, sediment deformation ; 8, water escape structure; 9, sand injection; 10, cross-bedding; 11,groove cast; 12,load cast; 13, small-scale scour surface; 14, erosional channel base with lag ;15 ,flame structure (Amer et. al., 2011).

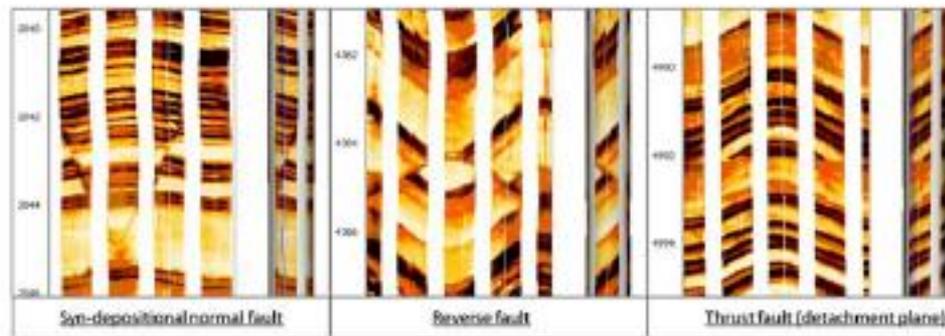
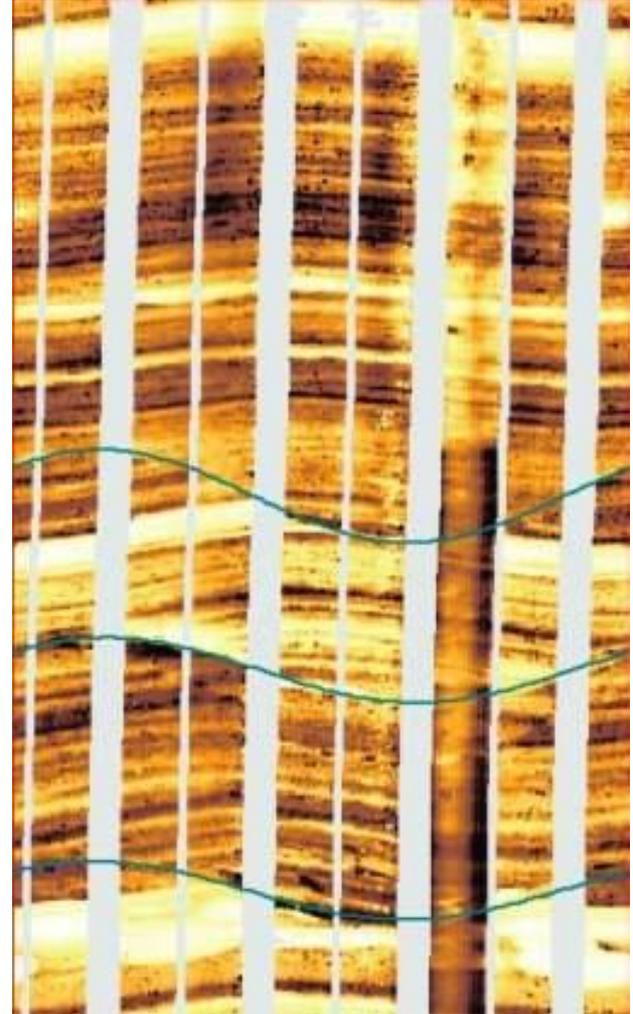


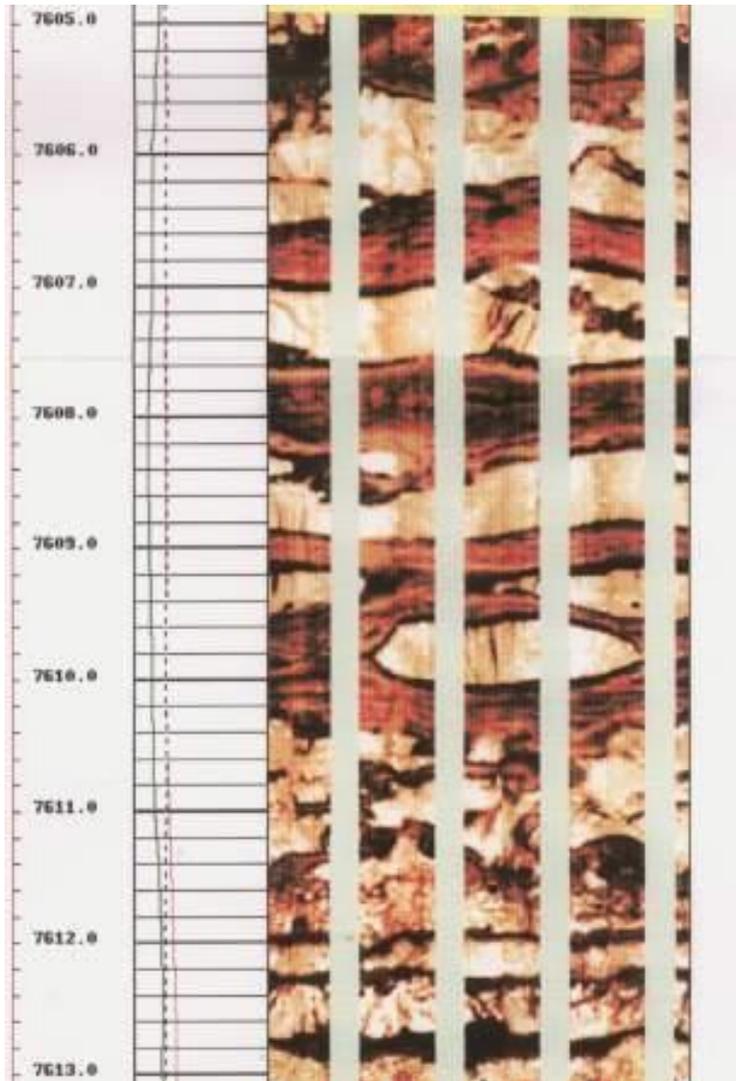
Figure 4. Normal, reverse and thrust faults as observed on high-resolution image log: (Amer et al., 2011).

# Faults on FMI log

- Offsets visible although throw is difficult to measure
- Dip changes may be visible
- Core to log



High resolution image logs allow identification of minor, narrow-aperture fractures when calibrated against core

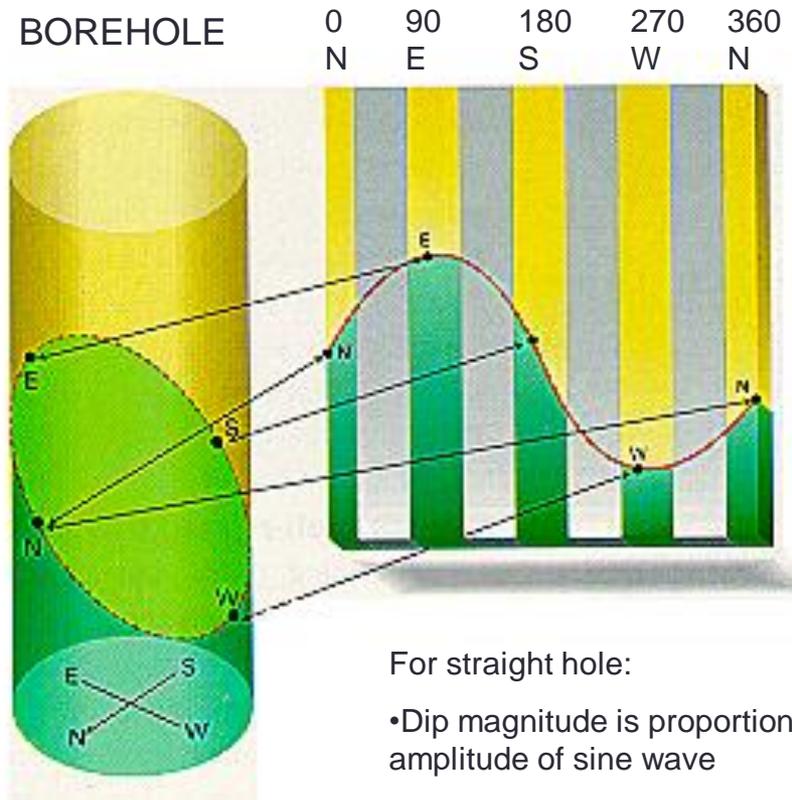


# Log Characterization

- Acoustic & electrical imaging logs and their interpretative workstations are becoming the *subsurface standard* for data acquisition, rapidly replacing core.
- Dipole sonic logs are attempting to quantify fracture occurrence and *fracture porosity*.

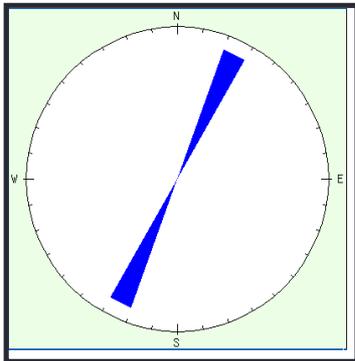
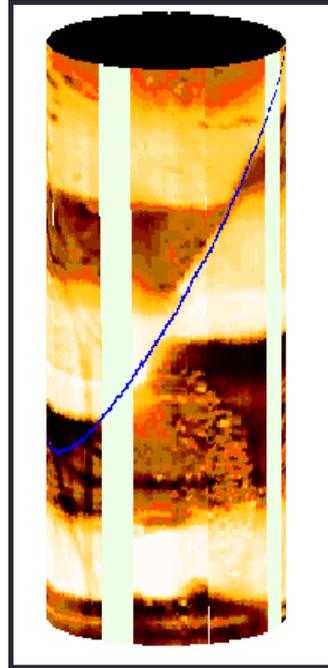
# Quantitative Fracture Analysis

- Planar features are expressed by ellipses on borehole walls which are expressed as sine waves
- Steepness of ellipses reflect the dip magnitude and orientation
- Apparent strike and dip relate to amplitudes and inflections in sine waves



TD: 53 / 270  
W  
David Spain (1998)

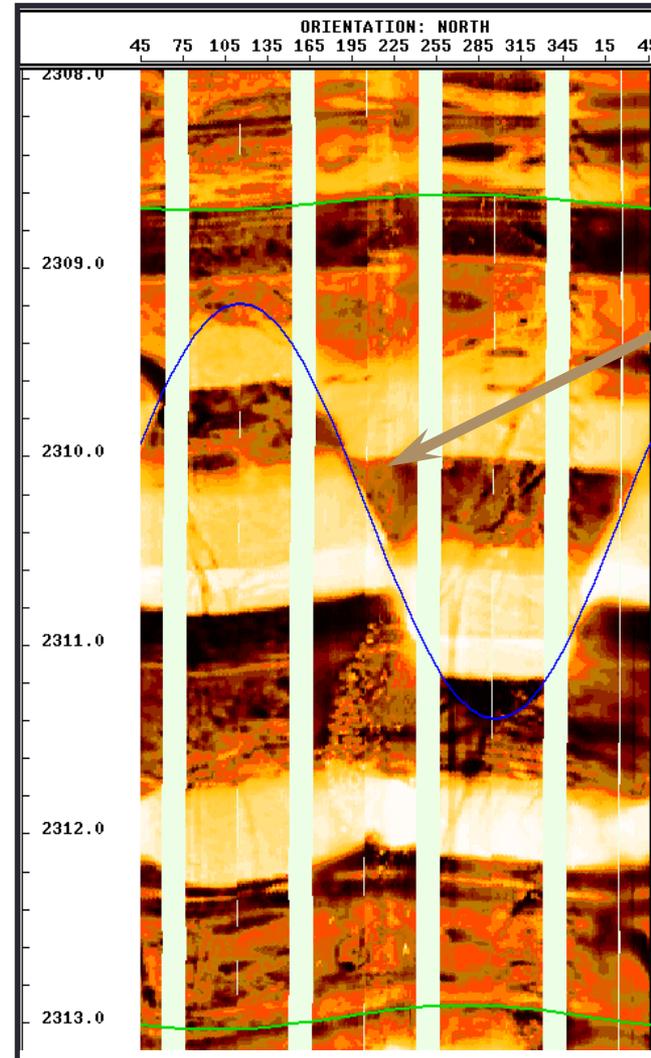
# Faults on FMI



Normal fault

Striking:  
N25E-S25W

Down to WNW



Fracture  
Trace

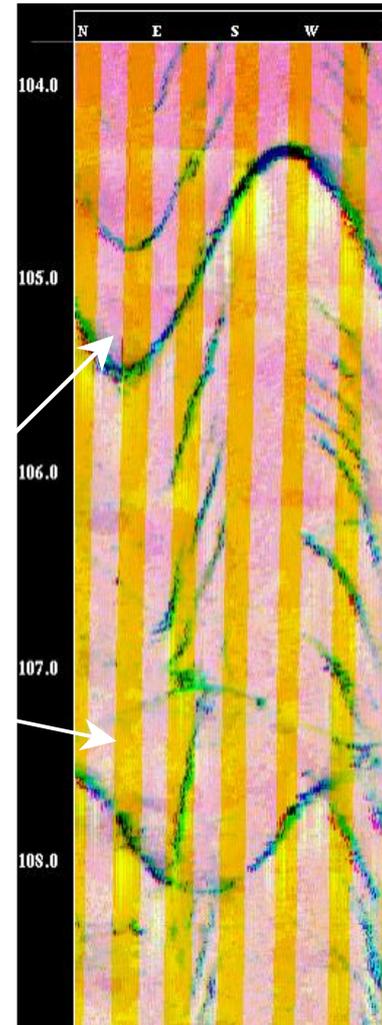
TD: 62/304

Oil well in granite.

:

Open fractures are black

Green fracture is filled with somewhat hard, resistive, slightly erodible material.



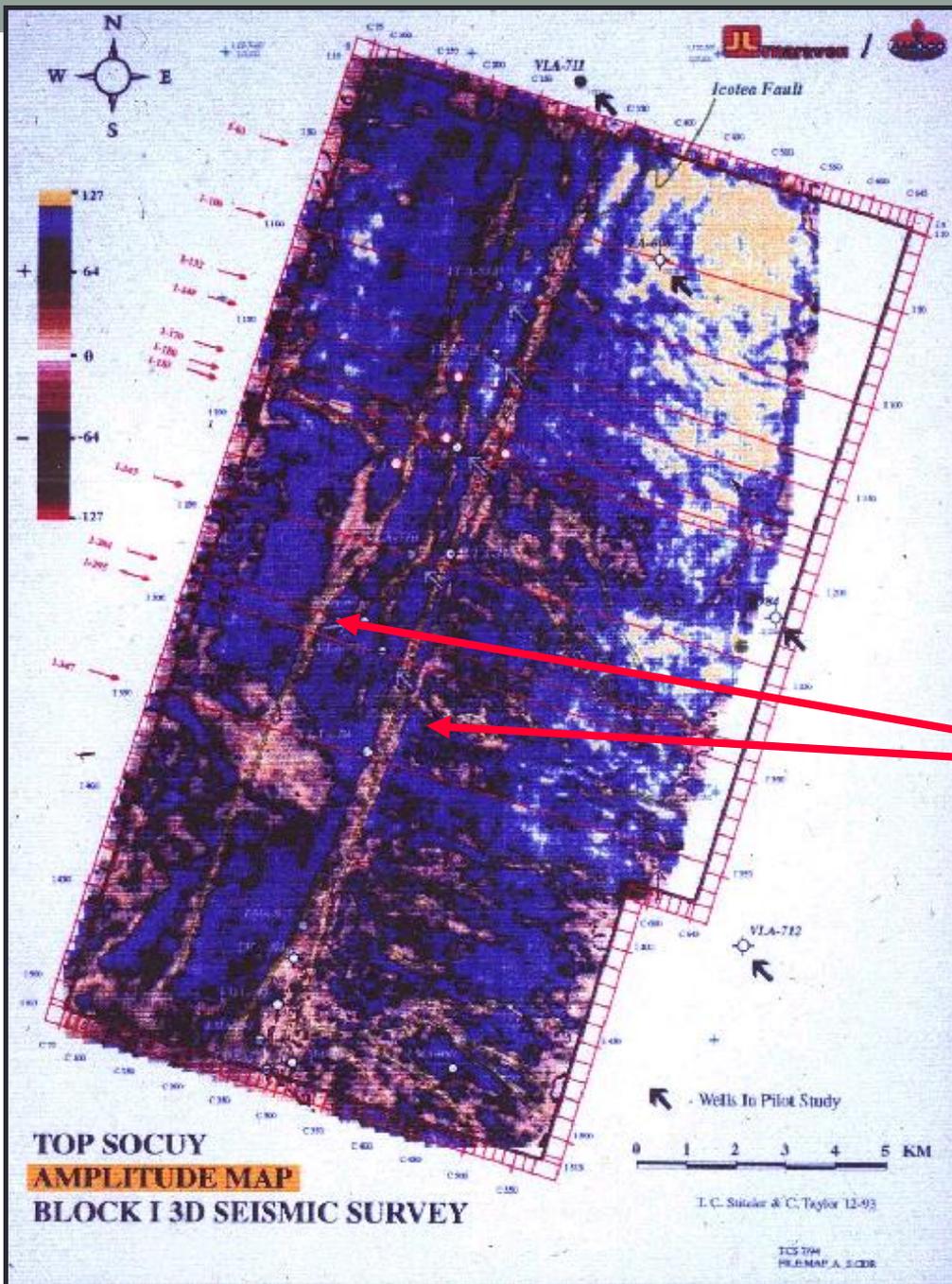
# Different fracture types are different colors in multivariate images.

| Examples                                  | Amplitude              | Microtopography  | Resistivity  |
|---|------------------------|--|--|
| Open                                      | Dark                   | Dark   | Dark   |
| Vein                                      | Bright                 | Bright   | Bright   |
| Fault gouge<br><i>Soft</i><br><i>Hard</i> | Moderate<br><br>Bright | Variable<br><br><i>Depends on<br/>drilling erosion</i> | <i>Permeable:</i><br><br>Dark<br><br><i>Impermeable:</i><br><br>Bright |

# Fracture Zone Identification

## Seismic attributes

- Single
- Multiple



Amplitude Map  
Top Socuy

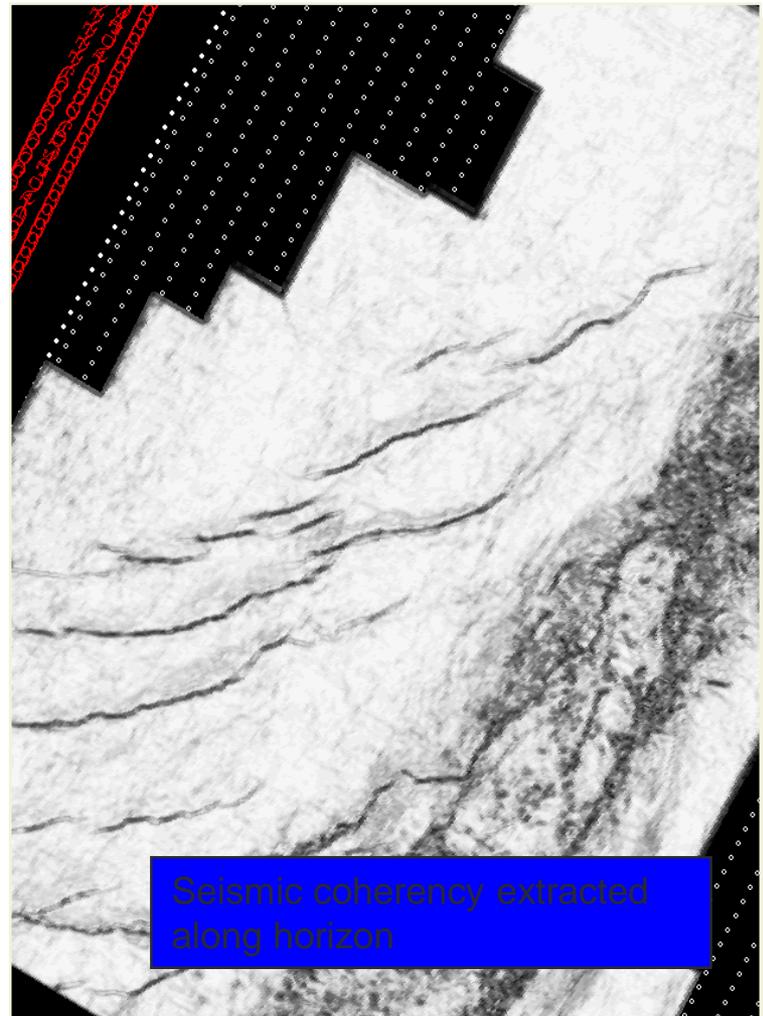
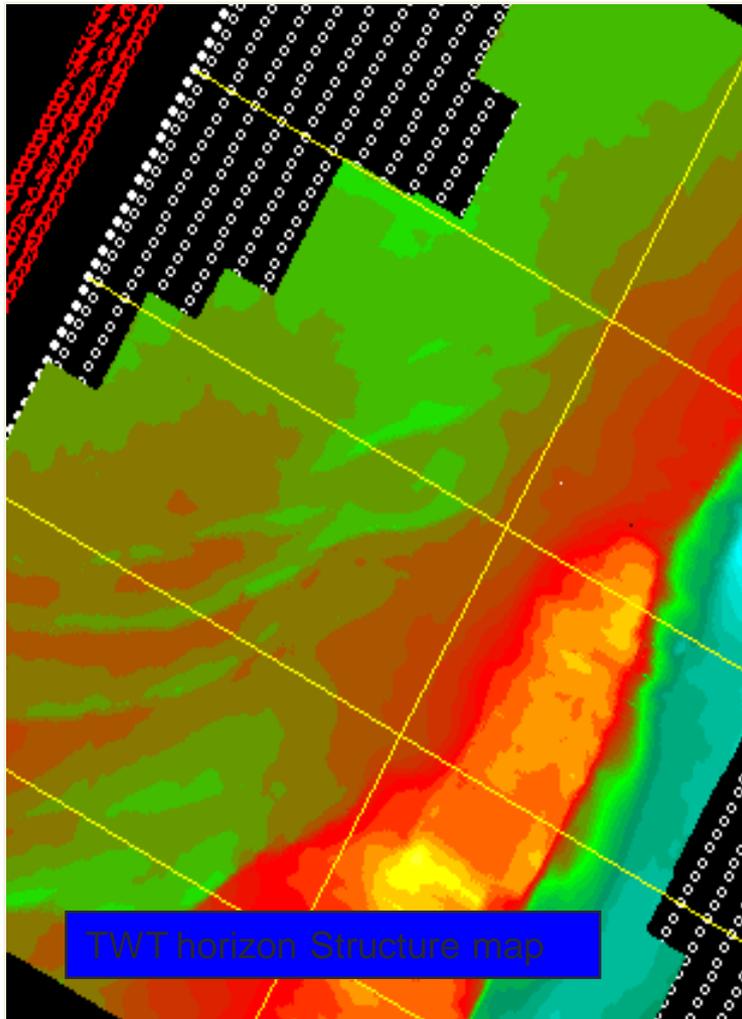
Lake Maravaibo,  
Venezuela

Note Fault Traces

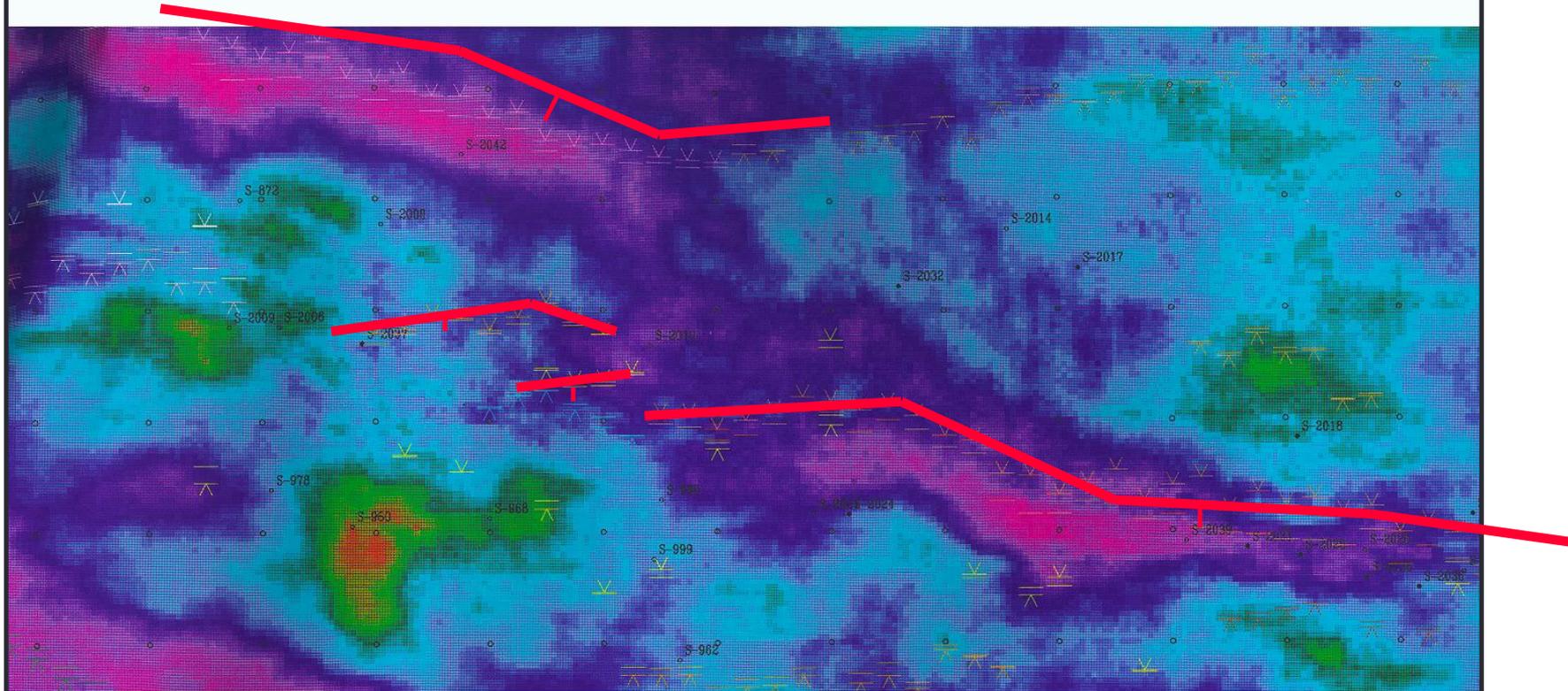
# 3-D Seismic data coherency :

delineating faults and fractures

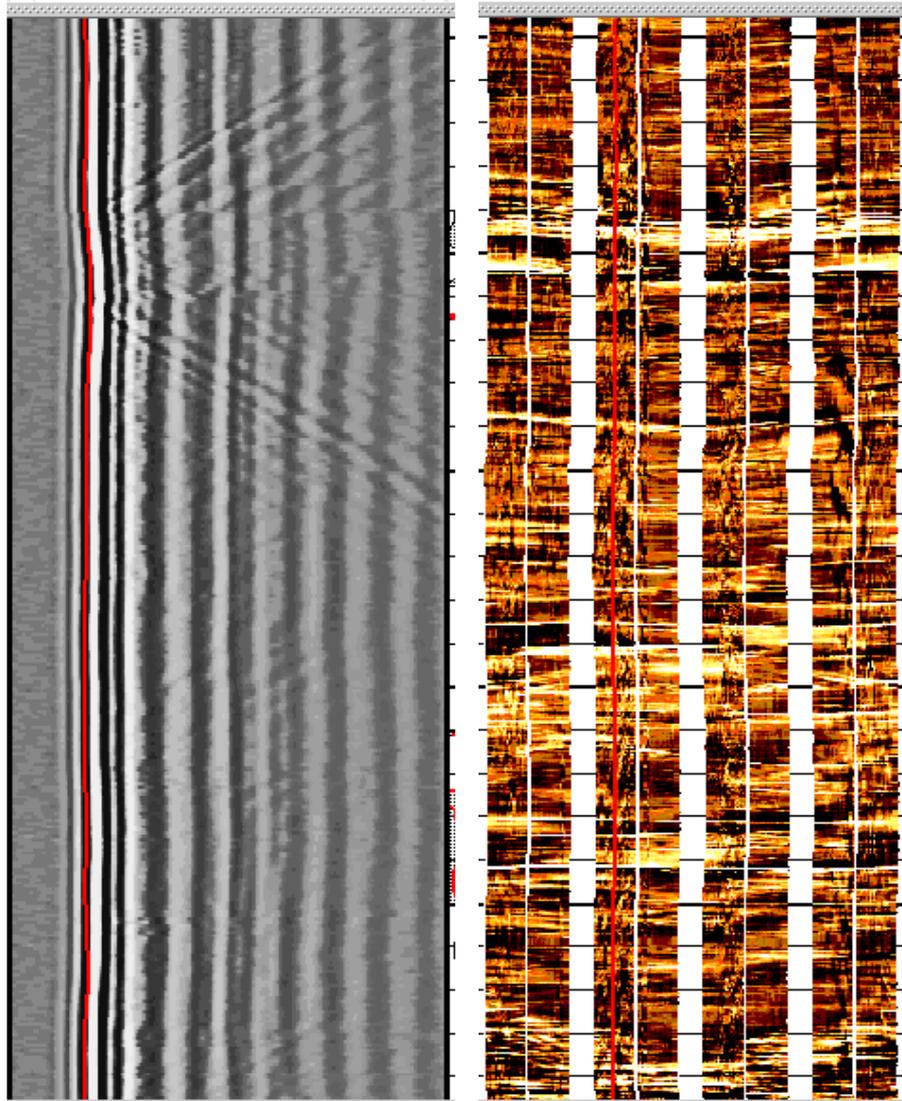
(Courtesy of Robert Humphreys)



# Sum of Absolute Amplitudes Over Normal Fault Segments Linked by Relay Zone



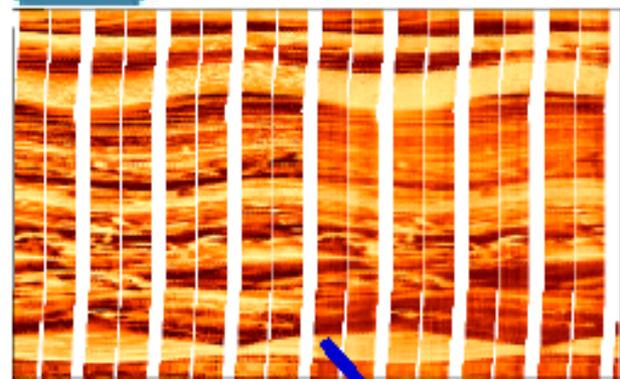
1 km



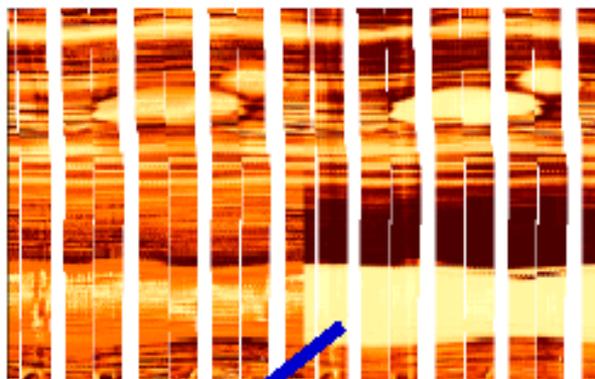
←  
OPEN FRACTURE

**Stoneley wave generation at open fracture**

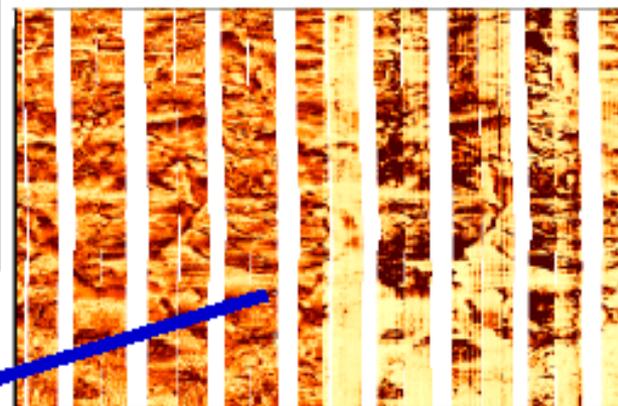
# Image Logs - Image facies and depositional environment reconstruction



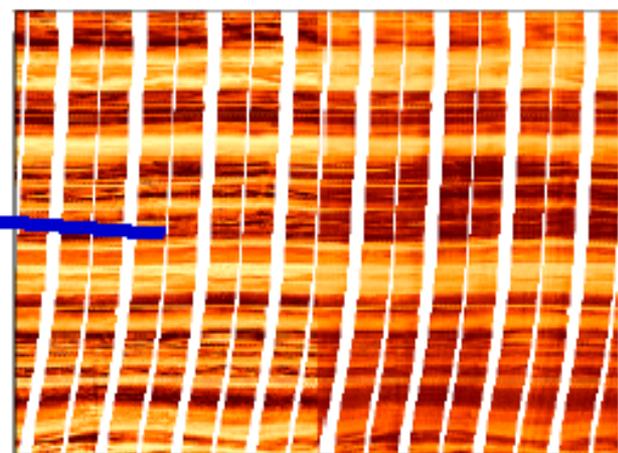
Cross-bedded sands



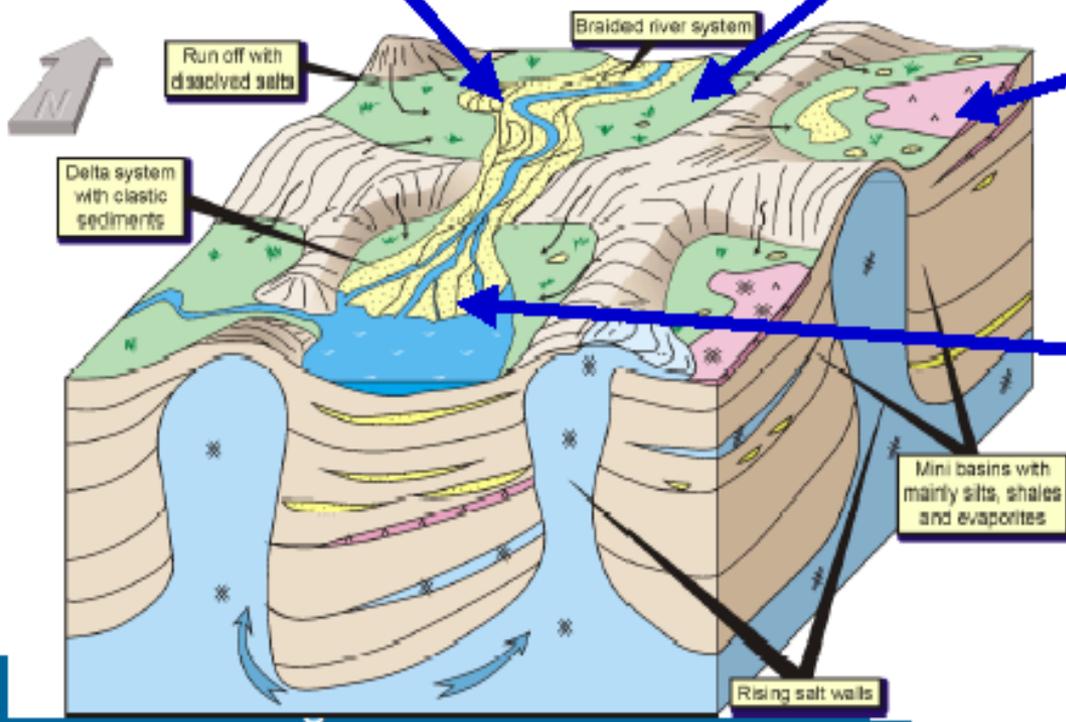
Cemented sands



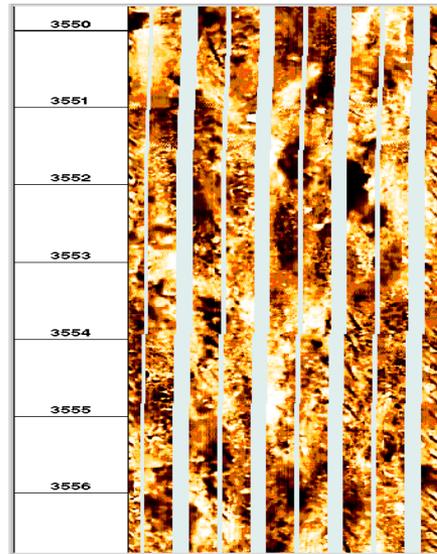
Anhydrite



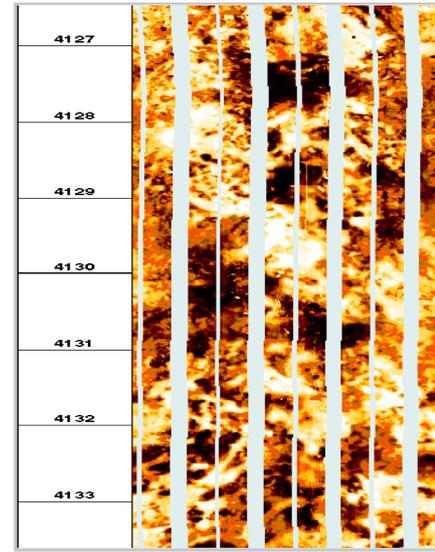
Low angle laminated sands



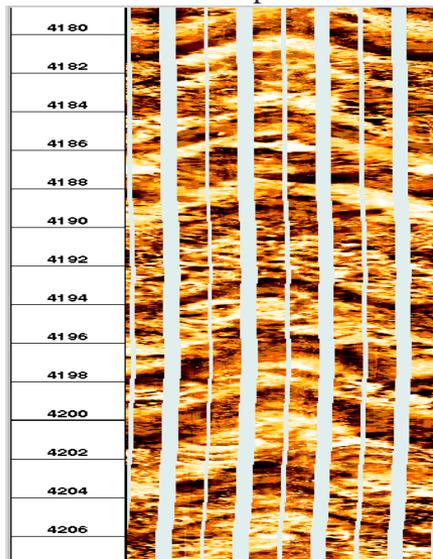
# Different Rock Fabrics from FMI log



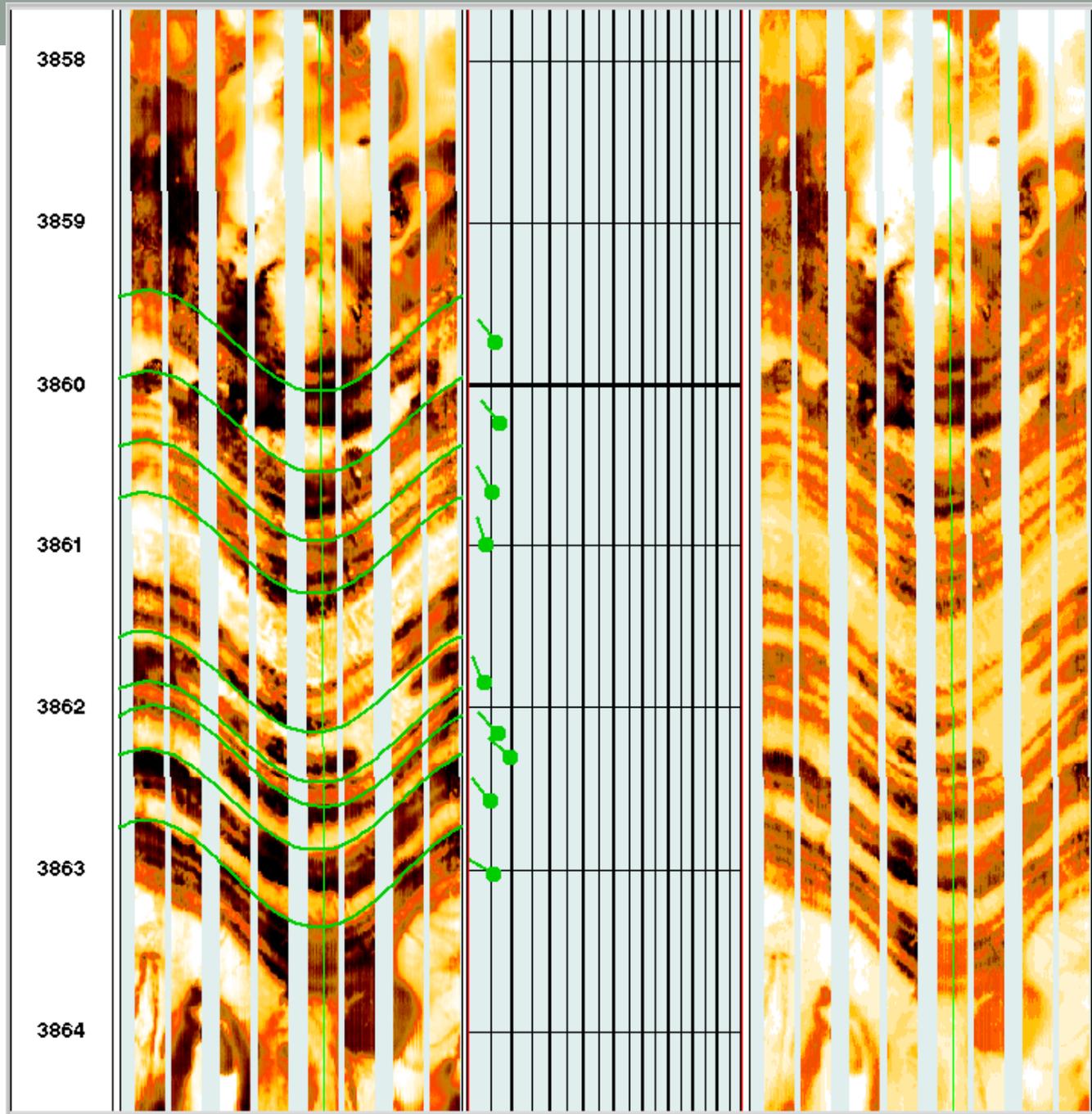
Inter-particle

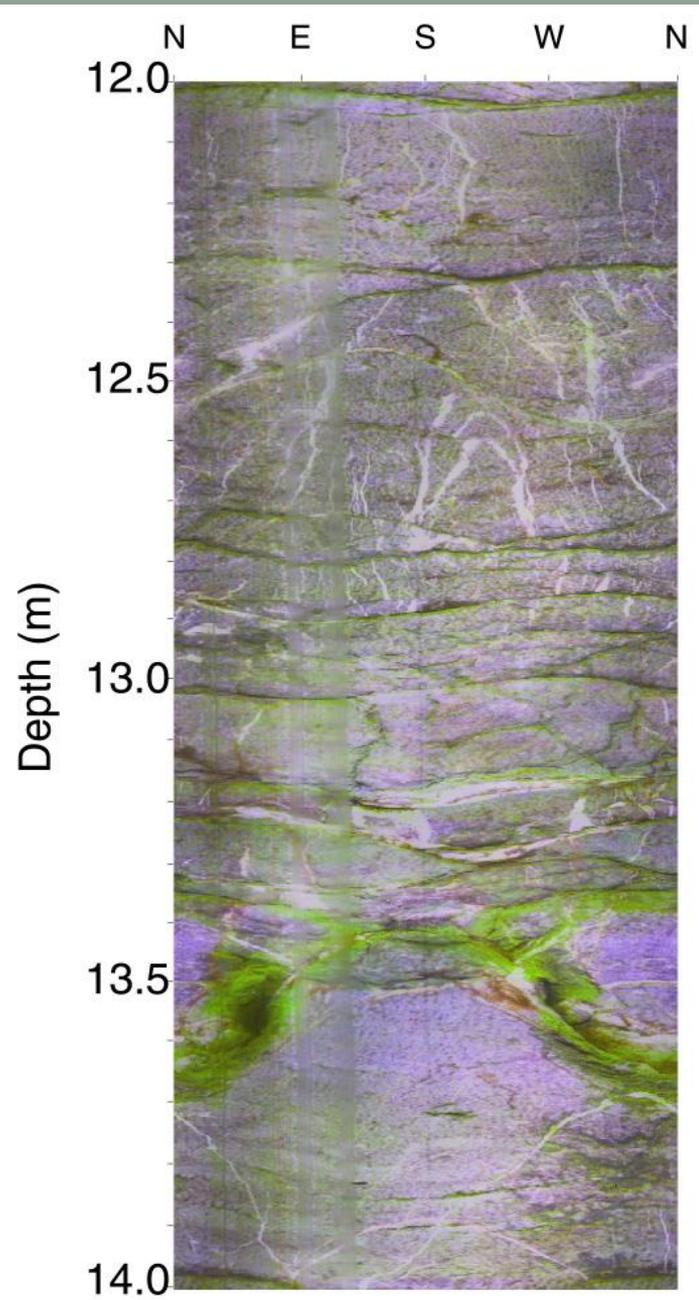


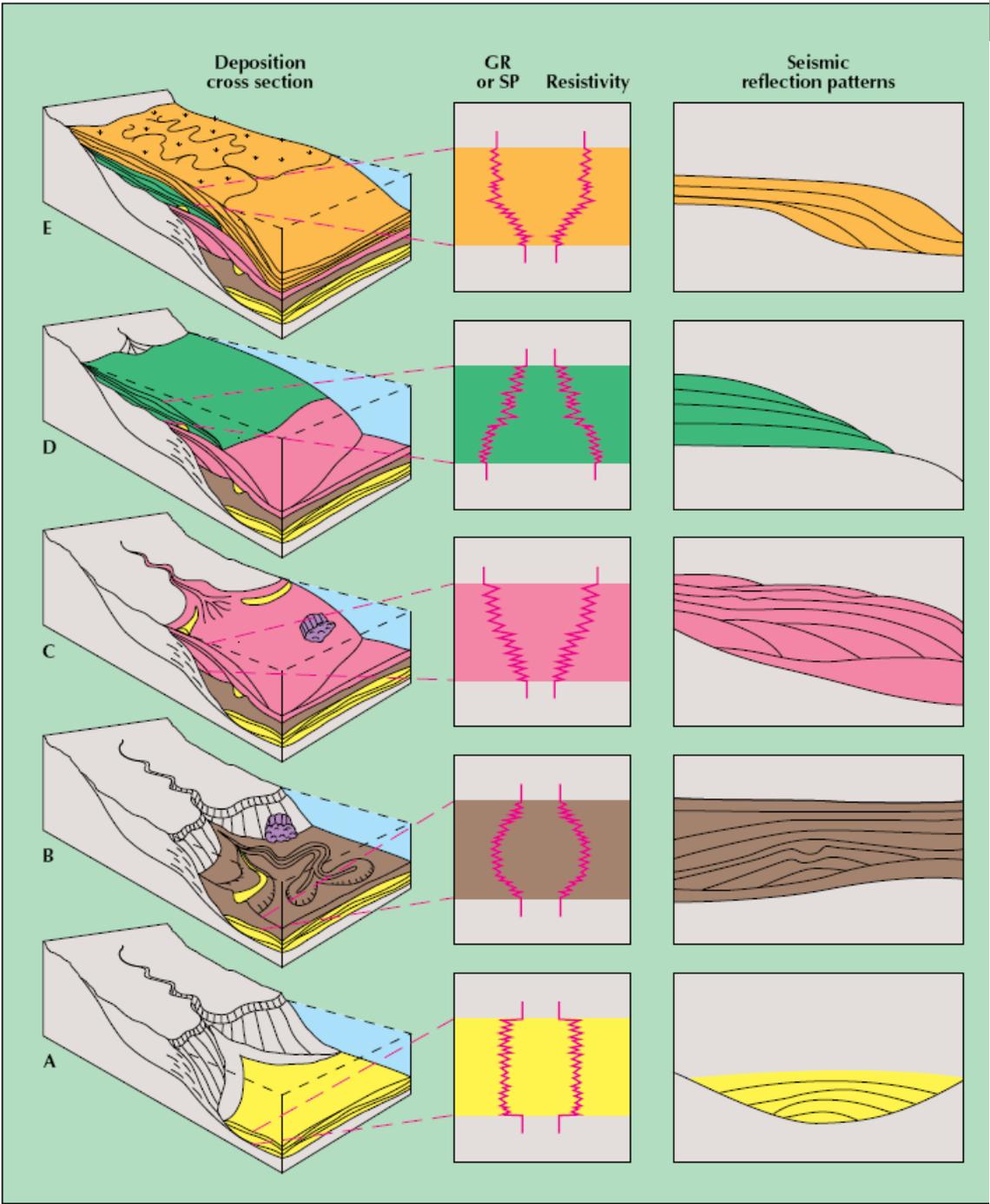
Patchy



Layered

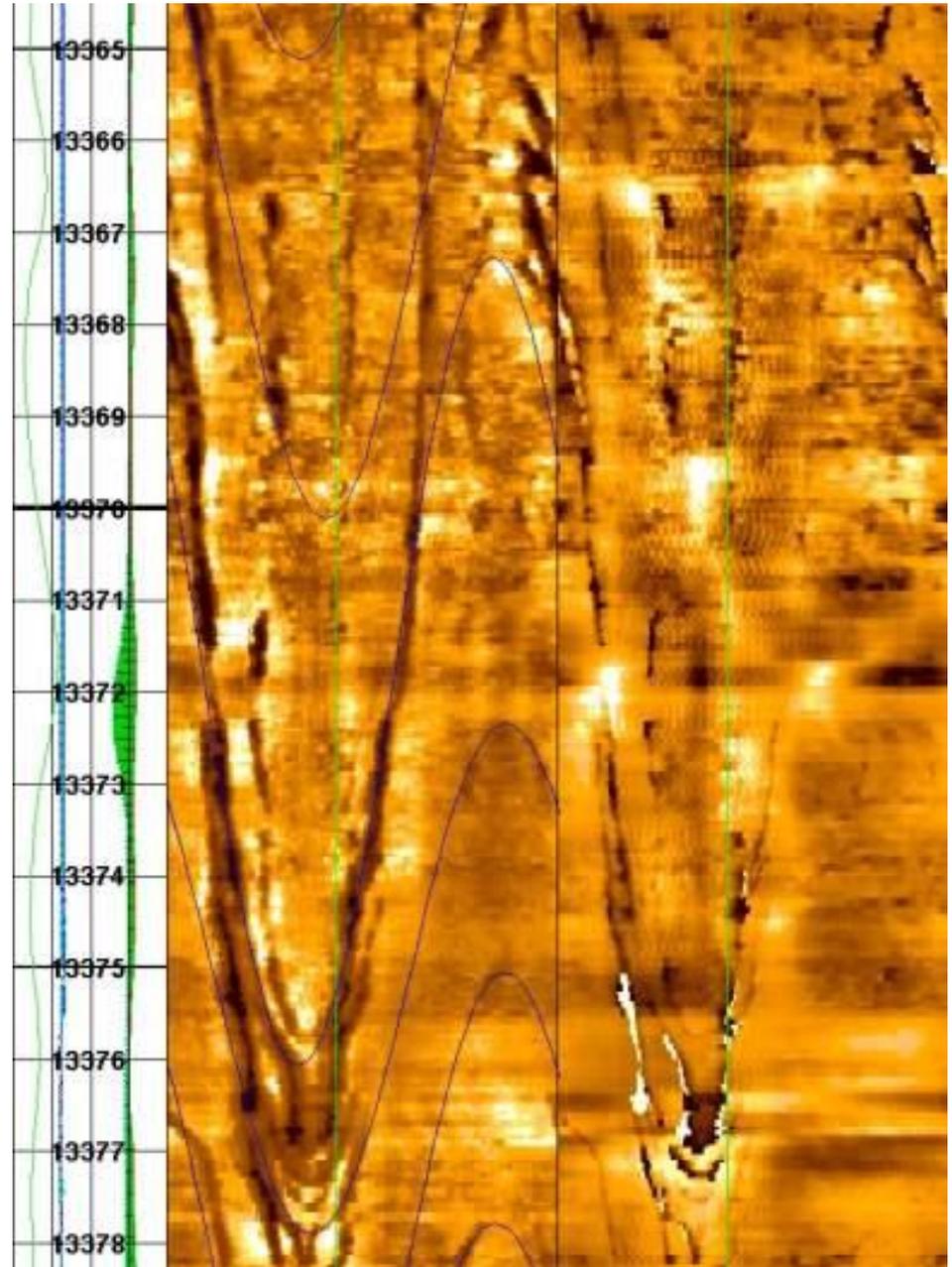




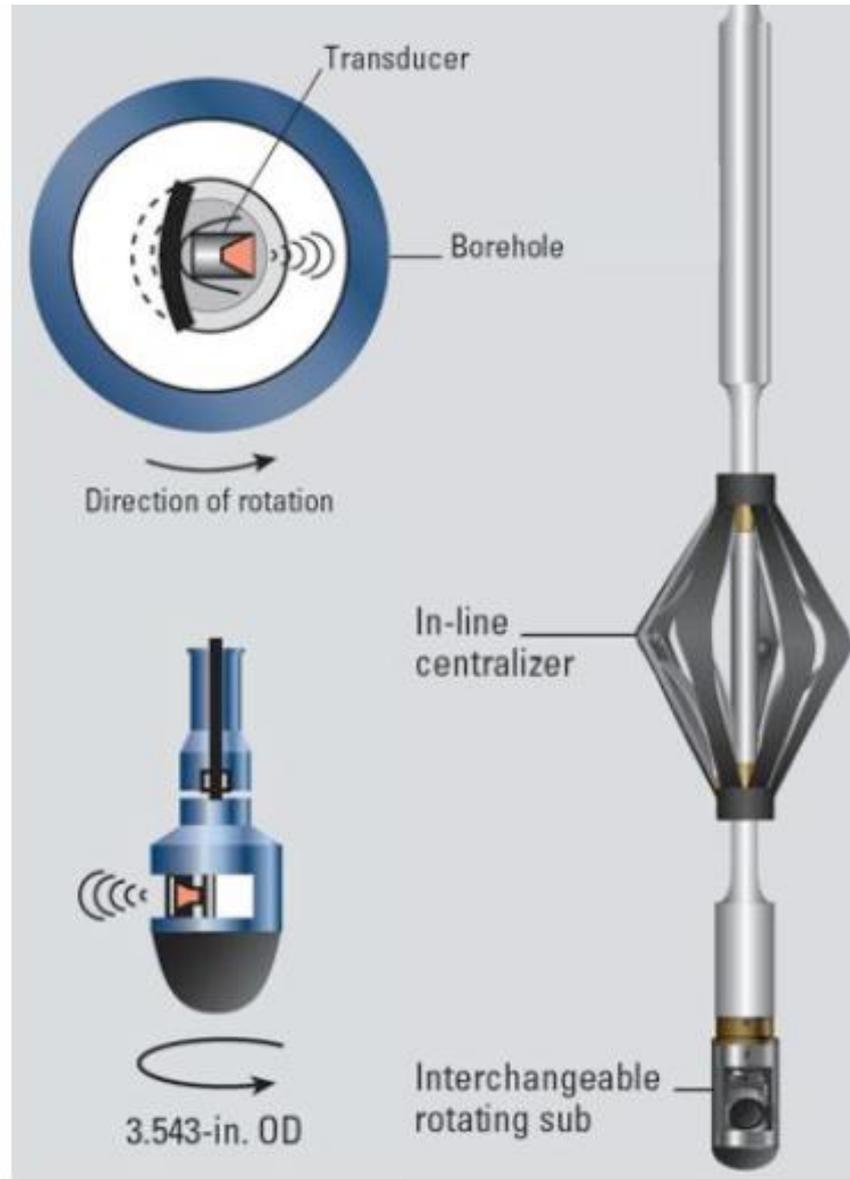


# UBI image of open fractures

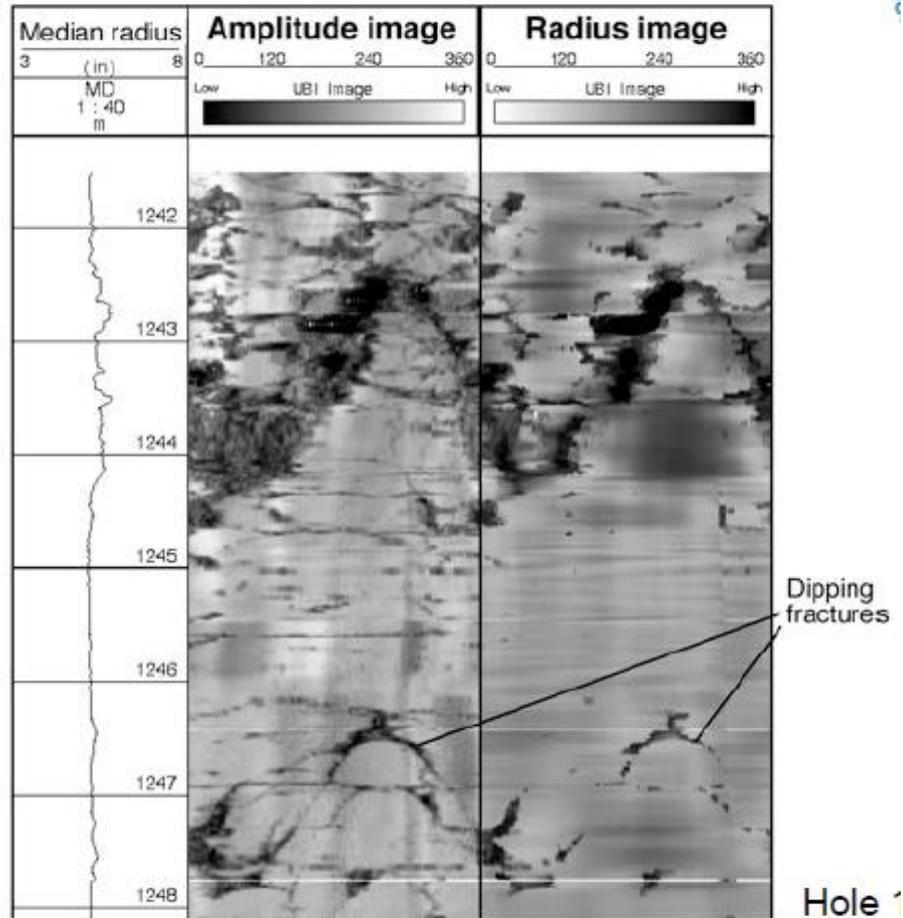
- Fractures make a sinusoidal trace on the borehole wall
- Data on type and orientation
- Acoustic show open fractures
- Resistivity show open and cemented fractures/faults



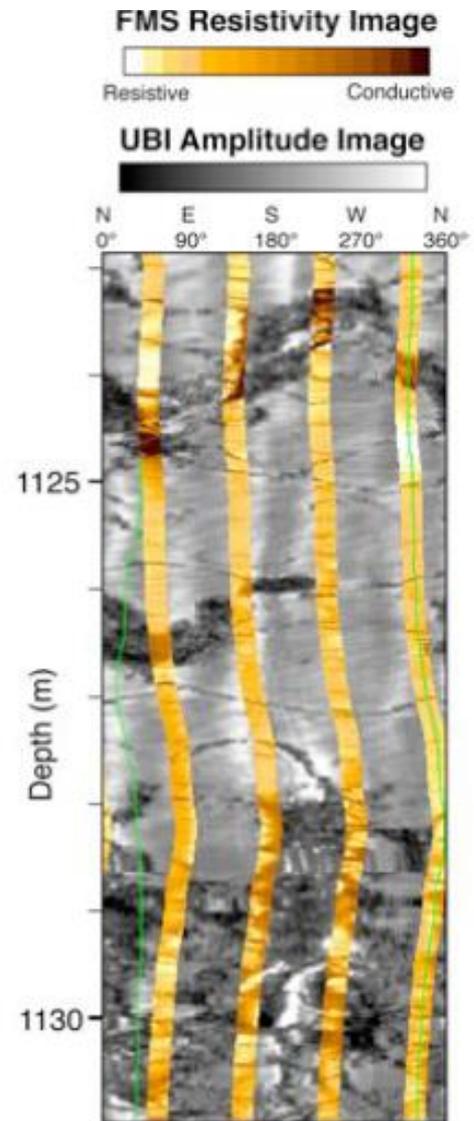
# Ultrasonic Borehole Imager



# UBI images



# UBI and FMS comparison



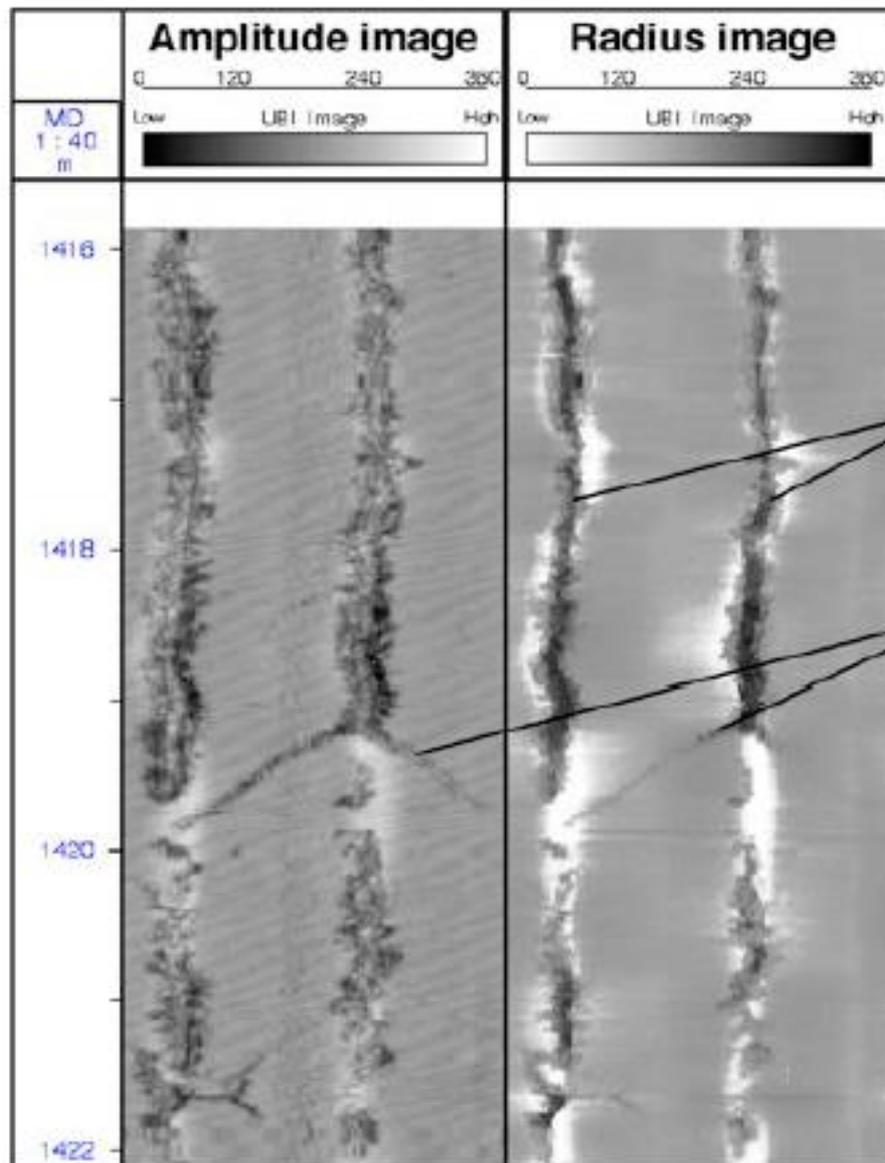
# Borehole Breakouts

Mark the minimum stress direction



Maximum Horizontal Stress

Minimum Horizontal Stress



Breakouts

Dipping fracture

## Core orientation

